



CS 410/510

Languages & Low-Level Programming

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Week 6: L4 Implementation

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Introducing “pork”

- pork = the “Portland Oregon Research Kernel”
- An implementation of (a subset of) L4 X.2
- Similar API to Pistachio, but specific to IA32 platform
- Written around the start of 2007
- “I have almost all the pieces that I need to build an L4 kernel ... perhaps I should try putting them together?”
- Built using the techniques we have seen so far in this course ...

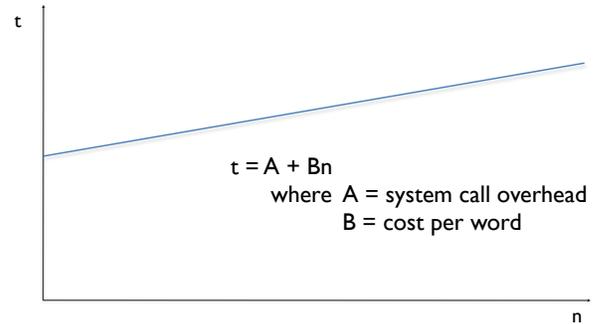
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Performance Benchmarking: Pingpong, Pistachio, and Pork

The pingpong benchmark

- A small L4 benchmark from the Karlsruhe Pistachio distribution, written in C++
- A single ipc call transfers contents of n message registers (MRs) between threads
- create two threads, “ping” & “pong”:
for $n = 0, 4, 8, \dots, 60$:
for 128K times:
 send n MRs from “ping” to “pong”
 send n MRs from “pong” to “ping”
 measure cycles & time per ipc call
- Cycles measured using rdtsc, time measured using interrupts

Expected Performance Model



Test Platform



- Dell Mini 9 netbook (1.6GHz Atom N270 CPU)
- Booting via grub from a flashdrive

Pistachio "Output"

```
5: INTER-AS (small)
s: print SQLite table
Benchmarking Inter-AS IPC...
IPC ( 0 MRs): 1240.67 cycles, 0.77us, 0.00 instrs
IPC ( 4 MRs): 1293.58 cycles, 0.81us, 0.00 instrs
IPC ( 8 MRs): 1301.64 cycles, 0.81us, 0.00 instrs
IPC (12 MRs): 1306.29 cycles, 0.81us, 0.00 instrs
IPC (16 MRs): 1317.96 cycles, 0.82us, 0.00 instrs
IPC (20 MRs): 1325.16 cycles, 0.83us, 0.00 instrs
IPC (24 MRs): 1333.26 cycles, 0.83us, 0.00 instrs
IPC (28 MRs): 1342.28 cycles, 0.84us, 0.00 instrs
IPC (32 MRs): 1358.34 cycles, 0.84us, 0.00 instrs
IPC (36 MRs): 1358.46 cycles, 0.85us, 0.00 instrs
IPC (40 MRs): 1362.88 cycles, 0.85us, 0.00 instrs
IPC (44 MRs): 1374.64 cycles, 0.86us, 0.00 instrs
IPC (48 MRs): 1382.88 cycles, 0.86us, 0.00 instrs
IPC (52 MRs): 1390.88 cycles, 0.87us, 0.00 instrs
IPC (56 MRs): 1398.02 cycles, 0.87us, 0.00 instrs
IPC (60 MRs): 1406.13 cycles, 0.88us, 0.00 instrs

What now?
g - Continue
q - Quit/New measurement
ESC - Enter KDB
```

Pork "Output"

```
The Portland 64 (small) (pork), February 2007
IPC ( 0 MRs): 1519.59 cycles, 0.95us, 0.00 instrs
IPC ( 4 MRs): 1538.14 cycles, 0.95us, 0.00 instrs
IPC ( 8 MRs): 1556.71 cycles, 0.99us, 0.00 instrs
IPC (12 MRs): 1579.67 cycles, 0.99us, 0.00 instrs
IPC (16 MRs): 1607.34 cycles, 1.02us, 0.00 instrs
IPC (20 MRs): 1634.98 cycles, 1.02us, 0.00 instrs
IPC (24 MRs): 1664.64 cycles, 1.02us, 0.00 instrs
IPC (28 MRs): 1687.47 cycles, 1.02us, 0.00 instrs
IPC (32 MRs): 1702.89 cycles, 1.06us, 0.00 instrs
IPC (36 MRs): 1721.46 cycles, 1.06us, 0.00 instrs
IPC (40 MRs): 1745.56 cycles, 1.10us, 0.00 instrs
IPC (44 MRs): 1787.86 cycles, 1.14us, 0.00 instrs
IPC (48 MRs): 1804.40 cycles, 1.14us, 0.00 instrs
IPC (52 MRs): 1818.78 cycles, 1.14us, 0.00 instrs
IPC (56 MRs): 1842.79 cycles, 1.14us, 0.00 instrs
IPC (60 MRs): 1875.66 cycles, 1.18us, 0.00 instrs

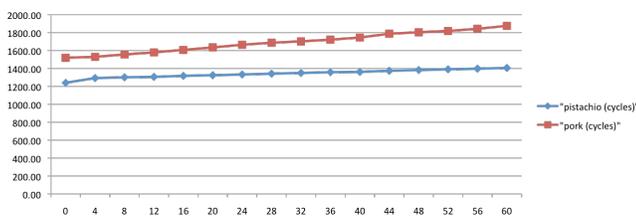
What now?
g - Continue
q - Quit/New measurement
```

Transcribed Data (Inter-AS)

#MRs	pistachio Inter-AS IPC		pork Inter-AS IPC		Ratio, pork/pistachio	
	cycles	microseconds	cycles	microseconds	cycles	microseconds
0	1240.67	0.77	1519.59	0.95	1.22	1.23
4	1293.58	0.81	1530.14	0.95	1.18	1.17
8	1301.64	0.81	1556.71	0.99	1.20	1.22
12	1306.29	0.81	1579.67	0.99	1.21	1.22
16	1317.96	0.82	1607.34	1.02	1.22	1.24
20	1325.16	0.83	1634.98	1.02	1.23	1.23
24	1333.26	0.83	1664.64	1.02	1.25	1.23
28	1342.28	0.84	1687.47	1.02	1.26	1.21
32	1358.34	0.84	1702.89	1.06	1.26	1.26
36	1358.46	0.85	1721.46	1.06	1.27	1.25
40	1362.88	0.85	1745.56	1.10	1.28	1.29
44	1374.64	0.86	1787.86	1.14	1.30	1.33
48	1382.88	0.86	1804.40	1.14	1.30	1.33
52	1390.88	0.87	1818.78	1.14	1.31	1.31
56	1398.02	0.87	1842.79	1.14	1.32	1.31
60	1406.13	0.88	1875.66	1.18	1.33	1.34

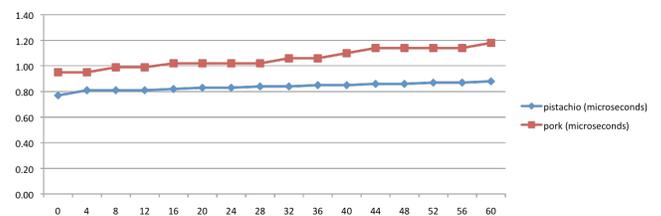
Inter-AS = "ping" and "pong" in different address spaces

Cycles (Inter-AS)

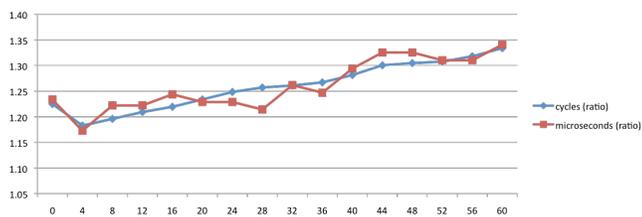


pistachio = 1274.66 + 2.27n (least squares)
 pork = 1512.57 + 6n

Microseconds (Inter-AS)



Pork : Pistachio (Inter-AS)

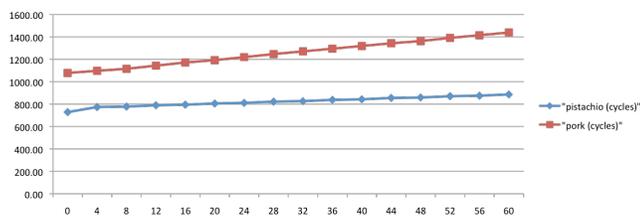


Transcribed Data (Intra-AS)

#MRs	pistachio Intra-AS IPC		pork Intra-AS IPC		Ratio, pork/pistachio	
	cycles	microseconds	cycles	microseconds	cycles	microseconds
0	729.19	0.45	1079.71	0.68	1.48	1.51
4	774.74	0.48	1097.90	0.68	1.42	1.42
8	778.49	0.48	1115.55	0.72	1.43	1.50
12	790.04	0.49	1143.99	0.72	1.45	1.47
16	795.65	0.49	1171.99	0.72	1.47	1.47
20	806.12	0.50	1193.23	0.76	1.48	1.52
24	811.85	0.50	1219.75	0.76	1.50	1.52
28	822.54	0.51	1247.19	0.76	1.52	1.49
32	827.20	0.51	1271.19	0.80	1.54	1.57
36	838.69	0.52	1295.20	0.80	1.54	1.54
40	843.37	0.52	1319.39	0.83	1.56	1.60
44	855.89	0.53	1343.43	0.83	1.57	1.57
48	859.57	0.53	1363.04	0.87	1.59	1.64
52	871.08	0.54	1391.45	0.87	1.60	1.61
56	875.72	0.54	1415.61	0.91	1.62	1.69
60	887.38	0.55	1439.58	0.91	1.62	1.65

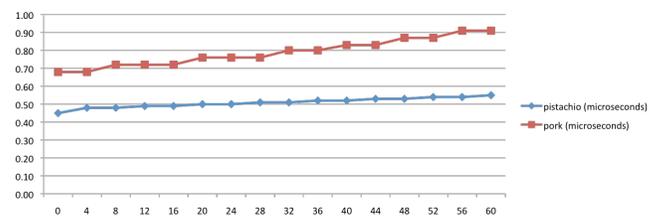
Intra-AS = "ping" and "pong" in same address space

Cycles (Intra-AS)

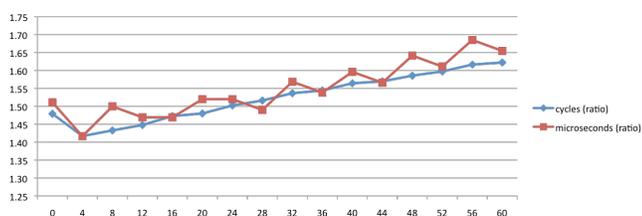


$$\begin{aligned} \text{pistachio} &= 756.54 + 2.21n \quad (\text{least squares}) \\ \text{pork} &= 1073.54 + 6.11n \end{aligned}$$

Microseconds (Intra-AS)



Pork : Pistachio (Intra-AS)



Estimating Clock Frequency

cycles/microsecond		cycles/microsecond	
pistachio	pork	pistachio	pork
1611.26	1599.57	1620.42	1586.34
1597.01	1610.67	1614.04	1614.56
1606.96	1572.43	1621.85	1549.38
1612.70	1595.63	1612.33	1588.88
1607.27	1575.82	1623.78	1627.76
1596.58	1602.92	1612.24	1570.04
1606.34	1632.00	1623.70	1604.93
1597.95	1654.38	1612.82	1641.04
1607.55	1606.50	1621.96	1588.99
1598.19	1624.02	1612.87	1619.00
1602.45	1586.87	1621.87	1589.63
1598.42	1588.30	1614.89	1618.59
1607.91	1582.81	1621.83	1566.71
1598.71	1595.42	1613.11	1599.37
1606.92	1616.48	1621.70	1555.62
1597.88	1589.54	1613.42	1581.96

Inter-AS

Intra-AS

Pretty consistent with 1.6GHz processor frequency, but estimates from pork are typically a little lower than those for Pistachio

Summary

Comparison	Range
Pork/Pistachio (Inter-AS)	1.17 – 1.35
Pork/Pistachio (Intra-AS)	1.42 – 1.65
Inter-AS/Intra-AS (Pork)	1.58 – 1.70
Inter-AS/Intra-AS (Pistachio)	1.30 – 1.40

- IPC in Pork is slower than Pistachio (17-65%)
- Overhead for crossing address spaces is higher in pork than Pistachio (65% vs 35%)

Performance Tuning Opportunities?

- Are there opportunities for performance-tuning pork to reduce the gap?
- **Inter-AS:**

pistachio	= 1274.66 + 2.27n	(least squares)
pork	= 1512.57 + 6n	
- **Intra-AS:**

pistachio	= 756.54 + 2.21n	(least squares)
pork	= 1073.54 + 6.11n	
- Example: pork takes ~6 cycles to transfer a machine word, where Pistachio uses around ~2

Transfer Message in pork

Source:

```
for (i=1; i<=u; i++) {
    rutcb->mr[i] = sutcb->mr[i];
}
```

Machine Code:

209: ba 01 00 00 00

mov	\$0x1, %edx	initialization
-----	-------------	----------------

20e: 8b 84 97 00 01 00 00
 215: 89 84 91 00 01 00 00
 21c: 83 c2 01
 21f: 39 d3
 221: 73 eb

mov	0x100(%edi, %edx, 4), %eax	
mov	%eax, 0x100(%ecx, %edx, 4)	
add	\$0x1, %edx	
cmp	%edx, %ebx	
jae	20e	loop

Transfer Message in Pistachio

Source:

```
INLINE void tcb_t::copy_mrs(tcb_t * dest, word_t start, word_t count)
{
    ASSERT(start + count <= IPC_NUM_MR);
    ASSERT(count > 0);
    word_t dummy;

    #if defined(CONFIG_X86_SMALL_SPACES)
        asm volatile ("mov %0, %%es" : : "r" (X86_KDS));
    #endif

    /* use optimized IA32 copy loop -- uses complete cacheline
       transfers */
    __asm__ volatile (
        "cld\n"
        "rep movsl (%0), (%1)\n"
        : /* output */
        "=s" (dummy), "=D" (dummy), "=c" (dummy)
        : /* input */
        "c" (count), "S" (&get_utcb()->mr[start]),
        "D" (&dest->get_utcb()->mr[start]);

    #if defined(CONFIG_X86_SMALL_SPACES)
        asm volatile ("mov %0, %%es" : : "r" (X86_UDS));
    #endif
}
```

Transfer Message in Pistachio

Machine Code:

b15: 31 c9
 b17: 8b 73 0c
 b1a: 8b 7d 0c
 b1d: 88 d1
 b1f: 81 c6 04 01 00 00
 b25: 81 c7 04 01 00 00
 b2b: fc
 b2c: f3 a5

xor	%ecx, %ecx	initialization
mov	0xc(%ebx), %esi	
mov	0xc(%ebp), %edi	
mov	%dl, %cl	
add	\$0x104, %esi	
add	\$0x104, %edi	
cld		
rep movsl	%ds:(%esi), %es:(%edi)	loop

Reflections

- In this case, the performance differences between pork and Pistachio can be understood and (likely) addressed
 - Could be handled by a **compiler intrinsic** (looks like a function, but treated specially by the compiler)
 - Familiar in C (memcpy)
- How easily can other performance gaps be closed?
 - Other opportunities for intrinsics? Special handling for fast paths? Algorithmic tweaks? Refined choice of data structures? etc.

Implementing pork

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Introducing “pork”

- pork = the “Portland Oregon Research Kernel”
- An implementation of (a subset of) L4 X.2
- Similar API to Pistachio, but specific to IA32 platform
- Written around the start of 2007
- “I have almost all the pieces that I need to build an L4 kernel ... perhaps I should try putting them together?”
- Built using the techniques we have seen so far in this course ...
- ... let’s take a tour!

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Boot

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boot.S should look very familiar ...

```
.global entry
entry: cli                                # Turn off interrupts

#-----
# Create initial page directory:
...
# Turn on paging/protected mode execution:
...
# Initialize GDT:
...
#-----
# Initialize IDT:
...
#-----
# Initialize PIC:
...
jmp    init                                # Jump off into kernel, no return!

#-----
# Halt processor: Also used as code for the idle thread.
.global halt
halt:  hlt
      jmp    halt

#-----
# Data areas:
.data
...
```

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Exception handlers

```
# Descriptors and handlers for exceptions: -----
intr  0, divideError
intr  1, debug
intr  2, nmiInterrupt
intr  3, breakpoint
intr  4, overflow

intr  5, boundRangeExceeded
intr  6, invalidOpcode
intr  7, deviceNotAvailable
intr  8, doubleFault,    err=HWERR
intr  9, coprocessorSegmentOverrun

intr 10, invalidTSS,    err=HWERR
intr 11, segmentNotPresent, err=HWERR
intr 12, stackSegmentFault, err=HWERR
intr 13, generalProtection, err=HWERR
intr 14, pageFault,    err=HWERR

// Slot 15 is Intel Reserved
intr 16, floatingPointError
intr 17, alignmentCheck, err=HWERR
intr 18, machineCheck
intr 19, simdFloatingPointException

// Slots 20-31 are Intel Reserved
```

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Hardware interrupt handlers

```
# Add descriptors for hardware irqs: -----
.equ  IRQ_BASE, 0x20    # lowest hw irq number

.irp  num, 0x21,0x22,0x23, 0x24,0x25,0x26,0x27, \
      0x28,0x29,0x2a,0x2b, 0x2c,0x2d,0x2e,0x2f
intr  \num, service=hardwareIRQ, err=(\num-IRQ_BASE)
.endr

intr  0x20, timerInterrupt
```

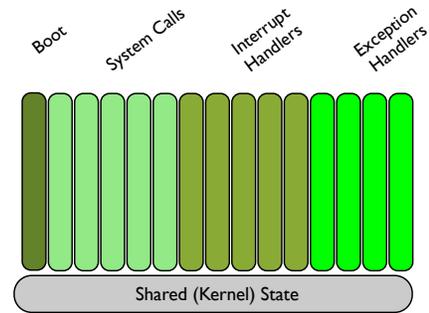
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System call entry points

```
# Add descriptors for system calls: -----
# These are the only idt entries that we will allow to be called
# from user mode without generating a general protection fault,
# so they will be tagged with dpl=3.
intr  INT_THREADCONTROL, threadControl,    err=NOERR, dpl=3
intr  INT_SPACECONTROL, spaceControl,      err=NOERR, dpl=3
intr  INT_IPC, ipc,                        err=NOERR, dpl=3
intr  INT_EXCHANGEREGS, exchangeRegisters, err=NOERR, dpl=3
intr  INT_SCHEDULE, schedule,              err=NOERR, dpl=3
intr  INT_THREADSWITCH, threadSwitch,     err=NOERR, dpl=3
intr  INT_UNMAP, unmap,                    err=NOERR, dpl=3
intr  INT_PROCCONTROL, processorControl,   err=NOERR, dpl=3
intr  INT_MEMCONTROL, memoryControl,      err=NOERR, dpl=3
intr  INT_SYSTEMCLOCK, systemClock,       err=NOERR, dpl=3
```

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Overall kernel structure



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An example exception handler

```
ENTRY invalidOpcode() {
    byte* eip = (byte*)current->context.iret.eip;
    if (eip[0]==0xf0 && eip[1]==0x90) { // Check for LOCK NOP instruction
        current->context.iret.eip += 2; // found => KernelInterface syscall
        KernelInterface_SetBaseAddress = kipStart(current->space);
        KernelInterface_SetAPIVersion = API_VERSION;
        KernelInterface_SetAPIFlags = API_FLAGS;
        KernelInterface_SetKernelId = KERNEL_ID;
        resume();
    }
    handleException(6);
}
```

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The KIP

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What's in the KIP?

~	SCHEDULE_SC	THREADSWITCH_SC	Reserved	+F0 / +1E0
EXCHANGEREGBITS SC	UNMAP_SC	LIPC_SC	IPC_SC	+E0 / +1C0
MEMORYCONTROL_pSC	PROCESSORCONTROL_pSC	THREADCONTROL_pSC	SPACECONTROL_pSC	+D0 / +1A0
ProcessorInfo	PageInfo	ThreadInfo	ClockInfo	+C0 / +180
ProcDescPtr	BootInfo	~	~	+B0 / +160
KipAreaInfo	UtcInfo	VirtualRegInfo	~	+A0 / +140
~	~	~	~	+90 / +120
~	~	~	~	+80 / +100
~	~	~	~	+70 / +E0
~	~	~	~	+60 / +C0
~	MemoryInfo	~	~	+50 / +A0
~	~	~	~	+40 / +80
~	~	~	~	+30 / +60
~	~	~	~	+20 / +40
~	~	~	~	+10 / +20
KernelDescPtr	APIFlags	APIVersion	0(0/32) K E 30 4 L	+0
+C / +18	+8 / +10	+4 / +8		+0

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kip.S

```
.data
.align (1<<PAGESIZE)
.global Kip, KipEnd
Kip:
.byte 'L', '4', 230, 'K'
.long API_VERSION, API_FLAGS, (KernelDesc - Kip)

.global Sigma0Server, SigmaServer, RootServer
Kdebug:
.long 0, 0, 0, 0 # Kernel debugger information
Sigma0Server:
.long 0, 0, 0, 0 # Sigma0 information
SigmaServer:
.long 0, 0, 0, 0 # Sigma1 information
RootServer:
.long 0, 0, 0, 0 # Rootserver information
.long RESERVED

.global MemoryInfo
.macro memoryInfo offset, number
.long ((\offset<<16) | \number)
.endm
MemoryInfo:
memoryInfo offset=(MemDesc-Kip), number=0

KdebugConfig:
.long 0, 0

.long RESERVED, RESERVED, RESERVED, RESERVED

VirtRegInfo:
.long NUMMRS-1 # virtual register information
...
```

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Onetime macros

```
KernelDesc:    .long    KERNEL_ID          # Kernel Descriptor

               .macro   kernelGenDate day, month, year
               .long    (\year-2000)<<9 | (\month<<5) | \day
               .endm
               kernelGenDate day=4, month=2, year=2007

               .macro   kernelVer ver, subver, subsubver
               .long    (((\ver<<8) | \subver)<<16) | \subsubver
               .endm
               kernelVer ver=1, subver=2, subsubver=0
```

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Kernel entry points

```
SystemCalls:  .long    (spaceControlEntry - Kip)
               .long    (threadControlEntry - Kip)
               .long    (ipcEntry - Kip)
               ...
               .long    (exchangeRegistersEntry - Kip)
               .long    (threadSwitchEntry - Kip)
               ...

               #-- Privileged system call entry points: -----
               .align   128

spaceControlEntry:
               int     $INT_SPACECONTROL
               ret

threadControlEntry:
               int     $INT_THREADCONTROL
               ret
               ...

ipcEntry:      #-- System call entry points: -----
               int     $INT_IPC
               ret

threadSwitchEntry:
               int     $INT_THREADSWITCH
               ret
               ...
```

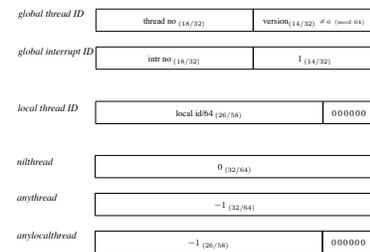
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Thread Ids

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Thread Ids

- User programs can reference other threads using thread ids



```
/*-----
 * Thread Ids:
 *-----*/
typedef unsigned ThreadId; // Global thread id
#define nilthread 0
#define anythread (-1)
#define anylocalthread ((-1)<<6)
#define threadId(t,v) ((t<<VERSIONBITS)|v)
#define threadNo(tid) mask((tid)>>VERSIONBITS, THREADBITS)
#define isGlobal(tid) (mask(tid,6))
```

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Flexpages

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Flexpages (fpages)

- A generalized form of “page” that can vary in size:



- Includes both 4KB pages and 4MB superpages as special cases
- Also includes special cases to represent the full address space (complete) and the empty address space (nilpage):



- Can be represented, in practice, using collections of 4KB and 4MB pages

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Alas, this could fail!

- Consider the following function:

```
void g1() { // 1 suffix because this function
           // allocates a page
    f();
    void* p = allocPage1();
    ...
}
```

- But now suppose f() takes the form:

```
void f() {
    if (availPages(1)) { ... allocPage1(); ... }
}
```

- Pork still uses this naming convention, but relies on “disciplined use”
- Maybe a type system could do better ... ?

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Thread Control Blocks

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Thread control blocks (TCBs)

```
struct TCB {
    ThreadId tid; // this thread's id and version number
    byte status; // thread status
    byte prio; // thread priority
    byte padding;
    byte count; // for gc of TCBs in kernel memory
    struct UTCB* utcb; // pointer to this thread's utcb
    unsigned vutcb; // virtual address of utcb

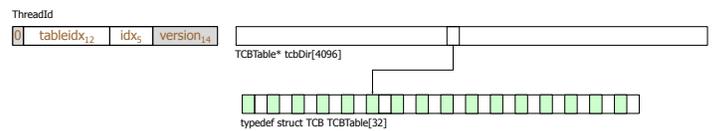
    struct TCB* sendqueue; // list of threads waiting to send
    struct TCB* receiver; // pointer to owner of sendqueue
    struct TCB* prev;
    struct TCB* next;

    struct Space* space; // pointer to this thread's addr space
    unsigned faultCode; // exception number or page fault addr
    struct Context context; // context of user level process

    ThreadId scheduler; // scheduling parameters
    unsigned timeslice;
    unsigned timeleft;
    unsigned quantleft;
};
```

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Thread control blocks (TCBs)

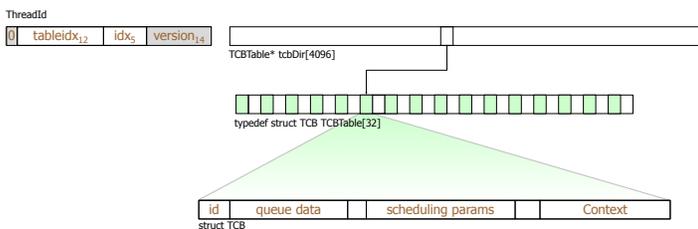


```
struct TCB* existsTCB(unsigned threadNo) {
    TCBTable* tab = tcbDir[threadNo >> TCBDIRBITS];
    if (tab) {
        struct TCB* tcb = ((struct TCB*)tab) + mask(threadNo, TCBDIRBITS);
        if (tcb->space) {
            return tcb;
        }
    }
    return 0;
}

struct TCB* findTCB(ThreadId tid) {
    struct TCB* tcb = existsTCB(threadNo(tid));
    return (tcb && tcb->tid==tid) ? tcb : 0;
}
```

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Thread control blocks (TCBs)



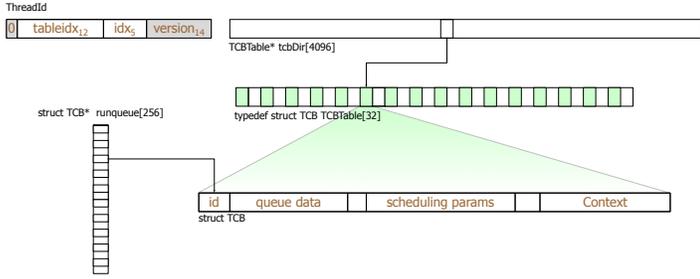
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Allocating and initializing TCBs

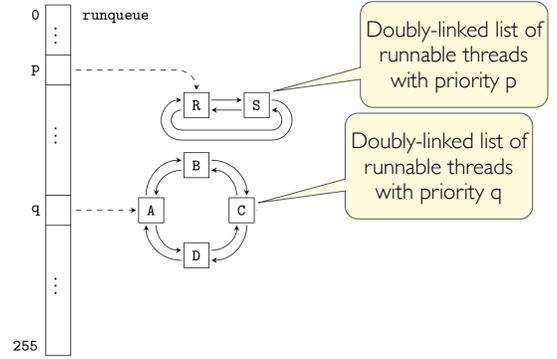
```
struct TCB* allocTCB1(ThreadId tid, struct Space* space, ThreadId scheduler) {
    unsigned threadNo = threadNo(tid);
    TCBTable* tab = tcbDir[threadNo >> TCBDIRBITS];
    if (!tab) {
        tab = tcbDir[threadNo >> TCBDIRBITS] = (TCBTable*)allocPage1();
    }
    ++tab[0]->count; // Count an additional TCB in this page
    struct TCB* tcb = ((struct TCB*)tab) + mask(threadNo, TCBDIRBITS);
    tcb->tid = tid;
    tcb->status = Halted;
    tcb->space = space;
    tcb->utcb = 0;
    tcb->vutcb = 0xffffffff;
    tcb->sendqueue = 0;
    tcb->next = tcb;
    tcb->prev = tcb;
    tcb->prio = 128; // Default is unspecified
    tcb->scheduler = scheduler;
    tcb->timeslice = 0;
    tcb->timeleft = 10000; // Default timeslice is 10ms
    tcb->quantleft = 0; // Default quantum is infinite
    initUserContext(&(tcb->context));
    enterSpace(space); // Register the thread in this space
    return tcb;
}
```

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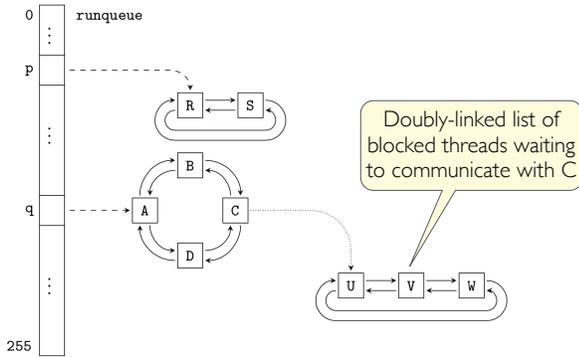
Thread Control Blocks (TCBs)



Scheduling data structures: runqueue



Scheduling data structures: runqueue



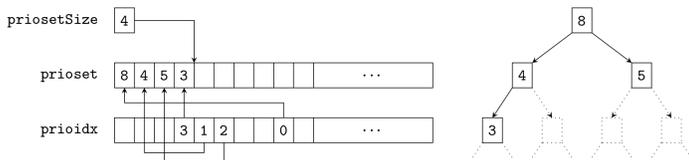
Switching to a new thread (w/o debugging)

```
static void inline switchTo(struct TCB* tcb) {
    struct Context* ctxt = &(tcb->context);
    current = tcb; // Change current thread
    *utcbptr = tcb->vutcb // Change UTCB address
    + (unsigned)&((struct UTCB*)0)->mr[0]);
    esp0 = (unsigned)(ctxt + 1); // Change esp0
    switchSpace(tcb->space); // Change address space
    returnToContext(ctxt);
}

...

void switchSpace(struct Space* space) {
    if (space->pdire) { // No switch for kernel/inactive threads
        if (currentSpace != space) {
            currentSpace = space;
            setPdir(currentSpace->pdire);
            currentSpace->loaded = 1;
        } else {
            refreshSpace();
        }
    }
}
```

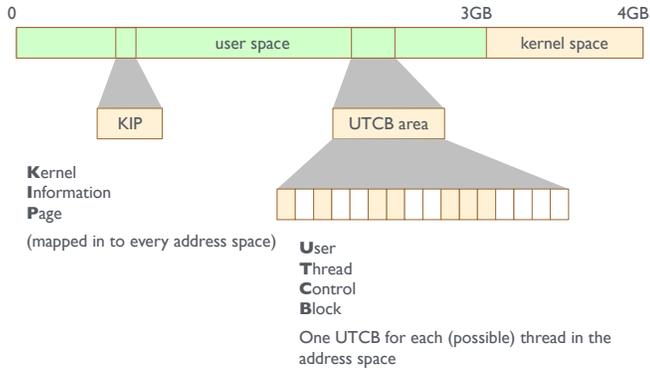
Scheduling data structures: prioset



```
/*-----
 * Select a new thread to execute. We pick the next runnable thread with
 * the highest priority.
 */
void reschedule() {
    switchTo(holder = priosetSize ? runqueue[prioset[0]] : idleTCB);
}
```

Address Spaces

Address space layout



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Representing address spaces

```

struct Space {
    unsigned pdir;           // Structure known only in this module
    unsigned mem;           // Physical address of page directory
    struct Mapping* map;     // Memory map
    struct Mapping* kipArea; // Location of kernel interface page
    Fpage utcbArea;         // Location of UCTBs
    unsigned count;         // Count of threads in this space
    unsigned active;        // Count of active threads in this space
    unsigned loaded;        // 1 => already loaded in cr3
};

...

void enterSpace(struct Space* space) {
    space->count++; // increment reference count;
}

...

void configureSpace(struct Space* space, Fpage kipArea, Fpage utcbArea) {
    ASSERT(!activeSpace(space), "configuring active space");
    space->kipArea = kipArea;
    space->utcbArea = utcbArea;
}
    
```

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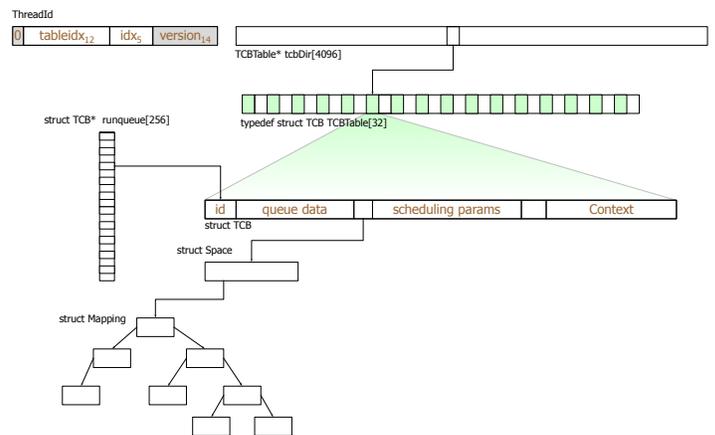
A typical system call

```

ENTRY spaceControl() {
    if (!privileged(current->space)) { /* check for privileged thread */
        retError(SpaceControl_Result, NO_PRIVILEGE);
    } else {
        struct TCB* dest = findTCB(SpaceControl_SpaceSpecifier);
        if (!dest) {
            retError(SpaceControl_Result, INVALID_SPACE);
        } else if (!activeSpace(dest->space)) { /* ignore if active threads */
            Fpage kipArea = SpaceControl_KipArea;
            Fpage utcbArea = SpaceControl_UtcbArea;
            unsigned kipEnd, utcbEnd;
            if (!isNilpage(utcbArea) /* validate utcb area */
                || fpageSize(utcbArea) < MIN_UTCBAREASIZE
                || (utcbEnd=fpageEnd(utcbArea)) >= KERNEL_SPACE) {
                retError(SpaceControl_Result, INVALID_UTCB);
            } else if (!isNilpage(kipArea) /* validate KIP area */
                || fpageSize(kipArea) != KIPAREASIZE
                || (kipEnd=fpageEnd(kipArea)) >= KERNEL_SPACE
                || (kipEnd=fpageStart(kipArea) && utcbEnd=fpageStart(kipArea))) {
                retError(SpaceControl_Result, INVALID_KIPAREA);
            } else {
                configureSpace(dest->space, kipArea, utcbArea);
            }
        }
        SpaceControl_Result = 1;
        SpaceControl_Control = 0; /* control parameter is not used */
        resume();
    }
}
    
```

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Spaces and mappings



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Representing mappings

```

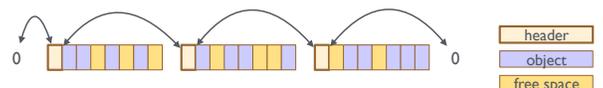
struct Mapping {
    struct Space* space; // Which address space is this in?
    struct Mapping* next;
    struct Mapping* prev;
    unsigned level;
    Fpage vfp; // Virtual fpage
    unsigned phys; // Physical address
    struct Mapping* left;
    struct Mapping* right;
};
    
```

- A binary search tree of memory regions within a single address space
- A mapping data base that documents the way that memory regions have been mapped between address spaces

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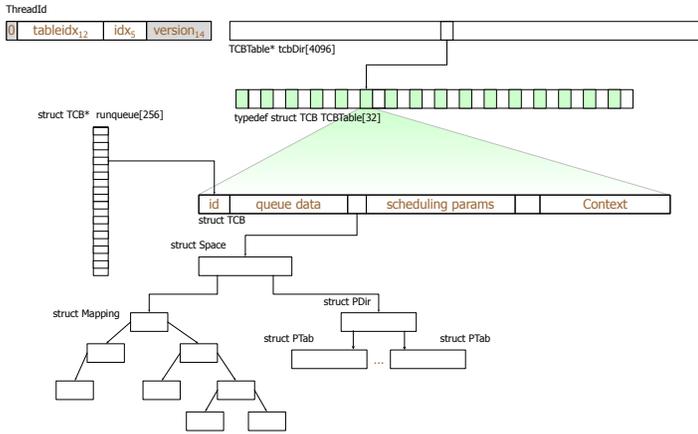
Small Objects

- Pork uses only two “small” object types (≤ 32 bytes):
 - Address space descriptors (Space)
 - Mapping descriptors (Mapping)
- Kernel allocates/frees pages to store small objects (each page can store up to 127 objects)
- Pages with free slots are linked together



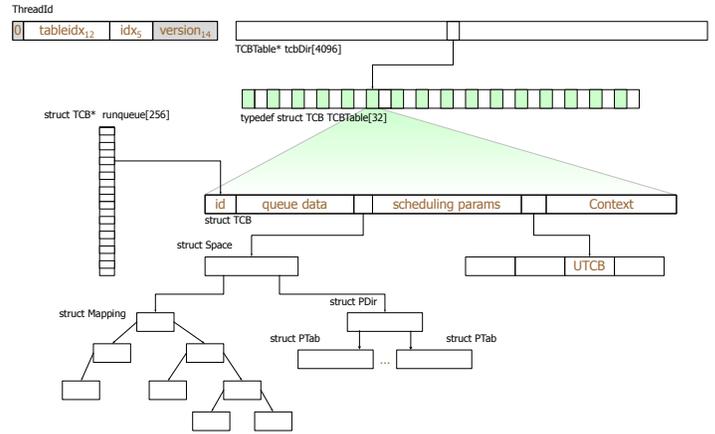
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Page Directories and Page Tables



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User TCBs (UTCBs)



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IPC

Thread status

```

/*-----
 * Thread status:
 * A byte field in each TCB specifies the current status of that thread:
 * +-----+-----+
 * | b6 | b5 | b4 | ipctype |
 * +-----+-----+
 * b3-b0: ipctype (4 bits)
 * b4: 1=>halted, or halt requested (i.e., will halt after IPC)
 * b5: 1=>blocked waiting to send an ipc of the specified type
 * b6: 1=>blocked waiting to receive an ipc of the specified type
 * A zero status byte indicates that the thread is Runnable.
 *-----*/

#define Runnable      0
#define Halted       0x10
#define Sending(type) (0x20|(type))
#define Receiving(type) (0x40|(type))

typedef enum {
    MRS, PageFault, Exception, Interrupt, Preempt, Startup
} IPCType;

static inline IPCType ipctype(struct TCB* tcb) {
    return (IPCType)(tcb->status & 0xf);
}
    
```

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The ipc system call

```

/*-----
 * The "IPC" System Call:
 *-----*/

ENTRY ipc() {

    ThreadId to = IPC_GetTo;           // Send Phase
    if (to!=nilthread) {
        if (!sendPhase(MRS, current, to)) {
            reschedule();
        }
    }

    ThreadId fromSpec = IPC_GetFromSpec(current); // Receive Phase
    if (fromSpec!=nilthread) {
        current->utcb->mr[0] = 0;
        recvPhase(MRS, current, fromSpec);
    }

    reschedule();
}
    
```

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The send phase (Part I)

```

static bool sendPhase(IPCType sendtype, struct TCB* send, ThreadId recvid) {
    // Find the receiver TCB:
    struct TCB* recv;
    if (recvid==anythread ||
        recvid==anylocalthread ||
        !recv=findTCB(recvid)) {
        sendError(sendtype, send, NonExistingPartner);
        return 0;
    }

    // Determine whether we can send the message immediately:
    if (isReceiving(recv)) {
        IPCType recvtype = ipctype(recv);
        ThreadId srcId = recvFromSpec(recvtype, recv);
        if ((srcId==send->tid) ||
            (srcId==anythread) ||
            (srcId==anylocalthread && send->space==recv->space)) {
            // Destination is blocked and ready to receive from send:
            IPCErr err = transferMessage(sendtype, send, recvtype, recv);
            if (err==NoError) {
                resumeThread(recv);
                return 1;
            } else {
                sendError(sendtype, send, err);
                recvError(recvtype, recv, err);
                return 0;
            }
        }
    }
    ...
}
    
```

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The send phase (Part 2)

```
...
// Destination is not ready to receive a message, so try to block: -----
if (sendCanBlock(sendtype, send)) {
    if (send->status==Runnable) {
        removeRunnable(send);
    }
    send->status = Sending(sendtype) | (Halted & send->status);
    send->receiver = rcv;
    rcv->sendqueue = insertTCB(rcv->sendqueue, send);
} else {
    sendError(sendtype, send, NoPartner);
}
return 0;
}
```

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Transferring messages

```
static IPCErr transferMessage(IPCType sendtype, struct TCB* send,
                             IPCType recvtype, struct TCB* recv) {
    if (recvtype==MRs) { // Send to MRS (Destination is user ipc)
        ...
        switch (sendtype) {
            case MRS : ... // Send between sets of message registers
            case PageFault : ... // Send pagefault message to pager
            case Exception : ... // Send message to an exception handler
            case Interrupt : ... // Send message to an interrupt handler
        }
    } else if (sendtype==MRs) { // Receive from MRS (Source is user ipc)
        ...
        switch (recvtype) {
            case PageFault : ... // Receive a response from a pager
            case Exception : ... // Receive a response from an exception handler
            case Interrupt : ... // Receive a response from an interrupt handler
            case Startup : ... // Receive startup message from thread's pager
        }
    }
    return Protocol; // Protocol error: incompatible types/format
}
```

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Regular IPC:

MRs ⇒ MRs

```
struct UTCB* rucb = rcv->utcb;
struct UTCB* sutc = send->utcb;
unsigned u = mask(sutc->mr[0], 6); // untyped items
unsigned t = mask(sutc->mr[0]>>6, 6); // typed items
if ((u+t)>NUMMRS) || (t&1) {
    return MessageOverflow;
} else {
    unsigned i;
    rucb->mr[0] = MsgTag(sutc->mr[0]>>16, 0, t, u);
    for (i=1; i<=u; i++) {
        rucb->mr[i] = sutc->mr[i];
    }
    if (t>0) {
        Fpage acc = rucb->acceptor;
        do {
            IPCErr err = transferTyped(send, rcv, acc,
                                       rucb->mr[i] = sutc->mr[i],
                                       rucb->mr[i+1] = sutc->mr[i+1]);
            if (err!=NoError) {
                return err;
            }
            i += 2;
        } while ((t-=2)>0);
    }
    return NoError;
}
```

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Example: IPCs from hardware interrupts

```
ENTRY hardwareIRQ() {
    unsigned n = current->context.iret.error;
    maskAckIRQ(n); // Mask and acknowledge the interrupt with the PIC
    struct TCB* irqTCB = existsTCB(n);

    if (irqTCB->status==Halted && irqTCB->vutcb!=nilthread) {
        if (sendPhase(Interrupt, irqTCB, irqTCB->vutcb)) {
            irqTCB->status = Receiving(Interrupt) | Halted;
        }
    }
    reschedule(); // allow the user level handler to begin ...
}
```

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Interrupt handler protocol

Interrupt ⇒ MRs

- When a hardware interrupt occurs, the kernel sends an IPC message from the interrupt thread to its pager with the tag:

From Interrupt Thread

-1 (12/44)	0 (4)	0 (4)	t = 0 (6)	u = 0 (6)	MR ₀
------------	-------	-------	-----------	-----------	-----------------

```
case Interrupt : // Send message to an interrupt handler
    rucb->mr[0] = MsgTag((-1)<<4, 0, 0, 0);
    return NoError;
```

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Interrupt handler protocol

MRs ⇒ Interrupt

```
case Interrupt : // Receive a response from an interrupt handler
    if (mask(sutc->mr[0],12)==0) {
        ASSERT(mask(rcv->tid, VERSIONBITS)==1, "Wrong irq version");
        ASSERT(threadNo(rcv->tid) < NUMIRQs, "IRQ out of range");
        enableIRQ(threadNo(rcv->tid)); // Reenable interrupt
        return NoError;
    }
    break;
```

- When the pager has finished handling the error, it sends an IPC message back to the interrupt thread to reenble the corresponding interrupt

To Interrupt Thread

0 (16/48)	0 (4)	t = 0 (6)	u = 0 (6)	MR ₀
-----------	-------	-----------	-----------	-----------------

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Example: IPCs from page faults

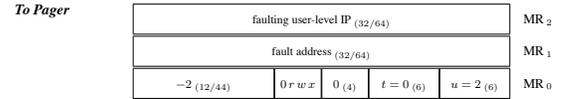
```
ENTRY pageFault() {
    asm(" movl %%cr2, %0\n" : "=r"(current->faultCode));

    if (current->space==sigma0Space && sigma0map(current->faultCode)) {
        printf("sigma0 case succeeded!\n");
    } else {
        ThreadId pagerId = current->utcb->pager;
        if (pagerId==nilthread) {
            haltThread(current);
        } else if (sendPhase(PageFault, current, pagerId)) {
            removeRunnable(current); // Block current if message already delivered
            current->status = Receiving(PageFault);
        }
    }
    refreshSpace();
    reschedule();
}
```

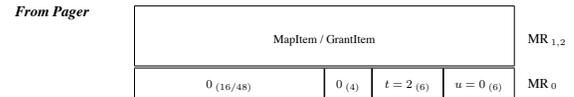
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Page fault protocol

- When a thread triggers a page fault, the kernel translates that event into an IPC to the thread's pager:



- The pager can respond by sending back a reply with a new mapping ... that also restarts the faulting thread:

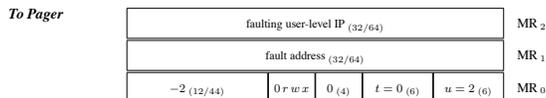


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Page fault protocol

PageFault ⇒ MRs

- When a thread triggers a page fault, the kernel translates that event into an IPC to the thread's pager:



```
case PageFault : { // Send pagefault message to pager
    unsigned rwx = (send->context.iret.error & 2) ? 2 : 4;
    rutcb->mr[0] = MsgTag((-2)<<4 | rwx, 0, 0, 2);
    rutcb->mr[1] = send->faultCode;
    rutcb->mr[2] = send->context.iret.eip;
}
return NoError;
```

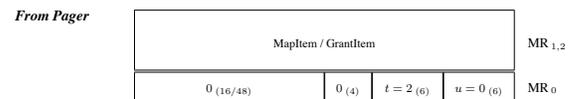
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Page fault protocol

MRs ⇒ PageFault

```
case PageFault : // Receive a response from a pager
    if (mask(sutcb->mr[0], 12) == MsgTag(0, 0, 2, 0)) {
        return transferTyped(send, recv,
            completeFpage(), sutcb->mr[1], sutcb->mr[2]);
    }
    break;
```

- The pager can respond by sending back a reply with a new mapping ... that also restarts the faulting thread:



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Time to poke around ... !

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