

Introduction to 2D and 3D Computer Graphics

Mastering 2D & 3D Computer Graphics Pipelines

Mastering 2D & 3D Graphics

Overview of 2D & 3D Pipelines

- What are pipelines?
- What are the fundamental components of pipelines?
- Example pipelines...
 - ...2D graphic object pipeline
 - ...3D graphic object pipeline
 - ...raster pipeline
 - ...bitmapped, HLHSR, illumination implications

Overview of 2D & 3D Pipelines

What are Pipelines?

- Are the fundamental concept around which graphics systems are based
- Represent conceptual models
- Describe the interaction and the flow of data for all functions
- Illustrate how the applications can create, save, modify, draw, and display pictures

Overview of 2D & 3D Pipelines

What are Pipelines?

- Illustrate how applications can create pictures
- Illustrate the use of functions to set up the environment
- Illustrate how the environment affects pictures being created
- Illustrate the interactions and the relationships between functions

Overview of 2D & 3D Pipelines

What are the fundamental components?

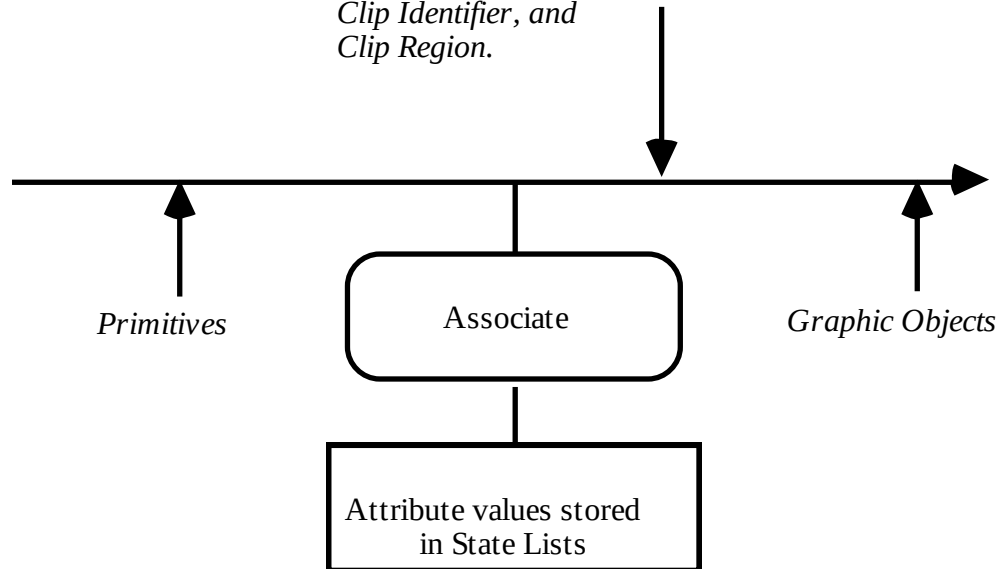
- Common components:
 - Attribute Association
 - Display-List Storage
 - Bundled Attribute Association
 - Modeling
 - Viewing & Clipping
 - Rendering
 - » with many sub-components!

Overview of 2D & 3D Pipelines

Attribute Association: pipeline illustration

*Graphic objects with
associated attributes;*

*for example: Primitive Attributes,
ASF Bundle Indicators,
Bundle Indices,
Width/Size Specification Mode,
Object Clipping Mode,
Transparency,
Drawing Mode,
Auxiliary Colour,
Pick Identifier,
Transformation (initially identity),
Clip Identifier, and
Clip Region.*



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Bundled Attribute Association

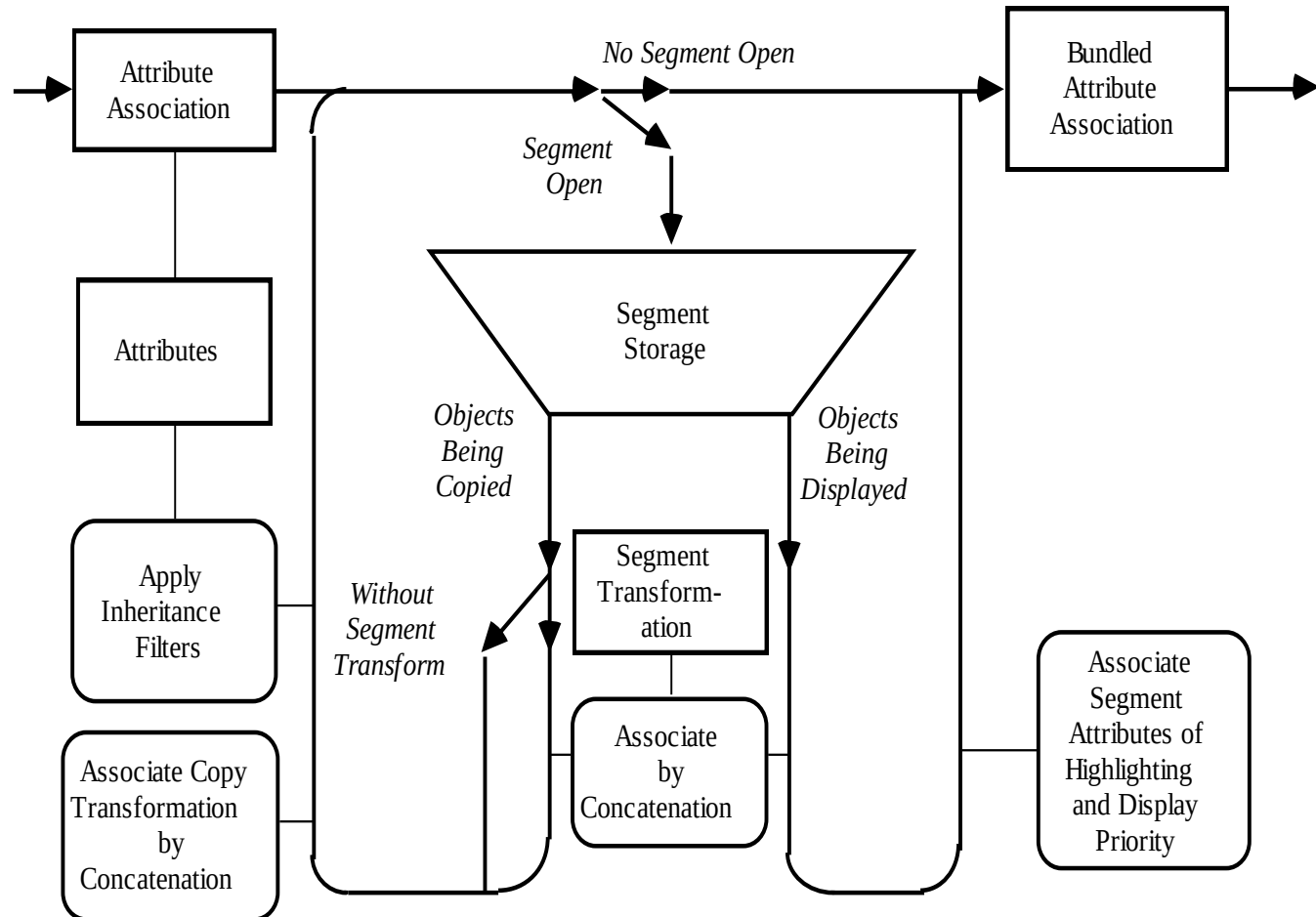
- Attributes set and accessed through tables...
 - ...are called bundled attributes
 - ...are grouped into bundle tables
 - ...can change the attributes associated with a graphic object as it flows along the pipeline

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Display-List Storage

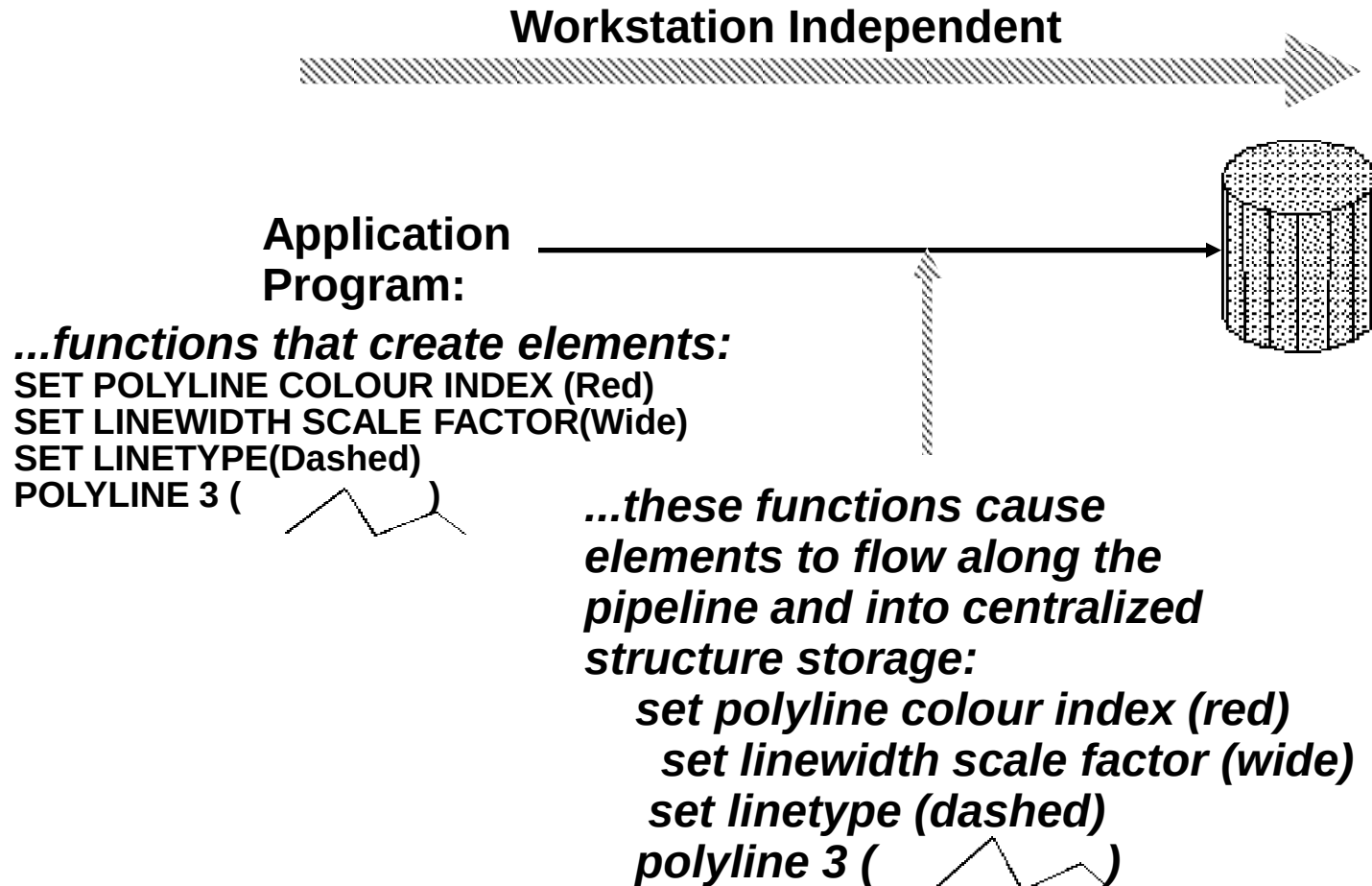
- Segment models...(e.g., CGI, GKS)
 - ...describe the mechanism for saving graphic objects
- Structure models...(e.g., PHIGS)
 - ...describe the mechanism for saving primitive and complex elements
- Macro & procedure models...(e.g., POSTSCRIPT®)
 - ...describe the mechanism for saving macros, procedures, & subroutines in memory for later use

One Approach to Display Lists *using segments*



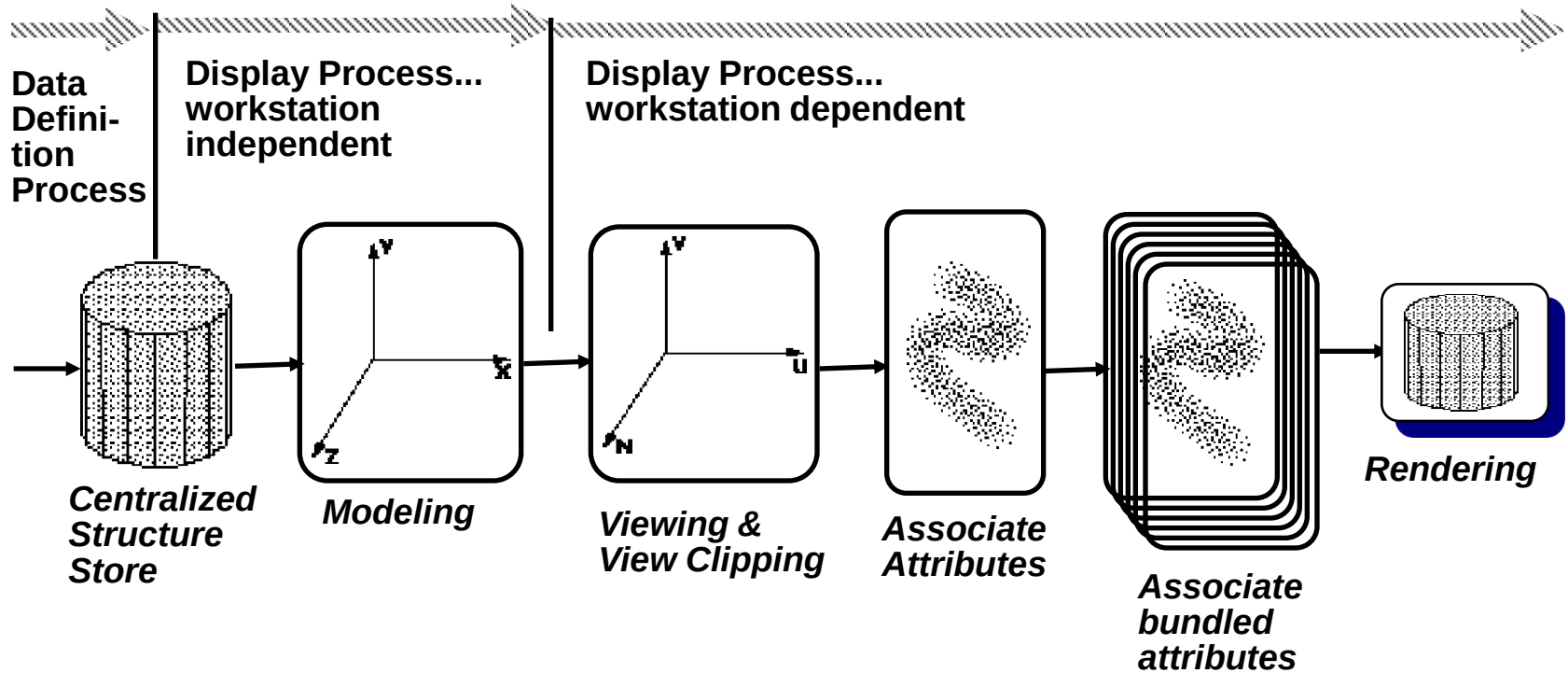
Or, with Structures...

Structure Creation: data definition process



Overview of 2D & 3D Pipelines

Example: 3D graphic object pipeline



Overview of 2D & 3D Pipelines

Modeling

- Modeling transformations...
 - ...allow objects to be defined in their own coordinate system
- Through modeling...
 - ...objects are transformed into world coordinates by scaling, rotation, and/or translation

Overview of 2D & 3D Pipelines

Modeling

- This allows all objects to initially be defined as centered around the origin...
 - ...and then modeling transformations can position, orient, and scale them into their correct geometric relationships
- This stage in the pipeline is independent of the display characteristics

Overview of 2D & 3D Pipelines

Modeling

- The modeling transformation...
 - ...maps modeling coordinates into world coordinates
 - ...is defined by transformation matrices inserted into a structure network
 - ...allows the picture to be composed of separate parts, each defined within its own modeling coordinate system
 - ...supports relative positioning of these parts when they are mapped to world coordinates

Overview of 2D & 3D Pipelines

Modeling

- Modeling Coordinates (called MC) are.
 - ...3D right-handed device-independent coordinates
 - ... specified by a homogeneous transformation matrix
- When modeling transformations are not inserted into a structure...
 - ...modeling coordinates are the same as world coordinates

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Coordinate Spaces

- 2D transformations are represented by 3X3 matrices using homogeneous coordinates...
- 3D transformations are represented by 4x4 matrices using homogeneous coordinates in 3-space

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Coordinate Spaces: homogeneous coordinates

- What are homogeneous coordinates?
- Well...instead of representing a point as (x, y, z) ...
 - ...we represent it as (x, y, z, W) ...but we most commonly refer to it as $(x/W, y/W, z/W, 1)$
- When we transform a point to this form...
 - ...it is called homogenizing

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Coordinate Spaces: homogeneous coordinates

- This means...that each point in 3-space is represented by a line through the origin in 4-space!
- So...homogenizing allows us to use points that form a 3D subspace of 4-space (i.e., $W=1$)

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Coordinate Spaces: right-handed

- Most graphics systems use the right-handed coordinate system for the definition of objects
- In right-handed systems...
 - ...positive rotations occur when looking from the positive axis to the origin
 - ...a 90° counterclockwise rotation will transform one positive axis into the other

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Coordinate Spaces: right-handed

- For example, to rotate around the x axis...
 - ...the positive rotation is from y to z
- Or, to rotate around the y axis...
 - ...the positive rotation is from z to x
- And lastly, to rotate around the z axis...
 - ...the positive rotation is from x to y

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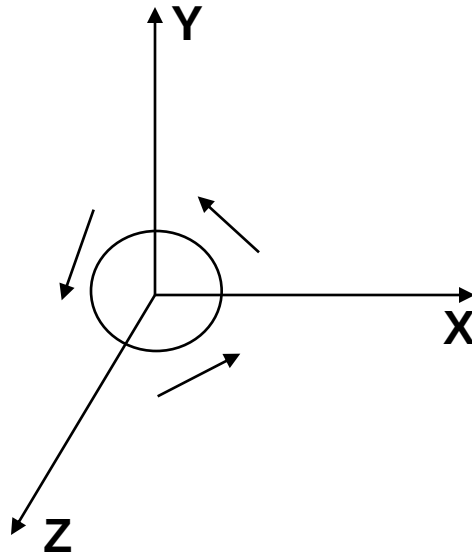
Coordinate Spaces: left-handed

- Some graphics systems use the left-handed coordinate system for viewing objects...
 - Left-handed systems may seem more natural...
...as larger z values appear further from the operator
- In left-handed systems...
 - ...positive rotations occur when looking from the positive axis to the origin
 - ...a 90° clockwise rotation will transform one positive axis into the other

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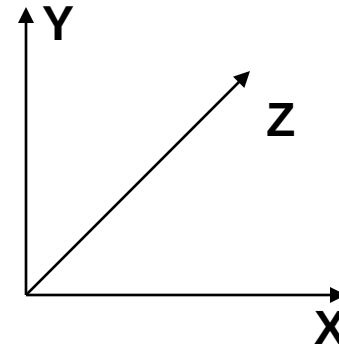
Coordinate Spaces

Right-Handed



Z is coming out of the display towards you

Left-Handed



Z is heading into the display (or away from you)

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Linear Transformations

- A set of vertices or 3D points belonging to an object...
 - ...can be transformed into another set of points...using linear transformations

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Linear Transformations

- Translation:

- $$[x' \ y' \ z' \ 1] = [x \ y \ z \ 1] \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ T_x & T_y & T_z & 1 \end{bmatrix}$$

- Translation means...

- $x' = x + T_x \quad y' = y + T_y \quad z' = z + T_z$

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Linear Transformations

- Scaling: S_x , S_y , and S_z are scaling factors

- $$\begin{bmatrix} x' & y' & z' & 1 \end{bmatrix} = \begin{bmatrix} x & y & z & 1 \end{bmatrix} \begin{bmatrix} S_x & 0 & 0 & 0 \\ 0 & S_y & 0 & 0 \\ 0 & 0 & S_z & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

- When $S_x = S_y = S_z$, there is uniform scaling...
 - ...otherwise scaling occurs only along the axes specified

$$x' = xS_x \quad y' = yS_y \quad z' = zS_z$$

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Linear Transformations

- To rotate an object in three-dimensional space, an axis of rotation must be specified...
 - ...it is best to use one of the coordinate axes
- Counterclockwise rotation about each of the axes uses (around X, Y, Z respectively)

■	1	0	0	0	$\cos^\circ$	0	$-\sin^\circ$	0	$\cos^\circ$	$\sin^\circ$	0	0
■	0	$\cos^\circ$	$\sin^\circ$	0	0	1	0	0	$-\sin^\circ$	$\cos^\circ$	0	0
■	0	$-\sin^\circ$	$\cos^\circ$	0	$\sin^\circ$	0	$\cos^\circ$	0	0	0	1	0
■	0	0	0	1	0	0	0	1	0	0	0	1

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Linear Transformations

- Around the Z axis, this means:
 - $x' = x\cos^\circ - y\sin^\circ$
 - $y' = x\sin^\circ + y\cos^\circ$
 - $z' = z$

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Linear Transformations

- When objects are not at the origin...
 - ...a simple rotation will not rotate the object in place
- Instead, we must...
 - ...first translate the object to the origin,
 - ...apply the desired rotation, and
 - ...translate the object back to its original position

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Linear Transformations

- This means for a rotation around the Z axis (when the Z axis passes through the point $(T_x, T_y, 0)$)...
 - $x' = x \cos^\circ - y \sin^\circ - T_x \cos^\circ + T_y \sin^\circ + T_x$
 - $y' = x \sin^\circ + y \cos^\circ - T_x \sin^\circ - T_y \cos^\circ + T_y$
 - $z' = z$

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Concatenating Transformations

- Useful in describing objects that have a natural hierarchy
- For example, a stylization of a human figure used in animation would...
 - ...have a set of local coordinate systems based on limb joints
 - ...describe a hierarchy based on these joints
 - ...allow the hand to move with respect to the wrist joint and the lower arm to move with respect to the elbow joint

Modeling Transformations

Composition: Concatenating Xforms

- With Preconcatenate...
 - ...the specified transformation is applied to the object first
 - ...if you preconcatenate a rotation, that rotation will be applied to the object before the other transformations
- Current xform x New ($L' = L \times M$)

Modeling Transformations

Composition: Concatenating Xforms

- With Postconcatenate...
 - ...the specified transformation is applied to the object after the current existing local transformation
- New x Current Xform ($L' = M \times L$)

Modeling Transformations

Composition: Inheritance

- Inheritance of modeling transformations means...
 - ...a parent's composite modeling transformation becomes the initial child's global modeling transformation
 - ...a child's initial local modeling transformation is the identity matrix
 - ...descendant structures do not affect parent structures

Modeling Transformations

Composition: Inheritance

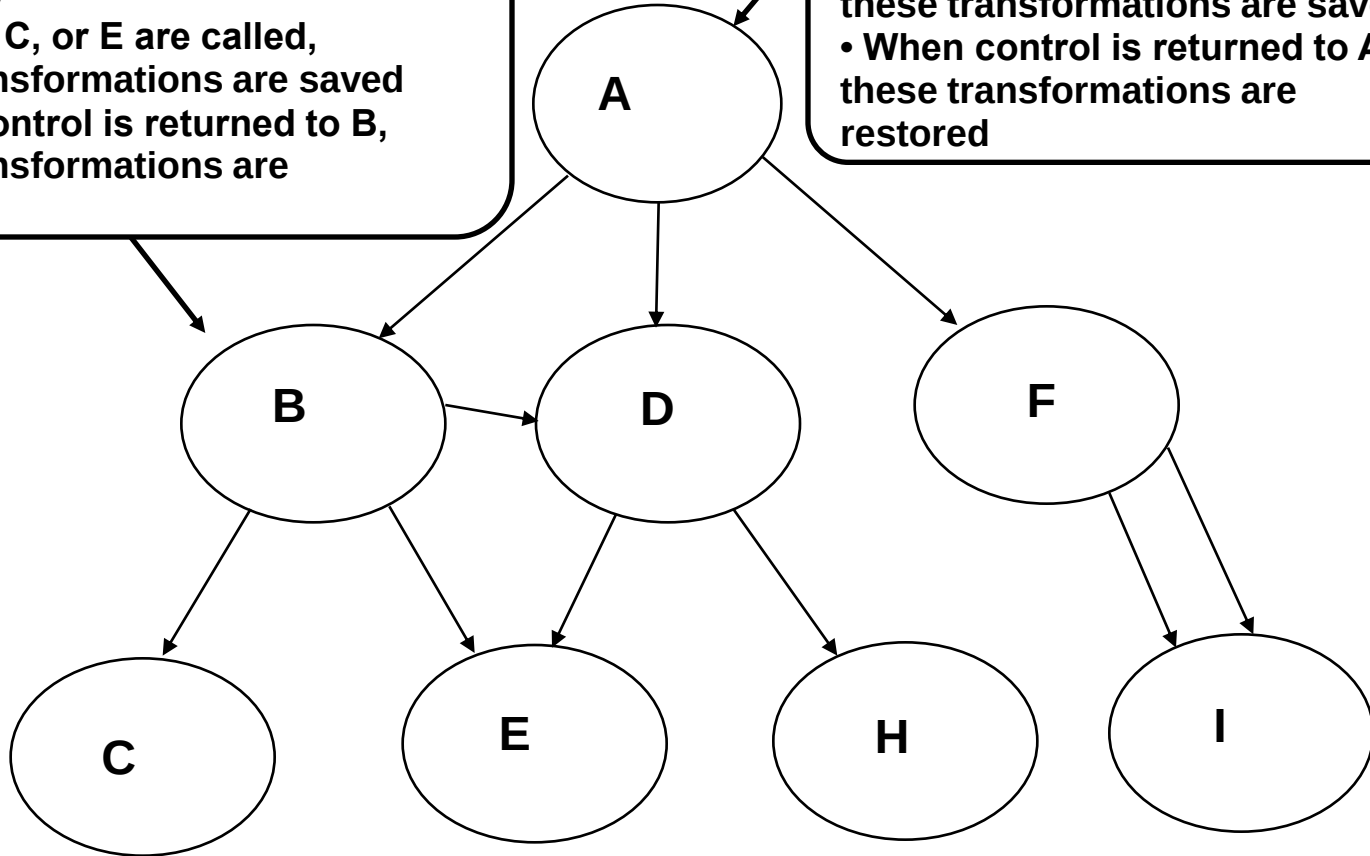
■ Modifications...

- to the global transformation only have effect within the structure in which they are encountered
- This allows structure hierarchies to be built with movable parts...
- ...since the motion of the parent structure is passed to its children via inheritance of the composite modeling transformation, the parts are kept connected

Inheritance...

- When B is called, A's composite transformation becomes B's global transformation
- B's initial local transformation is identity
- When D, C, or E are called, these transformations are saved
- When control is returned to B, these transformations are restored

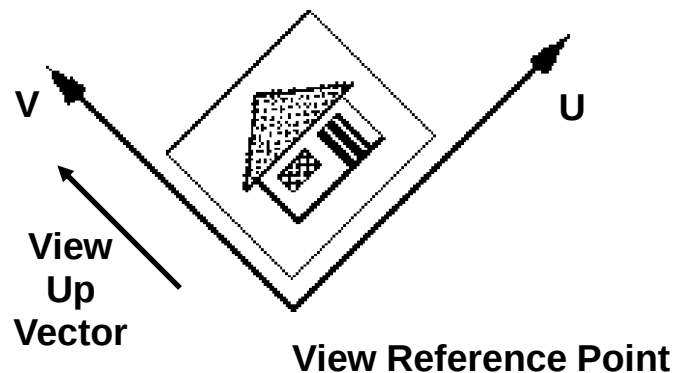
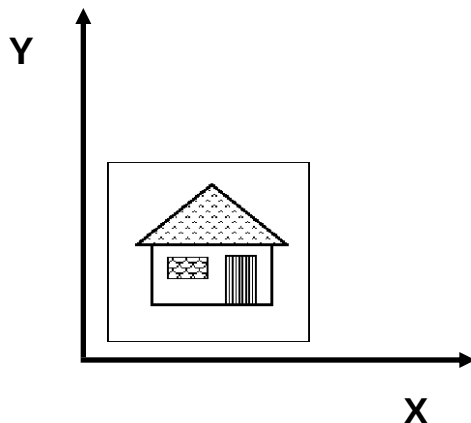
- Initial identity local & global transformations
- When B, D, or F are called, these transformations are saved
- When control is returned to A, these transformations are restored



2D Viewing Transformations

View Orientation Transformation

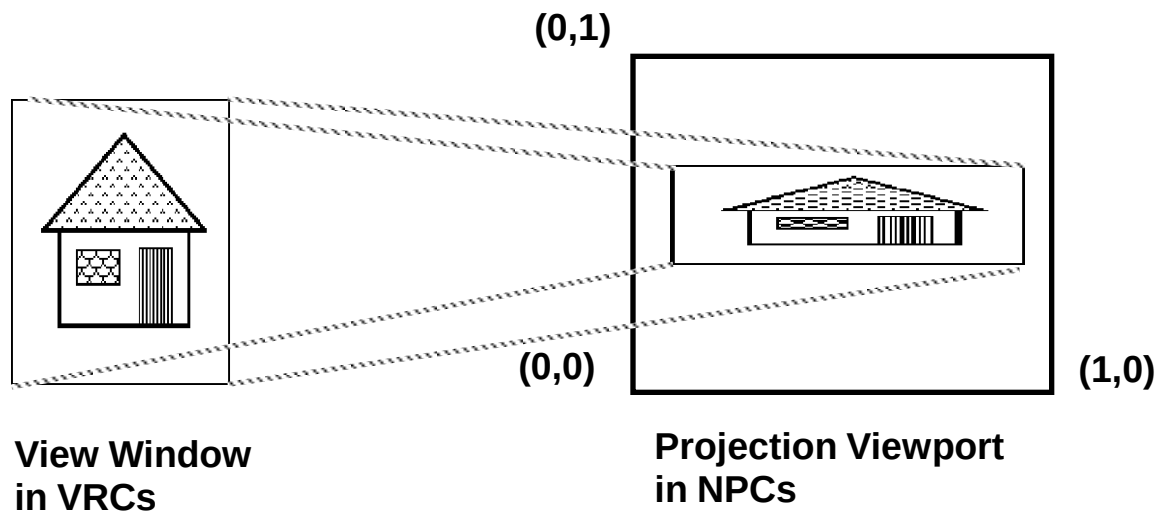
- View orientation transformation...
 - ...defines the position and orientation of view reference coordinates relative to world coordinates



2D Viewing Transformations

View Mapping Transformation

- View mapping transformation...
 - ...defines the mapping of view reference coordinates to normalized projection coordinates, allowing for distortion...



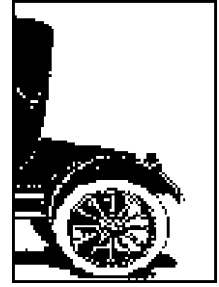
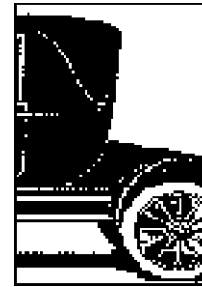
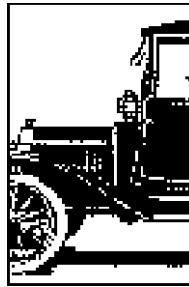
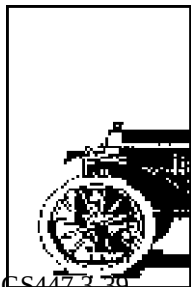
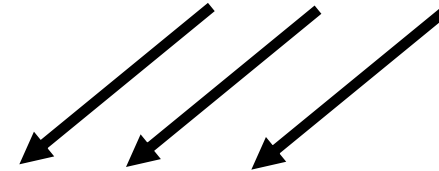
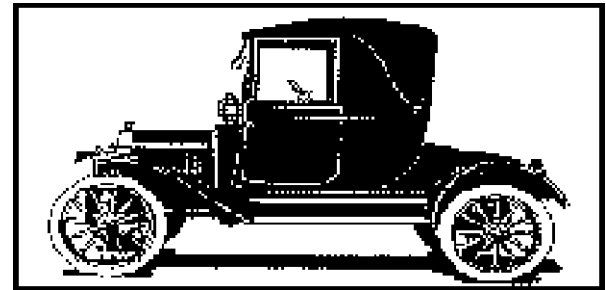
2D Viewing Transformations

View Mapping Transformation

- Allows dynamic horizontal and vertical panning...
 - ...by continuously adding to both sides of the view window, or
 - ...by changing the view reference point and leaving the view window unchanged
- Remember, panning is achieved by changing the window location!

2D Viewing Transformations

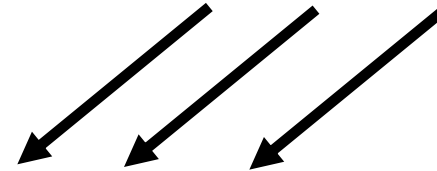
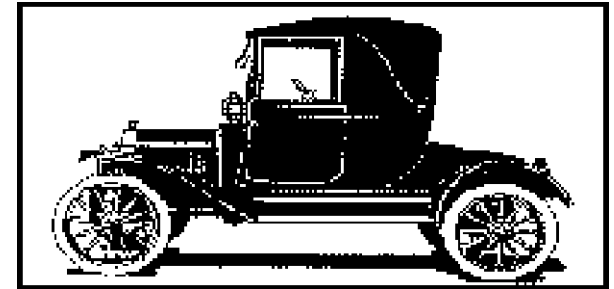
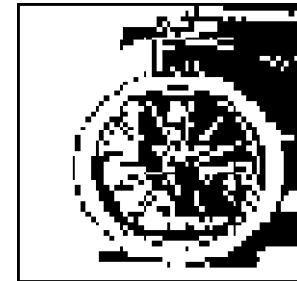
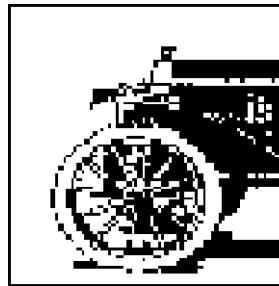
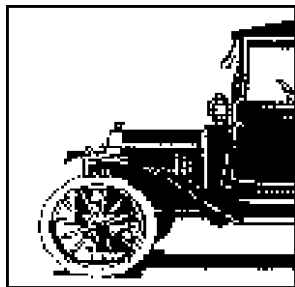
View Mapping Transformation



2D Viewing Transformations

View Mapping Transformation

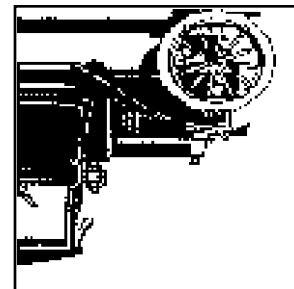
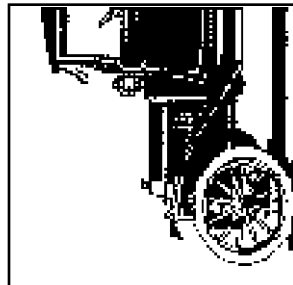
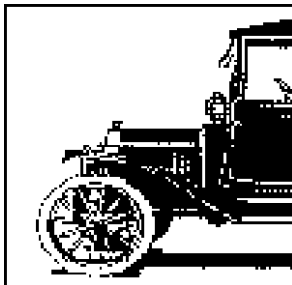
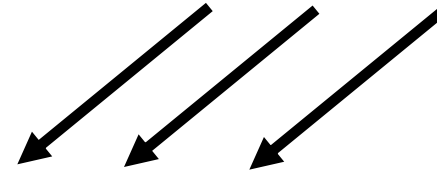
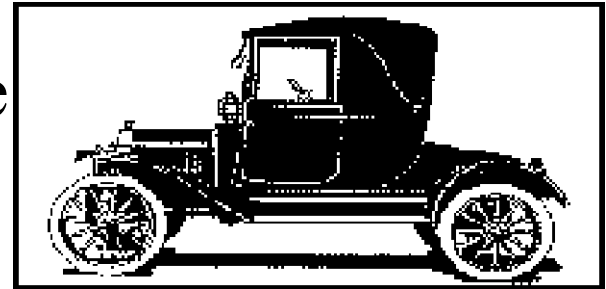
- Allows dynamic zooming...
 - ...by continuously changing the view window by a uniform percentage in the horizontal and vertical directions



2D Viewing Transformations

View Mapping Transformation

- Allows dynamic rotation...
 - ...by continuously changing the view up vector
 - The effect is as if you were rotating a camera used to view your picture



Overview of 2D & 3D Pipelines

3D Viewing & Clipping

- Three operations are associated with 3D viewing...
 - ...view orientation
 - ...view mapping ...XYZ clipping
- View orientation...
 - ...maps world coordinates to view reference coordinates
 - ...transforms and defines the position and orientation of the VRCs relative to world coordinates

Overview of 2D & 3D Pipelines

3D Viewing & Clipping

- View mapping...
 - ...maps view reference coordinates to normalized projection coordinates
 - ...specifies a 3D volume of VRC to be mapped to a 3D volume of NPC (a unit cube extending from 0.0 to 1.0 in X,Y,Z)
- XYZ clipping...
 - ...is performed on the XY boundary (or clip rectangle), and front and back planes

Overview of 2D & 3D Pipelines

Rendering

- Is the general process for changing a 2D or 3D graphic object to a shaded 2D projection onto a drawing surface
- Rendering involves...
 - ...setting up data structures for polygon mesh models to ensure that they will contain all of the information required in the shading process

Overview of 2D & 3D Pipelines

Rendering

- Rendering also involves...
 - ...setting up data structures for polygon mesh models to ensure that they will contain all of the information required in the shading process
 - ...culling back-facing polygons (3D Only)
 - ...applying a hidden surface removal algorithm(3D Only) ...scan converting or rasterizing polygons: converting an object's vertices into a set of pixel coordinates & shading

Overview of 2D & 3D Pipelines

Example: 2D graphic object pipeline

