GADTs

GADTs in Haskell

ADT vs GADT

Algebraic Datatype

Data List a = Nil | Cons a (List a)

```
Data Tree a b =
Tip a
| Node (Tree a b) b
| Fork (Tree a b) (Tree a b)
```

Generalized Algebraic Datatype

Data List a where Nil:: List a Cons:: a -> List a -> List a

```
Data Tree a b where

Tip a : Tree a b

Node: Tree a b ->

b ->

Tree a b

Fork:: Tree a b ->

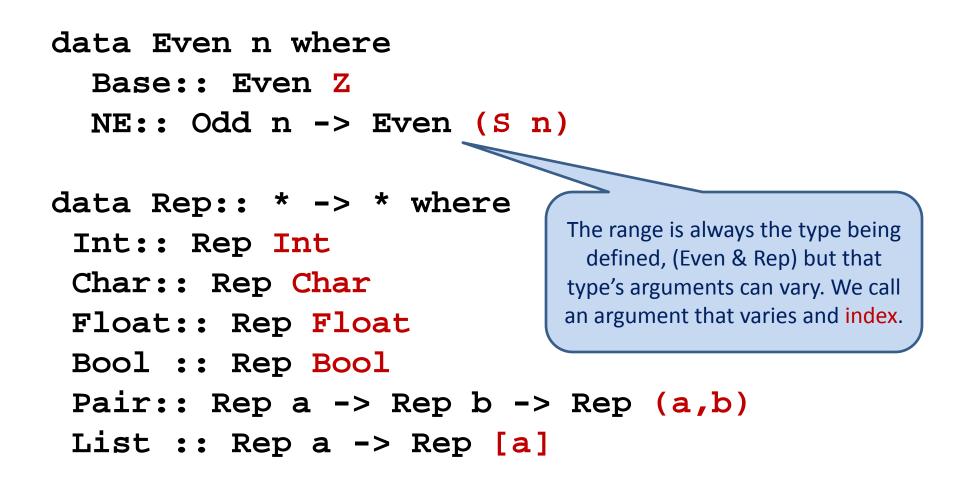
Tree a b ->

Tree a b ->

Tree a b ->
```

Note that types than can be expressed as an ADT always have the identical range types on all their constructors

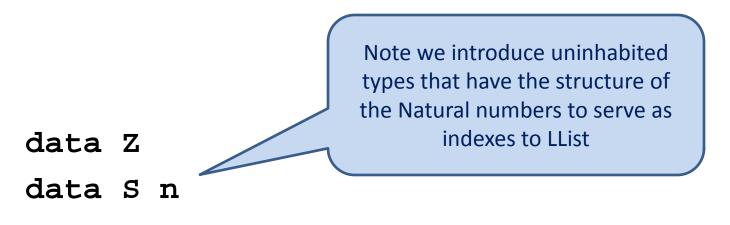
GADTs relax the range restriction

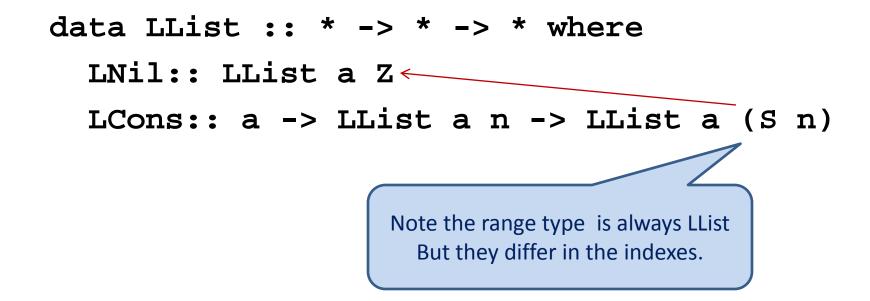


Examples

- Length indexed lists
- Balanced Trees
 - Redblack trees
 - 2-threes trees
 - AVL trees
- Representation types
- Well-typed terms
 - Terms as typing judgements
 - Tagless interpreters
 - Subject reduction
 - Type inference
- Witnesses
 - Odd and Even
 - Well formed join and cross product in relational algebra
- Well structured paths in trees
- Units of measure (inches, centimeters, etc)
- Provable Equality
- Proof carrying code

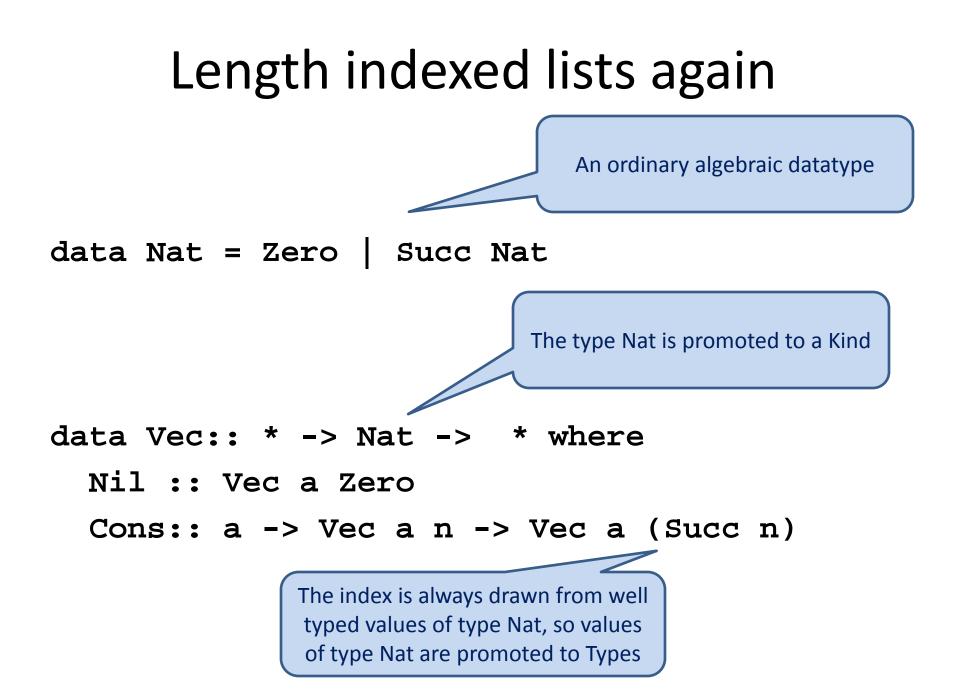
Length indexed lists





Promotion

- As of GHC version 7 GHC allows indexes to be ordinary datatypes.
- One says the datatype is promoted to the type level.
- This is very usefull, as it enforces a typing system on the indexes.
 - For example does (LList Int String) make any sense. The index is supposed to be drawn from Z and S



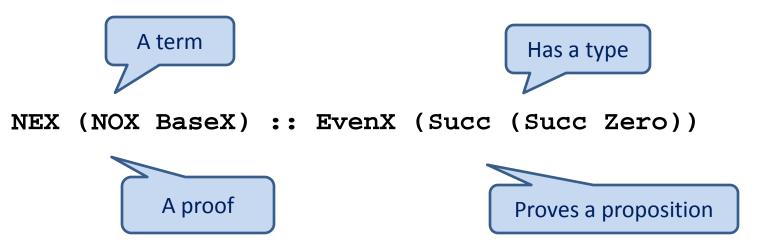
GADTs as proof objects

- data EvenX:: Nat -> * where
 BaseX:: EvenX Zero
 NEX:: OddX n -> EvenX (Succ n)
 data OddX:: Nat -> * where
 - NOX:: EvenX n -> OddX (Succ n)

• What type does NEX (NOX BaseX) have?

The Curry-Howard isomorphism

- The Curry-Howard isomorphism says that two things have exactly the same structure.
 - A term has a type
 - A proof proves a proposition



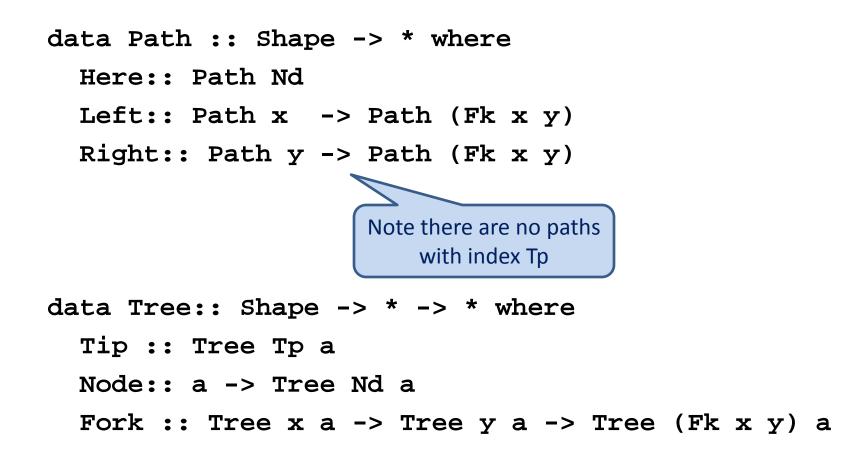
Note that there is no term with type: EvenX (Succ Zero)

Proofs and witnesses

- GADTs make the Curry-Howard isomorphism useful in Haskell.
- Sometime we say a term "witnesses" a property. I.e the term NEX (NOX BaseX) witnesses that 2 is even.
- We use GADTs has indexes to show that some things are not possible.

Paths and Trees

```
data Shape = Tp | Nd | Fk Shape Shape
```



Well formed paths

find:: Eq a => a -> Tree sh a -> [Path sh]
find n Tip = []
find n (Node m) =
 if n==m then [Here] else []
find n (Fork x y) =
 (map Left (find n x)) ++
 (map Right (find n y))

Using a path. No possibility of failure

extract:: Eq a => Tree sh a -> Path sh -> a
extract (Node n) (Here) = n
extract (Fork l r) (Left p) = extract l p
extract (Fork l r) (Right p) = extract r p

- -- No other cases are possible,
- -- Since there are no Paths with index Tp

Balanced Trees

- Balanced trees are used as binary search mechanisms.
- They support log(n) time searches for trees that have n elements
- They rely on the trees being balanced.
 - Usually saying that all paths from root to leaf have roughly the same length
- Indexes make perfect tools to represent these invariants.

Red Black Trees

- A red-black tree is a binary search tree with the following additional invariants:
 - Each node is colored either red or black
 - The root is black
 - The leaves are black
 - Each Red node has Black children
 - for all internal nodes, each path from that node to a descendant leaf contains the same number of black nodes.
- We can encode these invariants by thinking of each internal node as having two attributes: a color and a black-height.

Red Black Tree as a GADT

data Color = Red | Black

data SubTree :: Color -> Nat -> * where LeafRB :: SubTree Black Zero RNode :: SubTree Black n -> Int -> SubTree Black n -> SubTree Red n BNode :: SubTree cL m -> Int -> SubTree cR m -> SubTree Black (Succ m)

data RBTree where
 Root:: (forall n. (SubTree Black n)) -> RBTree

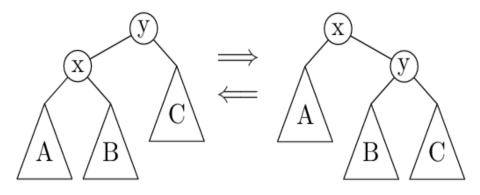
AVL Trees

• In an AVL tree, the heights of the two child sub trees of any node differ by at most one;

```
data Balance:: Nat -> Nat -> Nat -> * where
Same :: Balance n n n
Less :: Balance n (Succ n) (Succ n)
More :: Balance (Succ n) n (Succ n)
data Avl:: Nat -> * where
TipA:: Avl Zero
NodeA:: Balance i j k -> Avl i -> Int ->
Avl j -> Avl (Succ k)
```

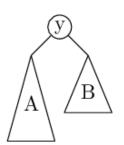
data AVL = forall h. AVL (Avl h)

Balancing Constructors. The algorithms for insertion and deletion each follow the same basic pattern: First do the insertion (or deletion) as you would for any other binary search tree. Then re-balance any subtree that became unbalanced in the process. The tool used for re-balancing is tree rotation, which is best described visually.

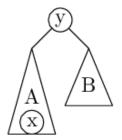


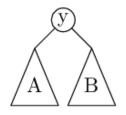
INPUT

OUTPUT

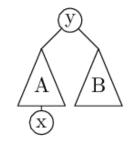


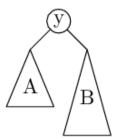
Post-insertion height is the same. Keep the same Balance



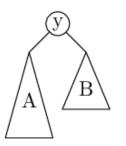


Height increases. Change Balance from Same to More

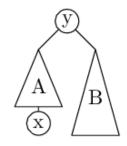


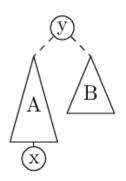


Height increases. Change Balance from Less to Same



Height increases. Rebalance with rotr

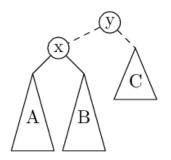


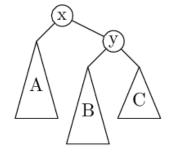


Insertion

```
insert :: Int -> AVL -> AVL
insert x (AVL t) = case ins x t of L t -> AVL t; R t -> AVL t
ins :: Int -> Avl n -> (Avl n + Avl (Succ n))
ins x TipA = R(NodeA Same TipA x TipA)
ins x (NodeA bal lc y rc)
   x = y = L(NodeA bal lc y rc)
   x < y = case ins x lc of
               L lc -> L(NodeA bal lc y rc)
               R lc ->
                 case bal of
                   Same -> R(NodeA More lc y rc)
                   Less -> L(NodeA Same lc y rc)
                   More -> rotr lc y rc -- rebalance
   x > y = case ins x rc of
                                                Note the rotations in red
               L rc -> L(NodeA bal lc y rc)
               R rc -> case bal of
                        Same -> R(NodeA Less lc y rc)
                        More -> L(NodeA Same lc y rc)
                        Less -> rotl lc y rc -- rebalance
```

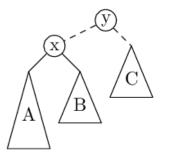
rotr (Node Same a x b) y c = R(Node Less a x (Node More b y c))

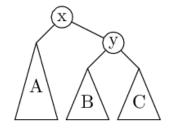




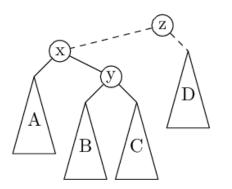
rotr (Node More a x b) y c

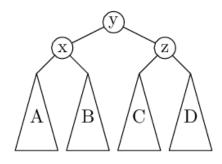
= L(Node Same a x (Node Same b y c))





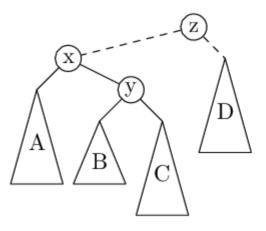
rotr (Node Less a x L(Node Same (Node Same a x b) y = (Node Same b y c)) z d (Node Same c z d))





rotr (Node Less a x (Node Less b y c)) z d = L(Node Same (Node More a x b) y (Node Same c z d))

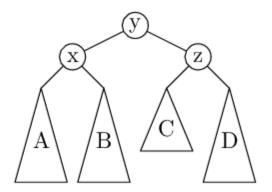
_



rotr (Node Less a x (Node More b y c)) z d

> A B C

L(Node Same (Node Same a x b) y (Node Less c z d))



Example code

The rest is in the accompanying Haskell file

data (+) a b = L a | R b

```
rotr :: Avl(Succ(Succ n)) -> Int -> Avl n ->
           (Avl(Succ(Succ n))+Avl(Succ(Succ(Succ n))))
-- rotr Tip u a = unreachable
rotr (NodeA Same b v c) u a = R(NodeA Less b v (NodeA More c u a))
rotr (NodeA More b v c) u a = L(NodeA Same b v (NodeA Same c u a))
-- rotr (NodeA Less b v TipA) u a = unreachable
rotr (NodeA Less b v (NodeA Same x m y)) u a =
      L(NODEA Same (NODEA Same b v x) m (NODEA Same y u a))
rotr (NodeA Less b v (NodeA Less x m y)) u a =
      L(NODEA Same (NODEA MORE b v x) m (NODEA Same y u a))
rotr (NodeA Less b v (NodeA More x m y)) u a =
     L(NODEA Same (NODEA Same b v x) m (NODEA Less y u a))
```

At the top level

- Insertion may make the height of the tree grow.
- Hide the height of the tree as an existentially quantified index.

data AVL = forall h. AVL (Avl h)

2-3-Tree

• a tree where every node with children (internal node) has either two children (2-node) and one data element or three children (3nodes) and two data elements. Nodes on the outside of the tree (leaf nodes) have no children and zero, one or two data elements

```
data Tree23:: Nat -> * -> * where
Three :: (Tree23 n a) -> a ->
        (Tree23 n a) -> a ->
        (Tree23 (Succ n) a)
Two:: (Tree23 n a) -> a ->
        (Tree23 n a) -> a ->
        (Tree23 n a) -> (Tree23 (Succ n) a)
Leaf1 :: a -> (Tree23 Zero a)
Leaf2 :: a -> a -> (Tree23 Zero a)
Leaf0 :: (Tree23 Zero a)
```

Witnessing equality

- Sometimes we need to prove that two types are equal.
- We need a type that represents this proposition.
- We call this a witness, since legal terms with this type only witness that the two types are the same.
- This is sometimes called provable equality (since it is possible to write a function that returns an element of this type).

data Equal:: k -> k -> * where
 Refl :: Equal x x

Representation types

```
data Rep:: * -> * where
Int:: Rep Int
Char:: Rep Char
Float:: Rep Float
Bool :: Rep Bool
Pair:: Rep a -> Rep b -> Rep (a,b)
List :: Rep a -> Rep [a]
```

• Some times this is called a Universe, since it witnesses only those types representable.

Generic Programming

```
eq:: Rep a -> a -> a -> Bool
eq Int x y = x = y
eq Char x y = x = y
eq Float x y = x = y
eq Bool x y = x = y
eq (Pair t1 t2)(a,b) (c,d) =
  (eq t1 a c) \& (eq t2 b d)
eq (List t) xs ys
   not(length xs == length ys) = False
  otherwise = and (zipWith (eq t) xs ys)
```

Using provable equality

• We need a program to inspect two Rep types (at runtime) to possible produce a proof that the types that they represent are the same.

test:: Rep a -> Rep b -> Maybe(Equal a b)

• This is sort of like an equality test, but reflects in its type that the two types are really equal.

Code for test

- test:: Rep a -> Rep b -> Maybe(Equal a b)
- test Int Int = Just Refl
- test Char Char = Just Refl
- test Float Float = Just Refl
- test Bool Bool = Just Refl
- test (Pair x y) (Pair m n) =
 - do { Refl <- test x m
 - ; Refl <- test y n
 - ; Just Refl }
- test (List x) (List y) =
 - do { Refl <- test x y</pre>
 - ; Just Refl}

test _ _ = Nothing

When we pattern match against Refl, the compiler know that the two types are statically equal in the scope of the match.

Well typed terms

data Exp:: * -> * where IntE :: Int -> Exp Int CharE:: Char -> Exp Char PairE :: Exp $a \rightarrow Exp b \rightarrow Exp (a,b)$ VarE:: String -> Rep t -> Exp t LamE:: String -> Rep t -> $Exp s \rightarrow Exp (t \rightarrow s)$ ApplyE:: Exp $(a \rightarrow b) \rightarrow$ Exp a -> Exp bFstE:: $Exp(a,b) \rightarrow Exp a$ SndE:: $Exp(a,b) \rightarrow Exp b$

Typing judgements

- Well typed terms have the exact same structure as a typing judgment.
- Consider the constructor ApplyE
 ApplyE:: Exp (a -> b) -> Exp a -> Exp b

Compare it to the typing judgement

$$\begin{array}{ccc} f:a \to b & x:a \\ f & x:b \end{array}$$

Tagless interpreter

- An interpreter gives a value to a term.
- Usually we need to invent a value datatype like data Value

= IntV Int FunV (Value -> Value) PairV Value Value

We also need to store Values in an environment
 - data Env = E [(String,Value)]

Valueless environments

data Env where Empty :: Env Extend :: String -> Rep t -> t -> Env -> Env

Note that the type variable "t" is existentially quantified.

Given a pattern (Extend var rep t more) There is not much we can do with t, since we do not know its type.

Tagless interpreter

```
eval:: Exp t -> Env -> t
eval (IntE n) env = n
eval (CharE c) env = c
eval (PairE x y) env = (eval x env, eval y env)
eval (VarE s t) Empty =
   error ("Variable not found: "++s)
eval (LamE nm t body) env =
   ( v \rightarrow eval body (Extend nm t v env))
eval (ApplyE f x) env = (eval f env) (eval x env)
eval (FstE x) env = fst(eval x env)
eval (SndE x) env = snd(eval x env)
eval (v@(VarE s t1)) (Extend nm t2 value more)
  s==nm = case test t1 t2 of
              Just Refl -> value
              Nothing -> error "types don't match"
   otherwise = eval v more
```

Units of measure

```
data TempUnit = Fahrenheit
| Celsius
| Kelvin
```

- data Degree:: TempUnit -> * where
 - F:: Float -> Degree Fahrenheit
 - C:: Float -> Degree Celsius
 - K:: Float -> Degree Kelvin

```
add:: Degree u -> Degree u -> Degree u
add (F x) (F y) = F(x+y)
add (C x) (C y) = C(x+y)
add (K x) (K y) = K(x+y)
```

N-way zip

 $zipN 1 (+1) [1,2,3] \rightarrow [2,3,4]$

zipN 2 (+) [1,2,3] [4,5,6] → [5,7,9]

zipN 3 (\ x y z -> (x+z,y))[2,3] [5,1] [6,8] → [(8,5),(11,1)]

The Natural Numbers with strange types

data Zip :: * -> * -> * where Z:: Zip a [a] S:: Zip b c -> Zip (a -> b) ([a] -> c) Z :: Zip a [a] (S Z) :: Zip (a -> b) ([a] -> [b]) (S (S Z)) :: Zip (a -> a1 -> b) ([a] -> [a1] -> [b])(S(S(SZ))) ::Zip (a -> a1 -> a2 -> b) ([a] -> [a1] -> [a2] -> [b])

Why these types.

- f :: (a -> b -> c -> d)
- (f x) :: (b -> c -> d)
- (f x y) :: (c -> d)
- (f x y z) :: d

(zip f) :: ([a] -> [b] -> [c] -> [d])
(zip f xs) :: ([b] -> [c] -> [d])
(zip f xs ys) :: ([c] -> [d])
(zip f xs ys za) :: [d]

To define zip using Zip', we write helper function, help :: Zip' a b -> a -> b -> b. The basic idea is captured by the table below.

2f:: (a -> b -> c)	zip f:: [a] -> [b] -> [c]	help two' f (zip f):: [a] -> [b] -> [c]
1 f x:: (b -> c)	zip f xs:: [b] -> [c]	help one' (f x) (zip f xs):: [b] \rightarrow [c]
0 f x y:: c	zip f xs ys:: [c]	help zero' (f x y) (zip f xs ys):: [c]

zero' = Z

one' = S Z

two' = S (S Z)

Code

```
skip:: Zip a b -> b
skip Z = []
skip (S n) = \setminus ys -> skip n
```

```
zipN:: Zip a b -> a -> b
zipN Z = \ n -> [n]
zipN (n@(S m)) =
   let zip f = help n f (\ x -> zip f x)
   in zip
```