

# Turing Machine

slides of Prof. K. J. Hintz used

# Turing Machine

- An FSM Cannot Compute a Number Comprised of an Infinite Number of Digits Since It Itself Is Finite.
- A Finite Method Can Be Developed to Compute an Infinite Length Number
- The Method Can Be Implemented by Reading and Writing Intermediate Results from/to an Assumed Infinite Memory

# Halting Problem

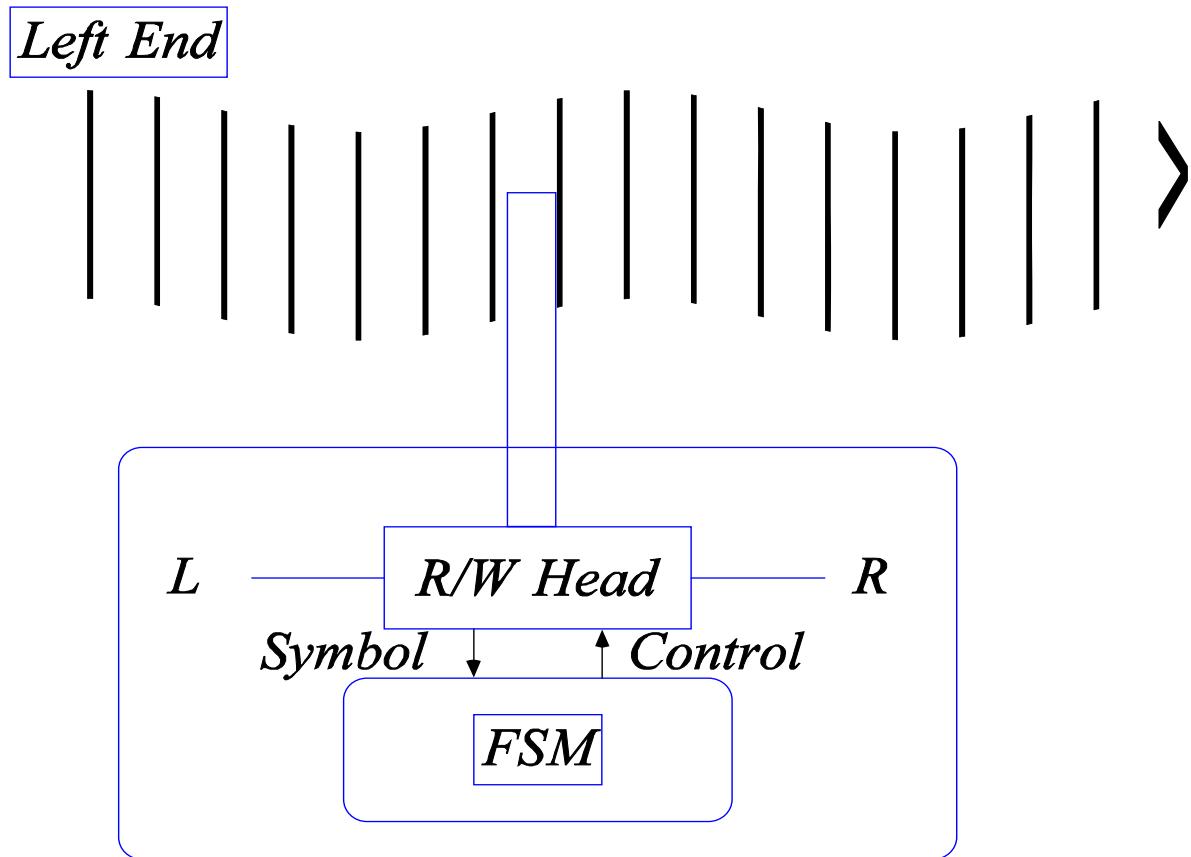
- Difficulty with the Turing Machine
  - Not guaranteed to terminate
  - Don't know when it will terminate
- Still an unsolved problem
  - Is there a method for analyzing a Turing machine to determine if and when it will terminate its computation?

# Turing Machine

- Devised by Alan Turing, 1937 paper\*
- Definition of Computable
- Some Problems are Not Computable

\* Turing, A. M., “On Computable Numbers, with an Application to the Entscheidungsproblem“, *Proceedings of the London Mathematical Society*, Series 2, 42:230-265 and 43:544-546, 1937.

# Physical Model of TM



# Properties

- Infinitely Long Readable/Writable Tape With Fixed Left End
- Moveable Read/Write Tape Head
  - Only read/write to current position
- Finite State Machine for Control
  - Movement of tape head +/- 1 tape position only
  - Symbols written to tape

# Properties

- String on Tape
  - Left End of String at Left End of Tape
  - Tape Head Is Initially at Right End of String.



*Left end of Tape*

*Tape Head Initial Position*

# TM Alternatives

- Multiple Heads
- Infinite Tape in Both Directions
- Tape Moves, Head Stationary
- Increased Number of Symbols

None of These Changes Affect the Basic Computability of Turing Machines

# TM Formal Definition

- A Turing Machine is a Quadruple

$$M_T = ( S, \Sigma, s, \delta )$$

**S** Finite set of states

**$\Sigma$**  { Tape Symbols  $\notin \{ L, R \}$  }  $\cup \{ \# \}$

**s** initial state

**$\delta$**  Deterministic transition function

$$\delta : S \times \Sigma \rightarrow ( S \cup h ) \times ( \Sigma \cup \{ L, R \} )$$

# TM Configuration

- The TM Configuration is a quadruple

$$C_T = ( s, t_L, t, t_R )$$

$$\in ( S \cup \{ h \} ) \times \Sigma^* \times \Sigma \times ( \Sigma^* ( \Sigma - \{ \# \} ) \cup \{ \Lambda \} )$$

s Current State

$t_L$  Sequence of symbols to the left of the tape head  $\in \Sigma^*$

$t$  Current read symbol under the head

$t_R$  Sequence of symbols to the right of the tape head

# TM Configuration

- A Shorthand Notation  
( current state,  
string with current head position underlined )

*e.g.,*

$$( q_2, ab\underline{b}aab )$$

# TM Delta Function

$$\delta : S \times \Sigma \rightarrow (S \cup \{ h \}) \times (\Sigma \cup \{ L, R \})$$

<i>Present State</i>	<i>Read Present Symbol</i>	<i>Next State &amp; Symbol</i>
$q1$	a	( p, b )
$q2$	#	( p, R )

If read an *a*, write a *b*.

If read a *blank (#)*, read-only, and move right one.

# Two TM Examples

- Quantity Doubler:
  - State Table: head movement and write are done in separate states
  - FSM: simultaneous write/move
- Odd Detector
  - Head movement and write are done simultaneously

# TM Example, 2X

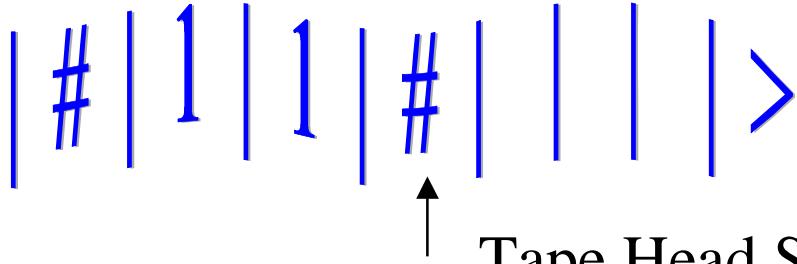
$$M_{T2x} = (S, \Sigma, s, \delta)$$

$$S = \{0, 1, 2, 3, 4, 5\}$$

$$\Sigma = \{\#, 1\}$$

$$s = s_0$$

$$\delta = \{( (s_0, \#), (s_1, L) ), \dots \}$$



Tape Head Starting Position

# TM Example, 2X

- Transition Function

PS	Input #	Input 1	Comment
S <sub>0</sub>	s <sub>1</sub> /L	s <sub>0</sub> /L	
S <sub>1</sub>	halt	s <sub>2</sub> /#	found a 1 to left, replace with #
S <sub>2</sub>	s <sub>3</sub> /R	s <sub>3</sub> /R	

# TM Example, 2X

PS	Input #	Input 1	Comment
s <sub>3</sub>	s <sub>4</sub> /1	s <sub>3</sub> /R	Move to right until at right-most end of string of 1's
s <sub>4</sub>		s <sub>5</sub> /R	
s <sub>5</sub>	s <sub>0</sub> /1	s <sub>5</sub> /R	

# TM Example, 2X

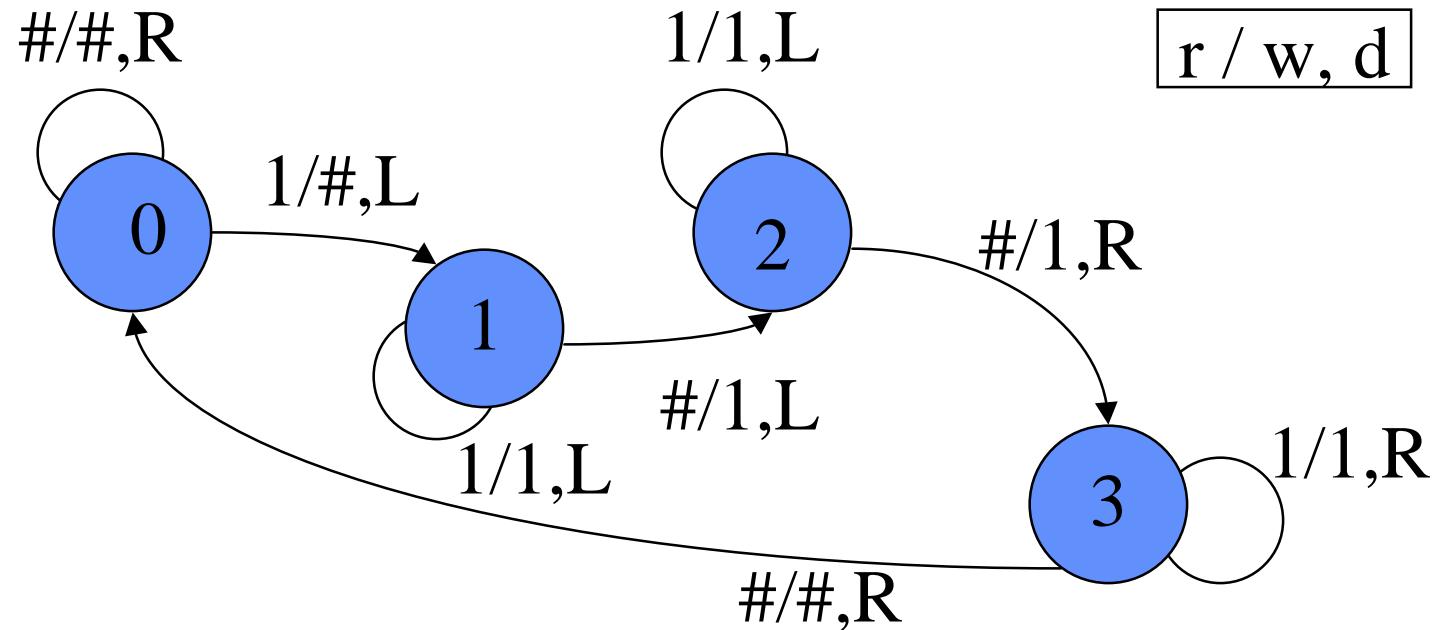
# 1 1 <u>#</u>	s <sub>0</sub>	# 1 <u>#</u> 1 1 #	s <sub>0</sub>
# 1 <u>1</u> #	s <sub>1</sub>	# <u>1</u> # 1 1 #	s <sub>1</sub>
# 1 <u>#</u> #	s <sub>2</sub>	# <u>#</u> # 1 1 #	s <sub>2</sub>
# 1 # <u>#</u>	s <sub>3</sub>	# # <u>#</u> 1 1 #	s <sub>3</sub>
# 1 # <u>1</u> #	s <sub>4</sub>	# # <u>1</u> 1 1 #	s <sub>4</sub>
# 1 # 1 <u>#</u>	s <sub>5</sub>	# # 1 <u>1</u> 1 #	s <sub>5</sub>
# 1 # 1 <u>1</u> #	s <sub>0</sub>	# # 1 1 <u>1</u> #	s <sub>5</sub>
# 1 # <u>1</u> 1 #	s <sub>0</sub>	# # 1 1 1 <u>#</u>	s <sub>5</sub>

# TM Example, 2X

#	#	1	1	1	<u>1</u>	s <sub>5</sub>
#	#	1	1	1	<u>1</u>	s <sub>0</sub>
#	#	1	1	<u>1</u>	1	s <sub>0</sub>
#	#	1	<u>1</u>	1	1	s <sub>0</sub>
#	#	<u>1</u>	1	1	1	s <sub>0</sub>
#	<u>#</u>	1	1	1	1	s <sub>0</sub>
<u>#</u>	#	1	1	1	1	s <sub>1</sub>

# FSM to Control 2x TM

## Simultaneous Write/Move



# TM Example 2, Odd Det.

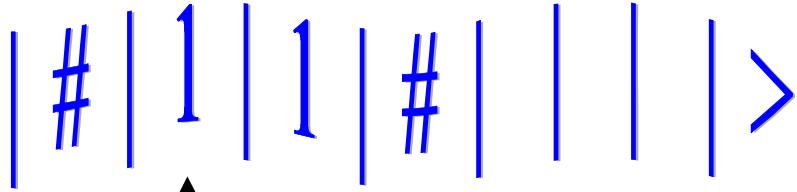
$$M_{T2x} = (S, \Sigma, s, \delta)$$

$$S = \{0, 1\}$$

$$\Sigma = \{\#, 1\}$$

$$s = s_0$$

$$\delta = \{( (s_0, \#), (s_1, L) ), \dots \}$$



Tape Head Starting Position

# TM Example 2, Odd Det.

- Transition Function

PS	Input #	Input 1	Comment
$s_0$	$s_0/\#/R$	$s_1/\#/F$	
$s_1$	halt	$s_0/\#/R$	Halts if Odd