Postulates of Quantum Mechanics

<u>SOURCES</u>

Angela Antoniu, David Fortin, Artur Ekert, Michael Frank, Kevin Irwig



Administrivia/Overview

- Readings & and homeworks are now posted
- Basic quantum theory
 - Background concepts: Systems & states
 - Distinguishable states, state vectors, Hilbert spaces
 - Ket Notation, measurement, wavefunctions
 - Operators, observables, entanglement
 - Unitary transformations & time-evolution

Linear Operators

- *V*,*W*: Vector spaces.
- A linear operator A from V to W is a linear function $A:V \rightarrow W$. An operator on V is an operator from V to itself.
- Given bases for *V* and *W*, we can represent linear operators as matrices.
- An operator *A* on *V* is *Hermitian* iff it is selfadjoint (*A*=*A*[†]). Its diagonal elements are real.

Eigenvalues & Eigenvectors

- v is called an *eigenvector* of linear operator A iff
 A just multiplies v by a scalar x, *i.e.* Av=xv
 "eigen" (German) = "characteristic".
- x, the *eigenvalue* corresponding to eigenvector v, is just the scalar that A multiplies v by.
- x is *degenerate* if it is shared by 2 eigenvectors that are not scalar multiples of each other.
- Any Hermitian operator has all real-valued eigenvectors, which are orthogonal (for distinct eigenvalues).

Unitary Transformations

- A matrix (or linear operator) U is *unitary* iff its inverse equals its adjoint: $U^{-1} = U^{\dagger}$
- Some properties of unitary transformations:
 - Invertible, bijective, one-to-one.
 - The set of row vectors is orthonormal.
 - Ditto for the set of column vectors.
 - Preserves vector length: $|U\Psi| = |\Psi|$
 - Therefore also preserves total probability over all states:

$$|\Psi|^2 \equiv \sum |\Psi(s_i)|^2$$

- Corresponds to a **change of basis**, from one orthonormal basis to another.

– Or, a generalized rotation of Ψ in Hilbert space

The Solvay Congress Werner Heisenberg of 1927 Louis de Broglie Erwin Schrödinger



Postulates of Quantum Mechanics Lecture objectives

• Why are postulates important?

-... they provide the connections between the physical, real, world <u>and</u> the quantum mechanics mathematics used to model these systems

Lecture Objectives

- Description of connections
- Introduce the postulates
- -Learn how to use them
- -...and when to use them

Physical Systems -Quantum Mechanics Connections

Postulate 1	Isolated physical system	2	Hilbert Space
Postulate 2	Evolution of a physical system	?	Unitary transformation
Postulate 3	Measurements of a physical system	2	Measurement operators
Postulate 4	Composite physical system	?	Tensor product of components



State Space

Systems and Subsystems

- Intuitively speaking, a *physical system* consists of a <u>region of spacetime</u> & all the entities (*e.g.* particles & fields) contained within it.
 - The universe (over all time) is a physical system

B

A

- Transistors, computers, people: also physical systems.
- One physical system A is a *subsystem* of another system B (write A⊆B) iff A is completely contained within B.
- Later, we may try to make these definitions more formal & precise.

Closed vs. Open Systems

- A subsystem is *closed* to the extent that no particles, information, energy, or entropy enter or leave the system.
 - The universe is (presumably) a closed system.
 - Subsystems of the universe may be *almost* closed
- Often in physics we consider statements about closed systems.
 - These statements may often be *perfectly* true only in a *perfectly* closed system.
 - However, they will often also be *approximately* true in any *nearly* closed system (in a well-defined way)

Concrete vs. Abstract Systems

- Usually, when reasoning about or interacting with a system, an entity (*e.g.* a physicist) has in mind a *description* of the system.
- A description that contains *every* property of the system is an *exact* or *concrete* description.
 That system (to the entity) is a *concrete* system.
- Other descriptions are *abstract* descriptions.
 The system (as considered by that entity) is an *abstract* system, to some degree.
- We *nearly always* deal with **abstract systems**! – Based on the descriptions that are available to us.

States & State Spaces

- A *possible state S* of an abstract system *A* (described by a description *D*) is any concrete system *C* that is consistent with *D*.
 - -I.e., it is possible that the system in question could be completely described by the description of C.
- The *state space* of *A* is the set of all possible states of *A*.
- Most of the class, the concepts we've discussed can be applied to *either* classical or quantum physics
 - Now, let's get to the **uniquely quantum** stuff...

Distinguishability of States

- Classical <u>and</u> quantum mechanics <u>differ</u> regarding the *distinguishability* of states.
- In **classical mechanics**, there is no issue:
 - Any two states s, t are either the same (s = t), or different $(s \neq t)$, and that's all there is to it.
- In quantum mechanics (*i.e. in reality*):
 - There are pairs of states s ≠ t that are mathematically distinct, but not 100% physically distinguishable.
 - Such states <u>cannot be reliably distinguished</u> by *any number of measurements, no matter how precise.*
 - But you *can* know the real state (with high probability), *if* you prepared the system to be in a certain state.

Postulate 1: State Space

- Postulate 1 defines "the setting" in which Quantum Mechanics takes place, which is the Hilbert space (inner product space which satisfies the condition of completeness)
- **<u>Postulate1</u>**: Any <u>isolated physical space</u> is associated with a complex vector space with inner product called the *State Space* of the system.
 - The system is <u>completely described</u> by a *state vector*, a unit vector, pertaining to the state space.
 - The state space describes all possible states the system can be in.
 - Postulate 1 does NOT tell us either what <u>the state space</u> or <u>state vector</u> is.

An example of a state space

A Qubit: The Simplest State Space

The simplest quantum system is a state space with 2 dimensions -- there are two possible states the system can be in! $|\psi\rangle = \alpha_0 |0\rangle + \alpha_1 |1\rangle \implies$ a qubit!

Recall: state vector is a unit vector, so

 $\langle \psi | \psi \rangle = 1 \Rightarrow |\alpha_0|^2 + |\alpha_1|^2 = 1$ (normalization condition)

A linear combination of states is called a *superposition* of states —>qualitatively new feature: a qubit can be a mixture of two classical bits!

Schroedinger's Cat and Explanation of Qubits



Postulate 1: An isolated physical system is described by a unit vector (*state vector*) in a Hilbert space (*state space*)

Distinguishability of States, more precisely

- Two state vectors **s** and **t** are (*perfectly*) distinguishable or orthogonal (write $s \perp t$) iff $s^{\dagger}t = 0$. (Their inner product is zero.)
- State vectors s and t are *perfectly indistinguishable* or *identical* (write *s=t*) iff s[†]t = 1. (Their inner product is one.)
- Otherwise, *s* and *t* are both *non-orthogonal*, and *non-identical*. *Not perfectly distinguishable*.
- We say, "the *amplitude* of state *s*, given state *t*, is *s*[†]*t*". <u>Note:</u> amplitudes are <u>complex numbers</u>.

State Vectors & Hilbert Space

- Let *S* be any maximal set of distinguishable possible states *s*, *t*, ... of an abstract system *A*.
- Identify the elements of *S* with unit-length, mutually-orthogonal (basis) vectors in an abstract complex vector space *H*.
 The "Hilbert space"
- Postulate 1: The possible states ψ of A can be *identified* with the unit vectors of H.



Evolution



• Evolution of an isolated system can be expressed as:

$$|\mathbf{v}(\mathbf{t}_2)\rangle = \mathbf{U}(\mathbf{t}_1,\mathbf{t}_2)|\mathbf{v}(\mathbf{t}_1)\rangle$$

where t_1 , t_2 are <u>moments in time</u> and $U(t_1, t_2)$ is a unitary operator.

- U may vary with time. Hence, the corresponding segment of time is explicitly specified:

$U(t_1, t_2)$ the process is in a sense Markovian (*history doesn't matter*) and reversible, since

$$\mathbf{U}^{\dagger}\mathbf{U}\mid\mathbf{v}
angle=\left|\mathbf{v}
ight
angle$$

Unitary operations preserve inner product

Example of evolution

Example: Hadamard Gate

$$\begin{aligned} \text{Hadamard Gate:} \ H|0\rangle &= \frac{1}{\sqrt{2}} \left(0 \right) + |1\rangle \right) \\ H|1\rangle &= \frac{1}{\sqrt{2}} \left(0 \right) - |1\rangle) \end{aligned} \Rightarrow H = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \\ |0\rangle &= \begin{bmatrix} 1 \\ 0 \end{bmatrix} \Rightarrow H|0\rangle = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \frac{1}{\sqrt{2}} \left(0 \right) + |1\rangle) \\ |1\rangle &= \begin{bmatrix} 0 \\ 1 \end{bmatrix} \Rightarrow H|1\rangle = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \frac{1}{\sqrt{2}} \left(0 \right) - |1\rangle) \end{aligned}$$

(in this case the unitary matrix *H* has trivial time dependence)

Time Evolution

- Recall the Postulate: (Closed) systems evolve (change state) over time via unitary transformations. $\Psi_{t2} = U_{t1 \rightarrow t2} \Psi_{t1}$
- Note that since *U* is linear, a small-factor change in amplitude of a particular state at t1 leads to a correspondingly small change in the amplitude of the corresponding state at t2.
 - Chaos (sensitivity to initial conditions) requires an ensemble of initial states that are different enough to be distinguishable (in the sense we defined)
 - Indistinguishable initial states never beget distinguishable outcomes "analog" computing is infeasible?

Wavefunctions

- Given any set **S** of system states (mutually distinguishable, or not),
- A quantum state vector can also be translated to a *wavefunction* $\Psi: S \rightarrow C$, giving, for each state
 - $s \in S$, the amplitude $\Psi(s)$ of that state.
 - When s is another state vector, and the real state is t, then $\Psi(s)$ is just $s^{\dagger}t$.
 - Ψ is called a *wavefunction* because its time evolution obeys an equation (Schrödinger's equation) which has the form of a *wave equation* when **S** ranges over a space of *positional* states.

Schrödinger's Wave Equation

We have a system with states given by (x, t) where:

- *t* is a <u>global time</u> coordinate, and
- **x** describes *N*/3 particles $(p_1, \dots, p_{N/3})$ with masses $(m_1, \dots, m_{N/3})$ in a <u>3-D Euclidean</u> space,
- where each p_i is located at coordinates $(x_{3i}, x_{3i+1}, x_{3i+2})$, and
- where particles interact with potential energy function V(x,t),
- the wavefunction $\Psi(x,t)$ obeys the following (2nd-order, linear, partial) differential equation:

 $-\frac{\hbar}{2}\left(\sum_{j=0}^{N-1}\frac{1}{m_{\lfloor j/3\rfloor}}\frac{\partial^2}{\partial x_j^2}\Psi(\boldsymbol{x},t)\right)+V(\boldsymbol{x},t)=i\hbar\frac{\partial}{\partial t}\Psi(\boldsymbol{x},t)$

Features of the wave equation

- Particles' *momentum* state p is encoded implicitly by the particle's wavelength λ : $p=h/\lambda$
- The *energy* of any state is given by the frequency v of rotation of the wavefunction in the complex plane: E=hv.
- By simulating this simple equation, one can observe basic quantum phenomena such as:
 - Interference fringes
 - Tunneling of wave packets through potential barriers



...in this class we are interested in Heisenberg's view.....



Quantum

Measurement

Probability and Measurement

- A *yes/no measurement* is an <u>interaction</u> designed to determine whether a given system is in a certain state *s*.
- The amplitude of state *s*, given the actual state *t* of the system determines the *probability* of getting a "yes" from the measurement.
- Important: For a system prepared in state *t*, any measurement that asks "is it in state s?" will return "yes" with probability Pr[s|t] = |s[†]t|²
 - After the measurement, the state is changed, in a way we will define later.

A Simple Example of distinguishable, nondistinguishable states and measurements

- Suppose abstract system *S* has a set of only 4 <u>distinguishable possible states</u>, which we'll call s_0, s_1, s_2 , and s_3 , with <u>corresponding ket vectors</u> $|s_0\rangle, |s_1\rangle, |s_2\rangle$, and $|s_3\rangle$.
- Another possible state is then the vector

$$\frac{1}{\sqrt{2}} |s_0\rangle - \frac{i}{\sqrt{2}} |s_3\rangle \qquad \qquad \begin{bmatrix} 1/\sqrt{2} \\ 0 \end{bmatrix}$$

- Which is equal to the column matrix: $\begin{bmatrix} 0 \\ -i \end{bmatrix} = \frac{1}{i}$
- If measured to see if it is in state s_0 , $\lfloor -t \rfloor$ we have a 50% chance of getting a "yes".

Observables

- Hermitian operator *A* on *V* is called an <u>observable</u> if there is an orthonormal (all unitlength, and mutually orthogonal) subset of its eigenvectors that forms a *basis* of *V*.
- **Postulate 3:** Every measurable physical property of a system is described by a corresponding operator *A*. <u>Measurement outcomes correspond to eigenvalues.</u>
- **Postulate 3a:** The probability of an outcome is given by the <u>squared absolute amplitude</u> of the corresponding eigenvector(s), given the state.

Towards QM Postulate 3 on measurement and general formulas

A measurement is described by an Hermitian operator (*observable*)

$$M=\sum_m m P_m$$

- $-P_m$ is the projector onto the eigenspace of M with eigenvalue m $P | w \rangle$
- After the measurement the state will be $\frac{P_m |\psi\rangle}{\sqrt{p(m)}}$ with probability $p(m) = \langle \psi | P_m | \psi \rangle$.
- e.g. measurement of a qubit in the computational basis
 - measuring $|\psi\rangle = \alpha |0\rangle + \beta |1\rangle$ gives:
 - $|0\rangle$ with probability $\langle \psi | 0 \rangle \langle 0 | \psi \rangle = |\langle 0 | \psi \rangle|^2 = |\alpha|^2$
 - |1> with probability $\langle \psi |1\rangle \langle 1|\psi\rangle = |\langle 1|\psi\rangle|^2 = |\beta|^2$



Quantum Measurement

The measurement of a closed system is described by a collection of operators \mathbf{M}_m which act on the state space such that

1) $p(m) = \langle \psi | \mathbf{M}_m^{\tau} \mathbf{M}_m | \psi \rangle$ describes the probability the measurement outcome *m* occurred 2) $|\psi'\rangle = \frac{\mathbf{M}_m |\psi\rangle}{\sqrt{\langle \psi | \mathbf{M}_m^{\tau} \mathbf{M}_m | \psi \rangle}}$ is the state of the system after measurement outcome *m* occurred 3) $\sum_m \mathbf{M}_m^{\tau} \mathbf{M}_m = \mathbf{I} \Leftrightarrow \sum_m p(m) = 1$ Completeness relation

Notes: Measurement is an external observation of a system and so disturbs its unitary evolution

Now we use this notation for an Example of Qubit Measurement

There are two possible outcomes in the measurement of a qubit: $|0\rangle$ and $|1\rangle$ $\longrightarrow \mathbf{M}_0 = |0\rangle\langle 0| \qquad \mathbf{M}_1 = |1\rangle\langle 1| \qquad (\mathbf{M}_0 + \mathbf{M}_1 = \mathbf{I})$

So the probability that $|\psi\rangle = \alpha_0 |0\rangle + \alpha_1 |1\rangle$ is in the state $|0\rangle$ is $p(0) = \langle \psi | \mathbf{M}_0^{\tau} \mathbf{M}_0 | \psi \rangle = (\alpha_0^* \langle 0 | + \alpha_1^* \langle 1 |) | 0 \rangle \langle 0 |)^{\tau} (|0\rangle \langle 0 |) (\alpha_0 | 0\rangle + \alpha_1 |1\rangle)$ $= |\alpha_0|^2 |\langle 0 | 0 \rangle|^2 = |\alpha_0|^2$

And the state vector changes: $|\psi\rangle \rightarrow \frac{M_o}{|\alpha_o|} |\psi\rangle = \frac{\alpha_o}{|\alpha_o|} |0\rangle$

What happens to a system after a Measurement?

- After a system or subsystem is measured from outside, its state appears to *collapse* to exactly match the measured outcome
 - the amplitudes of all states perfectly distinguishable from states consistent with that outcome drop to zero
 - states consistent with measured outcome can be considered "renormalized" so their probabilities sum to 1
- This "collapse" *seems* nonunitary (& nonlocal)
 - However, this behavior is now explicable as the expected consensus phenomenon that would be experienced even by entities within a closed, perfectly unitarily-evolving world (Everett, Zurek).

Distinguishability

Only orthogonal states can be distinguished in a measurement!

Why? Suppose $|\Psi_1\rangle$ and $|\Psi_2\rangle$ are not orthogonal, but can be distinguished by two measurement operators, \mathbf{E}_1 and \mathbf{E}_2 where $\mathbf{E}_1 + \mathbf{E}_2 = \mathbf{I}$, and $\mathbf{E}_i = \mathbf{M}_i^{\tau} \mathbf{M}_i$. We must have $\langle \Psi_1 | \mathbf{E}_1 | \Psi_1 \rangle = 1$ and $\langle \Psi_2 | \mathbf{E}_2 | \Psi_2 \rangle = 1$

since by assumption the states can be distinguished. However we can also write $|\psi_2\rangle = \alpha |\psi_1\rangle + \beta |\varphi\rangle$ where $\langle \psi |\varphi\rangle = 0$ and $|\alpha|^2 + |\beta|^2 = 1$

Since $\mathbf{E}_1 + \mathbf{E}_2 = \mathbf{I}$ we have $\langle \psi_1 | \mathbf{E}_2 | \psi_1 \rangle = 0$. But then

$$\langle \boldsymbol{\psi}_{2} | \mathbf{E}_{2} | \boldsymbol{\psi}_{2} \rangle = |\boldsymbol{\beta}|^{2} \langle \boldsymbol{\varphi} | \mathbf{E}_{2} | \boldsymbol{\varphi} \rangle \leq |\boldsymbol{\beta}|^{2} < 1$$

(Unless $\alpha = 0$ in which case states are orthogonal)

On the other hand

Thus we have contradiction, states can be distinguished unless they are orthogonal

Projective Measurements

Observable: A Hermitian operator on the state space.

Can write:
$$\mathbf{M} = \sum_{m} m \mathbf{P}_{m} \Rightarrow p(m) = \langle \boldsymbol{\psi} | \mathbf{P}_{m}^{\mathsf{T}} \mathbf{P}_{m} | \boldsymbol{\psi} \rangle = \langle \boldsymbol{\psi} | \mathbf{P}_{m} | \boldsymbol{\psi} \rangle$$

(each measurement operator is a projector!)

Average value of a measurement:

$$E(\mathbf{M}) = \sum_{m} mp(m) = \sum_{m} m\langle \psi | \mathbf{P}_{m} | \psi \rangle = \langle \psi | \sum_{m} m\mathbf{P}_{m} | \psi \rangle = \langle \psi | \mathbf{M} | \psi \rangle$$
(expectation value)

Standard deviation of a measurement:

$$\Delta(\mathbf{M}) = \sqrt{\left\langle \left(\mathbf{M} - \left\langle \mathbf{M} \right\rangle\right)^2 \right\rangle} = \sqrt{\left\langle \mathbf{M}^2 \right\rangle - \left\langle \mathbf{M} \right\rangle^2} \quad \text{where } \left\langle \mathbf{M} \right\rangle = \left\langle \psi \left| \mathbf{M} \right| \psi \right\rangle$$

Uncertainty Principle

$$\Delta(\mathbf{p})\Delta(\mathbf{q}) \geq \frac{\left| \langle \boldsymbol{\psi} | [\mathbf{p}, \mathbf{q}] \boldsymbol{\psi} \rangle \right|}{2}$$

Why?

$$\langle \psi | \mathbf{A}^2 | \psi \rangle \langle \psi | \mathbf{B}^2 | \psi \rangle \ge |\langle \psi | \mathbf{A} \mathbf{B} | \psi \rangle|^2 = \frac{1}{4} |\langle \psi | [\mathbf{A}, \mathbf{B}] + \{\mathbf{A}, \mathbf{B}\} | \psi \rangle|^2$$

 $\frac{1}{4} |\langle \psi | [\mathbf{A}, \mathbf{B}] \psi \rangle|^2 + |\langle \psi | \{\mathbf{A}, \mathbf{B}\} | \psi \rangle|^2 | \ge \frac{1}{4} |\langle \psi | [\mathbf{A}, \mathbf{B}] \psi \rangle|^2$
Set $\mathbf{A} = \mathbf{p} - \langle \mathbf{p} \rangle, \mathbf{B} = \mathbf{q} - \langle \mathbf{q} \rangle$ and the result follows!

Measurement errors are not arbitrarily reducible!

Positive Operator-Valued Measurements (POVM)

POVM: Any complete set $\{\mathbf{E}_m\}$ of positive operators $\left(\sum_m \mathbf{E}_m = 1\right)$

Recall $|\Psi_1
angle$ and $|\Psi_2
angle = lpha |\psi_1
angle + eta |arphi
angle$. Write

$$\mathbf{E}_{1} = |\boldsymbol{\varphi}\rangle\langle\boldsymbol{\varphi}|$$

$$\mathbf{E}_{2} = \frac{(\beta^{*}|\boldsymbol{\psi}_{1}\rangle - \boldsymbol{\alpha}^{*}|\boldsymbol{\varphi}\rangle)(\beta\langle\boldsymbol{\psi}_{1}| - \boldsymbol{\alpha}\langle\boldsymbol{\varphi}|)}{|\boldsymbol{\alpha}|^{2} + |\boldsymbol{\beta}|^{2}}$$

$$\mathbf{E}_{3} = \boldsymbol{I} - \mathbf{E}_{1} - \mathbf{E}_{2}$$

POVMs:

Advantage: can never mis-identify a state Disadvantage: sometimes you get no information

 $\left.\begin{array}{c} \text{If you observe}\\ \mathbf{E}_1 \text{ then you know}\\ \text{the state is} | \Psi_2 \rangle \ .\\ \text{If you observe } \mathbf{E}_2\\ \text{then you know the}\\ \text{state is} | \Psi_1 \rangle \ . \text{ If you}\\ \text{observe } \mathbf{E}_3 \text{ then you}\\ \text{don't know the state} \end{array}\right.$

Phase

Global Phase: $e^{i\theta} |\psi\rangle$ is physically indistinguishable from $|\psi\rangle$ $\langle \psi | e^{-i\theta} \mathbf{M}_m^{\tau} \mathbf{M}_m e^{i\theta} |\psi\rangle = \langle \psi | \mathbf{M}_m^{\tau} \mathbf{M}_m |\psi\rangle$

Relative Phase: $|\psi\rangle = |\chi\rangle + |\varphi\rangle$ can be physically distinguished from $|\psi\rangle = |\chi\rangle + e^{i\theta} |\varphi\rangle$

a basis-dependent concept

Local Phase: If the phase is a function of position and/or time we say that it is local

> $\theta = \theta(\vec{x}, t)$ (not relevant (yet) for quantum computing)

Density Operators

For a given state |ψ⟩, the probabilities of all the basis states s_i are determined by an Hermitian operator or matrix ρ (the *density* matrix):

$$\rho = [\rho_{i,j}] = |\psi\rangle\langle\psi| = [c_j^*c_i] = \begin{vmatrix} c_1^*c_1 & \cdots & c_n^*c_1 \\ \vdots & \ddots & \vdots \\ c_1^*c_n & \cdots & c_n^*c_n \end{vmatrix}$$

- The diagonal elements ρ_{i,i} are the probabilities of the basis states.
 - The off-diagonal elements are "coherences".
- The density matrix describes the state exactly.

Mixed States

- Suppose one only knows of a system that it is in one of a *statistical ensemble* of state vectors v_i ("pure" states), each with density matrix ρ_i and probability P_i. This is called a *mixed state*.
- This ensemble is *completely described*, for all *physical purposes*, by the expectation value (weighted average) of density matrices: $\rho = \sum P_i \rho_i$
 - Note: even if there were *uncountably* many v_i , the state remains fully described by $< n^2$ complex numbers, where *n* is the number of basis states!







Compound Systems

- Let **C=AB** be a system composed of two separate subsystems A,B each with vector spaces A, B with bases $|a_i\rangle$, $|b_j\rangle$.
- The state space of C is a vector space $C=A\otimes B$ given by the *tensor product* of spaces A and B, with basis states labeled as $|a_ib_j\rangle$.





The state space of a composite system is the tensor product of the state spaces of its components.

System A: $|\chi\rangle$
System B: $|\varphi\rangle$ System AB: $|\chi\rangle \otimes |\varphi\rangle$

Common usage: Physical system (call it V) $|\chi\rangle \otimes |\varphi\rangle$ Ancilla system (corresponds to measurement outcomes -- call it M)

> Unitary Dynamics + Projective Measurements = General Measurement

Composition example

The state space of a composite physical system is the *tensor product of the state spaces of the components*

- -n qubits represented by a 2^n -dimensional Hilbert space
- composite state is $|\psi\rangle = |\psi_1\rangle \otimes |\psi_2\rangle \otimes \ldots \otimes |\psi_n\rangle$
- e.g. 2 qubits:

$$|\psi_1\rangle = \alpha_1|0\rangle + \beta_1|1\rangle$$

$$|\psi_2\rangle = \alpha_2|0\rangle + \beta_2|1\rangle$$

 $|\psi\rangle = |\psi_1\rangle \otimes |\psi_2\rangle = \alpha_1 \alpha_2 |00\rangle + \alpha_1 \beta_2 |01\rangle + \beta_1 \alpha_2 |10\rangle + \beta_1 \beta_2 |11\rangle$

– entanglement

2 qubits are *entangled* if $|\psi\rangle \neq |\psi_1\rangle \otimes |\psi_2\rangle$ for any $|\psi_1\rangle, |\psi_2\rangle$ e.g. $|\psi\rangle = \alpha |00\rangle + \beta |11\rangle$



• If the state of compound system C <u>can be</u> <u>expressed</u> as a tensor product of states of two independent subsystems A and B,

 $\psi_c = \psi_a \otimes \psi_b,$

- then, we say that A and B are *not entangled*, and they have individual states.
 - $\text{E.g. } |00\rangle + |01\rangle + |10\rangle + |11\rangle = (|0\rangle + |1\rangle) \otimes (|0\rangle + |1\rangle)$
- Otherwise, A and B are *entangled* (basically correlated); their states are not independent.
 E.g. |00⟩+|11⟩

Size of Compound State Spaces

- Note that a system composed of many separate subsystems has a *very large* state space.
- Say it is composed of *N* subsystems, each with *k* basis states:
 - The compound system has k^N basis states!
 - There are states of the compound system having nonzero amplitude in *all* these k^N basis states!
 - In such states, all the distinguishable basis states are (simultaneously) possible outcomes (each with some corresponding probability)
 - Illustrates the "many worlds" nature of quantum mechanics.

General Measurements in compound spaces

Let $U: V \otimes M \to V \otimes M$ be defined so that

$$\mathbf{U}|\boldsymbol{\psi}\rangle|0\rangle \equiv \sum \mathbf{M}_{m}|\boldsymbol{\psi}\rangle|m\rangle$$

for a fixed state $\ket{0}$ in M and a general state $\ket{\psi}$ in V

$$\implies (\mathbf{U}|\varphi\rangle|0\rangle)^{\mathrm{T}}(\mathbf{U}|\psi\rangle|0\rangle) = \langle \varphi|\langle 0|\mathbf{U}^{\mathrm{T}}\mathbf{U}|\psi\rangle|0\rangle = \sum_{m,m'} \langle \varphi|\mathbf{M}^{\mathrm{T}}_{m}\mathbf{M}_{m'}|\psi\rangle\langle m|m'\rangle$$

 $= \sum_{m} \langle \varphi | \mathbf{M}_{m}^{\mathsf{T}} \mathbf{M}_{m} | \psi \rangle = \langle \varphi | \psi \rangle \Longrightarrow \mathbf{U} \text{ can be defined on}$ entire space $\mathbf{V} \otimes \mathbf{M}$

Now set $\mathbf{P}_m = \mathbf{I}_{\mathbf{V}} \otimes |m\rangle \langle m|$

$$\implies p(m) = \langle \psi | \langle 0 | \mathbf{U}^{\tau} \mathbf{P}_{m} \mathbf{U} | \psi \rangle | 0 \rangle = \sum_{m',m''} \langle \psi | \mathbf{M}^{\tau}_{m'} \langle m' | (\mathbf{I}_{\mathbf{V}} \otimes | m \rangle \langle m |) \mathbf{M}_{m''} | \psi \rangle | m'' \rangle$$
$$= \sum_{m} \langle \psi | \mathbf{M}^{\tau}_{m} \mathbf{M}_{m} | \psi \rangle \implies \text{General Measurement!}$$



Idea: exploit entanglement to send more information from point A to point B that would classically be allowed

Problem: Alice has 2 classical bits of information she wants to send to Bob, but is only allowed to send Bob a single qubit. Can she do it?

Solution: Yes! Put Alice's qubit in an entangled state with Bob's! Alice acts on her qubit and then sends it to Bob -- this allows Bob to uniquely deduce Alice's 2 classical bits!

Key Points to Remember:

- An abstractly-specified system may have many possible states; only some are *distinguishable*.
- A quantum state/vector/wavefunction Ψ assigns a complex-valued *amplitude* $\Psi(s_i)$ to each distinguishable state s_i (out of some basis set)
- The probability of state s_i is $|\Psi(s_i)|^2$, the square of $\Psi(s_i)$'s length in the complex plane.
- States evolve over time via unitary (invertible, length-preserving) transformations.
- Statistical mixtures of states are represented by weighted sums of density matrices $\rho = |\Psi\rangle\langle\Psi|$.

Bibliography & acknowledgements

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