Prof. K. J. Hintz

Department of Electrical and Computer Engineering George Mason University

## Structural Descriptions

- Port Mappings Can Be Specified Two Ways
  - Positional association
    - » Order is important
  - Named association
    - » For connecting some signals
    - » Easier to read which signals are connected to which internal signals
    - » Order is not important
  - Can only use one type of association at a time

### Structural Descriptions

- Entity Ports Declared in an Architecture Body Are Signals
  - These signals are not available outside the architecture unless connected to one of the architectures ports

### Structural Descriptions

#### Subelement Association

- Separate, actual signals can be associated with individual elements of the architecture port
- All elements of the composite port must be associated
- All associations for a particular port must be grouped together with no intervening ports among them.
- Ranges can be associated

# Design Processing

- Simulation and Synthesis Require
  - Analysis of model
    - » Performs syntax check
    - » Places entities and architectures in design library
    - » Dependency relations
      - primary units contain entity declarations
      - secondary units contain architecture bodies

## Design Processing

#### Elaboration

- » A collection of processes connected by nets
- » Entity declarations replaced by architecture bodies

### Execution

- Simulation Time Set to Zero
- Signals Assigned Initial Values
- Every Process Executed at Least Once
- Advance Simulation Clock to Next Scheduled Timeout
- Perform Transactions and Update Signals
- Resume Sensitive Processes

- Define Algorithms for Computing Values or Exhibiting Behavior
  - Type conversion
  - Define resolution functions for signals
  - Define portions of a process

- Two types
  - Procedure
  - Function
- Return Statements Allow for Different Exit Points
  - Function must always have a return statement
  - Procedure does not return a value

- Declared Variables, Constants and Files Are Local and Instantiated When Called.
  - No signals allowed

Procedure declarations can be nested

Procedures can call procedures

### Value of Subprograms

■ Write Once, Use Often

Can Be Called Recursively

Can Be Called Repeatedly From Within Scope

### Procedure Subprograms

#### Procedure

- Encapsulates a collection of sequential statements into a single statement
- Executed for their effect
- May return zero or more values
- May execute in zero or more simulation time
- Can modify a calling parameter because it is a statement and doesn't return a value

### Function Subprograms

#### Functions

- Algorithmically generates and returns only one value
  - » May be on right hand side of expression
- Must Alway returns a value
- Executes in zero simulation time
  - » i.e., cannot contain a wait statement

### Subprogram Declaration

- Names the Subprogram
- Specifies Required Parameters
- Contains the Sequential Statements
  Defining the Behavior of the Subprogram
- Defines the Return Type for Function Subprograms

### Subprogram Declaration

- Local Declarations
  - Types
  - Subtypes
  - Constants and variables
  - Nested subprogram declarations

# Procedure Syntax

```
procedure identifier
[ parameter_interface _list ] is
{ subprogram_declarative_part }
begin
{ sequential_statement }
end [ procedure ] [ identifier ] ;
```

# Procedure Syntax

parameter\_interface \_list <=</pre>

- Specifies Class of Object(s) Passed
  - Constant (assumed if mode is in)
  - Variable (assumed if mode is out)
  - Signal (passed by reference, not value)
    - » If wait statement is executed inside a procedure, the value of a signal may change before the rest of the procedure is calculated
    - » If mode **inout**, reference to both signal and driver passed

- Associates Identifier With Formal Parameter(s)
  - Allows reference to a parameter in procedure body
  - Formal parameters are replaced with actual values when called

- Specifies optional mode(s)
  - -in
    - » assumed if not specified
  - out
    - » cannot use value for computations
  - inout
    - » both read & write

- Specifies Type(s)
  - Provides error checking for type mismatches
  - Unconstrained arrays are allowed (<>)
    - » Attributes of unconstrained arrays can be used to set local constants or variables within procedures such as looping parameters

- Specifies Optional Default Value(s)
  - Values to be used if a parameter is not specified
  - If default value is desired, use keyword open for parameter
  - If default value is at end of list, can omit actual value or use open

## Procedure Example\*

```
procedure do_arith_op (
 op1, op2 : in integer ;
          : in func code ) is
 go
 variable result : integer ;
 begin
  case op is
   when add => result := op1 + op2 ;
   when subtract => result := op1-op2 ;
  end case ;
```

\*Ashenden, p 197

## Procedure Example\*

```
dest <= result after Tpd;
Z_flag <= (result = 0) after Tpd;
end procedure do_arith_op;</pre>
```

## Procedure Calling

- Once a Procedure is Declared, It Can Be Called From Other Parts of Model
- A Procedure Is a Sequential Statement, So it Can Be Called From
  - Process
  - Other subprogram body

## Procedure Calling Syntax

```
label : ] procedure_name
   [ parameter_association_list ] ;
parameter_association_list <=</pre>
 ( [ parameter_name => ] expression
     signal_name
     variable_name
     open )
   { , . . . }
```

## Procedure Calling

- Same Syntax As Ports
  - Positional association
  - Named association
  - Mix Positional and named
    - » All Positional parameters must come first

### Concurrent Procedure Calling

- A Shorthand for A Procedure Call Where Only a Concurrent Statement Would Be Allowed
- Identical Syntax to Procedure Call Statement
- Sensitive to Non-constant Parameters Passed to It

### Concurrent Procedure Example\*

```
procedure check_setup
  ( signal data, clock : in bit ;
    constant Tsu : in time ) is
begin
   if (clock'event and clock = '1') then
     assert data'last_event >= Tsu
    report "setup time violation" severity
  error ;
  end if ;
end procedure check_setup ;
```

\*Ashenden, p 208

### Concurrent Procedure Example\*

#### Formal Parameters

- data, clock, Tsu
- Actual Parameters
  - ready, phi2, Tsu\_rdy\_clk
  - Procedure is sensitive to signals ready and phi2

#### Concurrent Procedures

- Advantages
  - Easier to read programs
  - Write once, use often
  - Check timing constraints

### Concurrent Procedures

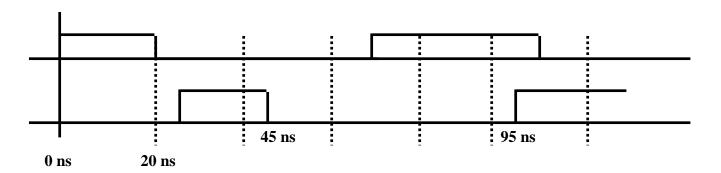
- If No in or inout Signals in Parameter List
  - No sensitivity list, hence no equivalent wait statement
  - If procedure returns, it suspends indefinitely
  - Desirable if want to execute procedure once at startup
  - If wait statements are included in procedure, then behaves like process

### Concurrent Procedure Example\*

```
procedure generate_clock
 ( signal clk : out bit ;
   constant Tperiod, Tpulse, Tphase : in time )
 is
begin
wait for Tphase ;
 loop
  clk <= '1', '0' after Tpulse ;
  wait for Tperiod ;
 end loop ;
end procedure generate_clock ;
```

\*Ashenden, p 208

### Concurrent Procedure Example\*



### Function Subprograms

- Generalized Expression
- Allows Definition of New Operators in Addition to Standard Ones (+, -, \*, etc.)
- Allows Overloading of Standard Operators
- Must Contain at Least One Return
  Statement
- [ label : ] return expression ;

# Function Syntax

```
[ pure | impure ] function identifier
[ parameter_interface_list ]
return type_mark is
{ subprogram_declarative_part }
begin
{ sequential_statement }
[ label : ] return expression ;
end [ function ] [ identifier ] ;
```

# Function Syntax

```
parameter_interface _list <=
  ( [ constant | signal ] identifier{ , . . . }:
      [ in ] subtype_indication [ := static_expression ] )
      { ; . . . }</pre>
```

### Function Example\*

```
function byte_to_int ( byte : word_8 )
  return integer is
   variable result : integer := 0 ;
begin
  for index in 0 to 7 loop
  result := result*2 + bit'pos(byte (index) ) ;
end loop ;
  return result ;
end function byte_to_int ;
```

\*Ashenden, VHDL Cookbook

- Specifies Class of Object(s) Passed
  - Constant (assumed)
  - Variable class is NOT allowed since the result of operations could be different when different instantiations are executed
  - Signal (passed by reference, not value)

- Associates Identifier With Formal Parameter(s)
  - Allows reference to a parameter in procedure body
  - Formal parameters are replaced with actual values when called
- Specifies Type of Return Value

- Optionally Specifies mode
  - in is the ONLY allowed mode
- Specifies Type(s)
  - Provides error checking for type mismatches
  - Unconstrained arrays are allowed (<>)
    - » Attributes of unconstrained arrays can be used to set local constants or variables within procedures such as looping parameters

- Specifies Optional Default Value(s)
  - Values to be used if a parameter is not specified
  - If default value is desired, use keyword open for parameter
  - If default value is at end of list, omit actual value or open

# Function Calling

- Once Declared, Can Be Used in Any Expression
- A Function Is Not a Sequential Statement So It Is Called As Part of an Expression

### **Function Calling**

- Same Syntax As Ports
  - Positional association
  - Named association
  - Mix positional and named
    - » All positional parameters must come first

```
( [ parameter_name => ]
        expression | signal_name
        | variable_name | open
{ , . . . } )
```

#### Pure Functions

- Function Does Not Refer to Any Variables or Signals Declared by Parent
- Result of Function Only Depends on Parameters Passed to It
- Always Returns the Same Value for Same Passed Parameters
- If Not Stated Explicitly, a Function Is Assumed to Be Pure

# Impure Functions

- Can State Explicitly and Hence Use Parents' Variables and/or Signals for Function Computation
- May Not Always Return the Same Value
- e.g.,

```
Impure Function Now
     Return Delay_Length ;
```

## Overloading

- Same Operation on Different Types
- More Than One Distinct Subprogram Can Be Defined With the Same Name Where Each Has
  - Different parameter types
  - Different number of parameters
- Context and Parameter List Determine Which Subprogram Is Executed

### Overloading Example\*

\*Ashenden, p 215

### Overloading Symbols

- Predefined Arithmetic Symbols Can Also Be Overloaded
- One Could Define Mixed Type Arithmetic and Write a Function
- Overloaded Boolean Operators Are Not "Short-Circuit" Evaluated

## Overloading Symbols

■ Predefined Arithmetic Symbol Is Quoted in Function Declaration, *e.g.*,

```
function "+" (left, right : in bit_vector )
return bit_vector ...
```

# Subprogram Declaration Visibility

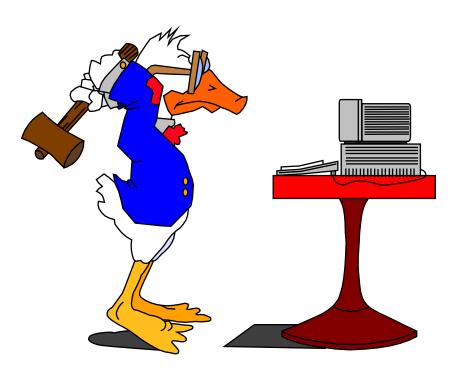
Visibility Follows Normal Scoping Rules

- All Variables Are Local and "directly visible"
  - Allows one to use function without insuring variable name has not been used before

### Visibility of Non-Local Variables

- Explicit reference can be made to non-local variables
  - "visible by selection"
  - prepend variable with name of procedure, e.g.,p1.v
  - as opposed to directly visible local variable

#### End of Lecture



- Structural Model
- Procedures
- Functions
- Overloading