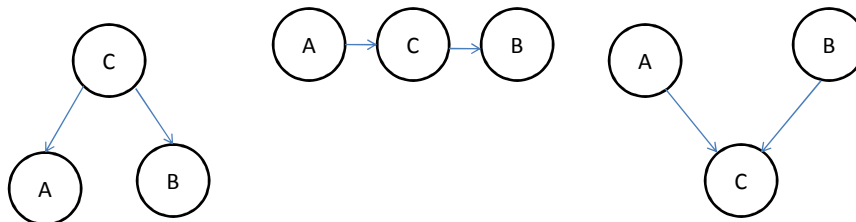


More on conditional independence and “Markov blankets”

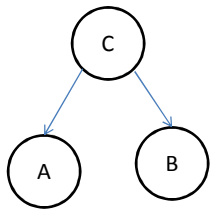
(from C. Bishop, Pattern Recognition and Machine Learning , Ch. 8)

- A random variable A is conditionally independent of a random variable B iff $p(A,B) = p(A)p(B)$
- A random variable A is conditionally independent of a random variable B given a third random variable C iff $p(A,B|C) = p(A|C)p(B|C)$

Consider three Bayesian networks:



When is A conditionally independent of B , not given C?
 When is A conditionally independent of B, given C?



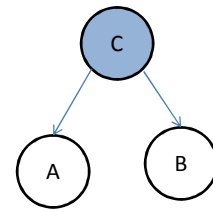
(1) C is not given (observed)

$$p(A, B, C) = p(A|C)p(B|C)p(C)$$

$$p(A, B) = \sum_C p(A|C)p(B|C)p(C)$$

$$\neq p(A)p(B)$$

In this case, A and B are **conditionally dependent.**



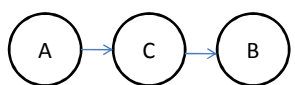
(2) C is given (observed)

$$p(A, B|C) = \frac{p(A, B, C)}{p(C)}$$

$$= p(A|C)p(B|C)$$

In this case, A and B are **conditionally independent.**

C is “tail to tail” with respect to the path between A and B .
 A and B are conditionally dependent, unless C is observed, which “blocks” the path from A to B and they become conditionally independent, given C .



(1) C is not given (observed)

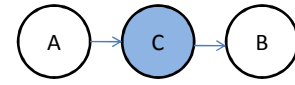
$$p(A, B, C) = p(A)p(C|A)p(B|C)$$

$$p(A, B) = p(A) \sum_C p(C|A)p(B|C)$$

$$= p(A)p(B|A)$$

$$\neq p(A)p(B)$$

In this case, A and B are **conditionally dependent.**



(2) C is given (observed)

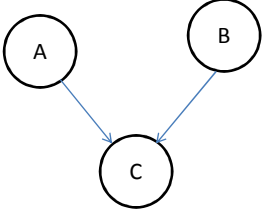
$$p(A, B|C) = \frac{p(A, B, C)}{p(C)}$$

$$= \frac{p(A)p(C|A)p(B|C)}{p(C)}$$

$$= p(A|C)p(B|C)$$

In this case, A and B are **conditionally independent.**

C is “head to tail” with respect to the path between A and B .
 A and B are conditionally dependent, unless C is observed, which “blocks” the path from A to B and they become conditionally independent, given C .



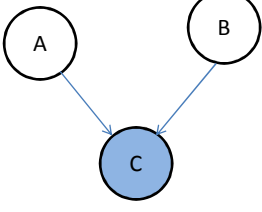
(1) C is not given (observed)

$$p(A, B, C) = p(A)p(B)p(C|A, B)$$

$$p(A, B) = p(A)p(B) \sum_C p(C|A, B)$$

$$= p(A)p(B)$$

In this case, A and B are **conditionally independent**.



(2) C is given (observed)

$$p(A, B|C) = \frac{p(A, B, C)}{p(C)}$$

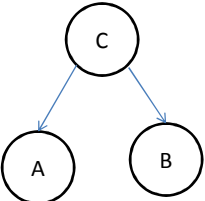
$$= \frac{p(A)p(B)p(C|A, B)}{p(C)}$$

$$\neq p(A|C)p(B|C)$$

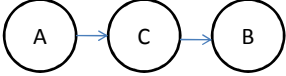
In this case, A and B are **conditionally dependent**.

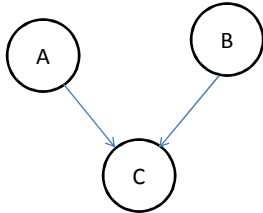
C is “head to head” with respect to the path between A and B .
 A and B are conditionally independent, unless C is observed, which “unblocks” the path from A to B and they become conditionally dependent.

Summary



C tail-to-tail or C head-to-tail: C leaves path unblocked unless C is observed, in which case it blocks path





C head-to-head: C blocks path unless C is observed, in which case it unblocks path

Battery
Charged 0.9 Dead 0.1

Fuel Tank
Full 0.9 Empty 0.1

```

    graph TD
      Battery((Battery)) --> FuelGauge((Fuel Gauge))
      FuelTank((Fuel Tank)) --> FuelGauge
    
```

Fuel Gauge

	Full	Empty
B, F	.8	.2
B, ¬F	.2	.8
¬ B, F	.2	.8
¬ B, ¬ F	.1	.9

1. What is probability that fuel tank is empty?
2. What is probability that fuel tank is empty given gauge
3. reads Empty?
4. What is probability that fuel tank is empty given gauge reads
5. Empty and battery is dead?

Notion of “explaining away”.

Summary

C head-to-head:
C blocks path unless C
is observed, in which case it unblocks
path

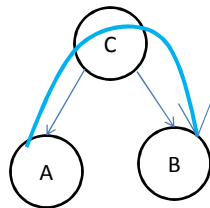
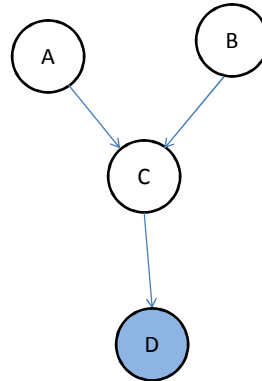
```

    graph TD
      A((A)) --> C((C))
      B((B)) --> C
      C --> D((D))
    
```

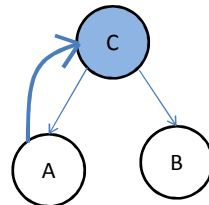
Summary

C head-to-head:

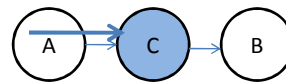
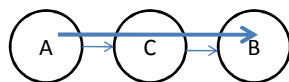
C blocks path unless *C* OR **A DESCENDANT OF *C*** is observed, in which case it unblocks path



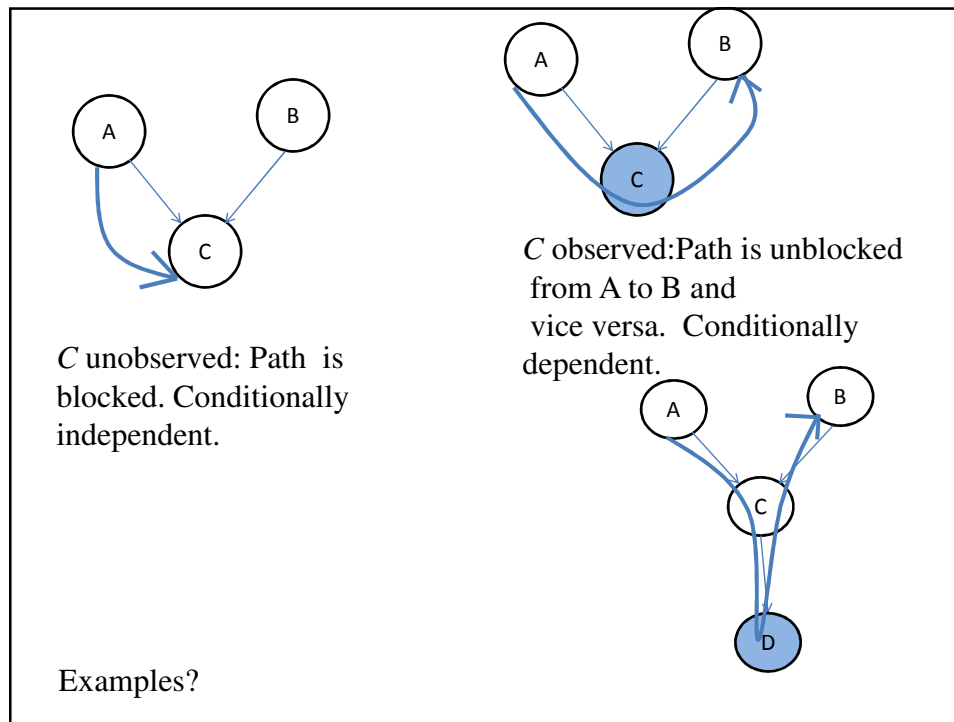
C unobserved: Path is unblocked from A to B and vice versa. Conditionally dependent.



C observed: Path is blocked. Conditionally independent



Examples?



d-separation

- *d* = “directed” — applies to directed graphs
- If all paths between node *A* and node *B* are blocked, then they are said to be **d-separated**, and are conditionally independent.

