

Knowledge Representation, Continued

- “When one encounters a new situation (or makes a substantial change in one’s view of a problem one selects from a memory structure called a ‘frame’. This is a remembered framework to be adapted to fit reality by changing details as necessary.”
- (Minsky, 1975)

Minsky, 1970s)
Frame example

From <http://www.wiziq.com/educational-tutorials/presentation/485-Introduction-to-Artificial-Intelligence>

a frame is a structured collection of data

- has slots (properties) and fillers (values)
- fillers can be links to other frames

This work led to the ideas for object-oriented programming!

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- ### Description logics (1990s, 2000s)
- Combination of semantic networks, frames, and first-order logic.
 - Allows both structured conceptual representation and logical inference methods.
 - Major current application: Language for “ontologies” for semantic web.

- E.g.,
 Bachelor = And(Unmarried, Adult, Male)
- First-order logic equivalent:
 Bachelor(x) = Unmarried(x) AND Adult(x) AND Male(x)
- DL allows direct logical operations on predicates, rather than having to first create sentences to be joined by connectives.

- DL: emphasis is on tractability of inference
- A problem instance is solved by describing it and then asking if it is subsumed by one of several possible solution categories. Need efficient algorithms for doing this.

Impossible (?) using the Syntactic Web...

- Complex queries involving **background knowledge**
 - Find information about “animals that use sonar but are neither bats nor dolphins”
- Locating information in **data repositories**
 - Travel enquiries
 - Prices of goods and services
 - Results of human genome experiments
- Finding and using “**web services**”
 - Visualise surface interactions between two proteins
- Delegating complex tasks to web “**agents**”
 - Book me a holiday next weekend somewhere warm, not too far away, and where they speak French or English

What is the Problem?

Consider a typical web page:



- Markup consists of:
- rendering information (e.g., font size and colour)
 - Hyper-links to related content
- Semantic content is accessible to humans, but not (easily) to computers... Requires (at least) NL understanding**

Solution(?): Add “Semantic Markup”

- Annotations added to web pages (and other web accessible resources)
- “Semantics” given by ontologies
 - Ontologies provide a vocabulary of terms used in annotations
 - New terms can be formed by combining existing ones
 - Meaning (*semantics*) of such terms is formally specified
 - Need to agree on a standard **web ontology language**

Structure of an Ontology

Ontologies typically have two distinct components:

- Names for important concepts in the domain
 - **Elephant** is a concept whose members are a kind of animal
 - **Herbivore** is a concept whose members are exactly those animals who eat only plants or parts of plants
 - **Adult_Elephant** is a concept whose members are exactly those elephants whose age is greater than 20 years
- Background knowledge/constraints on the domain
 - **Adult_Elephants** weigh at least 2,000 kg
 - All **Elephants** are either **African_Elephants** or **Indian_Elephants**
 - No individual can be both a **Herbivore** and a **Carnivore**

A Semantic Web — First Steps

Make web resources more accessible to automated processes

- Extend existing rendering markup with **semantic markup**
 - Metadata annotations that describe content/function of web accessible resources
- Use Ontologies to provide **vocabulary** for annotations
 - “Formal specification” is accessible to machines
- A prerequisite is a standard web ontology language
 - Need to agree common **syntax** before we can share semantics
 - Syntactic web based on **standards** such as **HTTP** and **HTML**

```
<HTML>
<HEAD>
<META HTTP-EQUIV="SHOE" CONTENT="VERSION=1.0">
<TITLE>Prof. James A. Hendler</TITLE>
</HEAD>
<BODY>
<INSTANCE KEY="http://www.cs.umd.edu/users/hendler/">
<USE-ONTOLOGY ID="cs-dept-ontology" VERSION="1.0" PREFIX="cs" URL="http://www.cs.umd.edu/projects/plus/SHOE/cs.html" />
<CATEGORY NAME="cs.Professor" FOR="http://www.cs.umd.edu/users/hendler/">
<RELATION NAME="cs.member">
<ARG POS=1 VALUE="http://www.cs.umd.edu/projects/plus/">
<ARG POS=2 VALUE="http://www.cs.umd.edu/users/hendler/">
</RELATION>
<RELATION NAME="cs.name">
<ARG POS=2 VALUE="Dr. James Hendler">
</RELATION>
<RELATION NAME="cs.doctoralDegreeFrom">
<ARG POS=1 VALUE="http://www.cs.umd.edu/users/hendler/">
<ARG POS=2 VALUE="http://www.brown.edu">
</RELATION>
<RELATION NAME="cs.emailAddress">
<ARG POS=2 VALUE="hendler@cs.umd.edu">
</RELATION>
<RELATION NAME="cs.head">
<ARG POS=1 VALUE="http://www.cs.umd.edu/projects/plus/">
<ARG POS=2 VALUE="http://www.cs.umd.edu/users/hendler/">
</RELATION>
```

[Markup demo](#)

Ontologies

- “An ontology is a document or file that formally defines the relations among terms.” (Berners-Lee et al., 2001)
- Consists of *taxonomy* and set of inference rules

Ontology examples

- <http://www.schemaweb.info/default.aspx>
- <http://ebiquity.umbc.edu/ontology/event.owl>

- What will the semantic web be good for?
- What kinds of knowledge and reasoning will be necessary?

A few other well-known knowledge representation methods

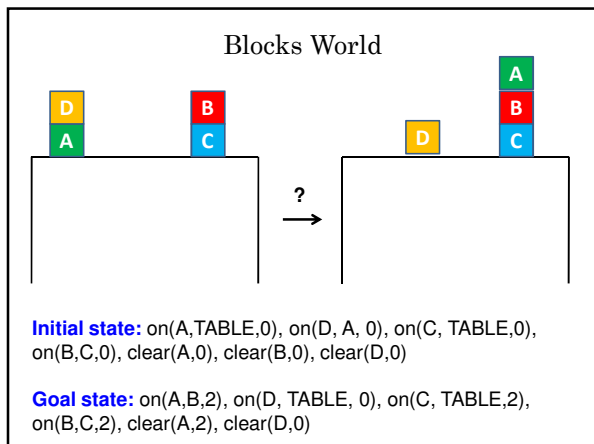
- Situation calculus
- Neural networks
- Decision trees
- Bayesian networks

Logic, Knowledge Representation, and Planning

Planning: Given a space of states and actions, find sequence of actions that allow problem solver to get from start state to goal state. (E.g., robot navigation planning.)

Approaches to planning:

- Heuristic search:
- Reinforcement learning:
- Logic



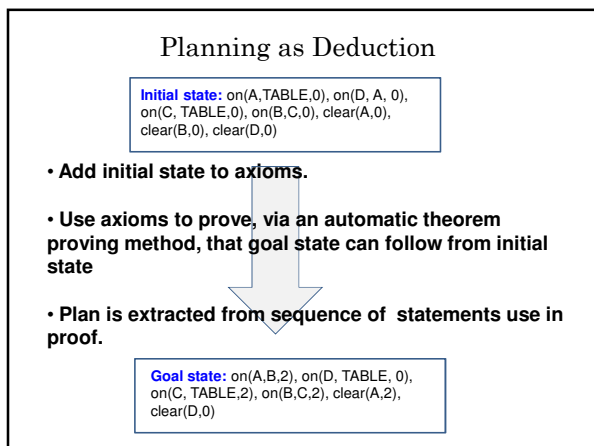
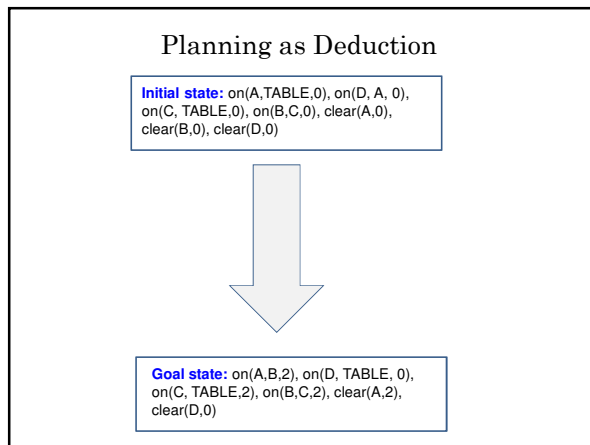
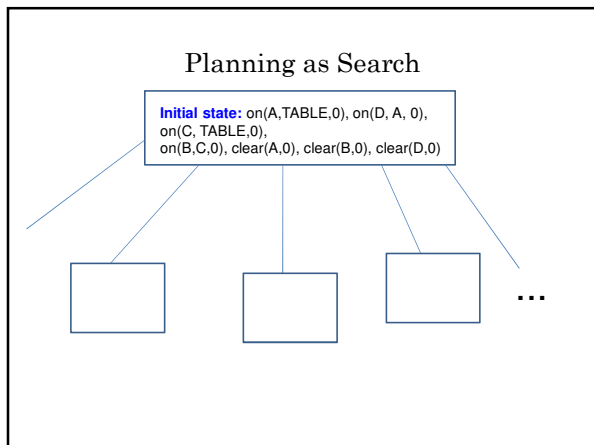
Predicates:

- $on(x, y, t)$
- $clear(x, y, t)$
- $move(x, y, z, i)$

Axioms:

- $\forall t: clear(TABLE, t)$
- $\forall x, y, z, t: on(x, y, i) \wedge clear(x, i) \wedge clear(z, i) \wedge move(x, y, z, i) \supset on(x, z, i+1) \wedge clear(y, i+1)$
- ...

“Frame” Axioms:
Describe the propositions an action does *not* affect.



Planning as Satisfiability

(Kautz & Selman, 1992)

- Encode planning problem as a conjunction of axioms plus initial state plus goal state. Expand axioms with

$$on(A, TABLE, 0) \wedge on(D, A, 0) \wedge on(C, TABLE, 0) \wedge on(B, C, 0) \wedge clear(A, 0) \wedge clear(B, 0) \wedge clear(D, 0) \wedge on(A, B, 2) \wedge on(D, TABLE, 0) \wedge on(C, TABLE, 2) \wedge on(B, C, 2) \wedge clear(A, 2) \wedge clear(D, 0) \wedge \dots$$

- Determine if this formula is satisfiable
- If so, extract plan from assignments to variables that satisfy formula
- If not, increment goal t and try again.

To convert actions to propositions:

$$\begin{aligned} \text{move}(d,a,b,1) &\Rightarrow \text{on}(d, a, 1) \wedge \text{clear}(d,1) \wedge \text{clear}(b,1) \\ &\Rightarrow \text{on}(d,b, 2) \wedge \text{clear}(a, 2) \end{aligned}$$

To convert quantified formulas as propositions:

$$\begin{aligned} \forall t: \text{clear}(\text{TABLE},t) &\rightarrow \\ \text{clear}(\text{TABLE},0) \wedge \text{clear}(\text{TABLE},1) \wedge \text{clear}(\text{TABLE},2) \end{aligned}$$

\exists : create disjunction of all possibilities

In short, formula has propositions for actions and states variables at each possible timestep