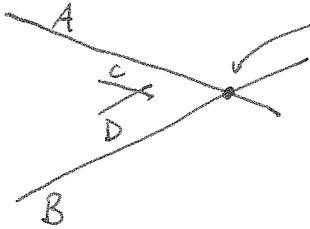


33.2-5

Left-to-right issue

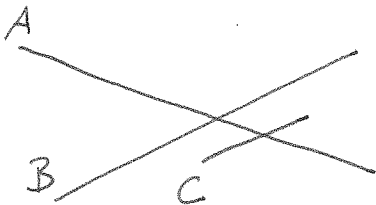


Finds the A-B intersection first, which is to the right of the C-D intersection.

All intersections issue

a) Counting: The for-loop in Any-Segments-Intersect executes  $2n$  times for  $n$  segments. Each iteration does either two intersection tests (left endpoint) or one such test (right endpoint). So  $3n$  tests in all, ~~but~~ at most  $3n$  intersections can be reported. But there can be up to  $(n^2 - n)/2$  intersections of  $n$  segments. So some must be missed.

Particular example:

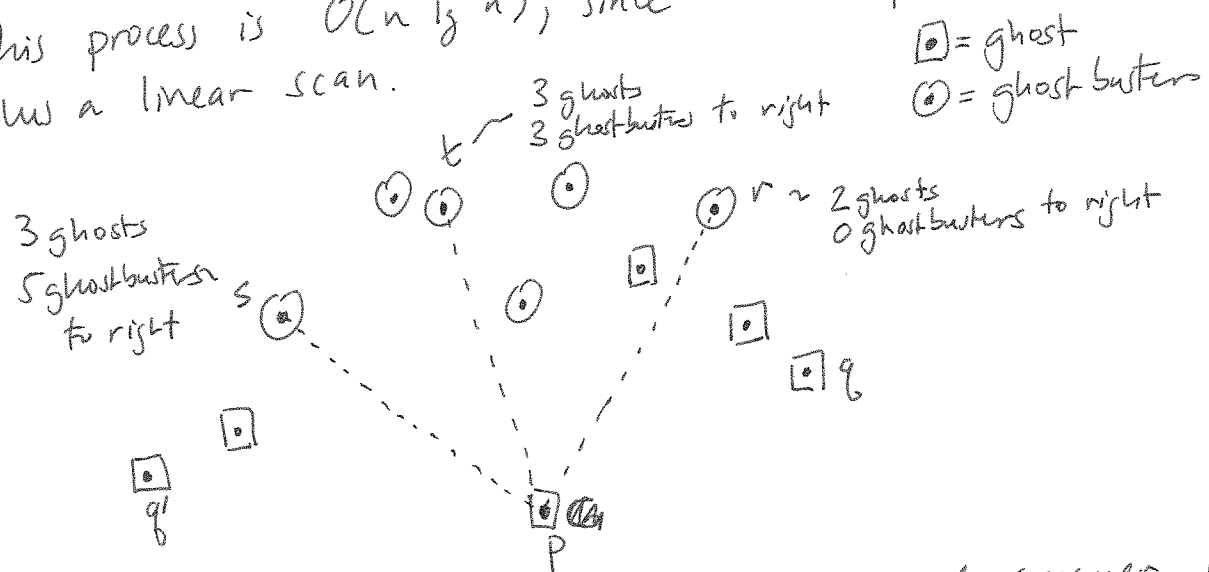


B always remains below A on the sweep line, so A and C never "see" each other to get tested for intersections.

33-3 a) Start with a point  $p$  on the convex hull (such as min  $y$  point). Assume  $p$  is a ghost. (The ghostbuster case works the same.) Sort the other points by increasing polar angle with  $p$ . Let the first point in this order be  $q$ . If  $q$  is a ghostbuster, we have the property we want: There are  $n-1$  ghosts and  $n-1$  ghostbusters to the left of the  $p-q$  line. (Same works if last point in order is a GB.)

If  $q$  is a ghost, too, then consider the line from  $p$  to  $r$ , where  $r$  is the first ghostbuster in order. There are  $0$  ghostbusters and  $c > 0$  ghosts to the right of

the p-r line (since at least q is included). So more ghosts than ghostbusters to the right. The line from p to s, where s is the last ghostbuster in polar-angle order, has n-1 ghostbusters to the right and n-1-d ghosts to the right (since the last point in order is a ghost). So more ghostbusters than ghosts. So there is some point t in between r and s where there are the same # of ghosts and ghostbusters to the right. This process is  $O(n \lg n)$ , since it is a polar-angle sort, plus a linear scan.



b) Use the previous result for divide-and-conquer. Find the partitioning line, and have the ghost shoot at the ghostbuster. Then solve left and right recursively. In the worst case, we have to repeat the process n times, because all the points land on one side of the line. So  $O(n \cdot n \lg n) = O(n^2 \lg n)$  worst case complexity.

5A. RFFT(0, 1, 2, 3)

- $y[0] = \text{RFFT}(0, 2)$ 
  - $y[0] = \text{RFFT}(0) = 0$
  - $y[1] = \text{RFFT}(2) = 2$
  - return  $(0 + 2(1), 0 - 2(1)) = (2, -2)$
- $y[1] = \text{RFFT}(1, 3)$ 
  - $y[0] = \text{RFFT}(1) = 1$
  - $y[1] = \text{RFFT}(3) = 3$
  - return  $(1 + 3(1), 1 - 3(1)) = (4, -2)$
- return  $(2 + 4, -2 + -2i, 2 - 4, -2 - 2i) = (6, -2 - 2i, -2, -2 + 2i)$

5B. We can merge the lists for different letters in a pattern. We need to offset the positions in the list for a letter by the position of the letter in the pattern.

Suppose the pattern is 'test'

So we merge

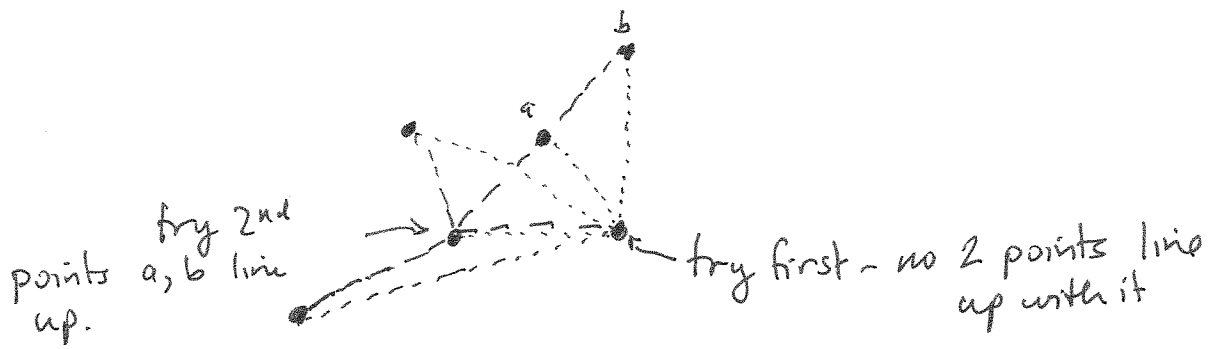
t-list (no offset) = 1, 11, 14, 16, 19	} intersect-merge = 11	pattern appears at position 11.
e-list (-1 offset) = 11, 16		
s-list (-2 offset) = 3, 5, 11		
t-list (-3 offset) = 8, 11, 13, 16		

5C. For each point, sort the other points by polar angle around that point. Go through the sorted list, and use X-product to see if the point plus any two consecutive points on the list are in a row.

$O(n \lg n)$  for the polar-angle sorting. To run through  $n$  points as the sorting origin is  $O(n^2 \lg n)$ .

SC example:

(4)



SD. The idea is to determine the Hamiltonian path by deleting edges ~~from~~ from  $G$  as long as they don't destroy the Hamiltonian path. (More accurately, we remove an edge if there is some Ham. path that doesn't use it.)

Let ~~HP~~<sup>HP</sup> be a polynomial-time algorithm that decides Ham-Path.

1. If  $HP(\langle G, v, w \rangle) = \text{false}$  return("no cycle")

2. For each edge  $e$  in  $G$   
- let  $G'$  be  $e$  with  ~~$e$~~  <sup>$e$</sup>  removed

- if  $HP(\langle G', v, w \rangle) = \text{true}$ , then  $G \leftarrow G'$

3. The edges in  $G$  form a path from  $v$  to  $w$ . The order of the nodes can be found, for example, with DFS.