

## Exercises 6

*Pages: 4.1-4.29**Instructor Name: John Lipor***Exercise 1**

Explain why items 1 and 2 are true on pg. 4.3.

**Exercise 2**

Assume you obtain  $N$  noisy measurements  $y_i = w^T x_i + n_i$ , where  $w \in \mathbb{R}^D$ ,  $x_i \in \mathbb{R}^D$  for  $i = 1, \dots, N$ , and  $n_i$  is a scalar that represents measurement noise. Define the matrix  $X$  and vector  $y$  such that finding  $w$  can be written as a least-squares problem.

**Exercise 3**

Derive the gradient equation given on pg. 4.9.

**Exercise 4**

Let  $A \in \mathbb{R}^{m \times n}$  with  $m > n$ . Name a condition on  $A$  such that the matrix  $A^T A$  is invertible. In this case, the least-squares solution is  $\hat{x} = (A^T A)^{-1} A^T y$ .

**Exercise 5**

Is the SVD applied on pg. 4.10 a full or thin SVD?

**Exercise 6**

Verify that  $\Sigma_r^{-1} U_r^T y$  gives the  $\hat{z}$  defined in Eq. (4.6).

**Exercise 7**

Why can the estimate  $\hat{x}$  be recovered as  $\hat{x} = Vz$  on pg. 4.12?

**Exercise 8**

Why do we need  $M \geq N$  for  $A \in \mathbb{R}^{M \times N}$  to have linearly independent columns?

**Exercise 9**

What size is  $V_0$  when computing the SVD of a tall, full-rank matrix  $A$ ? A tall matrix is one with more rows than columns.

**Exercise 10**

Use the properties of the pseudoinverse to show that  $A^+ = V_r \Sigma_r^{-1} U_r^T$ .

**Exercise 11**

Complete the exercise given on pg. 4.19.

**Exercise 12**

Verify that  $Ax = 0$  for  $x \in \mathcal{N}(A)$ .

**Exercise 13**

Write in words what is meant by the optimization problem given in Eq. (4.16) on pg. 4.29.

**Exercise 14**

Why is  $A^+y \in \mathcal{R}(V_r)$  on pg. 4.29?

**Exercise 15**

BV 12.1