

**CS 201**

**Signals**

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# Signals

A **signal** is a message that notifies a process that an event of some type has occurred.

Signals are the operating system abstraction for exceptions and interrupts.

- Asynchronous
- Interrupts the process like an interrupt, but via software

# Signal Concepts

## Sending a signal

- Kernel *sends* (delivers) a signal to a *destination process*.
- Kernel sends a signal for one of the following reasons:
  - Kernel has detected a system event such as divide-by-zero (SIGFPE) or the termination of a child process (SIGCHLD)
  - Another process has invoked the `kill` system call to request the kernel to send a signal to the destination process.

# Let's pause for a concrete example

A process dereferences a null pointer.

What happens at the hardware level?

You see something like: “Segmentation fault. Core dumped.” Your program terminates.

The operating system lingo for how the kernel propagates an exception to the process is, it sends the process a signal.

The process “receives” the signal.

- Usually this means the signal kills the process.

# Signal Concepts (cont)

## Receiving a signal

- A destination process *receives* a signal sent by the kernel.
- By default, most signals cause the process to terminate.
- But, there's a way a process can handle most signals. We'll see how.
- Three possible ways to react:
  - Ignore the signal (do nothing)
  - Terminate the process.
  - *Catch* the signal by executing a user-level function called a *signal handler*.
    - » Analogous to a kernel exception handler
    - » Asynchronous

A signal is *pending* if it has been sent but not yet received.

# Signals

Sent by the kernel to a process.

Different signals are identified by small integer ID's

The only information in a signal is its ID and the fact that it arrived.

A few frequently seen signals:

| ID | Name    | Default Action   | Corresponding Event                      |
|----|---------|------------------|------------------------------------------|
| 2  | SIGINT  | Terminate        | Interrupt from keyboard (ctrl-c)         |
| 9  | SIGKILL | Terminate        | Kill program (cannot override or ignore) |
| 11 | SIGSEGV | Terminate & Dump | Segmentation violation                   |
| 14 | SIGALRM | Terminate        | Timer signal                             |
| 17 | SIGCHLD | Ignore           | Child stopped or terminated              |

# Default Actions

Each signal type has a predefined *default action*, which is one of:

- The process terminates
- The process terminates and dumps core.
- The process stops until restarted by a SIGCONT signal.
- The process ignores the signal.

# Putting it all together

**Remember *exceptions*? An exception is an event that alters the flow of control at the hardware level.**

- Control goes to the kernel, via an interrupt vector.
- The kernel has a handler for each kind of event.
- Usually this detour of control is invisible to the user process.

**For some events, particularly faults, the kernel handles the event by sending a *signal* to the process.**

**Signals are the higher level, software abstraction of exceptions.**

- Alters the flow of control of a process.
- Can also have a handler (analogous to an exception handler)



# Putting it all together (continued)

Signals typically alter the flow of control at the user level.

- By default, most signals (but not all) terminate the process.
- Can send control to a *signal handler* in the user program.

# Installing Signal Handlers

The `signal` function modifies the default action associated with the receipt of signal `signum`:

```
handler_t *signal(int signum, handler_t *handler);
```

Different values for `handler`:

- `SIG_IGN`: ignore signals of type `signum`
- `SIG_DFL`: revert to the default action for signals of type `signum`.
  - Yes, this is weird, but you can assign these integer values to a pointer.
- Otherwise, `handler` is the address of a *signal handler*

# Signal Handling Example

```
void sigint_handler(int sig)
{
    printf("Process %d received signal %d\n",
           getpid(), sig);
    exit(0);
}

main()
{
    . . . // Do stuff
    signal(SIGINT, sigint_handler);
    . . . // Do more stuff
}
```

What exactly happens when signal is called from main?  
What will happen when the user hits Control-C?

# Signal Handlers

A signal handler is a function you write, to handle a signal.

- Called when process receives signal of type `signum`
- Referred to as “*installing*” the handler.
- Executing handler is called “*catching*” or “*handling*” the signal.

When a signal is received, control is diverted to the handler.

When the handler returns, control passes back to:

- In some cases, the next instruction.
- In some cases, the instruction that was interrupted by an exception.

# **wait: Synchronizing with children**

```
int wait(int *child_status)
```

- What does the `wait` system call actually do?
- What is the default action of `SIGCHLD`?
- What does a `SIGCHLD` signal do if you have called `wait`?
- What does it do if you haven't called `wait`?
- Can you catch a `SIGCHLD` signal with a handler?
- What happens if you fork a child, the child exits, you don't have a `SIGCHLD` handler, and you never call `wait`?

# Exercise

**Write a small program that installs a handler for the SIGSEGV signal, and then accesses an illegal memory address in order to execute the handler.**

# Sending Signals with `kill` Program

`kill` program sends arbitrary signal to a process or process group

## Examples

- `kill -9 24818`
  - Send SIGKILL to process 24818
- `kill -9 -24817`
  - Send SIGKILL to every process in process group 24817.

```
linux> ./forks 16
linux> Child1: pid=24818 pgrp=24817
Child2: pid=24819 pgrp=24817
```

```
linux> ps
  PID TTY          TIME CMD
24788 pts/2        00:00:00 tcsh
24818 pts/2        00:00:02 forks
24819 pts/2        00:00:02 forks
24820 pts/2        00:00:00 ps
```

```
linux> kill -9 -24817
```

```
linux> ps
  PID TTY          TIME CMD
24788 pts/2        00:00:00 tcsh
24823 pts/2        00:00:00 ps
linux>
```

# Other useful system calls

```
#include <sys/types.h>
#include <signal.h>
int kill(pid_t pid, int sig);
```

- Sends signal *sig* to process *pid*
- Although the name is 'kill,' it can be used for communication
  - The recipient process can catch the signal if not SIGKILL
  - Synchronization between processes



# Other useful system calls

```
#include <sys/types.h>
#include <sys/wait.h>
pid_t waitpid(pid_t pid, int *status,
    int options);
```

- A newer, more versatile form of *wait*
- Can wait on a particular pid, a process group, or all child processes
- Options:
  - WNOHANG: Return immediately if no child has exited (and if a child has exited, return the pid)
  - WUNTRACED: Also return for children which are stopped but not traced.

# Other useful system calls

```
#include <unistd.h>
```

```
unsigned int alarm(unsigned int seconds);
```

- Sends signal *SIGALRM* to this process after *seconds*
- What is the default action for SIGALRM?

# Sending Signals with kill Function

```
void fork12()
{
    pid_t pid[N];
    int i, child_status;
    for (i = 0; i < N; i++)
        if ((pid[i] = fork()) == 0)
            while(1); /* Child infinite loop */

    /* Parent terminates the child processes */
    for (i = 0; i < N; i++) {
        printf("Killing process %d\n", pid[i]);
        kill(pid[i], SIGINT);
    }

    /* Parent reaps terminated children */
    for (i = 0; i < N; i++) {
        pid_t wpid = wait(&child_status);
    }
}
```

# What does this program do?

```
#include <unistd.h>

main()
{
    int i;
    int j = alarm(6);

    while(1);
    printf("exiting\n");
    exit(0);
}
```

# A Program That Reacts to Internally Generated Events

```
#include <stdio.h>
#include <signal.h>

int beeps = 0;

/* SIGALRM handler */
void handler(int sig) {
    printf("BEEP\n");
    fflush(stdout);

    if (++beeps < 5)
        alarm(1);
    else {
        printf("BOOM!\n");
        exit(0);
    }
}
```

```
main() {
    signal(SIGALRM, handler);
    alarm(1); /* send SIGALRM in
               1 second */

    while (1) {
        /* handler returns here */
    }
}
```

**What does this program do?**

**Signals do not interrupt a handler for the same signal**

**While handling a signal, that signal is *blocked*.**

**That is one way that signals get to be pending.**

**When the handler returns, then the blocked signal can be received.**

# Signals do not have queues

Just one bit for each pending signal type

What happens if many signals arrive at once?

- The process is handling the first one
- The second one is *pending*
- Other signals may be lost

```

int ccount = 0;
void child_handler(int sig)
{
    int child_status;
    pid_t pid = wait(&child_status);
    ccount--;
    printf("Received signal %d from process %d\n", sig, pid);
}

int main()
{
    pid_t pid[N];
    int i, child_status;
    ccount = N;
    signal(SIGCHLD, child_handler);
    for (i = 0; i < N; i++)
        if ((pid[i] = fork()) == 0) {
            exit(0);
        }
    while (ccount > 0)
        pause(); /* Suspend until signal occurs */
}

```



**If a process has many children and wants to reliably know when each one terminates, how do you do it?**

# Sigaction()

The newer version of *signal* with a zillion options.

Problem: different flavors of Unix have subtle variations in how they handle signals (see sec. 8.5)

- Really a problem to standardize

The POSIX solution : sigaction can specify in detail how signal handling should behave

Use sigaction to write portable signal-handling code.

On POSIX-compliant systems, signal is implemented using sigaction.

- but POSIX doesn't specify in detail how signal should behave.

# Summary

## Signals provide process-level exception handling

- Can generate signals from user programs
- Can handle them with signal handlers

## Some caveats

- Very high overhead
  - >10,000 clock cycles
  - Only use for exceptional conditions
- They don't have queues
  - Just one bit for each pending signal type