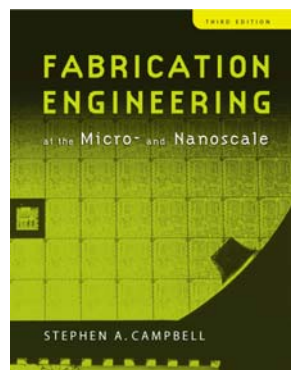


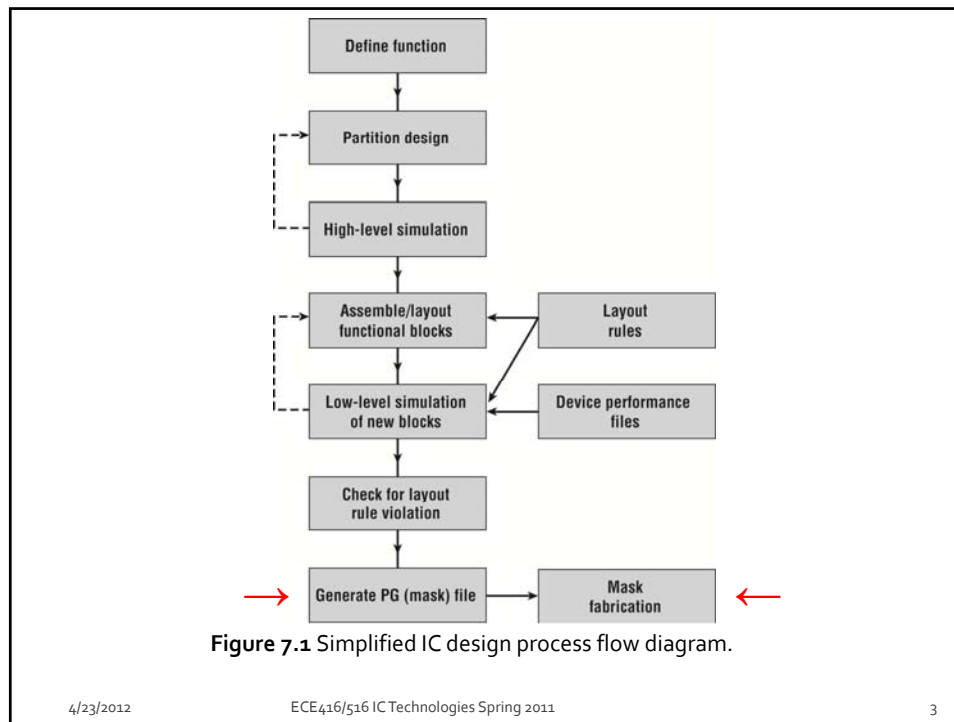
ECE 416/516 IC Technologies Lecture 7: Optical Lithography

Professor James E. Morris
Spring 2012

Chapter 7

Optical Lithography





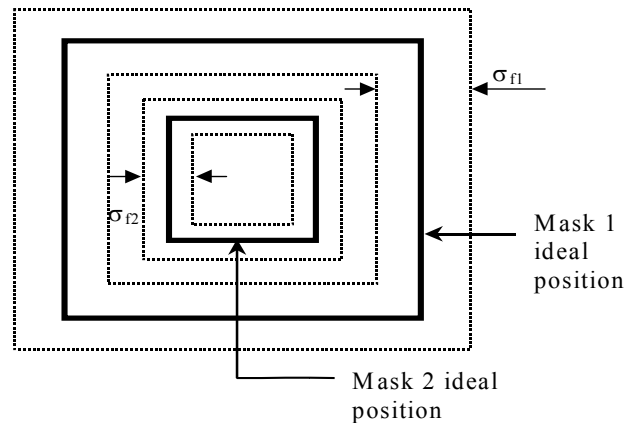
Optical Lithography

- Lecture topics:
 - A. Light sources
 - B. Wafer exposure systems
 - 1. Optics
 - 2. Projection
 - 3. Proximity/contact
 - 4. Immersion
 - C. Photoresist (also lecture 8)
 - D. Simulation
 - E. Sub-wavelength lithography
 - F. Interference effects
 - G. Minimum feature sizes
- Lecture Objectives:
 - Can calculate resolution limits and line width errors due to optical limitations
 - Can calculate PR exposure variations due to standing wave effects
- Lecture emphasis:
 - Optical Limits
 - Proximity Printing
 - Projection Printing
 - Technology Comparisons

Introduction

- Process of image transfer to wafer
 - Origin pattern drawn N x
- Images control diffusion, oxidation, & metallization sequences
 - expose parts, mask others
- "Masking levels" refer to each mask used
- Lithographic Sequence:
 1. Draw mask 100-2000x final size
 2. Photographically reduce to 10x final size (glass)
 3. Step & repeat -> [1 x final size] x [matrix of images] (glass)
 4. Spin coat substrate with photoresist
 - thickness \propto (spin rate)^{-1/2}
 5. Expose PR through mask & "develop" to dissolve unwanted PR, etc.

Masking Registration #1



Registration tolerance --> design rules

Masking Registration #2

Estimated final tolerance:

$$- T \approx 3[(\sigma_{f1}/2)^2 + (\sigma_{f2}/2)^2 + \sigma_r^2]^{1/2}$$

where σ_r is registration error

σ 's Gaussian distribution if independent

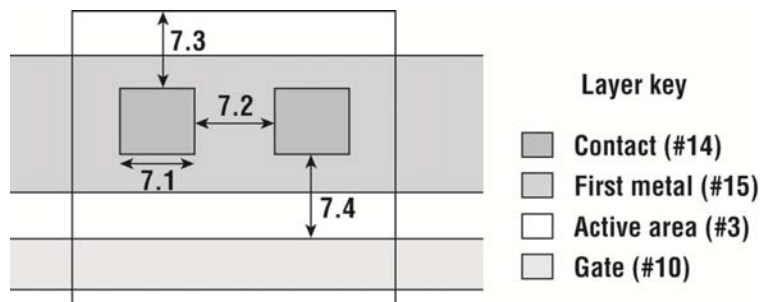
For $\sigma_{f1} \sim \sigma_{f2} \sim \sigma_r \sim \pm 0.15\mu\text{m}$

$$- T \sim 0.6 \mu\text{m}$$

- limits how densely features can be packed

Ideal feature separation mask 1 to mask 2

$$> 1/2 (\sigma_{f1} + \sigma_{f2})$$



7.1	Contact size (fixed)	1.0 μm x 1.0 μm
7.2	Minimum contact to contact space	1.2 μm
7.3	Minimum active area overlap of contact	1.2 μm
7.4	Minimum contact to gate spacing	0.8 μm
	Maximum contact to gate spacing	
	For standard device performance file	1.5 μm
	etc.	

Figure 7.2 Excerpt of typical design rule set.

This portion deals with first metal rules for a particular technology.

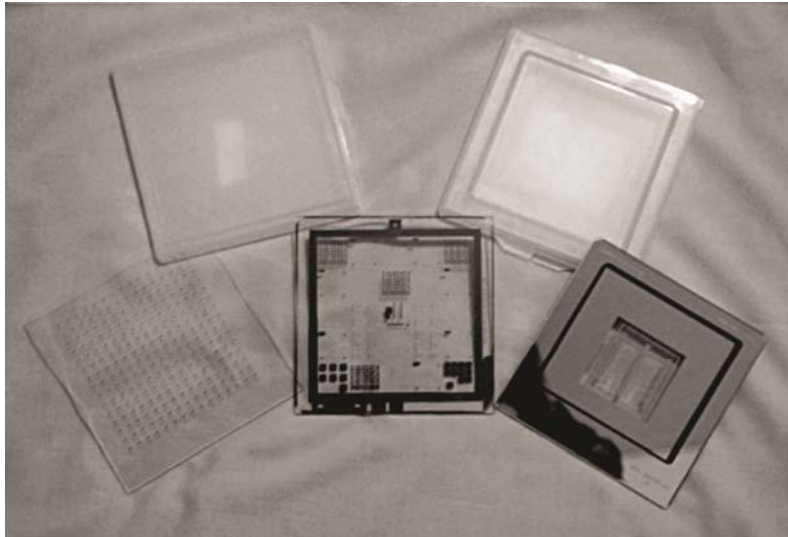


Figure 7.3 Typical photomasks including (from left) a 1' plate for contact or projection printing, a 10' plate for a reduction stepper, and a 10' plate with pellicles.

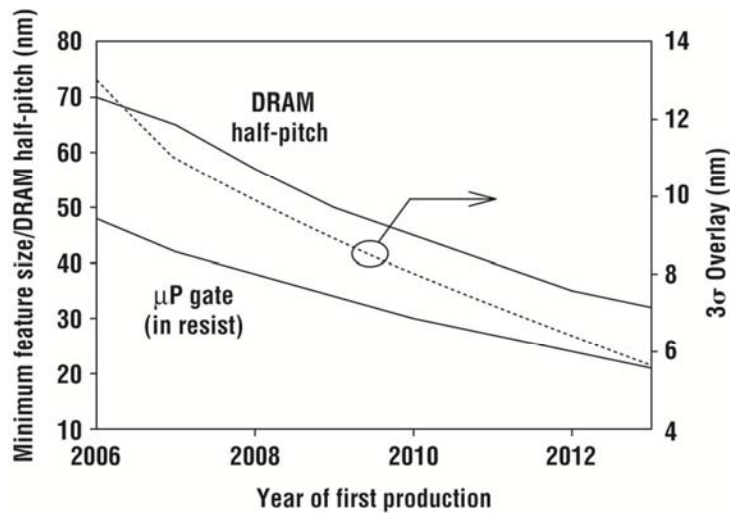


Figure 7.4 Projected lithography requirements showing overlay accuracy (right axis) and resolution requirements (left axis). Data taken from 2005 International Technology Roadmap for Semiconductors.

LITHOGRAPHY

Year of Production	1998	2000	2002	2004	2007	2010	2013	2016	2018
Technology Node (half pitch)	250 nm	180 nm	130 nm	90 nm	65 nm	45 nm	32 nm	22 nm	18 nm
MPU Printed Gate Length		100 nm	70 nm	53 nm	35 nm	25 nm	18 nm	13 nm	10 nm
DRAM Bits/ Chip (Sampling)	256M	512M	1G	4G	16G	32G	64G	128G	128G
MPU Transistors/Chip ($\times 10^6$)				550	1100	2200	4400	8800	14,000
Gate CD Control 3σ (nm)				3.3	2.2	1.6	1.16	0.8	0.6
Overlay (nm)				32	23	18	12.8	8.8	7.2
Field Size (mm)	22x32	22x32	22x32	22x32	22x32	22x32	22x32	22x32	22x32
Exposure Technology	248 nm	248 nm	248 nm + RET	193nm + RET	193nm + RET	193nm + RET + H ₂ O	193nm + RET + H ₂ O	157nm??	???
Data Volume/Mask level (GB)				216	729	1644	3700	8326	12490

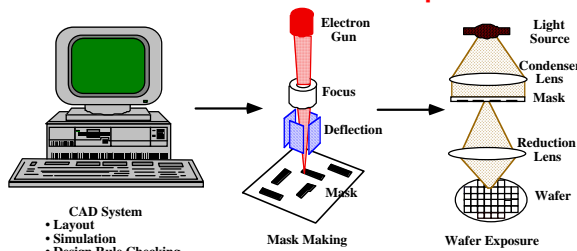
- 0.7X in linear dimension every 3 years.
- Placement accuracy $\approx 1/3$ of feature size.
- $\approx 35\%$ of wafer manufacturing costs for lithography.
- Note the **???** - single biggest uncertainty about the future of the roadmap.

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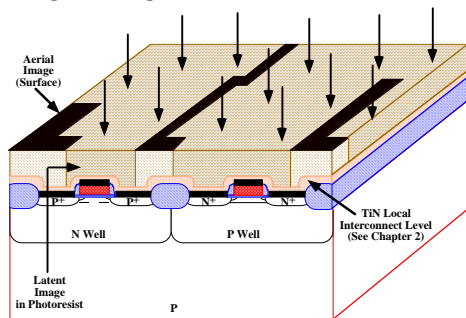
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Historical Development and Basic Concepts



- Patterning process consists of mask design, mask fabrication and wafer printing.



- It is convenient to divide the wafer printing process into three parts A: Light source, B. Wafer exposure system, C. Resist.
- **Aerial image** is the pattern of optical radiation striking the top of the resist.
- **Latent image** is the 3D replica produced by chemical processes in the resist.

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A. Light Sources

- Decreasing feature sizes require the use of shorter λ .
- Traditionally Hg vapor lamps have been used which generate many spectral lines from a high intensity plasma inside a glass lamp.
- (Electrons are excited to higher energy levels by collisions in the plasma. Photons are emitted when the energy is released.)
 - g line - $\lambda = 436 \text{ nm}$
 - i line - $\lambda = 365 \text{ nm}$ (used for $0.5 \mu\text{m}$, $0.35 \mu\text{m}$)

- Brightest sources in deep UV are excimer lasers



- KrF - $\lambda = 248 \text{ nm}$ (used for $0.25 \mu\text{m}$, $0.18 \mu\text{m}$, $0.13 \mu\text{m}$)
- ArF - $\lambda = 193 \text{ nm}$ (used for $0.13 \mu\text{m}$, $0.09 \mu\text{m}$, . . .)
- FF - $\lambda = 157 \text{ nm}$ (used for ??)

- Issues include finding suitable resists and transparent optical components at these wavelengths.

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Figure 7.13 Typical high pressure, short arc mercury lamp (courtesy Osram Sylvania).



High-T electrons \rightarrow gray body radiation, (absorbed by silica glass)

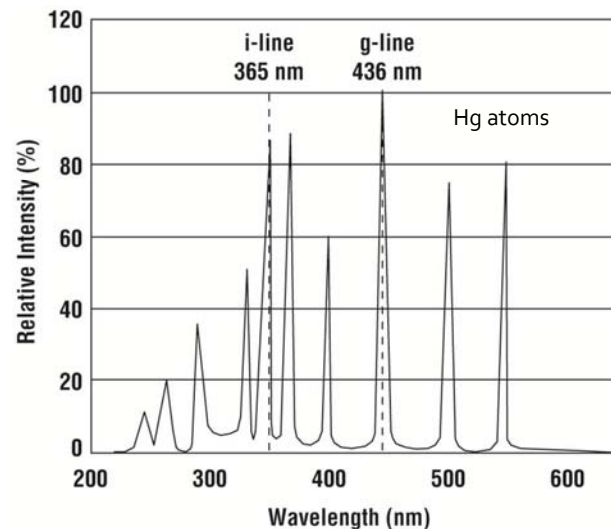
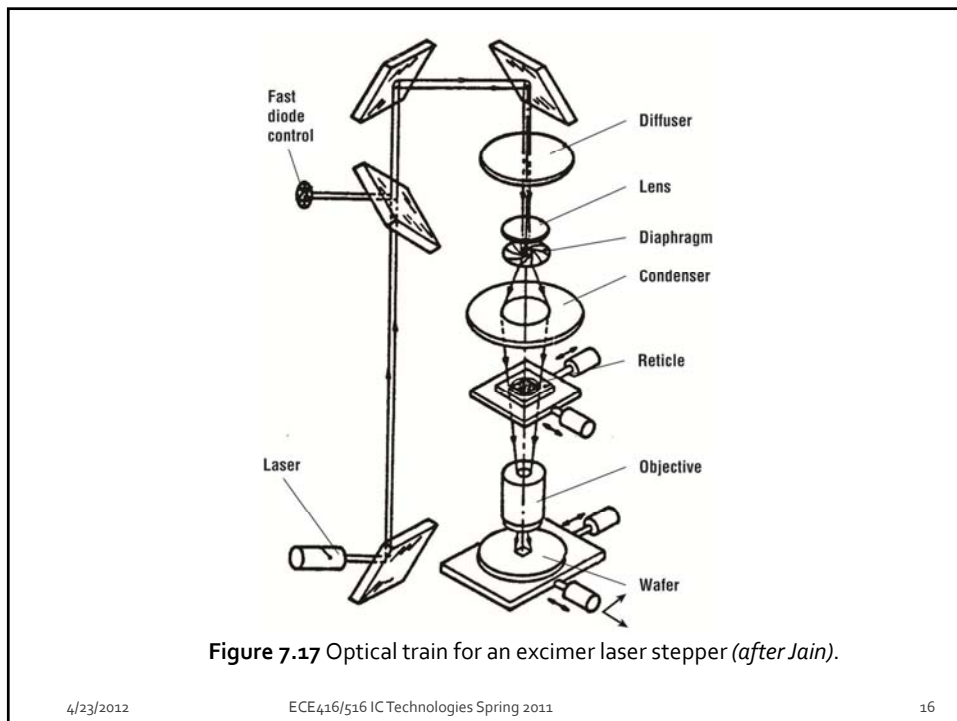
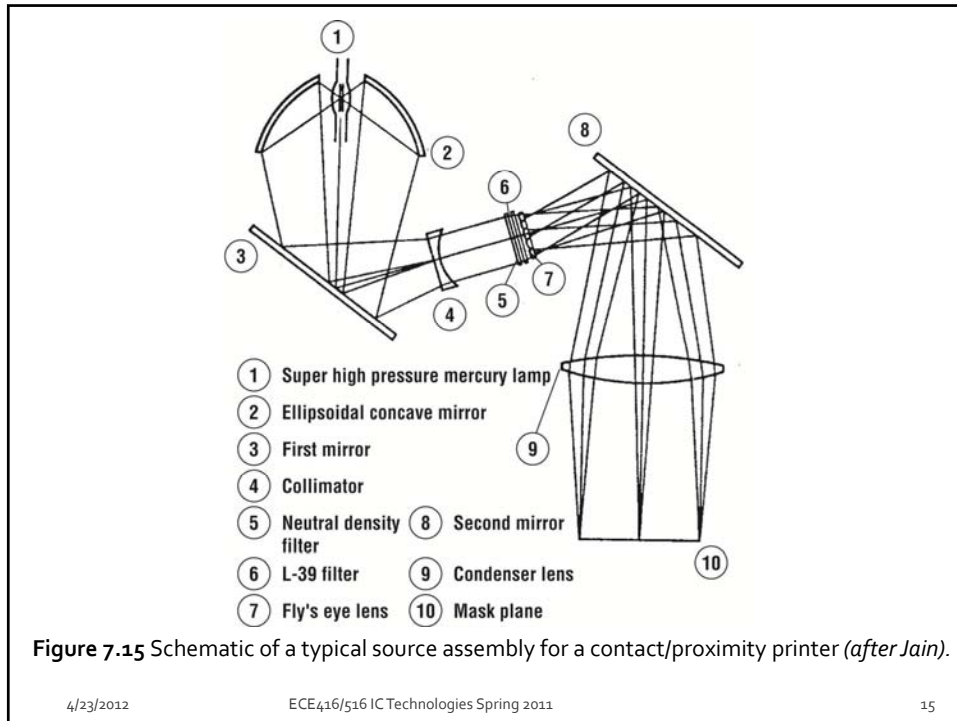


Figure 7.14 Line spectra of typical mercury arc lamp showing the positions of the two lines most commonly used in lithography.

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B. Wafer Exposure Systems

1:1 Exposure Systems

Light Source

Optical System

Mask
Photoresist
Si Wafer

Contact Printing

Gap

Proximity Printing

Usually 4X or 5X Reduction

Projection Printing

• Three types of exposure systems have been used.

- Contact printing is capable of high resolution but has unacceptable defect densities.
- Proximity printing cannot easily print features below a few μm (except for x-ray systems).
- Projection printing provides high resolution and low defect densities and \therefore dominates today.
- Typical projection systems use reduction optics (2X - 5X), step and repeat or step and scan mechanical systems, print ≈ 50 wafers/hour and cost \$10 - 25M.

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Wafer exposure systems

Contact Proximity Projection

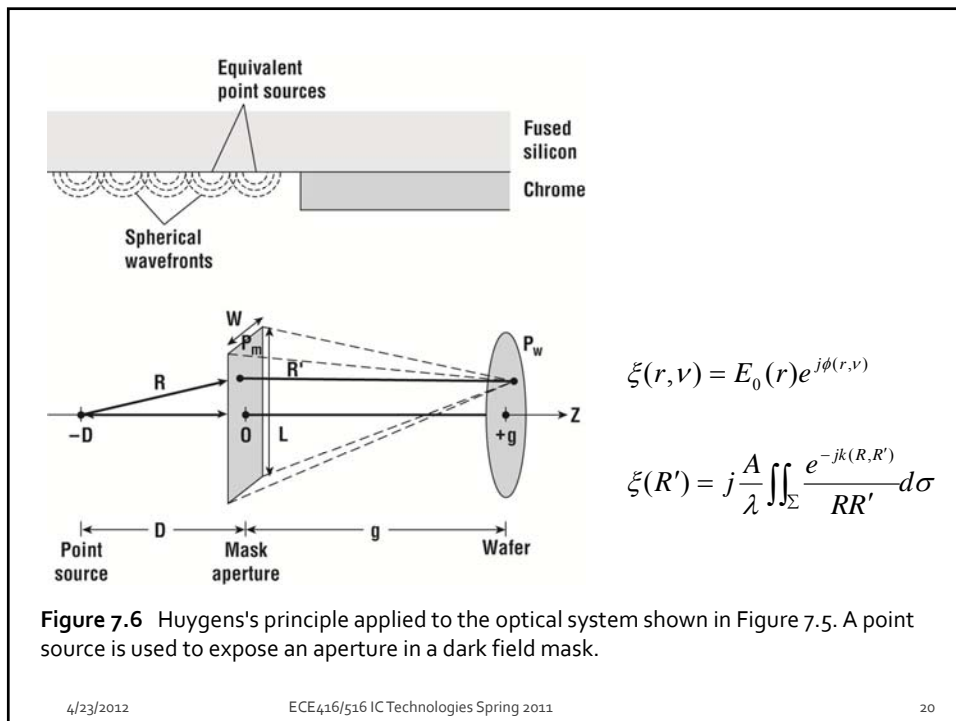
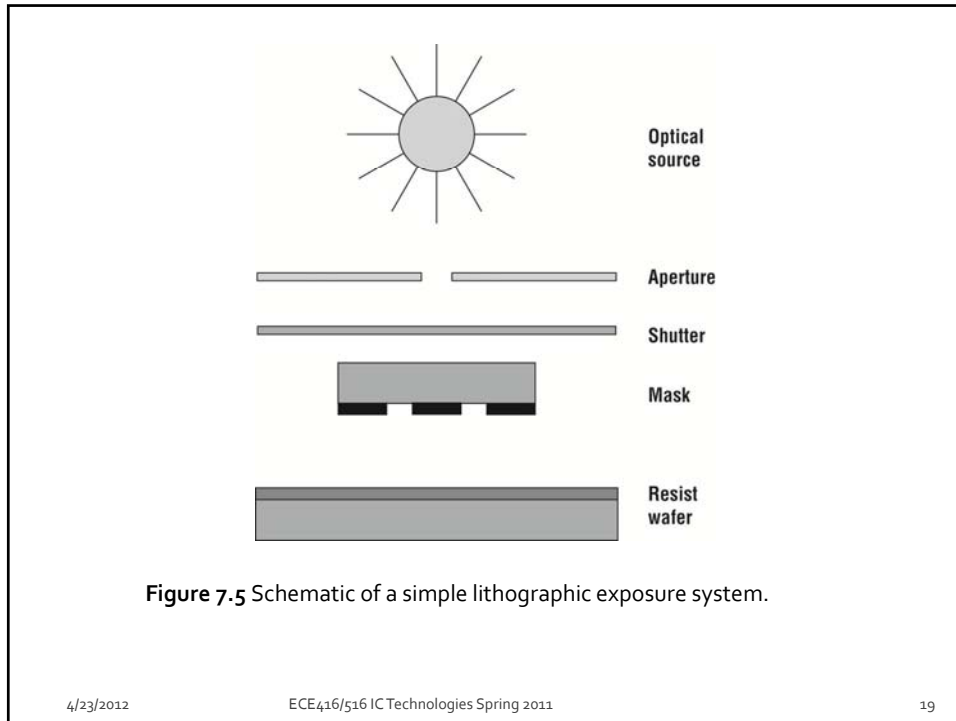
mask

PR

wafers

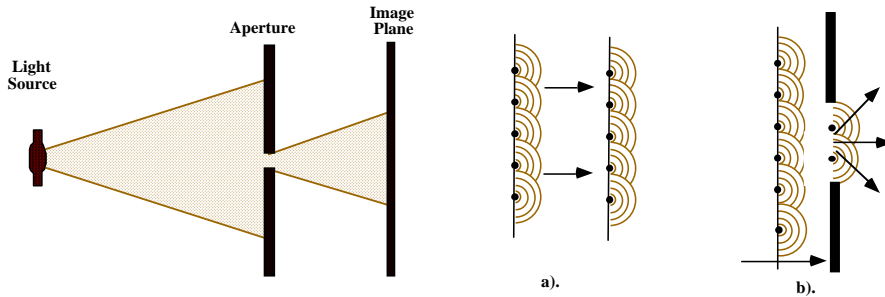
Simultaneous XY scan of mask & wafer

Usually x, y, & θ control to align mask to substrate
- alignment marks



B1. Optics - Basics and Diffraction (Huygens-Fresnel principle)

- Ray tracing (assuming light travels in straight lines) works well as long as the dimensions are large compared to λ .
- At smaller dimensions, diffraction effects dominate.



- If the aperture is on the order of λ , the light spreads out after passing through the aperture. (The smaller the aperture, the more it spreads out.)

$$(a) W, L \rightarrow \infty \quad I = \xi \xi^* = E_0 e^{j\phi} E_0 e^{-j\phi} = E_0^2$$

$$(b) W, L \rightarrow 0 \quad I = (E_1 e^{j\phi_1} + E_0 e^{j\phi_2}) (E_1 e^{-j\phi_1} + E_0 e^{-j\phi_2}) \text{ for 2 point sources}$$

$$= E_1^2 + E_0^2 + E_1 E_0 \cos(\phi_1 - \phi_2)$$

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- If we want to image the aperture on an image plane (resist), we can collect the light using a lens and focus it on the image plane.
- But the finite diameter of the lens means some information is lost (higher spatial frequency components).
- A simple example is the image formed by a small circular aperture (Airy disk).
- Note that a point image is formed only if $\lambda \rightarrow 0$, $f \rightarrow 0$ or $d \rightarrow \infty$, where f =focal length, d =focusing lens diameter

Diameter of central maximum = $1.22 \lambda f / d$

- Diffraction is usually described in terms of two limiting cases:
 - Fresnel diffraction - near field.
 - Fraunhofer diffraction - far field.

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B2
Projection
printing

If $W^2 \ll \lambda \sqrt{g^2 + r^2} \rightarrow$ Fraunhofer diffraction

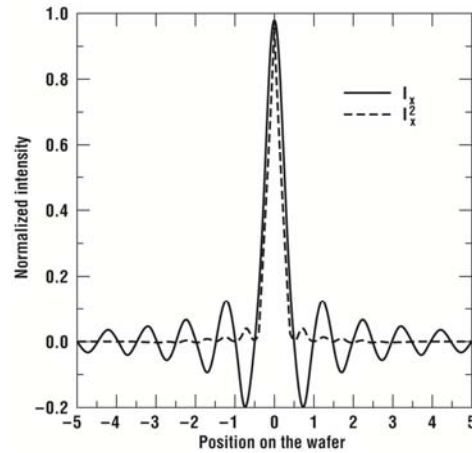


Figure 7.8 Typical far field (Fraunhofer) image.

$$I(x, y) = I_e(o) \left[\frac{(2W)(2L)}{\lambda g} \right]^2 I_x^2 I_y^2, I_x = \frac{\sin \frac{2\pi x W}{\lambda g}}{2\pi x W}, I_y = \frac{\sin \frac{2\pi y L}{\lambda g}}{2\pi y L}$$

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Projection

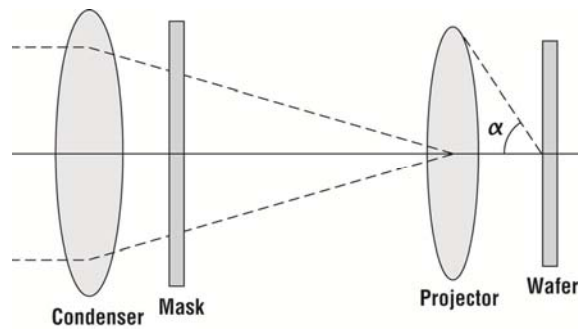


Figure 7.21 Schematic for the optical train of a simple projection printer.

$NA = n \sin \alpha$
 Refractive index $n = 1$ for air
 Rayleigh's resolution criterion $W_{\min} = k_1 \lambda / NA$

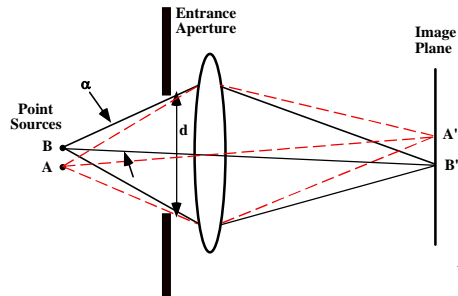
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B2. Projection Systems (Fraunhofer Diffraction)

- These are the dominant systems in use today. Performance is usually described in terms of:
 - resolution
 - depth of focus
 - field of view
 - modulation transfer function
 - alignment accuracy
 - throughput



- Consider this basic optical projection system.
- Rayleigh suggested that a reasonable criterion for resolution is that the central maximum of each point source lie at the first minimum of the Airy pattern.
- With this definition,

$$R = \frac{1.22\lambda f}{d} = \frac{1.22\lambda f}{n(2f \sin \alpha)} = \frac{0.61 \lambda}{n \sin \alpha} \quad (2)$$

- The numerical aperture of the lens is by definition, $NA \equiv n \sin \alpha$ (3)
- NA represents the ability of the lens to collect diffracted light.

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$$\therefore R = \frac{0.61 \lambda}{NA} = k_1 \frac{\lambda}{NA} \quad (4)$$

- k_1 is an experimental parameter which depends on the lithography system and resist properties ($\approx 0.4 - 0.8$).

- Obviously resolution can be increased by:

- decreasing k_1
- decreasing λ
- increasing NA (bigger lenses)

- However, higher NA lenses also decrease the depth of focus. (See next slide for derivation.)

$$DOF = \pm \frac{\lambda}{2(NA)^2} = \pm k_2 \frac{\lambda}{(NA)^2} \quad (5)$$

- k_2 is usually experimentally determined.

- Thus a 248nm (KrF) exposure system with a NA = 0.6 would have a resolution of $\approx 0.3 \mu\text{m}$ ($k_1 = 0.75$) and a DOF of $\approx \pm 0.35 \mu\text{m}$ ($k_2 = 0.5$).

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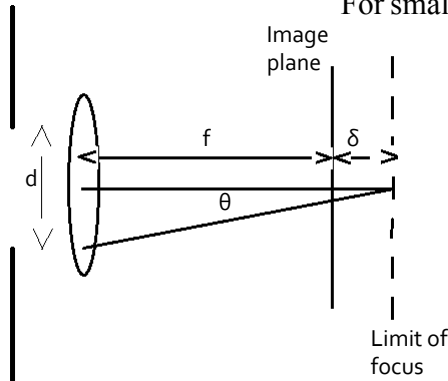
R=W_{min} & DOF=σ in Campbell
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Depth of focus

Rayleigh criterion for DOF: $\delta - \delta \cos \theta \leq \lambda / 4$

Entrance aperture



For small θ : $\frac{\lambda}{4} = \delta \left[1 - \left(1 - \frac{\theta^2}{2} \right) \right] \approx \delta \frac{\theta^2}{2}$

$$\theta \approx \sin \theta = \frac{d/2}{f} = NA$$

$$\therefore DOF = \delta = \pm \frac{\lambda}{2(NA)^2} \rightarrow k_2 \frac{\lambda}{(NA)^2}$$

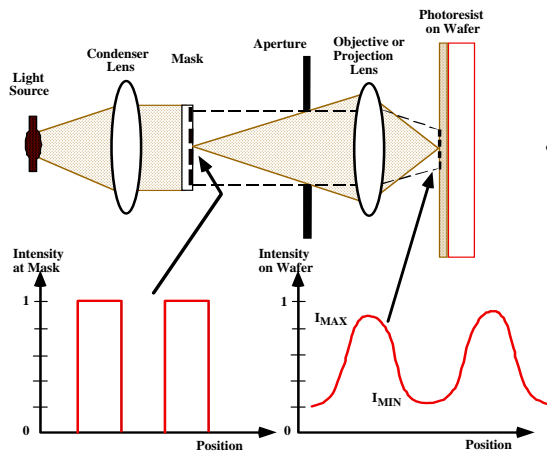
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- Another useful concept is the modulation transfer function or MTF, defined as shown below.

$$MTF = \frac{I_{MAX} - I_{MIN}}{I_{MAX} + I_{MIN}} \quad (6)$$

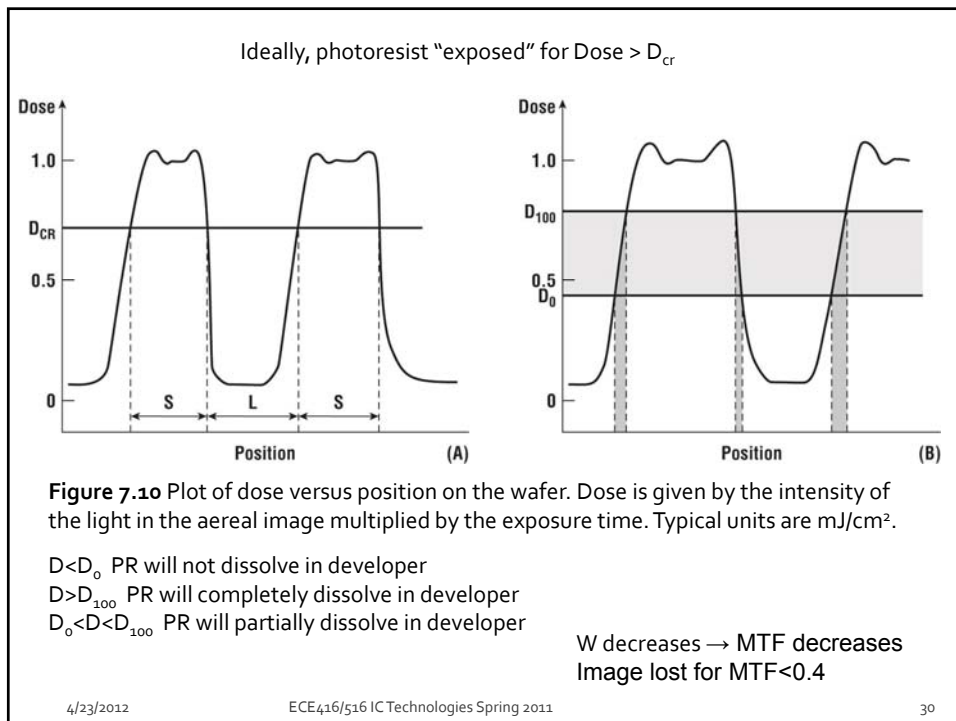
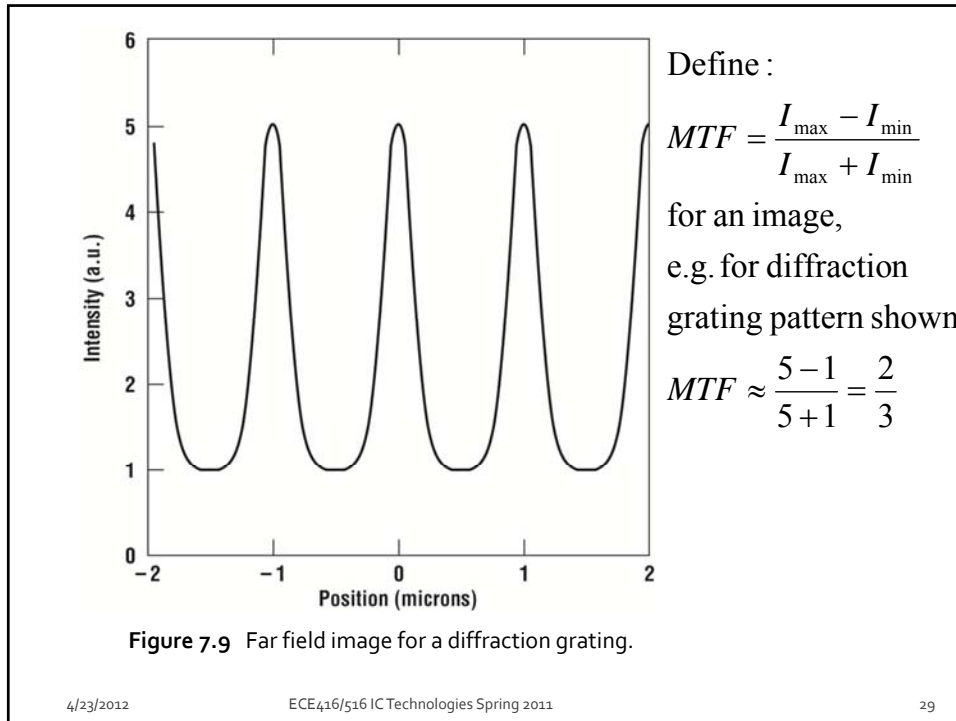


- Note that MTF will be a function of feature size

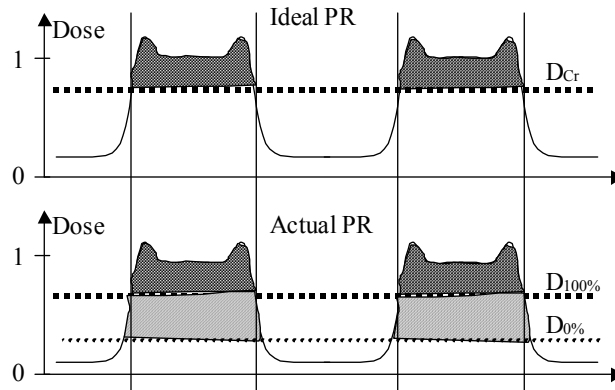
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Projection Printing Resolution #1

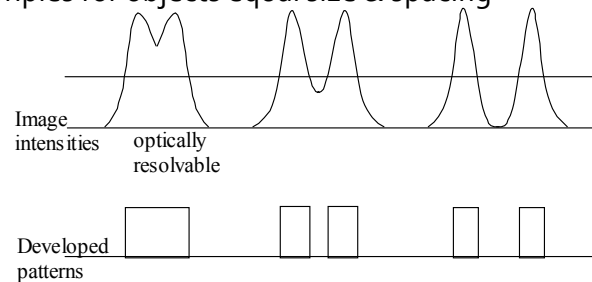


Ideal PR develops for $D > D_{cr}$ only

- Actual PR partially develops for $D_0 > D > D_{100}$
--> Partially dissolves

Projection Printing Resolution #2

- Rayleigh resolution limit:
Resolvable separation $S_r = 0.6 \lambda / NA$
- Examples for objects equal size & spacing



- Note square pattern from "sine" intensity allows optical print to finer lines than originally predicted (due to "clipping action" of non-linear PR)
- Note also coherence effects (Campbell Fig. 7.18)

- Finally, another basic concept is the spatial coherence of the light source.
- Practical light sources are not point sources.
 - ∴ the light striking the mask will not be plane waves.

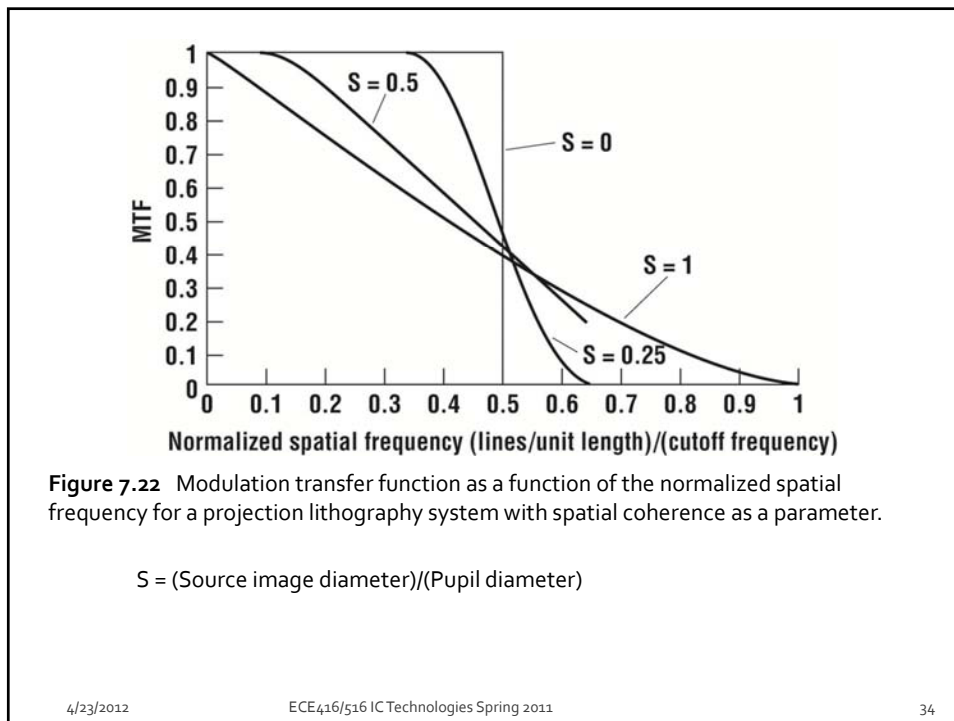
• The spatial coherence of the system is defined as $S = \frac{\text{light source diameter}}{\text{condenser lens diameter}} = \frac{s}{d}$ (7)

or often as $S = \frac{NA_{\text{condenser}}}{NA_{\text{projection optics}}}$ (8)

- Typically, $S \approx 0.5$ to 0.7 in modern systems.

[Note: Sketch MTF vs (feature size)⁻¹ and variation with S next]

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Illumination System Engineering

- Advanced optical systems using Kohler illumination and/or off axis illumination are commonly used today.
- Kohler illumination systems focus the light at the entrance pupil of the objective lens. This “captures” diffracted light equally well from all positions on the mask.
- “Off-axis illumination” also allows some of the higher order diffracted light to be captured and hence can improve resolution.

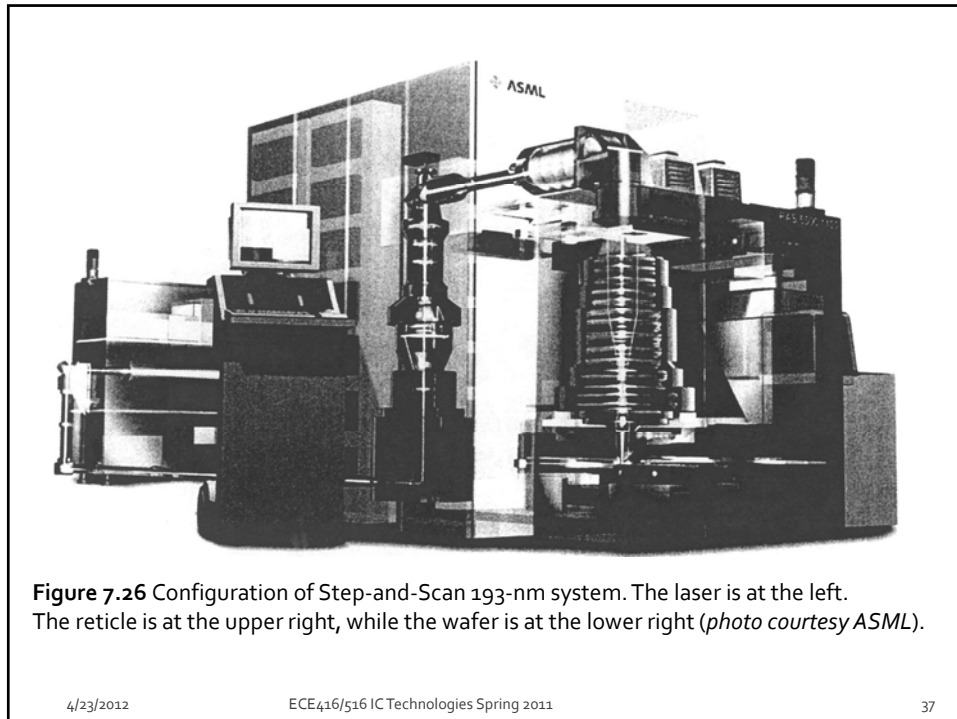
The diagrams illustrate the optical paths in different illumination systems. The top-left diagram shows a point source being collimated by a lens and focused at an aperture. The top-right diagram shows off-axis illumination where light from different mask positions is directed towards the lens, with some light being lost and some captured. The bottom-right diagram shows a similar setup with a different angle of incidence.

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The schematic shows a scanning mirror projection lithography system. A concave mirror focuses an illuminating light beam onto a convex mirror. The convex mirror reflects the beam onto a trapezoidal mirror, which then projects it onto a photomask. The photomask is scanned in a linear direction. The light then projects onto a wafer, which is also scanned in a linear direction. Labels include: Concave mirror, Illuminating light beam, SCANNING DIRECTION (LINEAR SCAN), Photomask, Convex mirror, Trapezoidal mirror, Wafer, and Illuminating light beam.

Figure 7.23 Schematic for the operation of a scanning mirror projection lithography system (courtesy of Canon U.S.A.).

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B3. Contact/proximity systems

If $W^2 \gg \lambda \sqrt{g^2 + r^2} \rightarrow$ Fresnel diffraction

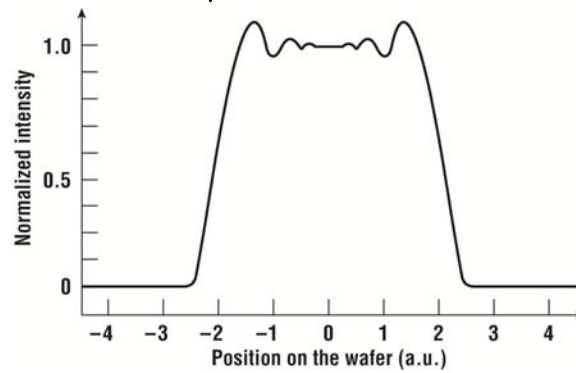


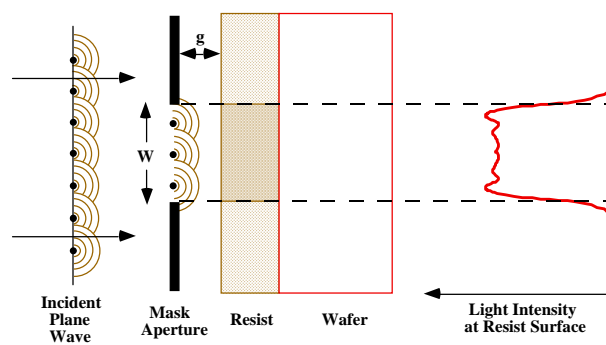
Figure 7.7 Typical near field (Fresnel) diffraction pattern.

For W very large \rightarrow ray tracing

Image width on wafer $\Delta W = W(g/D)$

B3. Contact and Proximity Systems (Fresnel Diffraction)

- Contact printing systems operate in the near field or Fresnel diffraction regime.
- There is always some gap g between the mask and resist.



- The aerial image can be constructed by imagining point sources within the aperture, each radiating spherical waves (Huygens wavelets).
- Interference effects and diffraction result in “ringing” and spreading outside the aperture.

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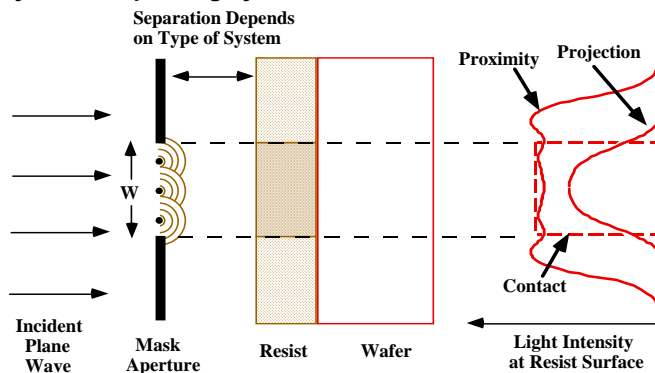
- Fresnel diffraction applies when

$$\lambda < g < \frac{W^2}{\lambda} \quad (9)$$

- Within this range, the minimum resolvable feature size is $W_{\min} \approx \sqrt{\lambda g}$ (10)

- Thus if $g = 10 \mu\text{m}$ and an i-line light source is used, $W_{\min} \approx 2 \mu\text{m}$.

- Summary of wafer printing systems:



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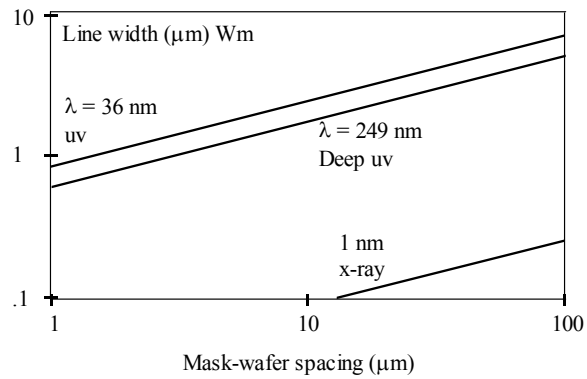
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Proximity Printing: Diffraction #1

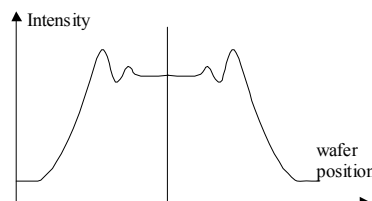
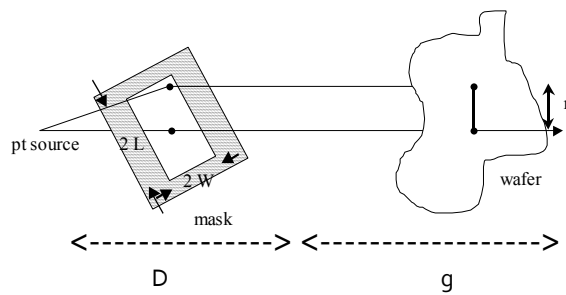
- Mask close to wafer/resist
minimize diffraction/divergence.
- Separation $\sim \mu\text{m}$ \rightarrow Fresnel (near-field) diffraction
- Minimum line width:

$$W_m = (d\lambda)^{1/2}$$

- (d = mask-wafer separation)



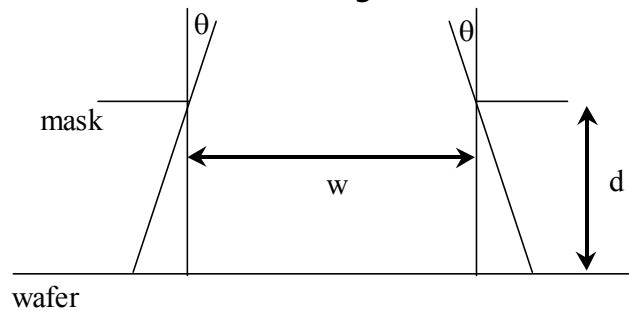
Proximity Printing: Diffraction #2



For $W^2 \gg \lambda (g^2 + r^2)^{1/2}$
 $\Delta W = W(g/D)$

Proximity Printing: Penumbra

- Penumbra effect on line width: $\Delta W = 2d \tan\theta$
where θ angle off collimation



Well collimated light minimizes penumbra.

- Well collimated light maximizes diffraction.
- $\theta \sim$ few degrees for optimum balance.

Contact exposure

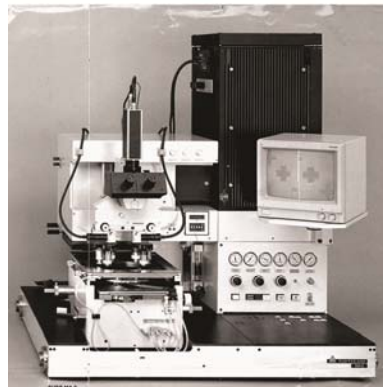
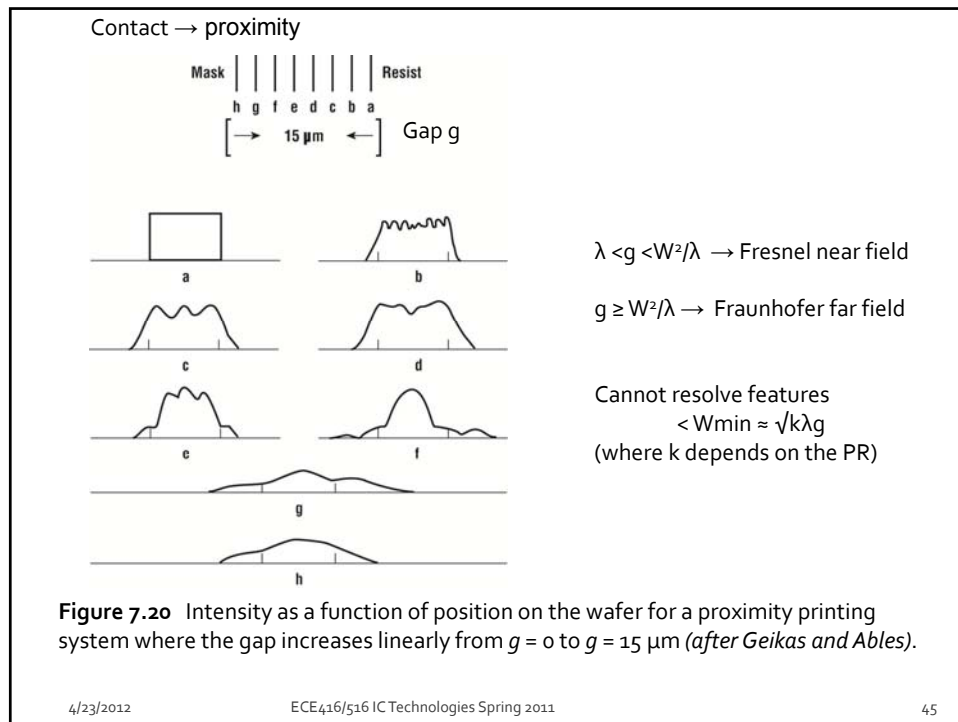


Figure 7.19 Typical contact exposure system (courtesy of Karl Suss).



Contact Printing: Dirt

Dirt can damage mask, and/or can mask exposure areas, e.g. oxide pinholes

Effect on yield:

- Total no. chips on wafer = N
- no. good chips = N_g
- no. of defects = N_d

Add another random defect -->

- probability of destroying a good chip = N_d/N

$$\therefore dN_g = -(N_d/N) dN_d$$

$$dN_g/N_g = -dN_d/N$$

$$\therefore \ln N_g = -N_d/N + \text{const}$$

$$N_g = \text{const} \times \exp - N_d/N$$

$$= N \exp - N_d/N$$

$$\text{since } N_g = N, \text{ if } N_d = 0$$

$$\therefore \text{Fractional yield } N_g/N = \exp - N_d/N \quad \rightarrow 1/e, \text{ if } N_d \sim N$$

B4. Immersion

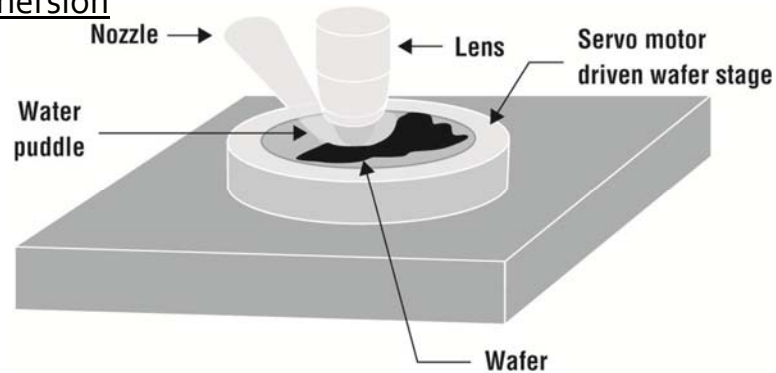


Figure 7.24 Setup of an immersion system using surface tension (from Switkes et al., reprinted from the May 2003 edition of *Microlithography World*. Copyright 2003 by PennWell.)

$$DOF = \frac{\lambda}{4n \cdot \sin^2(\theta_p / 2)} \text{ and } \frac{DOF_{n(\text{liq})}}{DOF_{n=1(\text{air})}} = \sqrt{\frac{n^2 - (\lambda / P)^2}{1 - (\lambda / P)^2}}$$

$$n = 1.43 \text{ for H}_2\text{O, and } \theta_p = \frac{\lambda}{n \cdot P} \text{ where } P = 2W \text{ for a uniform grating}$$

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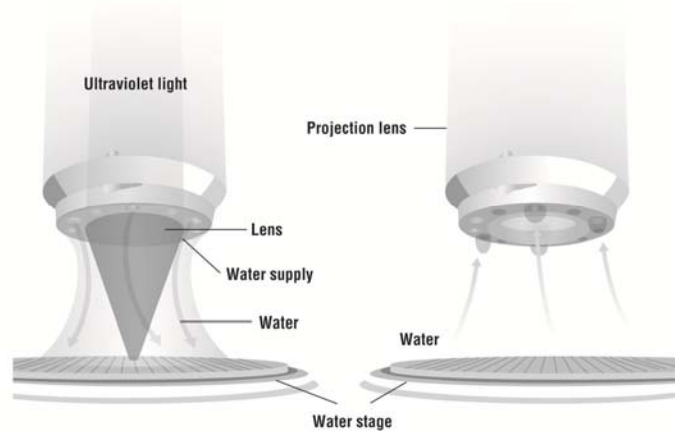


Figure 7.25 Nozzle system used by Nikon to put the water down and suction it up for each stage (from Geppert, reprinted by permission IEEE.)

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C. Optical Intensity Pattern in the Resist (Latent Image)

- The second step in lithography simulation is the calculation of the latent image in the resist.
- The light intensity during exposure in the resist is a function of time and position because of
 - Light absorption and bleaching.
 - Defocusing.
 - Standing waves.

• These are generally accounted for by modifying Eqn. (21) as follows:

$$I(x, y, z) = I_i(x, y) I_r(x, y, z) \tag{22}$$

where $I_r(x, y, z)$ models these effects.

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- Example of calculation of light intensity distribution in a photoresist layer during exposure using the ATHENA simulator. A simple structure is defined with a photoresist layer covering a silicon substrate which has two flat regions and a sloped sidewall. The simulation shows the [PAC] calculated concentration after an exposure of 200 mJ cm⁻². Lower [PAC] values correspond to more exposure. The color contours thus correspond to the integrated light intensity from the exposure.

C. Photoresist Exposure

- Neglecting standing wave effects (for the moment), the light intensity in the resist falls off as

$$\frac{dI}{dz} = -\alpha I \tag{23}$$

(The probability of absorption is proportional to the light intensity and the absorption coefficient.)

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- The absorption coefficient depends on the resist properties and on the [PAC].

$$\alpha_{\text{resist}} = Am + B \quad (24)$$

where A and B are resist parameters (first two Dill parameters) and

$$m = \frac{[\text{PAC}]}{[\text{PAC}]_0} \quad (25)$$

- m is a function of time and is given by

$$\frac{dm}{dt} = -CIm \quad C \text{ is 3rd Dill parameter} \quad (26)$$

- Substituting (24) into (23), we have:

$$\frac{dI}{dz} = -\alpha I = -(Am + B)I \quad (27)$$

- Eqns. (26) and (27) are coupled equations which are solved simultaneously by resist simulators.

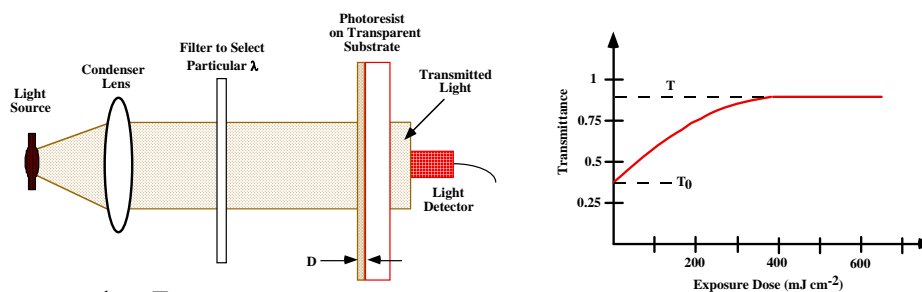
[PAC] = photoactive compound concentration

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- The Dill resist parameters (A, B and C) can be experimentally measured for a resist.



$$A = \frac{1}{D} \ln \frac{T_{\infty}}{T_0}$$

$$B = -\frac{1}{D} \ln T_{\infty}$$

$$C = \frac{A + B}{AT_0(1 - T_0)T_{12}} \frac{dT}{dE} \Big|_{E=0} \quad \text{where } T_{12} = 1 - \left(\frac{n_{\text{resist}} - 1}{n_{\text{resist}} + 1} \right)^2$$

- By measuring T₀ and T_∞, A, B and C can be extracted.

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D. Simulation

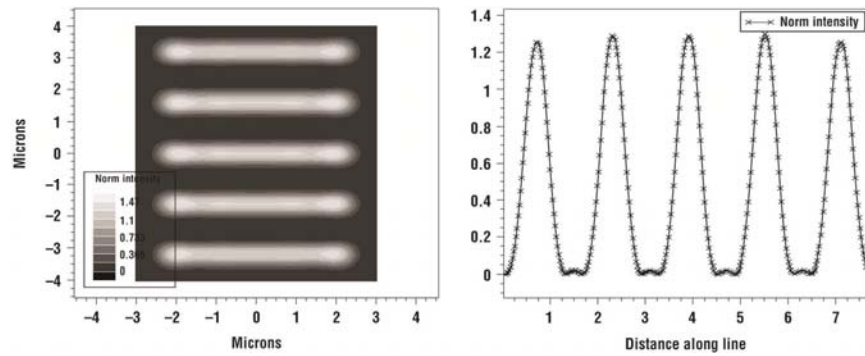


Figure 7.11 Contour plot (left) and 1D slice through the center of projected intensity as a function of position for a grating with $1.6 \mu\text{m}$ pitch, exposed at $R = 436 \text{ nm}$ and $\text{NA} = 0.43$.

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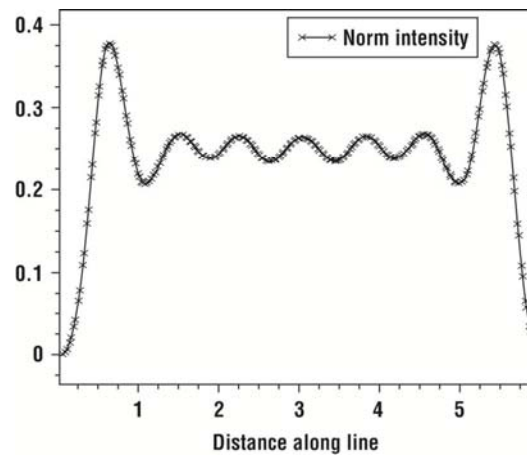


Figure 7.12 Same 1D plot for a grating with a pitch of $0.8 \mu\text{m}$ exposed on the same system.

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Models and Simulation

- Lithography simulation relies on models from two fields of science:
 - Optics to model the formation of the aerial image.
 - Chemistry to model the formation of the latent image in the resist.

A. Wafer Exposure System Models

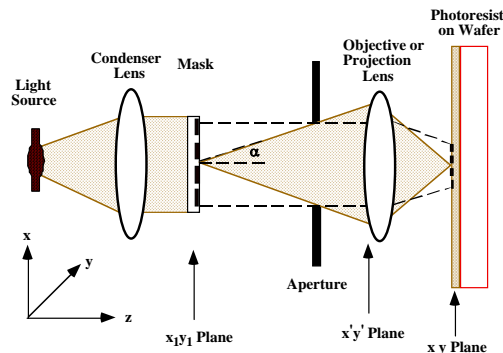
- There are several commercially available simulation tools that calculate the aerial image - PROLITH, DEPICT, ATHENA. All use similar physical models.
- We will consider only projection systems.

- Light travels as an electromagnetic wave.

$$\epsilon(P, t) = C(W) \cos(\omega t + \phi(t)) \tag{13}$$

or, in complex exponential notation,

$$\epsilon(W, t) = \text{Re} \{ U(W) e^{-j\omega t} \} \text{ where } U(W) = C(W) e^{-j\phi(P)} \tag{14}$$



- Consider a generic projection system:

- The mask is considered to have a digital transmission function:

$$t(x_1, y_1) = \begin{cases} 1 & \text{in clear areas} \\ 0 & \text{in opaque areas} \end{cases} \tag{15}$$

- After the light is diffracted, it is described by the Fraunhofer diffraction integral:

$$\epsilon(x', y') = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} t(x_1, y_1) e^{-2\pi j(f_x x + f_y y)} dx dy \tag{16}$$

where f_x and f_y are the spatial frequencies of the diffraction pattern, defined as

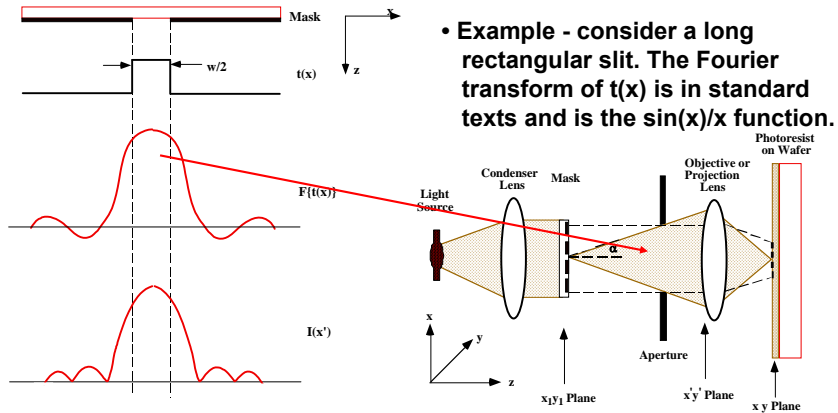
$$f_x = \frac{x'}{z\lambda} \text{ and } f_y = \frac{y'}{z\lambda}$$

- $\epsilon(x',y')$ is the Fourier transform of the mask pattern.

$$\epsilon(f_x, f_y) = F\{t(x_1, y_1)\} \quad (17)$$

- The light intensity is simply the square of the magnitude of the ϵ field, so that

$$I(f_x, f_y) = |\epsilon(f_x, f_y)|^2 = |F\{t(x_1, y_1)\}|^2 \quad (18)$$



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- But only a portion of the light is collected. This is characterized by a pupil function:
- $$P(f_x, f_y) = \begin{cases} 1 & \text{if } \sqrt{f_x^2 + f_y^2} < \frac{NA}{\lambda} \\ 0 & \text{if } \sqrt{f_x^2 + f_y^2} > \frac{NA}{\lambda} \end{cases} \quad (19)$$

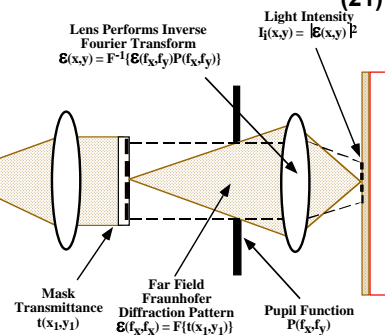
- The objective lens now performs the inverse Fourier transform.

$$\epsilon(x, y) = F^{-1}\{\epsilon(f_x, f_y)P(f_x, f_y)\} = F^{-1}\{F\{t(x_1, y_1)\}P(f_x, f_y)\} \quad (20)$$

resulting in a light intensity at the resist surface (aerial image) given by

$$I_i(x, y) = |\epsilon(x, y)|^2 \quad (21)$$

Summary: Lithography simulators perform these calculations, given a mask design and the characteristics of an optical system. These simulators are quite powerful today. Math is well understood and fast algorithms have been implemented in commercial tools. These simulators are widely used.

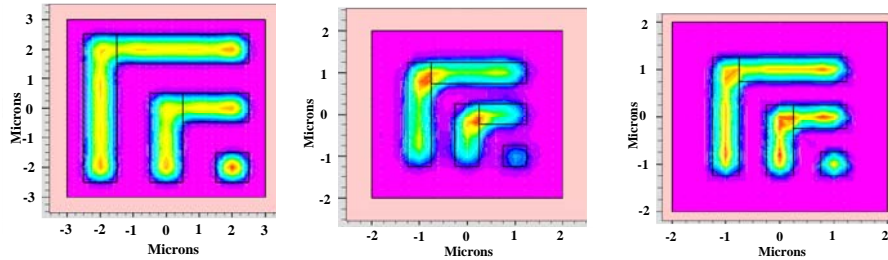


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- ATHENA simulator (Silvaco). Colors correspond to optical intensity in the aerial image.



Exposure system: NA = 0.43, partially coherent g-line illumination ($\lambda = 436 \text{ nm}$). No aberrations or defocusing. Minimum feature size is $1 \text{ }\mu\text{m}$.

Same example except that the feature size has been reduced to $0.5 \text{ }\mu\text{m}$. Note the poorer image.

Same example except that the illumination wavelength has now been changed to i-line illumination ($\lambda = 365 \text{ nm}$) and the NA has been increased to 0.5. Note the improved image.

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E. SubWavelength Lithography

- Beginning in ≈ 1998 , chip manufacturers began to manufacture chips with feature sizes smaller than the wavelength of the light used to expose the photoresist.
- This is possible because of the use of a variety of “tricks”
 - illumination system optimization
 - optical pattern correction (OPC), and
 - phase shift mask techniques.

E. Mask Engineering - OPC and Phase Shifting

- Optical Proximity Correction (OPC) can be used to compensate somewhat for diffraction effects.
- Sharp features are lost because higher spatial frequencies are lost due to diffraction. These effects can be calculated and \therefore can be compensated for.

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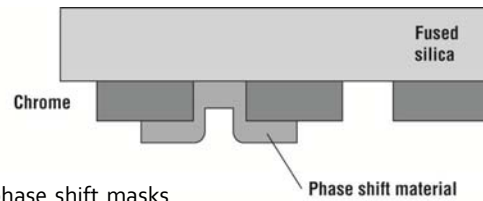


Figure 7.27 Basic concept of phase shift masks as described by Levenson *et al.* [49].

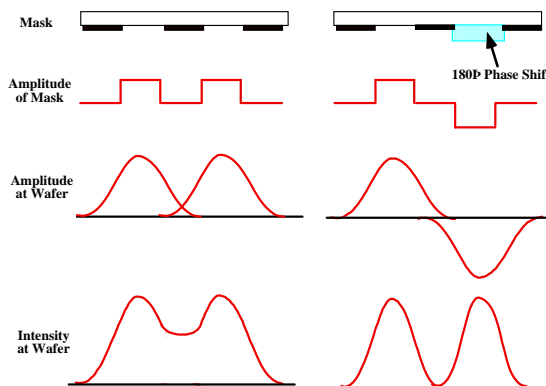
- **Creating phase shift masks involves massive numerical calculations and often the implementation involves two exposures - a binary mask and a phase shift mask - before the resist pattern is developed.**

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- **Another approach uses phase shifting to “sharpen” printed images.**

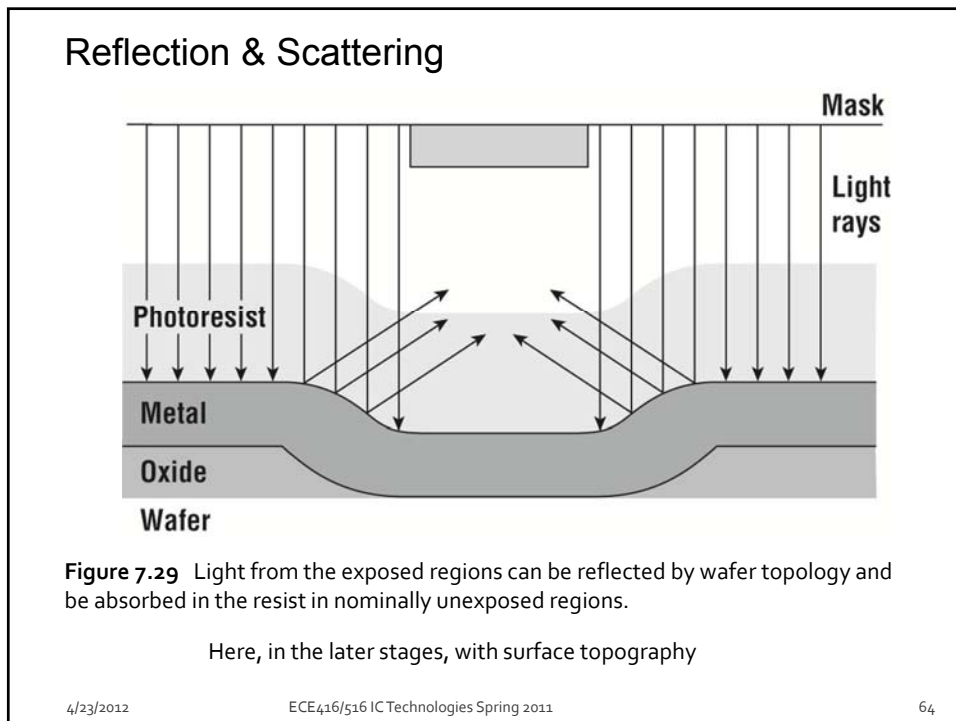


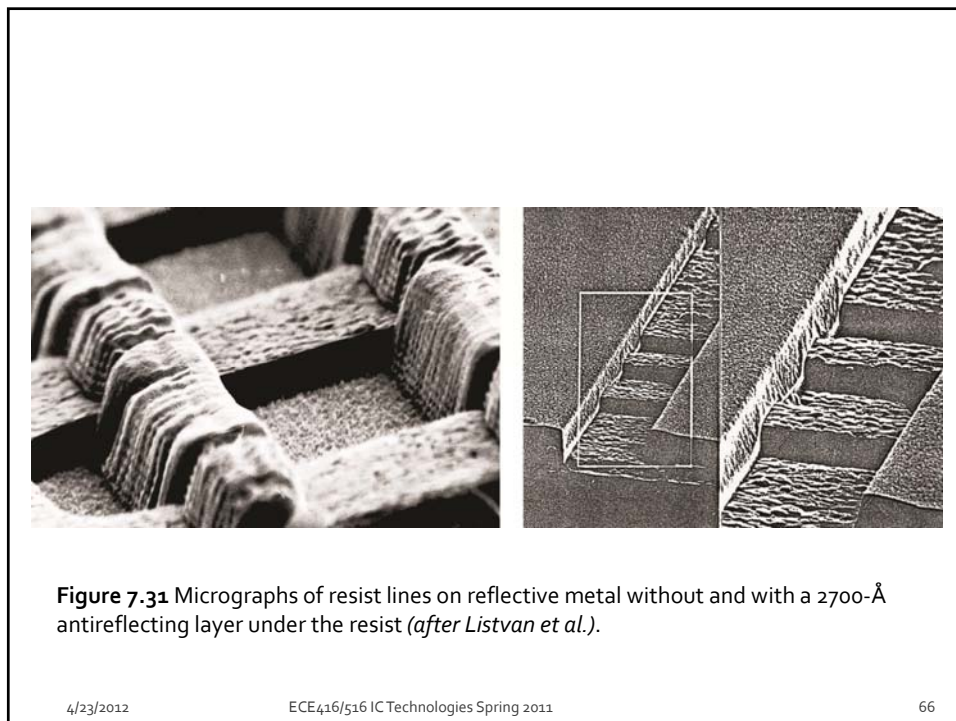
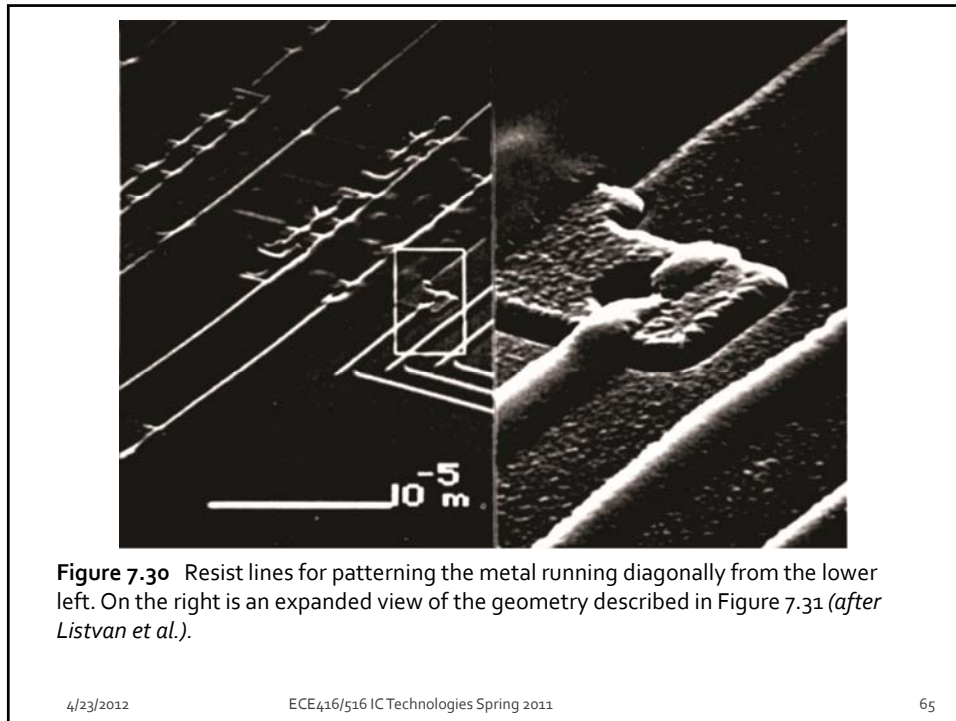
- **A number of companies now provide OPC and phase shifting software services.**
- **The advanced masks which these make possible allow sharper resist images and/or smaller feature sizes for a given exposure system.**

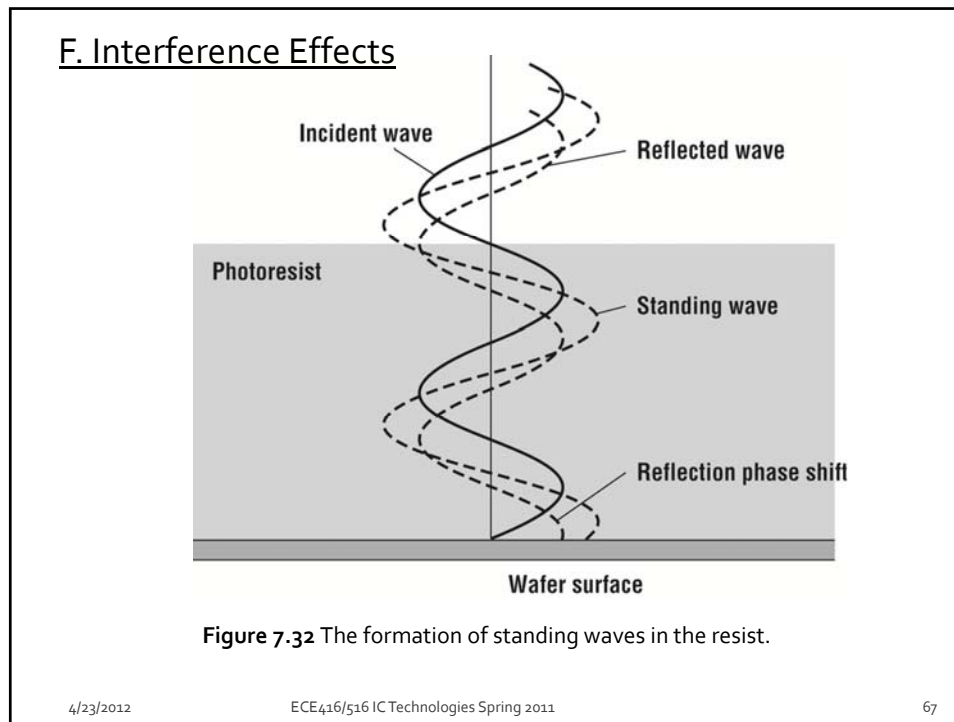
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Reflection & Standing Waves

$$E_i = E_o \cos(\omega t - \beta z)$$

$$E_r = R E_o \cos(\omega t + \beta z)$$

$$\beta = 2 \pi (n - i k) / \lambda$$

$$R = \text{reflection coefficient} = r^2$$

$$= [(n_1 - n_2) / (n_1 + n_2)]^2$$

n_2 = Si complex refractive index
 n_1 = PR complex refractive index
 $k \approx 0$ for PR or oxide, $\beta \approx 2\pi n / \lambda$

$$E_i + E_r = E_o [\cos(\omega t - \beta z) + R \cos(\omega t + \beta z)]$$

--> Standing Wave

$$E_s = E_{s0} \sin \omega t \sin((2\pi n z) / \lambda + \theta)$$

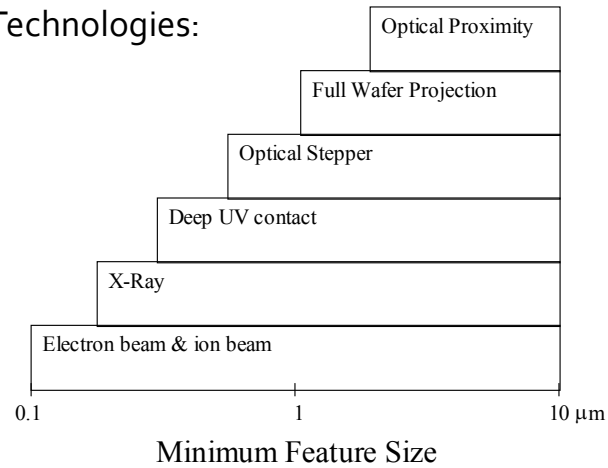
Maxima/Minima separations $\lambda / 2n$
 Minima when $(2\pi n z / \lambda) + \theta = m\pi$
 $m = 0, 1, 2, \dots$

For $r = -1$ (Si, GaAs, metals), $\theta = 0$.
 minima at $z = m\lambda / 2n$, $m = 0, 1, 2, \dots$
 & exposure due to intensity $I = I_o \sin^2 \beta z$

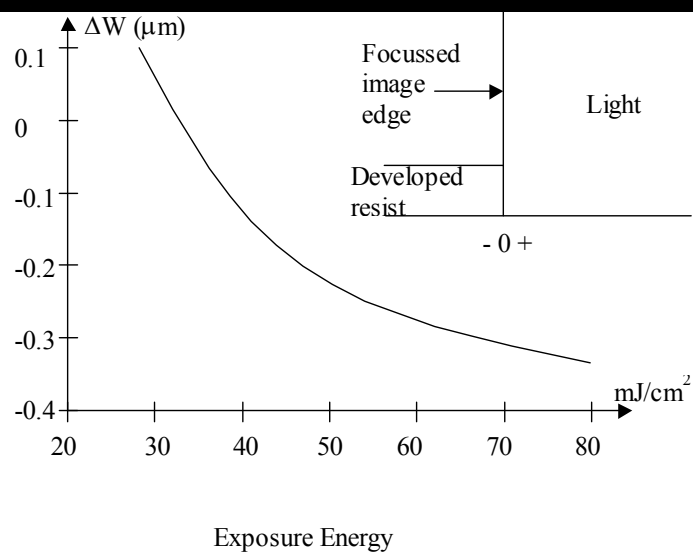
- Notes: (1) Poor development at surface
 (2) PR on oxide
 --> optical properties similar,
 so SW continuous across interface;
 adjust thickness of oxide Z_o to get anti-
 node at PR/oxide interface.
 $Z_o = (2m + 1) \lambda / 4n$
- (3) Eliminate SW formation:
 (a) thin absorbing layer
 between Si & PR
 (b) dye in PR for light scatter
- (4) Plasma etch removes PR
 residue

Minimum Feature Sizes

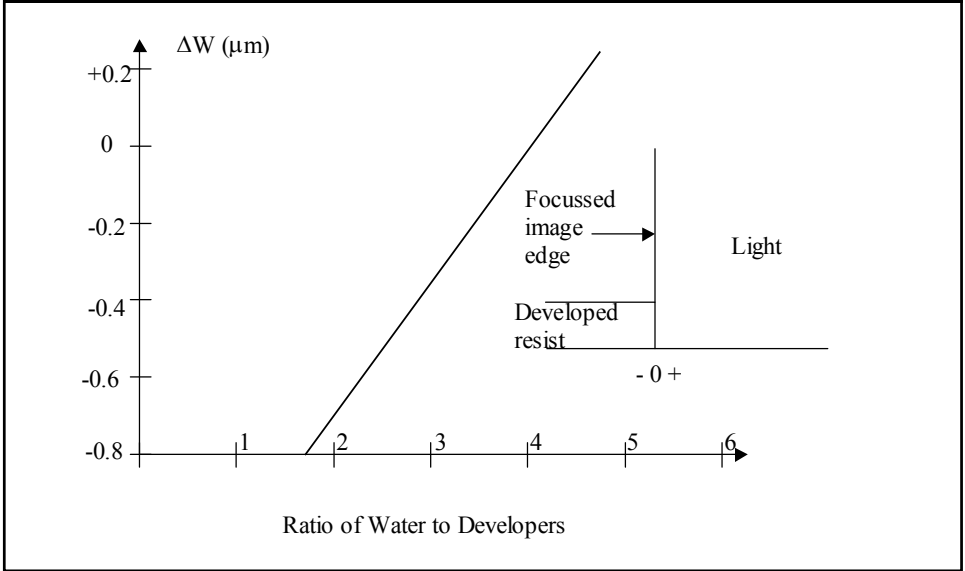
1988 Technologies:



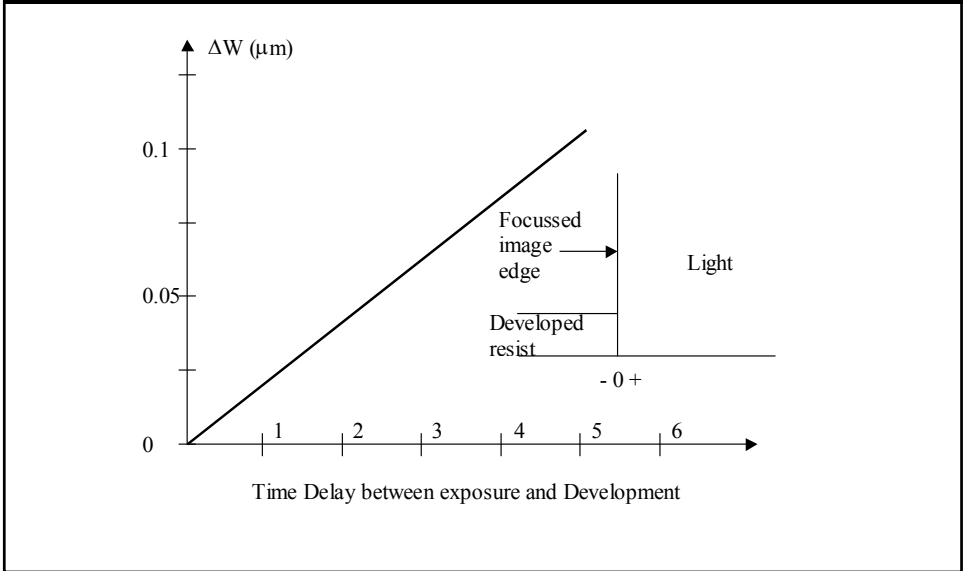
Other Line Width Limits #1



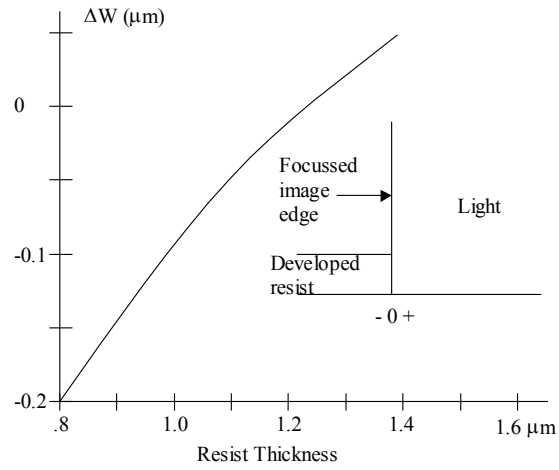
Other Line Width Limits #2



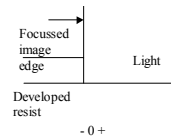
Other Line Width Limits #3



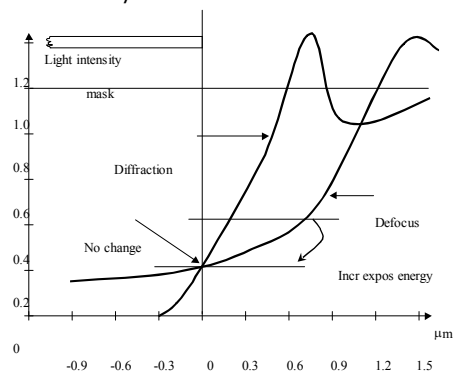
Other Line Width Limits #4



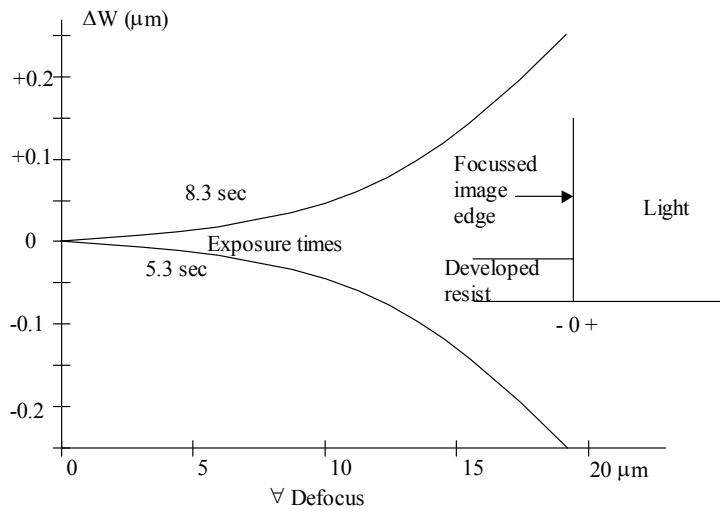
Other Line Width Limits #5



Increasing exposure time decreases intensity for threshold.



Other Line Width Limits #6



Misalignment

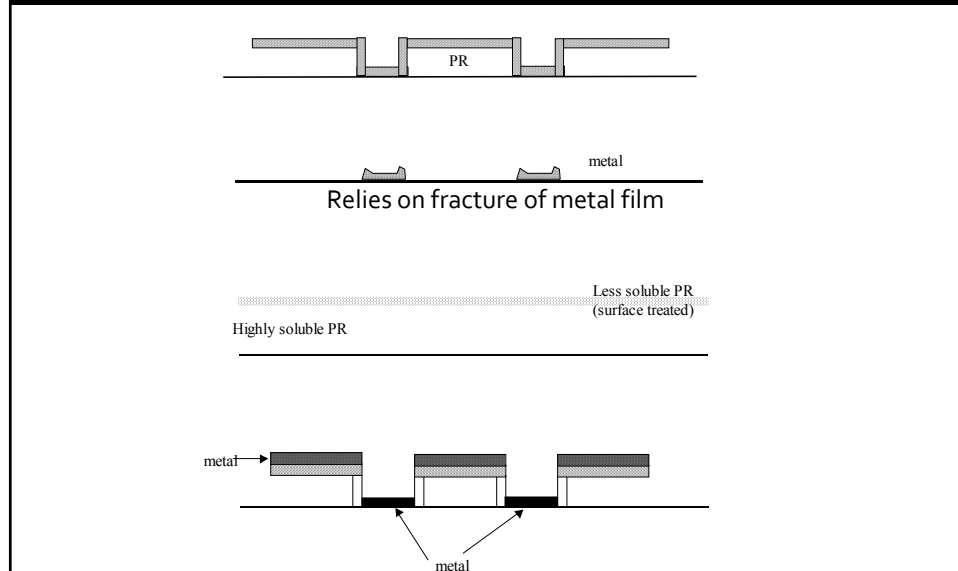


Runout

Temperature changes

Figure 7.33 Two typical registration errors.

Lift-Off Techniques



Some Final Thoughts

- Lithography is the key pacing item for developing new technology generations.
- Exposure tools today generally use projection optics with diffraction limited performance.
- Lithography simulation tools are based on Fourier optics and do an excellent job of simulating optical system performance. Thus aerial images can be accurately calculated.
- A new approach to lithography may be required in the next 10 years.

Assignment #3

Problems: 6.1 7.4
 6.2 7.5
 6.5 7.6/7

Mid-term course evaluation:

Summarize what you like about the course,
and what you don't like.

(Suggestion: Identify 5 each.)

Consider lectures, textbook, assignments,
notes, videos, etc. (Weighted as 2 problems)

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Grad project topics: (PPT presentations Monday June 4th)

- Phase masking
 - Specific design example
- Optical proximity correction
 - Specific design example
- Through-silicon vias (TSVs)
 - Solid copper & barrel
- Planarization
 - Chemical/Mechanical Polishing
- On-chip resistors
 - Materials/fabrication/properties
- On-chip inductors
 - Spiral and ferrite
- Wafer thinning
 - Thin wafer applications
- Cryopumping
 - Theory and practice
- Unbalanced magnetron
 - Sources/deposition
- Thin metal film resistivity
 - (Continuous) thickness variation
- Stiction avoidance
 - Including surface structuring
- Electroless deposition
 - Theory and techniques
- Atomic layer deposition
 - Theory and techniques
- MEMS motor fabrication
 - Linear and rotational

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