

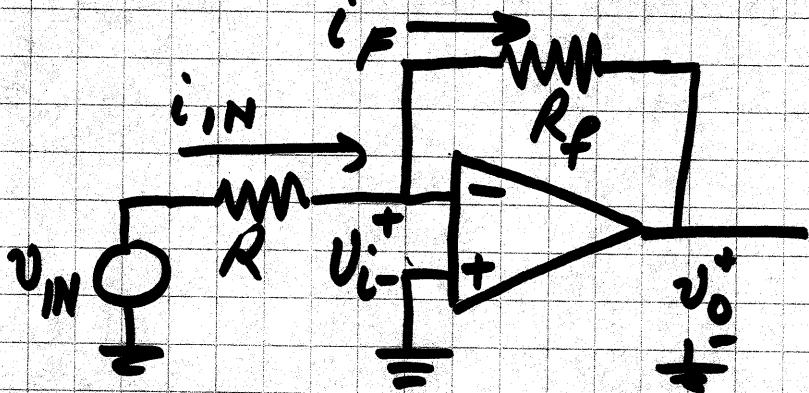
On-line password:

ece321f@6

Streaming source from NH454:

"Video Services"

# NEGATIVE FEEDBACK & the VIRTUAL S.C.



$$\text{Virtual SC} \rightarrow v^- = v^+ = 0$$

If  $v^- \rightarrow +ve$ ,  $v_i \rightarrow +ve$  &  $v_o \rightarrow -Av_i \rightarrow (-\infty)$

$$\therefore i_f = i_{IN} \rightarrow \frac{v_i - (-Av_i)}{R_f} \approx \frac{Av_i}{R_f} \rightarrow (\infty)$$

$$\therefore v_i = v_{IN} - i_{IN} R \rightarrow -\infty$$

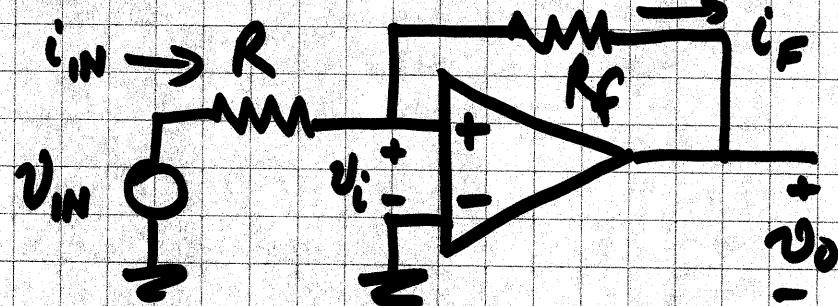
i.e. VERY large opamp gain has effect of "over-reacting" to any changes in  $v_i$ , i.e.  $v^-$

Small +ve  $v^- \rightarrow$  large tendency to negative  $v^-$

" -ve "  $\rightarrow$  " " " positive "

i.e.  $v_i$  held to zero  $\rightarrow$  virtual short circuit.

# Note for POSITIVE FEEDBACK



If  $v_i > 0$   $v_o = A v_i \rightarrow +\infty$  Limited at  $+V_s$

$$i_F < 0 \quad i_F = i_{IN} = \frac{V_s - v_{IN}}{R + R_F}$$

$$\therefore v_i = v_{IN} + R \frac{(V_s - v_{IN})}{R + R_F} = \frac{R_F}{R + R_F} v_{IN} + \frac{R}{R + R_F} V_s$$

$$\therefore v_o \Rightarrow A v_i \rightarrow V_s \quad (> 0 \text{ consistent})$$

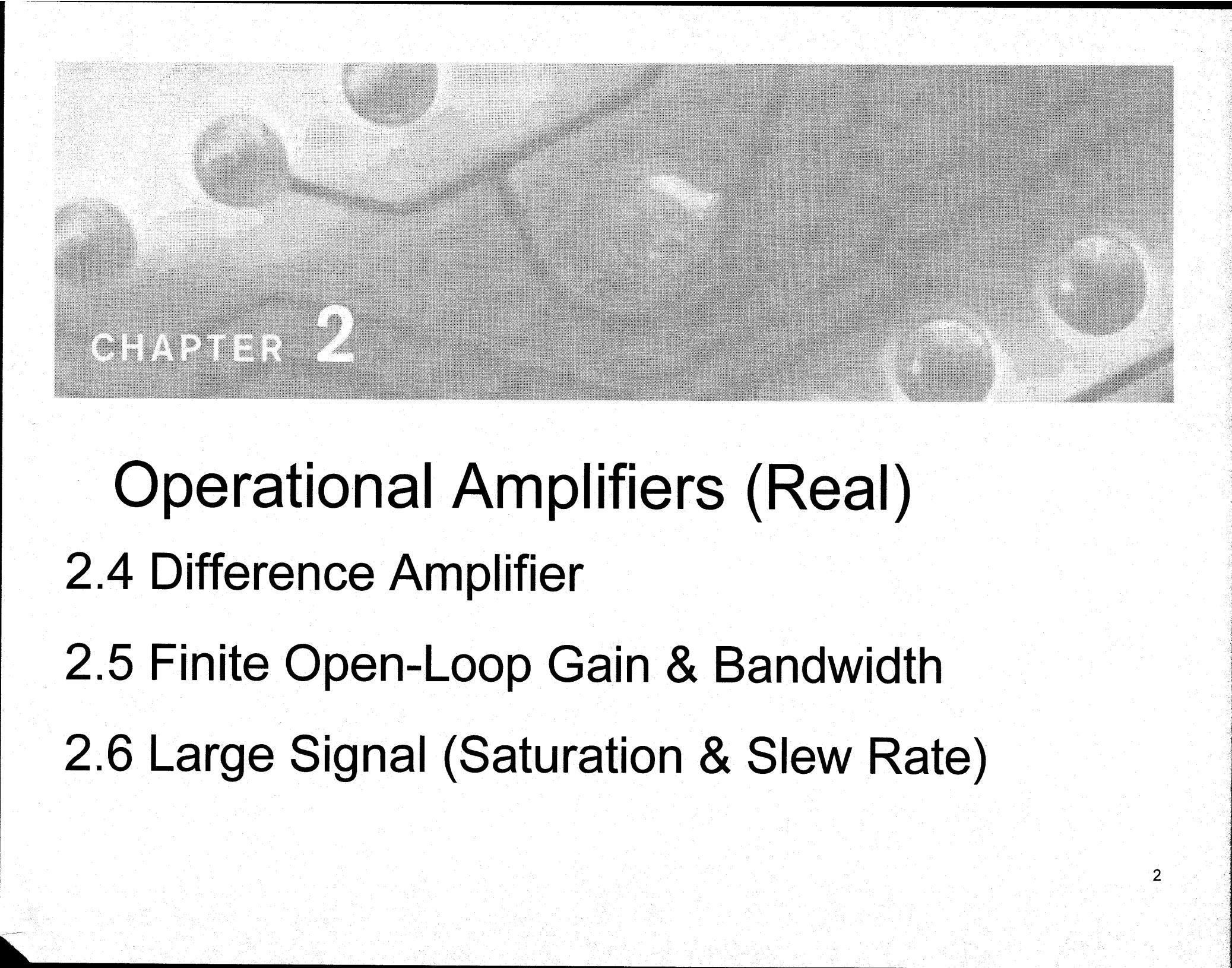
Positive feedback  $\rightarrow$  large  $A$  drives  $v_o \rightarrow \pm V_s$

# **ECE321 ELECTRONICS I**

## **FALL 2006**

**PROFESSOR JAMES E. MORRIS**

**Lecture 3**  
**3<sup>rd</sup> October, 2006**



## CHAPTER 2

# Operational Amplifiers (Real)

2.4 Difference Amplifier

2.5 Finite Open-Loop Gain & Bandwidth

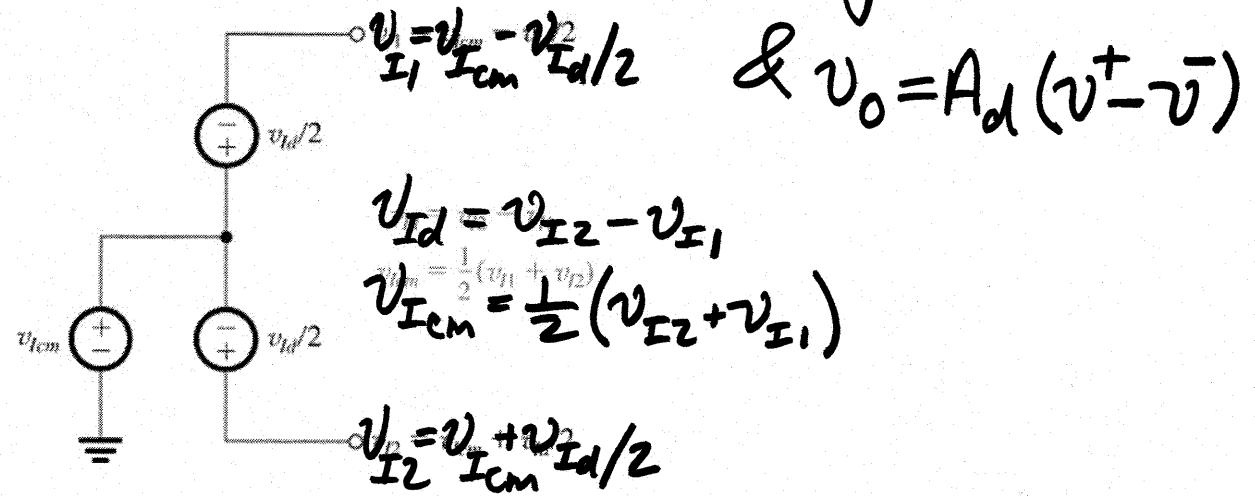
2.6 Large Signal (Saturation & Slew Rate)

# Common Mode & Difference Amp's

Remember

$$v_o = A_d v_{Id} + A_{cm} v_{Icm}$$

↑ Ideally 0



Define  $CMRR = 20 \log_{10} \frac{|A_d|}{|A_{cm}|}$

Figure 2.15 Representing the input signals to a differential amplifier in terms of their differential and common-mode components.

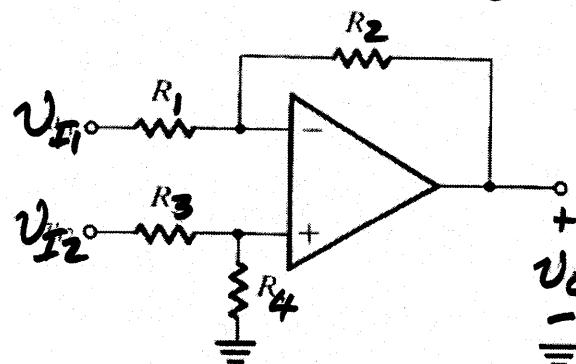
Common Mode Rejection Ratio

# Difference Amplifier: Assume $A = \infty$

We are interested in non-ideal common-mode effects here.

Solve from first principles:  $v^- = v^+$

$$v_{I1} + \frac{R_1}{R_1+R_2} (v_0 - v_{I1}) = \frac{R_4}{R_3+R_4} v_{I2}$$



& solve  $\Rightarrow v_0 = \frac{R_4}{R_1} \cdot \frac{R_1+R_2}{R_3+R_4} v_{I2} - \frac{R_2}{R_1} v_{I1}$

To work as a difference amplifier, we need

$$\frac{R_4}{R_1} \cdot \frac{R_1+R_2}{R_3+R_4} = \frac{R_2}{R_1}, \text{ i.e. } \frac{R_3+R_4}{R_4} = \frac{R_1+R_2}{R_2}$$

Figure 2.16 A difference amplifier.

i.e.  $R_3/R_4 = R_1/R_2$  to get  $v_0 = \frac{R_2}{R_1} (v_{I2} - v_{I1})$

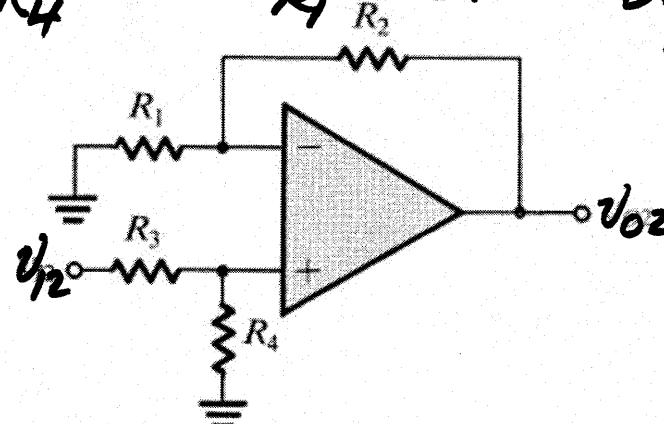
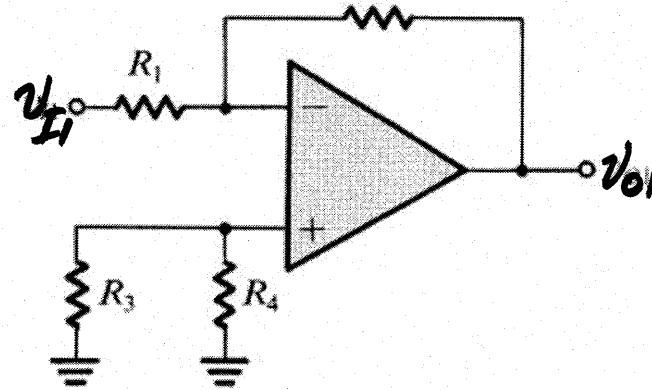
OR do this by superposition (skipped some algebra)

$$V_{O1} = -\frac{R_2}{R_1} V_{I1}$$

$$\begin{aligned} V_{O2} &= \left(1 + \frac{R_2}{R_1}\right) \frac{R_4}{R_3 + R_4} V_{I2} \\ &= \frac{R_4}{R_1} \frac{R_1 + R_2}{R_3 + R_4} V_{I2} \end{aligned}$$

$$\therefore V_O = V_{O1} + V_{O2} = \frac{R_4}{R_1} \frac{R_1 + R_2}{R_3 + R_4} V_{I2} - \frac{R_2}{R_1} V_{I1}$$

Same result!!



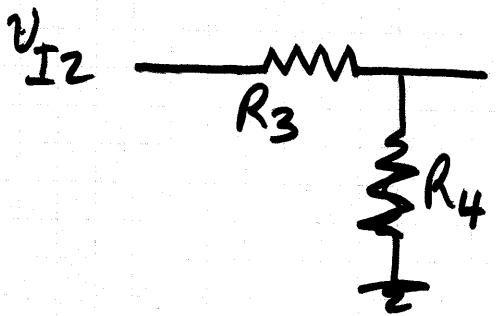
(a)  
So superposition is not as obvious as brute force, but probably easier, and definitely less error-prone.

Note the concept here — combine inv & non-inv amp's

Figure 2.17 Application of superposition to the analysis of the circuit of Fig. 2.16.

But non-inv gain  $(1 + R_2/R_1) >$  inv gain  $R_2/R_1$

$\therefore$  Reduce non-inv gain by voltage divider & make:



$$\frac{R_4}{R_3+R_4} v_{I2} \times \left(1 + \frac{R_2}{R_1}\right)$$

equal to  $\frac{R_2}{R_1}$

$$\frac{R_4}{R_3+R_4} \frac{R_1+R_2}{R_1} = \frac{R_2}{R_1}$$

→ same result

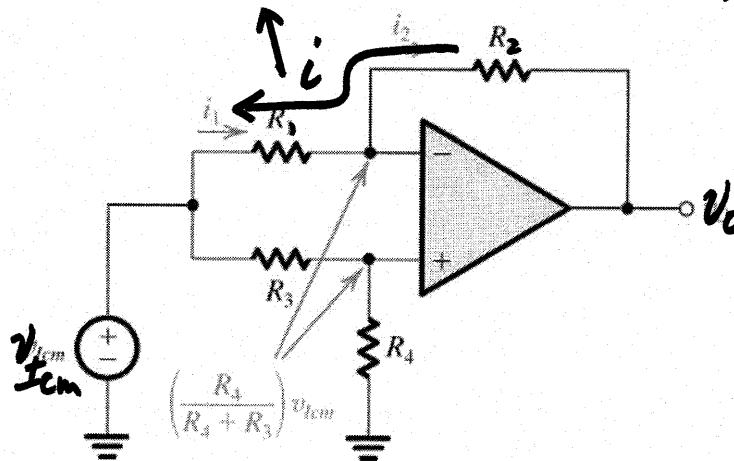
$$\frac{R_3}{R_4} = \frac{R_1}{R_2}$$

Often make  $R_1 = R_3$  and  $R_2 = R_4$

Back to CMRR — need  $A_{cm}$

Voltage divider :  $v^+ = \frac{R_4}{R_3 + R_4} v_{Icm} = v^-$

$$\therefore v_{Icm} + R_1 \left( \frac{v_o - v_{Icm}}{R_1 + R_2} \right) = \frac{R_4}{R_3 + R_4} v_{Icm}$$



Rearrange to get

$$\frac{v_o}{v_{Icm}} = \frac{R_4}{R_1} \cdot \frac{R_1 + R_2}{R_3 + R_4} - \frac{R_2}{R_1} \quad \underline{\underline{\frac{R_4}{R_3} = \frac{R_2}{R_1}}} \rightarrow 0$$

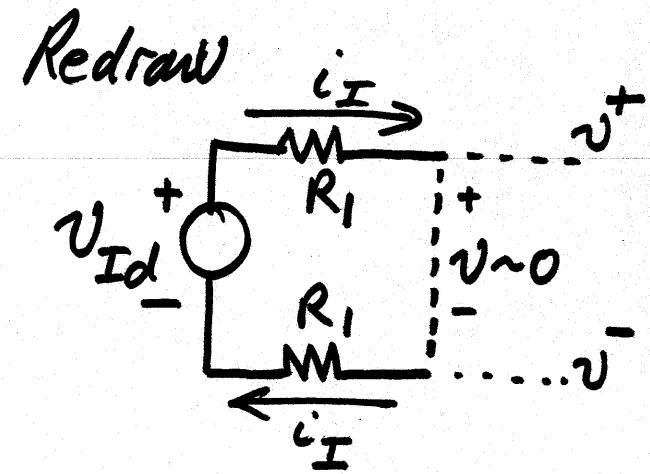
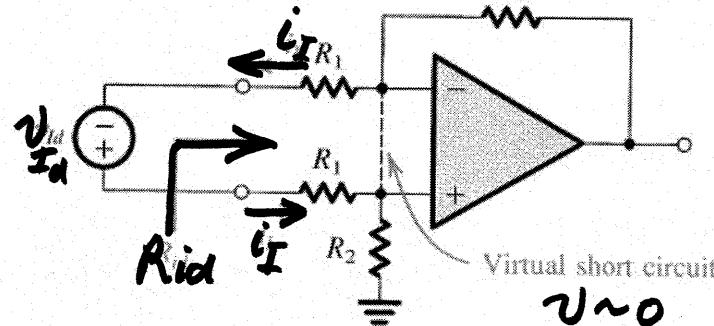
i.e.  $CMRR \rightarrow \infty$   
if diff amp condition met

Figure 2.18 Analysis of the difference amplifier to determine its common-mode gain  $A_{cm}$ ;  $v_o / v_{Icm}$ .

Also want high  $R_{in}$  for difference signal

$R_{id} = V_{Id} / i_I$  as shown  
& use virtual S.C. again

( $R_3 = R_1, R_4 = R_2$  for simplicity)



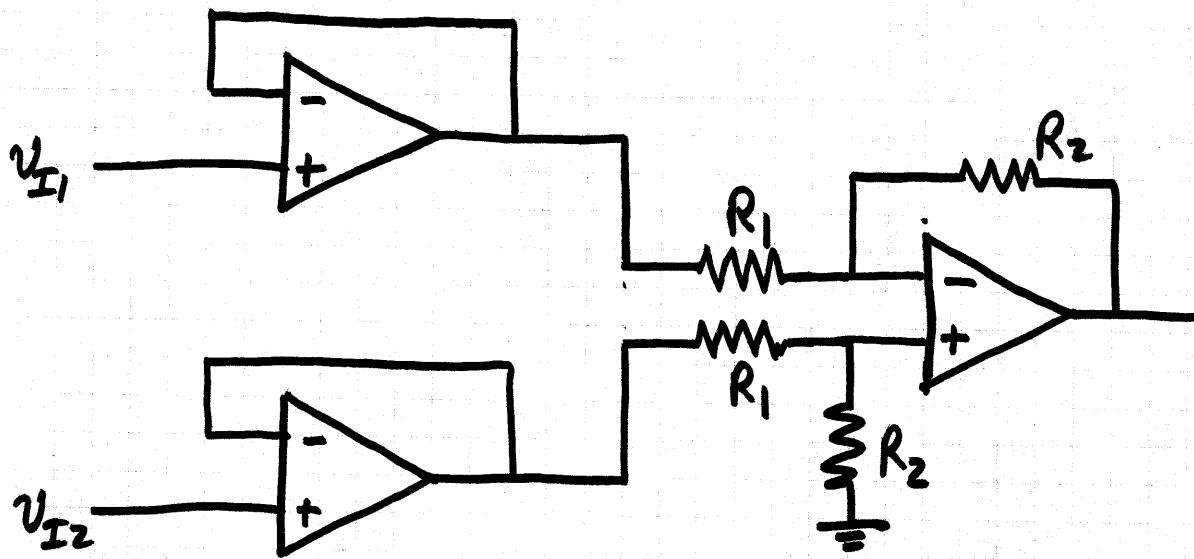
$$\therefore R_{id} = \frac{V_{Id}}{i_I} = 2R_1$$

$R_{id}$  not as high as we would like!

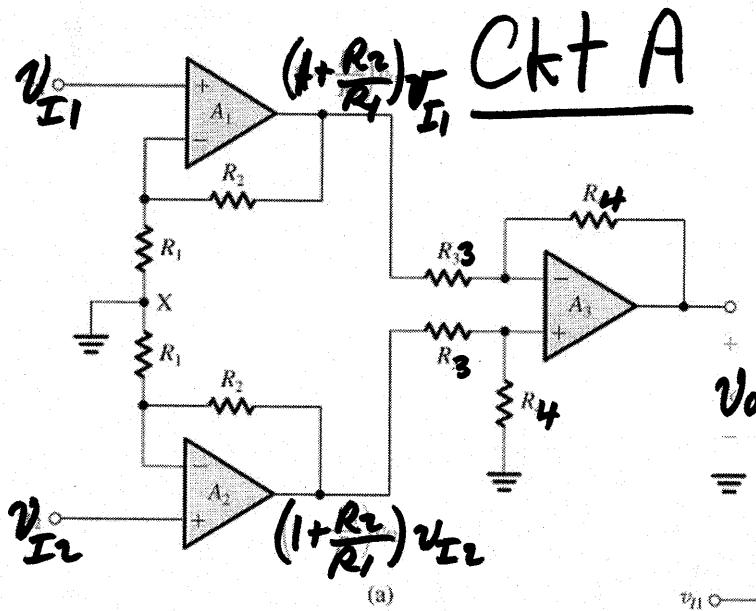
Figure 2.19 Finding the input resistance of the difference amplifier for the case  $R_3 = R_1$  and  $R_4 = R_2$ .

Obvious solution:

Voltage follower buffers



But here all the gain from one stage  
Better to use cascaded lower gain stages



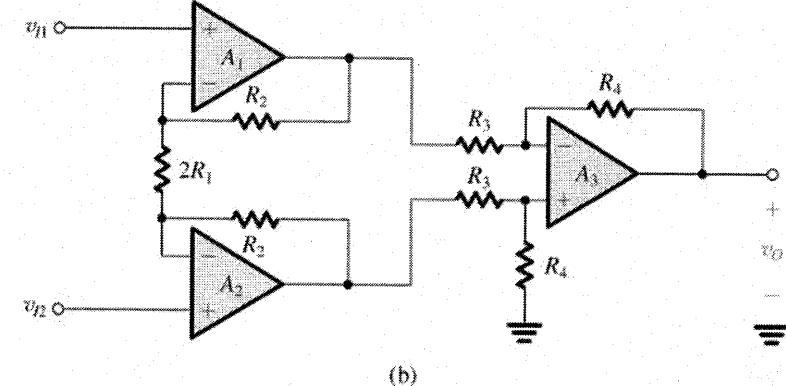
(a)

$$v_o = \frac{R_4}{R_3} \left(1 + \frac{R_2}{R_1}\right) v_{Id}$$

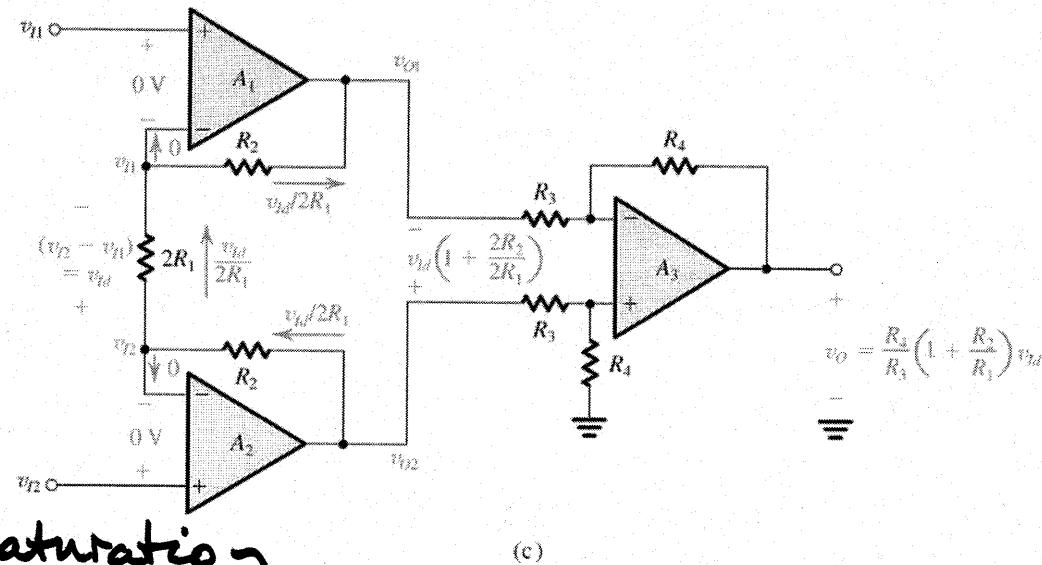
But  $A_1, A_2$  amplify CM signals  $\times (1 + R_2/R_1)$

Possible problems:  $A_1, A_2$  saturation  
Non-ideal 3rd stage transmit CM signal

Figure 2.20 A popular circuit for an instrumentation amplifier: (a) Initial approach to the circuit; (b) The circuit in (a) with the connection between node X and ground removed and the two resistors  $R_1$  and  $R_1$  lumped together. This simple wiring change dramatically improves performance; (c) Analysis of the circuit in (b) assuming ideal op amps.

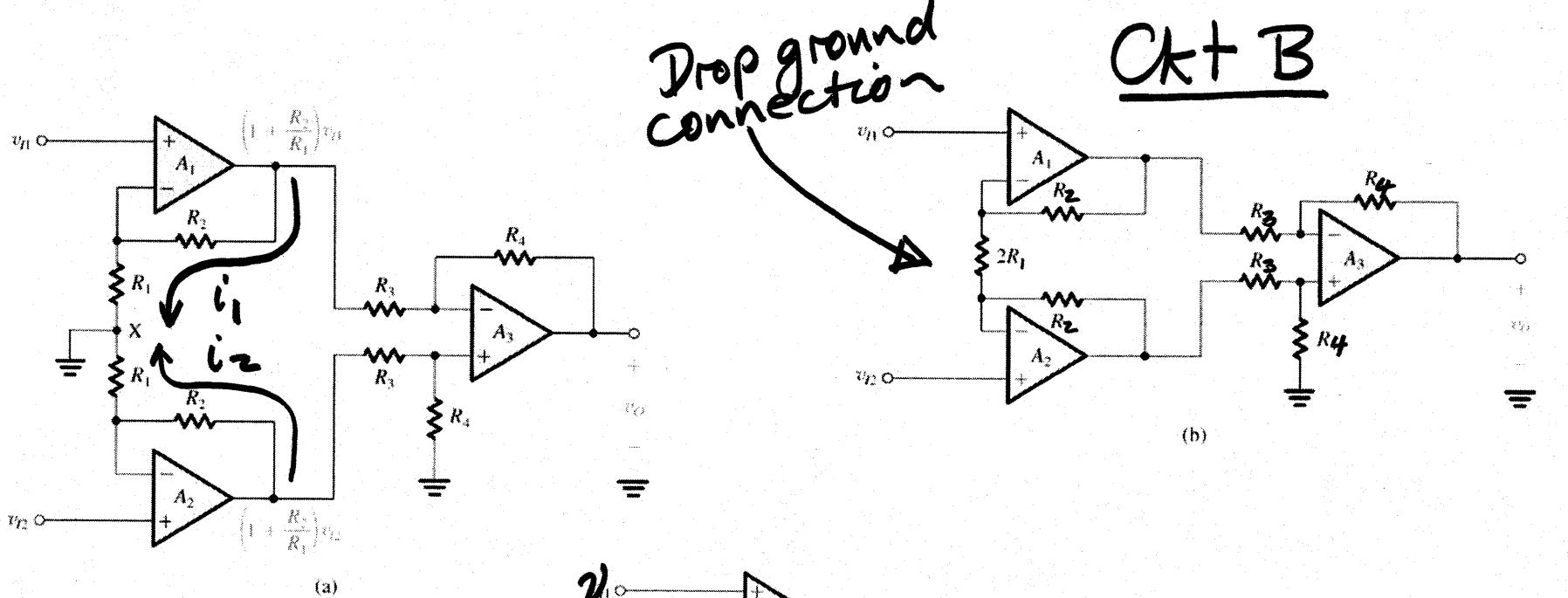


(b)

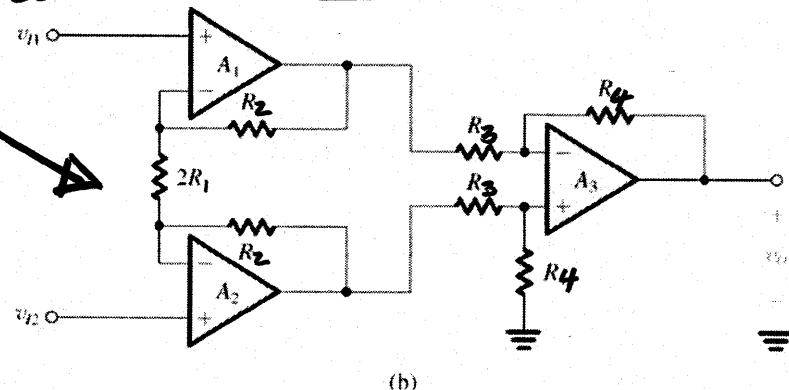


(c)

Also: Must simultaneously vary 2 R's to change gain

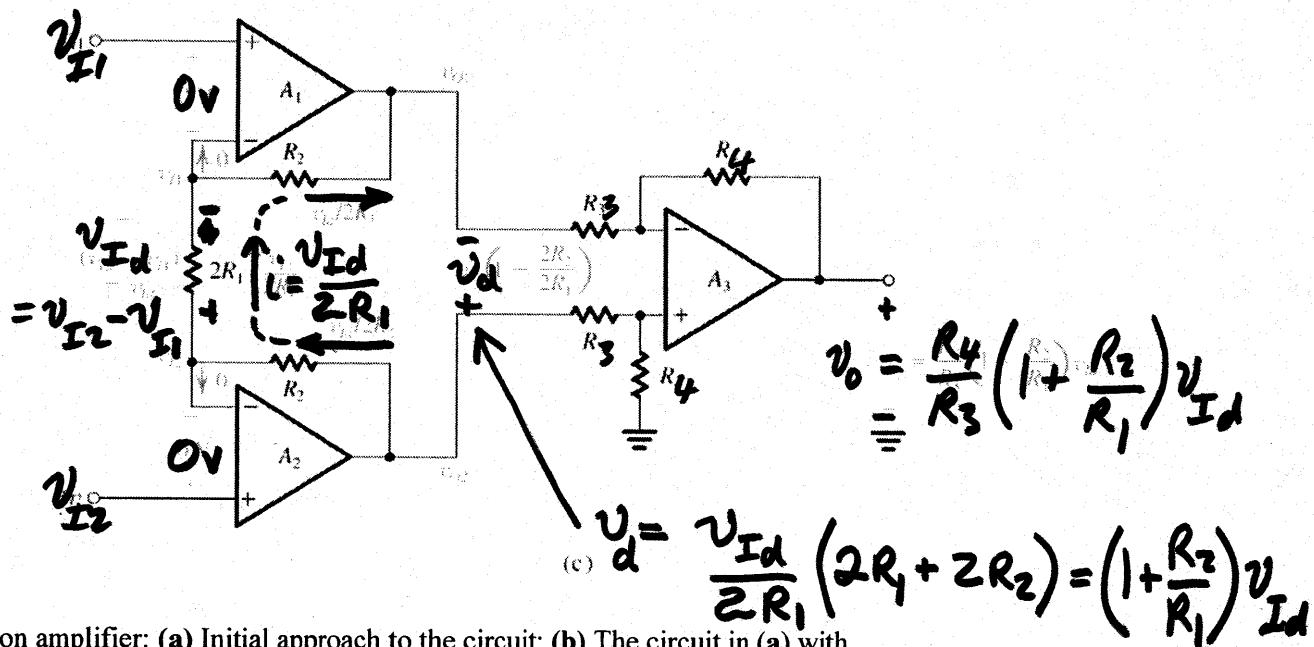


(a)



(b)

Balanced:  $i_1 = i_2$   
 $\therefore$  No ground current  
 $\therefore$  No purpose

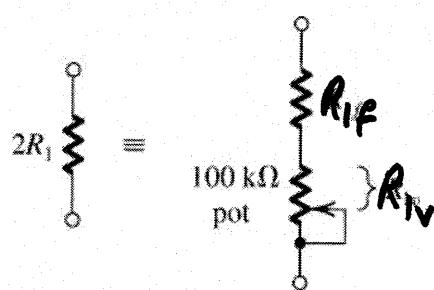


(c)

Figure 2.20 A popular circuit for an instrumentation amplifier: (a) Initial approach to the circuit; (b) The circuit in (a) with the connection between node X and ground removed and the two resistors  $R_1$  and  $R_1$  lumped together. This simple wiring change dramatically improves performance; (c) Analysis of the circuit in (b) assuming ideal op amps.

Note:  $i$  completely defined by  $v_{Id}$  — no CM amplification  
 Vary gain with  $2R_1$  — now single resistor

## Note Example 2.3



Vary gain, bias points  
etc by "pot"  
(potentiometer)

Here  $R_{If} + R_{lv}$   
 $R_{If} \rightarrow R_{If} + 100\text{ k}\Omega$

**Figure 2.21** To make the gain of the circuit in Fig. 2.20(b) variable,  $2R_1$  is implemented as the series combination of a fixed resistor  $R_{If}$  and a variable resistor  $R_{lv}$ . Resistor  $R_{If}$  ensures that the maximum available gain is limited.

Frequency-dependent gain: adapt RC concepts  
 $A$  not  $\infty$ , and decreases with frequency

$$A(j\omega) = \frac{A_0}{1 + j \frac{\omega}{\omega_b}}$$

$$= \frac{A_0}{1 + j \frac{f}{f_b}}$$

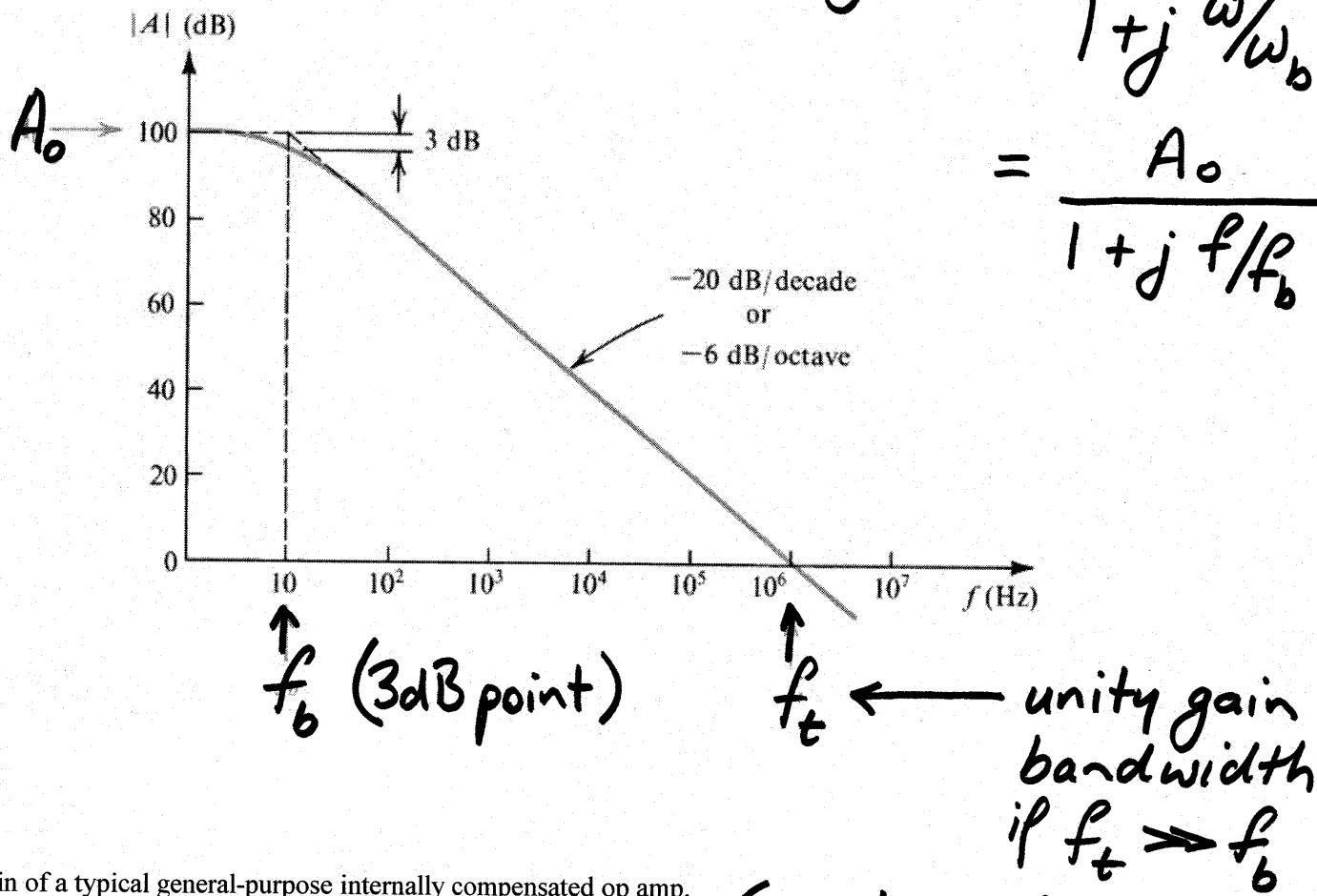


Figure 2.22 Open-loop gain of a typical general-purpose internally compensated op amp.

(Note:  $G \times BW$  is  
 Gain-Bandwidth Product)

$$\text{So } 1 \approx \frac{A_0}{\omega_t/\omega_b}$$

$$\omega_t \approx A_0 \omega_b \text{ or } f_t \approx A_0 f_b = G \times BW$$

# Non-Inverting Amplifier

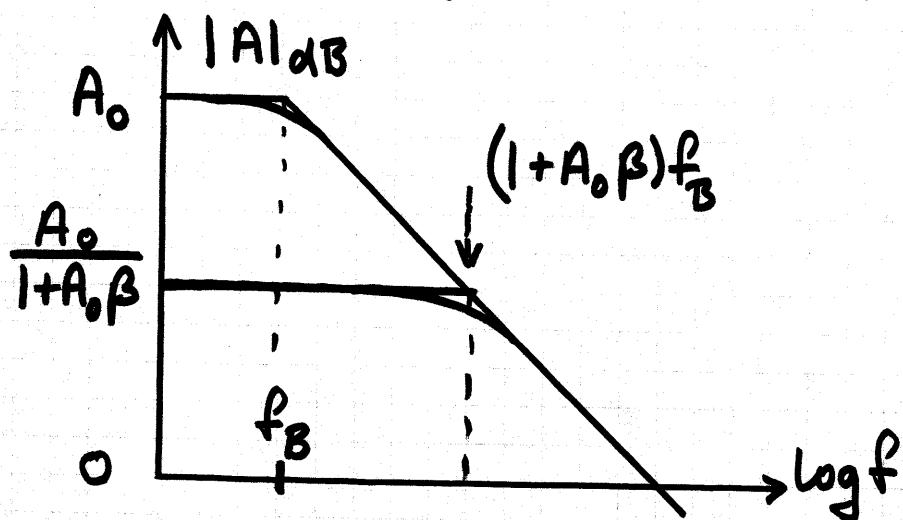
Previous result

$$\frac{V_o}{V_I} = \frac{A}{1+A\beta}$$

$$\text{where } \beta = \frac{R_1}{R_1+R_2}$$

$$\approx 1/\beta \text{ for } A \rightarrow \infty$$

$$\begin{aligned} \frac{V_o}{V_I} &= \frac{A(j\omega)}{1+A(j\omega)\beta} = \frac{A_0/[1+j(f/f_B)]}{1+\beta A_0/[1+j(f/f_B)]} = \frac{A_0}{A_0\beta + [1+j(f/f_B)]} \\ &= \frac{A_0}{(1+A_0\beta) + j(f/f_B)} = \frac{A_0}{(1+A_0\beta)(1 + \frac{jf}{(1+A_0\beta)f_B})} \xrightarrow{A_0 \rightarrow \infty} \frac{1}{\beta} \frac{1}{1+j\frac{f}{(1+A_0\beta)f_B}} \end{aligned}$$



Note:  $G \times \text{BW product}$

$$\frac{A_0}{1+A_0\beta} \cdot (1+A_0\beta)f_B = A_0 f_B = \text{constant}$$

Independent of  $\beta$

# Inverting Amplifier

Previous result:  $\frac{V_o}{V_I} = -\frac{R_2}{R_1+R_2} \frac{A}{1+A\beta}$  where  $\beta = \frac{R_1}{R_1+R_2}$

$$\begin{aligned} \therefore \frac{V_o}{V_I} &\rightarrow -\frac{R_2}{R_1+R_2} \frac{\frac{A_0}{1+jf/f_B}}{1+\beta A_0 \frac{(1+jf/f_B)}{(1+jf/f_B)}} \\ &= -\frac{R_2}{R_1+R_2} \frac{A_0}{1+A_0\beta} \cdot \frac{1}{1+j\frac{f}{(1+A_0\beta)f_B}} \xrightarrow{A_0 \rightarrow \infty} -\frac{R_2}{(R_1+R_2)} \frac{\cancel{(R_1+R_2)}}{R_1} \frac{1}{1+j\frac{f}{(1+A_0\beta)f_B}} \end{aligned}$$

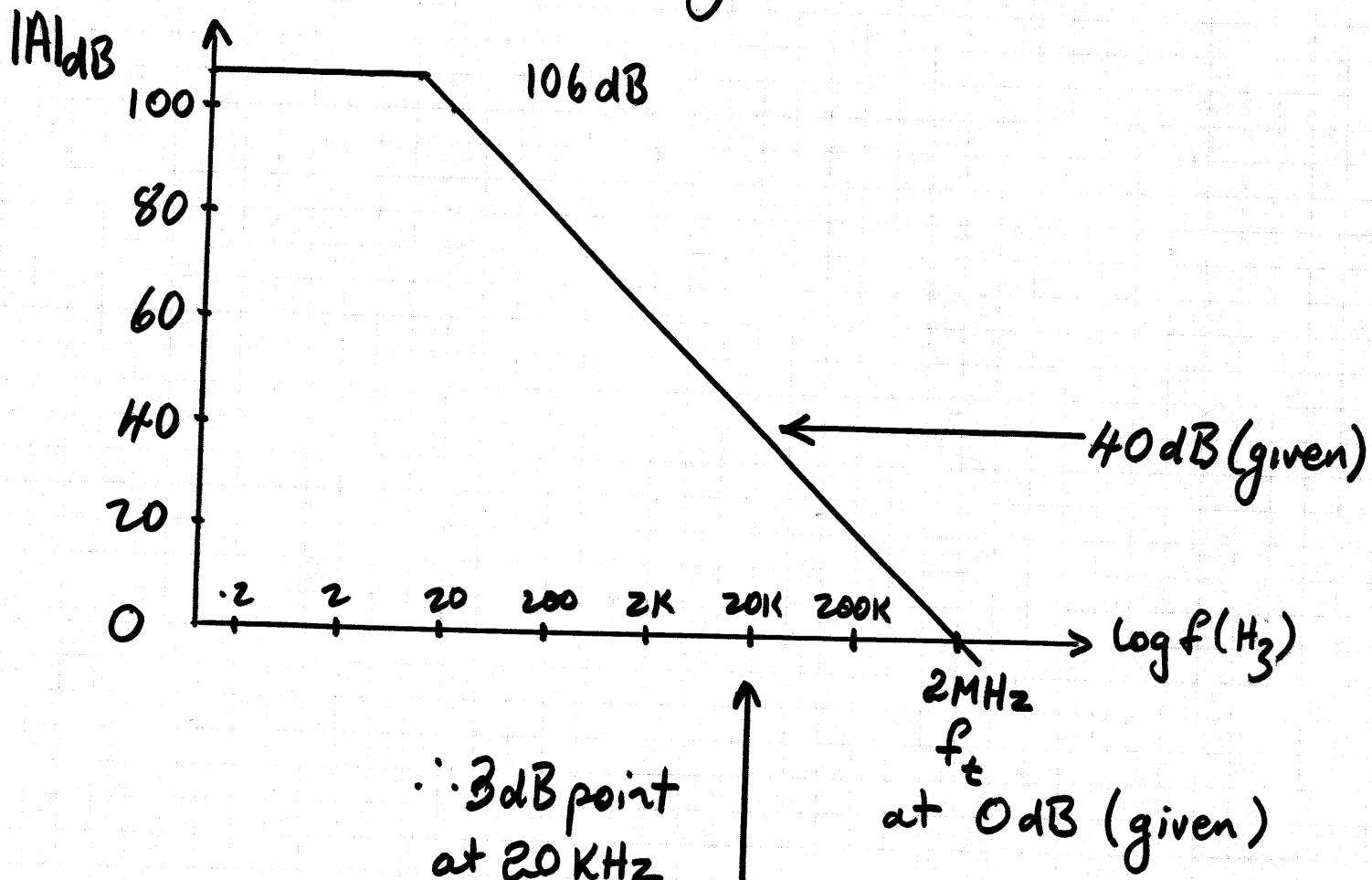
Note:  $G \times BW = \frac{R_2}{R_1+R_2} \frac{A_0}{1+A_0\beta} \times (1+A_0\beta) f_B$

$$= A_0 f_B \frac{R_2}{R_1+R_2} = A_0 f_B \frac{(R_2/R_1)}{1+(R_2/R_1)}$$

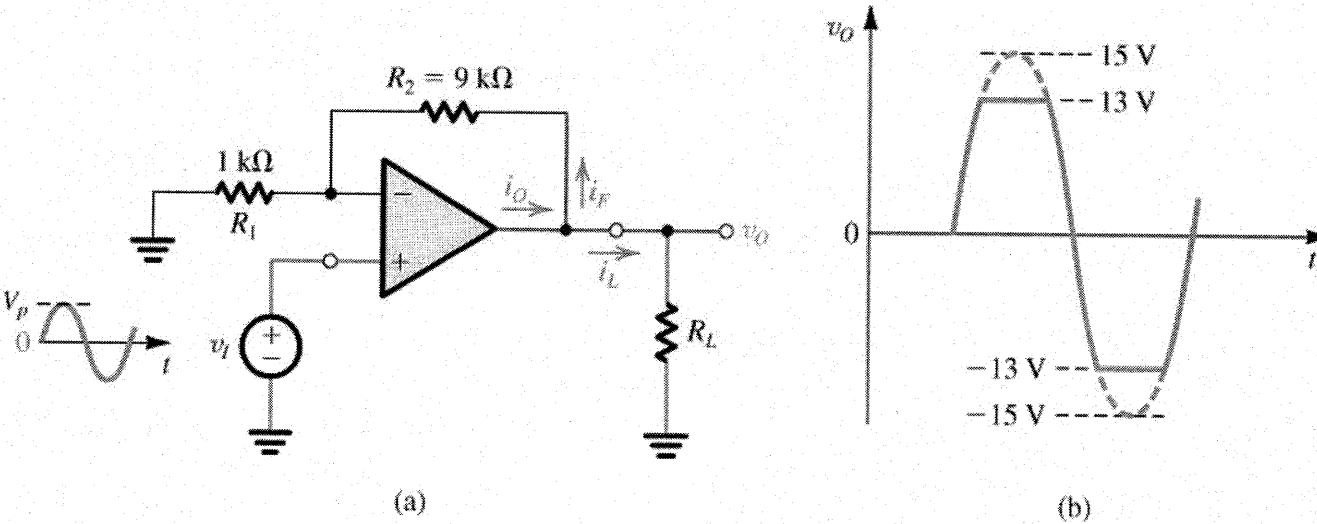
Ex. 2.20 Opamp  $A_o = 106 \text{ dB}$   $f_t = 2 \text{ MHz}$

Non-Inv amp = dc gain 100, (i.e. 40dB)

Find 3dB point of CL gain

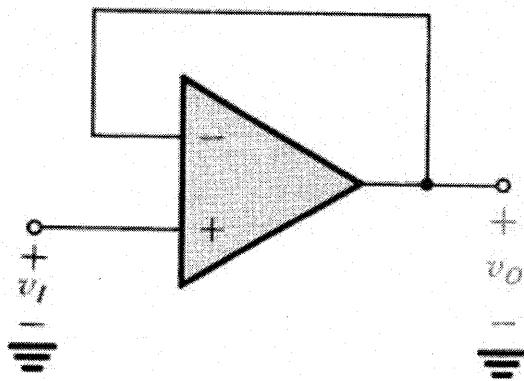


# Large Signal : Saturation

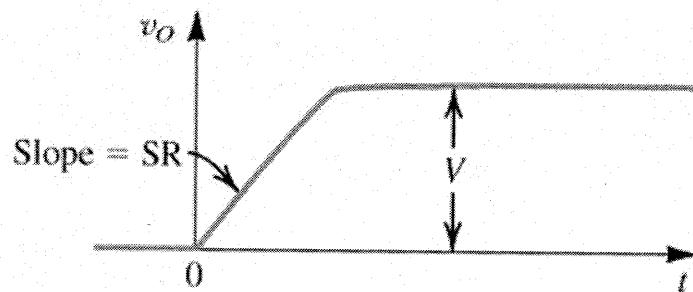


**Figure 2.25** (a) A noninverting amplifier with a nominal gain of 10 V/V designed using an op amp that saturates at  $\pm 13\text{-V}$  output voltage and has  $\pm 20\text{-mA}$  output current limits. (b) When the input sine wave has a peak of 1.5 V, the output is clipped off at  $\pm 13\text{ V}$ .

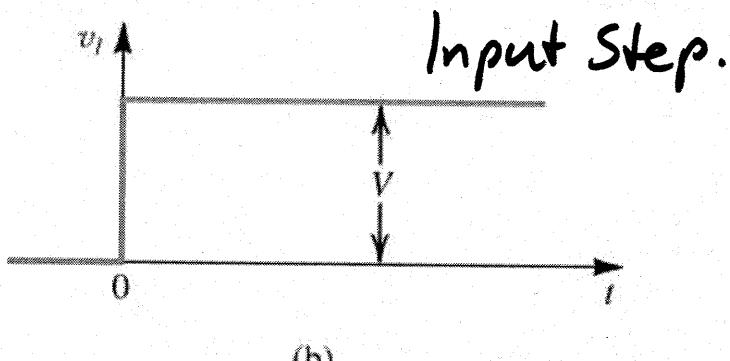
# Frequency Response Limited and Slew Rate



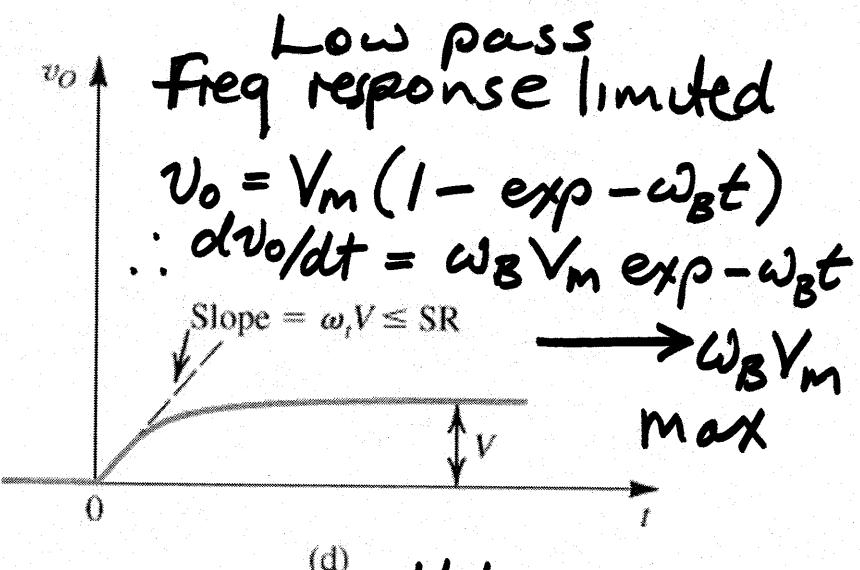
**Voltage Follower**  
**Unity Gain Bandwidth**  
**(fastest possible)**



**Slew rate limited**



**(b)**



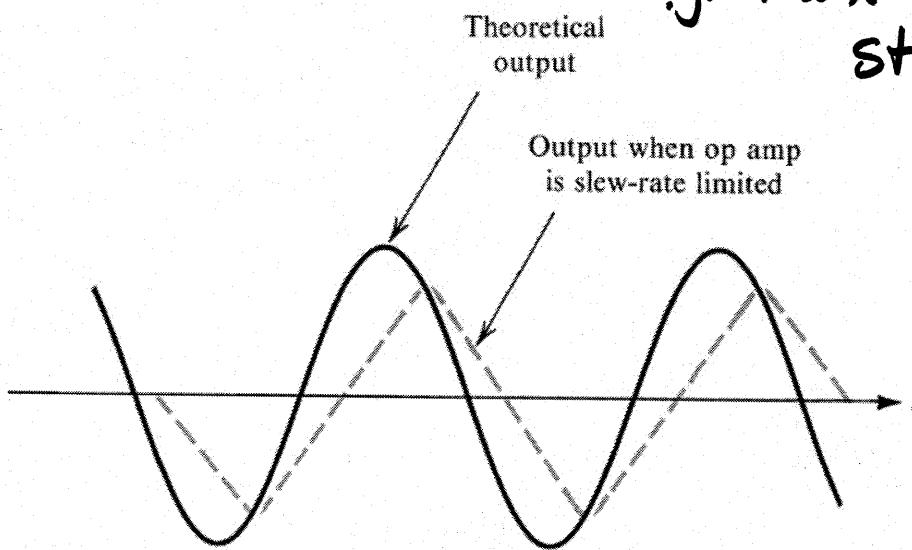
**(d)**

**Note:**  $\omega_B \rightarrow \omega_t$   
for Voltage Follower

**Figure 2.26** (a) Unity-gain follower. (b) Input step waveform. (c) Linearly rising output waveform obtained when the amplifier is slew-rate limited. (d) Exponentially rising output waveform obtained when  $V$  is sufficiently small so that the initial slope ( $v_i V$ ) is smaller than or equal to SR.

$$\text{Slew Rate (SR)} = \frac{dV_o}{dt} \Big|_{\text{max}}$$

Due to internal limits e.g. max current to charge stray capacitance.



$$\text{Ideal } V_o = V_m \sin \omega t$$

For no SR limiting, need  $\frac{dV_o}{dt} \Big|_{\text{max}}$  at  $t=0$

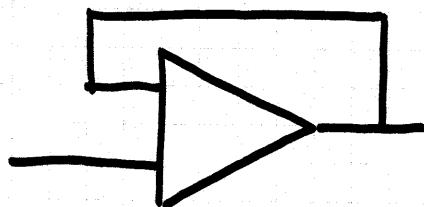
$$= \omega V_m \cos \omega t \rightarrow \omega V_m < \text{SR}$$

Figure 2.27 Effect of slew-rate limiting on output sinusoidal waveforms.

$\therefore$  Limit frequency or  $V_m$

$$\text{Full power BW } f_m = \frac{\text{SR}}{2\pi V_m}$$

Ex. 2.21



Output & Input:

$$V_{max} (1 - \exp - w_t t)$$

Initial slope  $w_t V_{max} \leq SR$

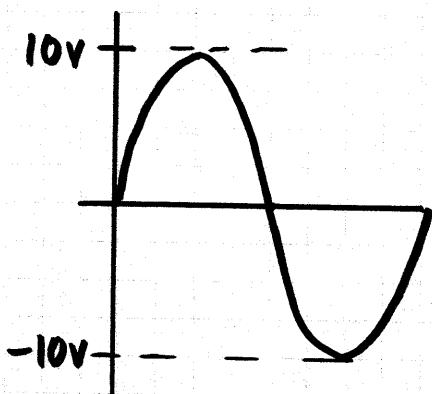
$$\therefore V_{max} \leq \frac{1\text{v}/\mu\text{s}}{2\pi f_+} = 10^6 / 2\pi 10^6 \approx 0.16 \text{ volts}$$

For 10%, 90%  $1 - \exp - 2\pi 10^6 t = 0.1, 0.9$  gives  $t = 0.017, 0.37 \mu\text{s}$   
 $\therefore 10-90\% \text{ risetime} = 0.37 - 0.02 \approx 0.35 \mu\text{s}$

For 1.6 volts; assume nearly fully SR limited (check)

$$\therefore 90\% = 1.44\text{v}, 10\% = 0.16\text{v} \quad \therefore 1.28\text{v linear rise at slew rate} \\ = 1.28 \mu\text{s}$$

Ex. 2.22 Opamp rated output  $\pm 10\text{v}$ ,  $SR = 1\text{v}/\mu\text{s}$ . Full power BW  $F_m$ ?  
For input sinusoid at  $5F_m$  to voltage follower, find max  $V_m$  for no SR limit.



$$10\text{v sin wt} \rightarrow \omega_m 10\text{v} \leq 1\text{v}/\mu\text{s} \quad \text{i.e. } \omega_m \leq \frac{10^6}{10} = 10^5$$

$$f_m = \frac{10^5}{2\pi} \approx 16 \text{ KHz}$$

For  $5F_m$  & unity gain  $\omega V_m$  still  $10^6$   
 $5\omega_m \quad \therefore 10^6 / 5 = 2\text{v}$

# Summary

- Difference (instrumentation) amplifier
  - $A_{cm}$  &  $A_d$  definitions; CMRR
  - Difference amplifier gain (formula or derive)
  - CMRR  $\rightarrow 0$  for ideal difference amp condition
  - High  $R_{id}$ ; ( $R_{id}$  and virtual SC)
- Finite  $A_0$  & bandwidth
  - $A(j\omega) = A_0 / (1 + j\omega/\omega_b)$
  - Derive  $A_{CL}(j\omega)$  for inv & non-inv amplifiers
  - Gain x bandwidth product; unity gain BW
- Large signal saturation & slew rate
  - Full power BW amplitude dependent