

Electrical Package Design

TKK 2009 Lecture 2

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Electrical Package Design

- **Lecture topics A: Introduction**
 - CMOS; R, L, & C
- **Lecture topics B: Transmission lines**
 - Z_0 , velocity, lossless lines, lossy lines
- **Lecture topics C: Transmission lines**
 - Transmission line reflections
- **Lecture topics D: Transmission lines**
 - Crosstalk
- **Lecture topics E: Electromagnetism & Modeling**
- **Lecture topics F: Electromagnetic Compatibility**

Lecture topics A: Introduction CMOS; R, L, & C

1. Interconnect modeling
2. Resistance, inductance, & capacitance
 - R, L, & C
3. Skin effect
4. Ground planes
5. MOS devices and CMOS
6. Delta-I (ΔI) switching noise

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1. Interconnect modeling

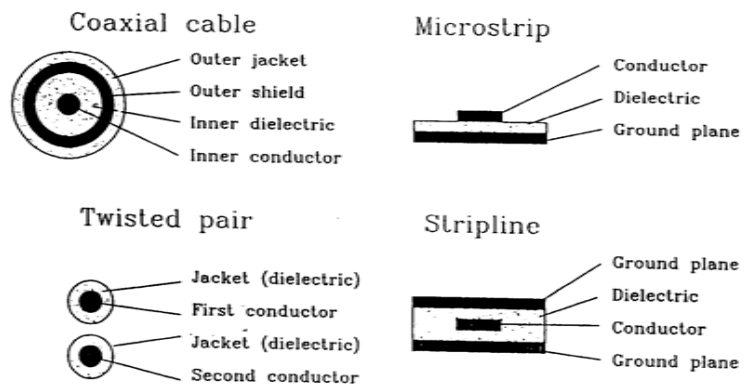


Figure 4.4 Cross sections of popular transmission line geometries.

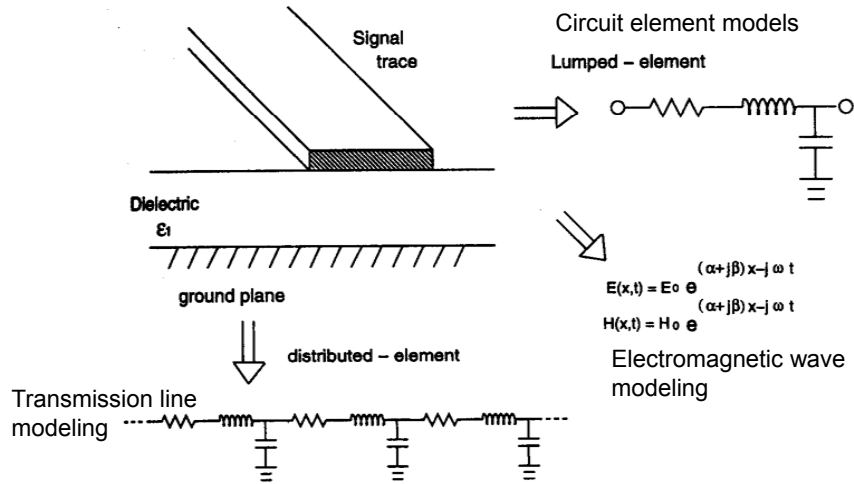
4.2.1 Ideal Distortionless, Lossless Transmission Line

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Three modeling approaches:



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(a) $\omega L \gg R$, (b) $R \gg \omega L$, (c) $R \approx 0$

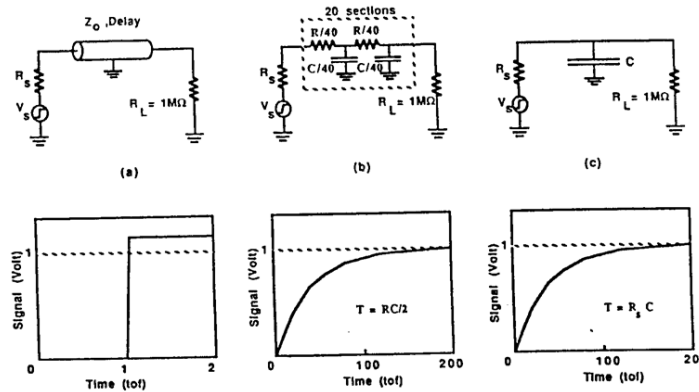


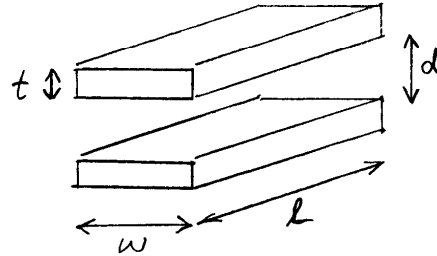
Figure 5-7 Simplified SPICE circuits & signal load responses for limiting propagation regimes. (a) Time-of-flight ($R_s < Z_o$) (b) lossy-line diffusion (c) R_s -limited; time scales are in units of time-of-flights

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2. R, G, L, and C

- Conductor:
 - $R = \rho L/A = \rho L/wt$
 - $R/L = \rho/wt$

- Dielectric:
 - $G = \sigma A/d = \sigma Lw/d$
 - $G/L = \sigma w/d$
 - $C = \epsilon A/d = \epsilon Lw/d$
 - $C/L = \epsilon w/d$



- Note: L=length in this slide; used for inductance later

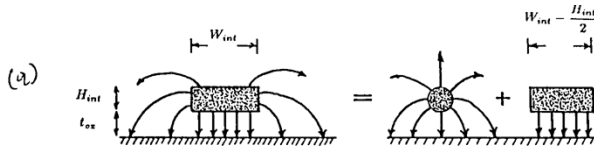
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Capacitance/unit length: Generalized geometries

- (a) "Visual" approximations



- (b) Method of images

- (c) Graphical approximations

- (d) Experimental field plotting

- (e) Numerical techniques (mesh/iteration)

- (f) Analytical: $V = \sum V_i$ for charges Q_i

FIGURE 4.2 Modeling of the contribution of fringing fields to interconnection capacitance. Total wire capacitance can be thought of having two components: a parallel plate capacitance determined by the perpendicular field lines between the wire and the ground plane and a fringing field component, which can be approximated by the capacitance of a cylindrical wire with a diameter equal to interconnection thickness [4.3]. Reprinted by permission of Addison-Wesley Publishing Co.

reduced by $H_{int}/2$ to account for some second-order effects [4.4]. This yields the interconnection capacitance per unit length C_{int} as

$$C_{int} = \epsilon_{ox} \left\{ \frac{W_{int}}{t_{ox}} - \frac{H_{int}}{2t_{ox}} + \frac{2\pi}{\ln \left[1 + \frac{2t_{ox}}{H_{int}} \left(1 + \sqrt{1 + \frac{H_{int}}{t_{ox}}} \right) \right]} \right\}. \quad (4.5)$$

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(g) Method of Moments: Example

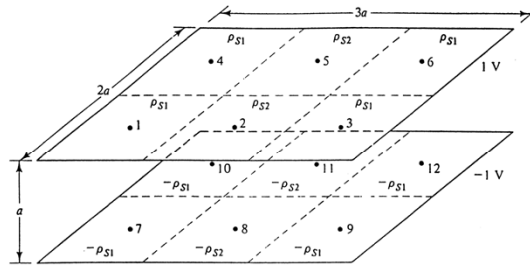


Figure 5.10. For finding the capacitance of a parallel-plate capacitor by the method of moments.

$$\text{For point 2 } \frac{\rho_{s1}a}{\pi\epsilon_0} \ln(1 + \sqrt{2}) + \frac{\rho_{s1}a^2}{4\pi\epsilon_0} \left(\frac{2}{a} + \frac{2}{\sqrt{2}a} - \frac{2}{\sqrt{2}a} - \frac{2}{\sqrt{3}a} \right) + \frac{\rho_{s2}a^2}{4\pi\epsilon_0} \left(\frac{1}{a} - \frac{1}{a} - \frac{1}{\sqrt{2}a} \right) = 1 \quad (5.31b)$$

or

$$2.9101\rho_{s1} + 0.4226\rho_{s2} = \frac{4\pi\epsilon_0}{a} \quad (5.32a)$$

$$0.8453\rho_{s1} + 2.8184\rho_{s2} = \frac{4\pi\epsilon_0}{a} \quad (5.32b)$$

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Method of Moments Example

PARALLEL PLATE CAPACITOR

$$C = \frac{\epsilon A}{d}$$

Field curvature \rightarrow non-uniform surface charge distribution ρ_s

eg. $3a \times 2a \times a$ capacitor. Charges $\rho_{s1}a^2, \rho_{s2}a^2$ by symmetry. Assume charges at center of \square 's.

Potential at point 1 due to ρ_{s1} at point 4 $\rightarrow \frac{(\rho_{s1} \times a^2)}{4\pi\epsilon a}$ distance

Potential at point 1 due to distributed charge $\rho_{s1}a^2$ on square #1 = $\frac{(\rho_{s1} \times a^2)}{\pi\epsilon a} \ln(1 + \sqrt{2})$

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∴ For fixed plate potentials $1_v, -1_v$

$$\text{Square \#1: } V_1 = \frac{\rho_{s1} a}{\pi \epsilon} \ln(1+\sqrt{2}) + \frac{\rho_{s1} a}{4\pi \epsilon} \left(\frac{1}{2} + 1 + \frac{1}{\sqrt{5}} - 1 - \frac{1}{\sqrt{5}} - \frac{1}{\sqrt{2}} \right) + \frac{\rho_{s2} a}{4\pi \epsilon} \left(\frac{1}{2} + \frac{1}{\sqrt{2}} - \frac{1}{\sqrt{2}} - \frac{1}{\sqrt{3}} \right) = 1_v$$

$$\text{Square \#2: } V_2 = \frac{\rho_{s2} a}{\pi \epsilon} \ln(1+\sqrt{2}) + \frac{\rho_{s1} a}{4\pi \epsilon} \left(2 + \frac{2}{\sqrt{2}} - \frac{2}{\sqrt{2}} - \frac{2}{\sqrt{3}} \right) + \frac{\rho_{s2} a}{4\pi \epsilon} \left(1 - 1 - \frac{1}{\sqrt{2}} \right) = 1_v$$

Solve: $\rho_{s1} = 3.8378 \epsilon/a$ $\rho_{s2} = 3.3075 \epsilon/a$

∴ Total $Q = 21.9662 \epsilon a$ & $C = Q/V = 10.983 \epsilon/a$ (cf 6E)

Inductance of a Straight Wire

$\vec{H}(r) = \frac{I}{2\pi r}$
 $0 < r < a \quad H(r) = \frac{\mu_0 I}{2\pi a^2} \cdot I \frac{1}{2\pi r} \hat{\phi} = \frac{I r}{2\pi a^2} \hat{\phi}$
 $a < r < \infty \quad H(r) = \frac{I}{2\pi r} \hat{\phi}$

Magnetic Field

r_w Internal inductance l_i
 External inductance $l_e \Rightarrow l_i$ usually
 $l = l_i + l_e \approx l_e$
 Also $l_e g = \mu_0 \epsilon$
 $l_e c = \mu \epsilon$

g, c leakage conduct/capac
 σ, ϵ, μ for external medium

$\oint_C \vec{H} \cdot d\vec{l} = I_{\text{enclosed}}$ Circular contour at r
 $H(r) \cdot 2\pi r = I$
 $H(r) = \frac{I}{2\pi r}$

Internal Inductance

low freq - uniform current.

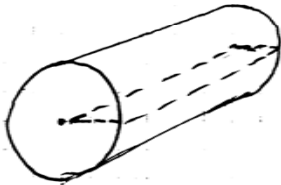
$$I_{\text{encl},i} = \pi r^2 \left(\frac{I}{\pi r_w^2} \right) = I \left(\frac{r}{r_w} \right)^2$$

$$\therefore H(r) \cdot 2\pi r = I \left(\frac{r}{r_w} \right)^2 \rightarrow H(r) = \frac{I}{2\pi r_w^2} \cdot r$$

&

$$\Psi_i = \int_S \underline{B}(r) \cdot d\underline{s} \Rightarrow \Psi_i \cdot L = \int_0^{r_w} \frac{I}{2\pi r_w^2} r \cdot L dr$$

↑
per unit length



$$\Psi_i = \frac{\mu_0 I}{4\pi}$$

$$L_i = \frac{\mu_0}{4\pi} \text{ H/m}$$

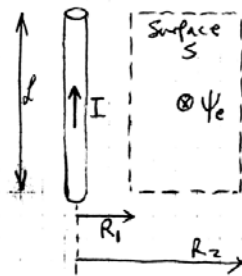
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External Inductance: Basic formula

Need to find total external flux



$$\begin{aligned} \Psi_e &= \int_S \underline{B}(r) \cdot d\underline{s} \\ &= \int_{R_1}^{R_2} \mu_0 \frac{I}{2\pi r} dr \\ &= \frac{\mu_0 I}{2\pi} \ln \left(\frac{R_2}{R_1} \right) \end{aligned}$$

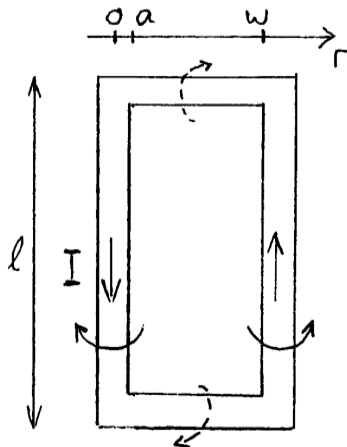
Note: To find $L_e = \frac{\Psi_e}{I} = \frac{\mu_0}{2\pi} \ln \left(\frac{R_2}{R_1} \right)$
over all space ($R_2 \rightarrow \infty$, $R_1 = r_w$)
requires assumption of specific geometries

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Compare:-



$$L = \frac{\phi}{I} = \frac{1}{I} \int_S \vec{B} \cdot d\vec{S}$$

$$= \frac{\mu}{I} \int \vec{H} \cdot d\vec{S}$$

$$\approx \frac{2\mu l}{I} \left[\int_0^a \frac{I r}{2\pi a^2} dr + \int_a^w \frac{I}{2\pi r} dr \right]$$

$$L/l = 2 \left[\frac{\mu}{4\pi} \left(1 + 2 \ln \frac{w}{a} \right) \right]$$

Hence "partial" inductance

$$L = \frac{\mu_0}{4\pi} + \frac{\mu_0}{2\pi} \ln \frac{w}{a}$$

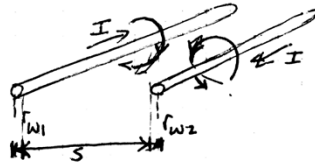
$$= L_i + L_e \approx L_e$$

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External Inductance: 2-wire line

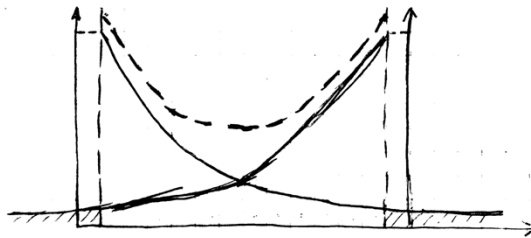
(a) 2-wire line

Total flux between wires



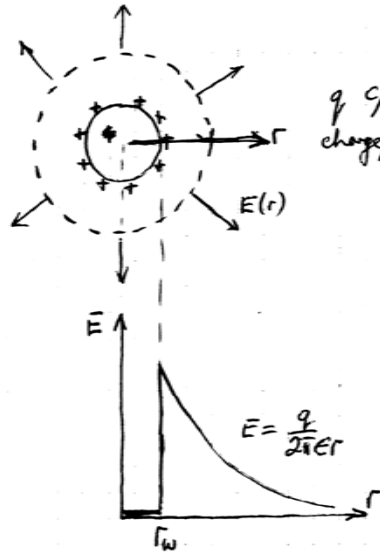
$$L_e = \frac{\phi_e}{I} = \frac{\mu_0 I}{2\pi} \left[\ln \left(\frac{s+r_{w1}}{r_{w1}} \right) + \ln \left(\frac{s+r_{w2}}{r_{w2}} \right) \right]$$

$$\Rightarrow s \gg r_{w1}, r_{w2} = r_w \quad \frac{\mu_0 I}{2\pi} \ln \frac{s^2}{r_w^2} = \frac{\mu_0 I}{\pi} \ln \frac{s}{r_w}$$



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Straight Wire: Radial Electric Field



q C/m
charge/unit length

$$\oint_S \vec{E} \cdot d\vec{s} = Q_{\text{encl.}}$$

$$\epsilon E (2\pi r \times L) = q \times L$$

$$\therefore E(r) = \frac{q}{2\pi\epsilon r}$$

$$\& V = - \int_C \vec{E} \cdot d\vec{l}$$

$$= - \int_{R_2}^{R_1} \frac{q}{2\pi\epsilon r} dr$$

$$= \frac{q}{2\pi\epsilon} \ln\left(\frac{R_2}{R_1}\right)$$

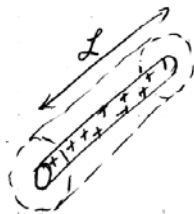
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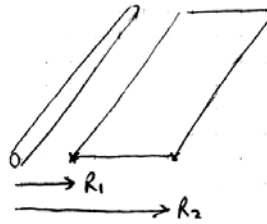
Magnetic and Electric Fields:

$$(2\pi)^{-1} \ln(R_2/R_1) = \epsilon V/q \text{ (electric)} = \psi_e / I \mu_0$$



$$Q_{\text{encl}} = qL$$

$$\text{Area} = 2\pi r \times L$$



$$\& \text{note } \frac{V}{q} = \frac{\psi_e}{\mu_0 I}$$

$$L_e = \frac{\psi_e}{I} = \mu_0 \epsilon \frac{V}{q} = \mu_0 \epsilon C^{-1}$$

↑ Capac/unit length

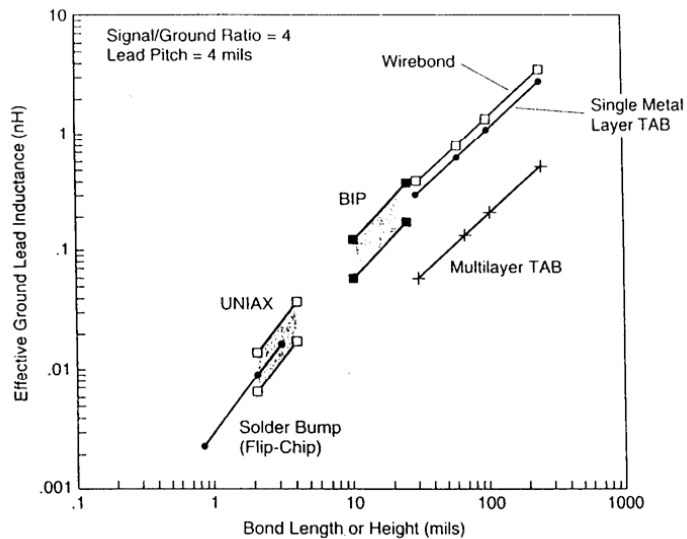
i.e. $L_e C = \text{constant} = \mu_0 \epsilon$

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Lead inductances



3. Skin Effect

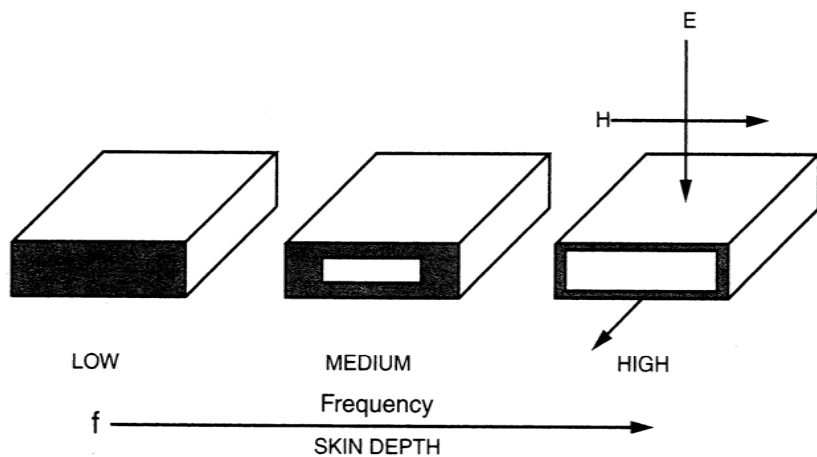


FIGURE 13.19 Effect of frequency on conductor cross section.

8. SKIN EFFECT



Consider wire to consist of concentric cylinders

Inductance of outer rings < Inductance of center rings

At high frequency, f current path seeks lower inductance \rightarrow outer "skin"

$$\text{SKIN DEPTH } \delta = \left(\frac{2\rho}{\omega\mu} \right)^{1/2}$$

As current area decreases, resistance increases ($R = \rho \ell / A$)

$$R \propto 1/\delta \propto \text{freq}^{1/2}$$

$$\text{and } L_{\text{SKIN}} \propto \text{freq}^{-1/2}$$

$$\text{Skin Reactance } \omega L_{\text{SKIN}} \propto \text{freq}^{1/2}$$

$$(L_{\text{internal}} \ll L_{\text{external}})$$

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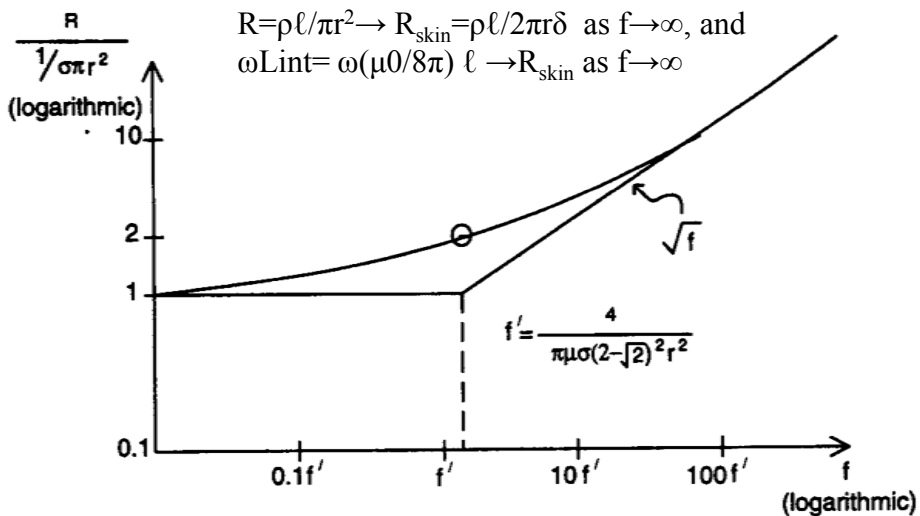


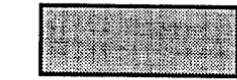
Figure 2.25 $R(f)$ for a wire of circular cross section, radius r .

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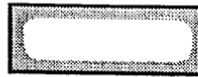
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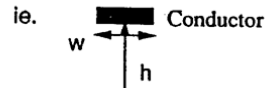
8. Skin Effect.



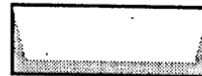
Current Distribution in the conductor at low frequencies.



Current distribution in the conductor at high frequencies (skin effect.) when $w/h \rightarrow 0$



Ground plane



Current distribution in the conductor at high frequencies (skin effect.) when $w/h \rightarrow \text{infinity}$



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Figure 7.5 The skin effect.

4. Ground planes

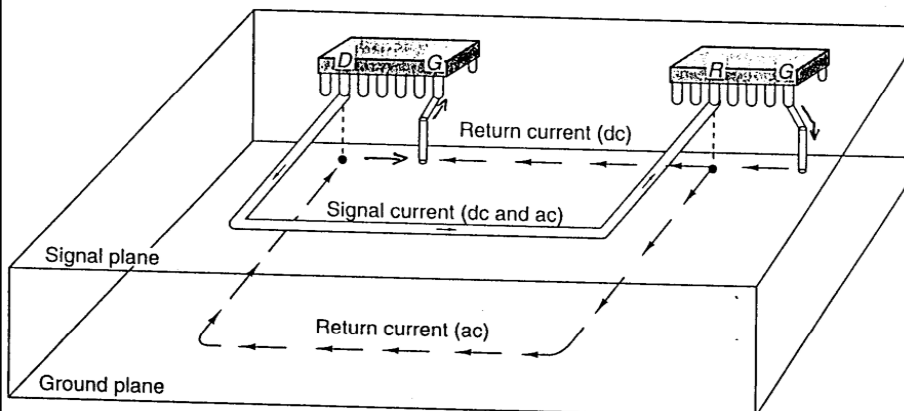


Figure 8.16 Paths for dc and ac ground returns on a multilayer board.

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Loss of coupled return → inductance, EMI

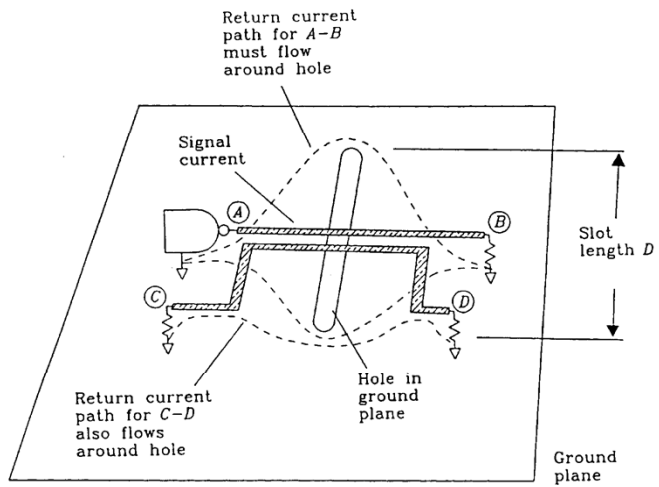


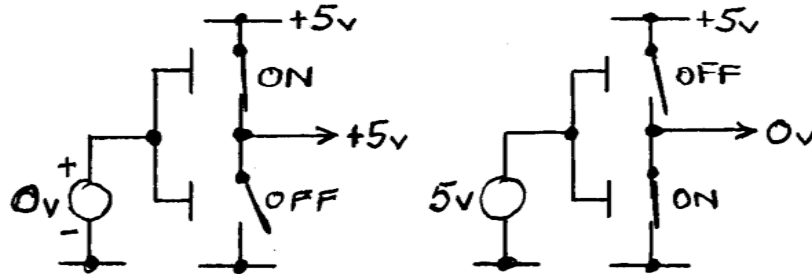
Figure 5.8 Crosstalk in a slotted ground plane.

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5. MOS devices and CMOS



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Derivation of MOSFET characteristic equations

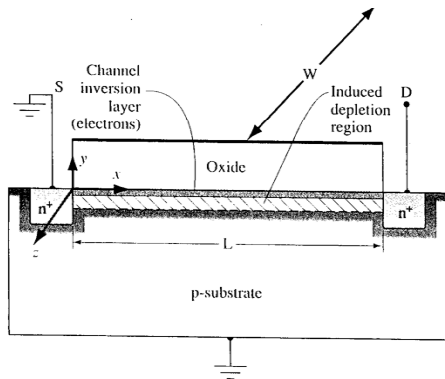


Figure 10.42 Geometry of a MOSFET for I_D versus V_{DS} derivation

$$I(x) = \int_y \int_z J(x) dy dz$$

$$= W \cdot \mu \int_y \sigma(x) \frac{dV(x)}{dx} dy$$

$$I(x) dx = \mu W q(x) dV(x)$$

$$\text{and } q(x) = \frac{C_{ox}}{e} [V_G - V(x)]$$

$$= C_{ox} [(V_G - V_T) - V(x)]$$

$$I_{DS} \int_0^L dx = \mu W C_{ox} \int_0^{V_{DS}} [(V_G - V_T) - V(x)] dV_x$$

$$I_{DS} \cdot L = \mu W C_{ox} [(V_G - V_T)V_{DS} - \frac{V_{DS}^2}{2}]$$

$$I_{DS} = \frac{\mu}{2} \frac{W}{L} C_{ox} [2(V_G - V_T) - V_{DS}] V_{DS}$$

$$\frac{\partial I_{DS}}{\partial V_{DS}} = \mu \frac{W}{L} C_{ox} [(V_G - V_T) - V_{DS}]$$

$$\rightarrow 0 \text{ when } V_{DS} = V_G - V_T$$

$$\text{Substitute: } I_{DS} \text{ SAT} = \frac{\mu}{2} \frac{W}{L} C_{ox} (V_G - V_T)^2$$

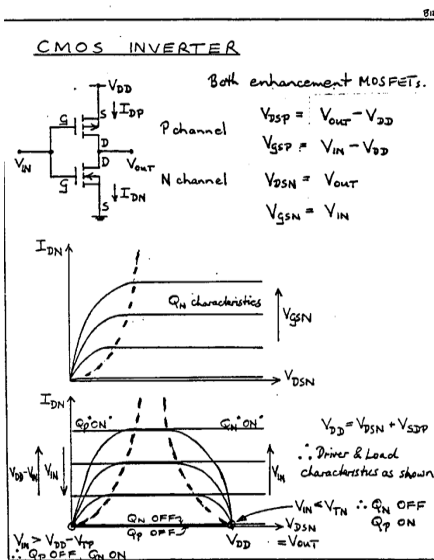
$$= \frac{\mu}{2} \frac{W}{L} C_{ox} V_{DS}^2$$

Now set $(\mu W/2L)C_{ox} = k \rightarrow$

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CMOS dynamic characteristics (part 1)



CMOS INVERTER (cont)

As V_{in} increases from 0 volts :-

(i) For $V_{in} < V_{TN}$, Q_N OFF $\therefore I = 0$

$\therefore V_{GSP} = V_{in} - V_{DD} = -V_{DD}$, Q_P not saturated.

$V_{out} = V_{DD}$ - see diagram.

(ii) For $V_{in} > V_{TN}$, Q_N begins to turn ON

(for Q_N saturated, Q_P not saturated - see diagram for $V_{in} < V_{DSP} + V_{TN}$)

$\therefore I_{DN} = I_{DP}$

gives $k_N (V_{GSN} - V_{TN})^2 = k_P [2(V_{GSP} - V_{TP})V_{DSP} - V_{DSP}^2]$

$\Rightarrow k_P [2(V_{GSP} + V_{TP})V_{DSP} - V_{DSP}^2]$

$k_N (V_{in} - V_{TN})^2 = k_P [2(V_{DD} - V_{in} + V_{TP})(V_{DD} - V_{out}) - (V_{DD} - V_{out})^2]$

$\therefore V_{out} = V_{DD} + (V_{DD} - V_{in} + V_{TP}) - \frac{k_N}{k_P} (V_{in} - V_{TN})^2$

NB. $V_{TN} > 0$

$V_{TP} < 0$ } for enhancement

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CMOS dynamic characteristics (part 2)

CMOS INVERTER (cont.)

(iii) Middle region, Q_N & Q_P both saturated.

Q_P saturates when $V_{S5P} = V_{S5P} - V_{TP}$

ie. when $V_{DD} - V_{THP} = V_{DD} - V_{OUT} - V_{TP}$
 $V_{IN} = V_{OUT} + V_{TP}$

Q_N goes out of saturation when $V_{S5N} = V_{S5N} + V_{TN}$

ie. when $V_{IN} = V_{OUT} + V_{TN}$

In region (iii) with both transistors saturated $I_{DP} = I_{DN}$

$$k_p (V_{S5P} + V_{TP})^2 = k_n (V_{S5N} - V_{TN})^2$$

$$k_p (V_{DD} - V_{IN} + V_{TP})^2 = k_n (V_{IN} - V_{TN})^2$$

$$V_{IN} = \frac{V_{DD} + V_{TP} + (\frac{k_n}{k_p})^{1/2} V_{TN}}{1 + (\frac{k_n}{k_p})^{1/2}}$$

NB. only V_{IN} defined, V_{OUT} changes abruptly.

NB. Need this transition at $V_{IN} = V_{DD}/2$ for symmetry ie. need:

$k_n = k_p$ ← Since $M_n \neq M_p$, need different geometries (P channel area > N channel area)
 & $V_{TP} = -V_{TN}$

CMOS INVERTER (cont.)

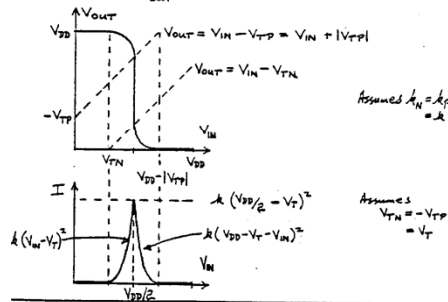
(iv) Q_N goes out of saturation
 Q_P still saturated

Complement of region (iii). Following same sequence:

$$V_{OUT} = (V_{IN} - V_{TN}) - \left[(V_{IN} - V_{TN})^2 - \left(\frac{k_p}{k_n}\right) (V_{DD} - V_{IN} + V_{TP})^2 \right]^{1/2}$$

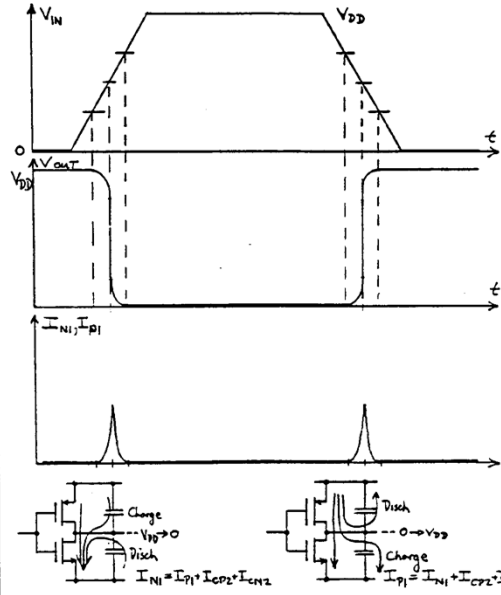
(v) When $V_{IN} > V_{DD} - V_{TP}$, Q_P turned OFF

$\therefore V_{OUT} = 0$



Switching current (1)

CMOS TRANSIENTS



Switching current (2)

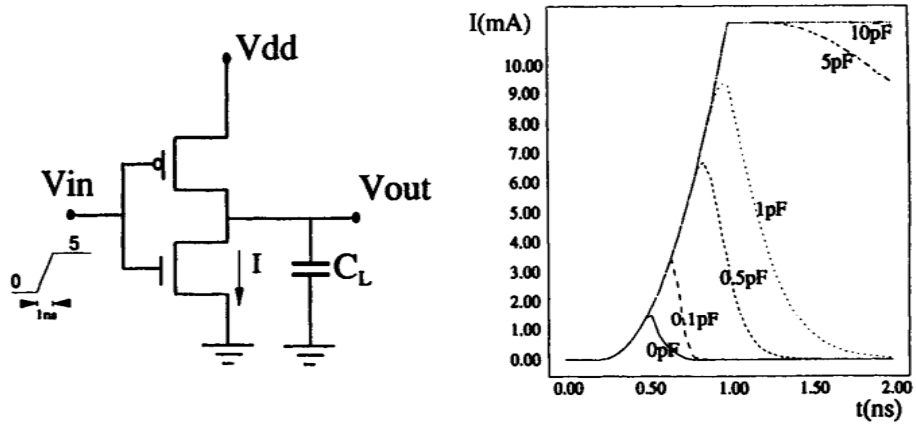


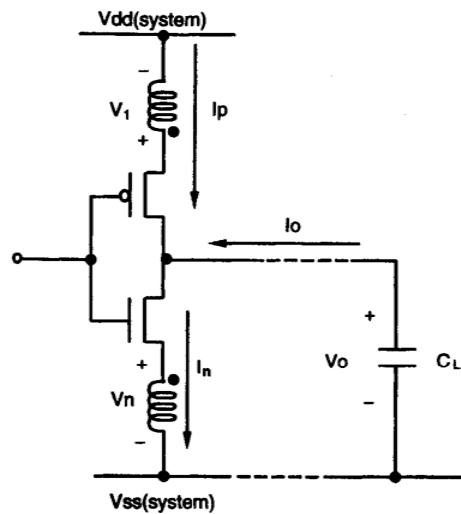
Figure 2.75 N-channel MOSFET current for various sizes of C_L .

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6. Delta-I (ΔI) switching noise



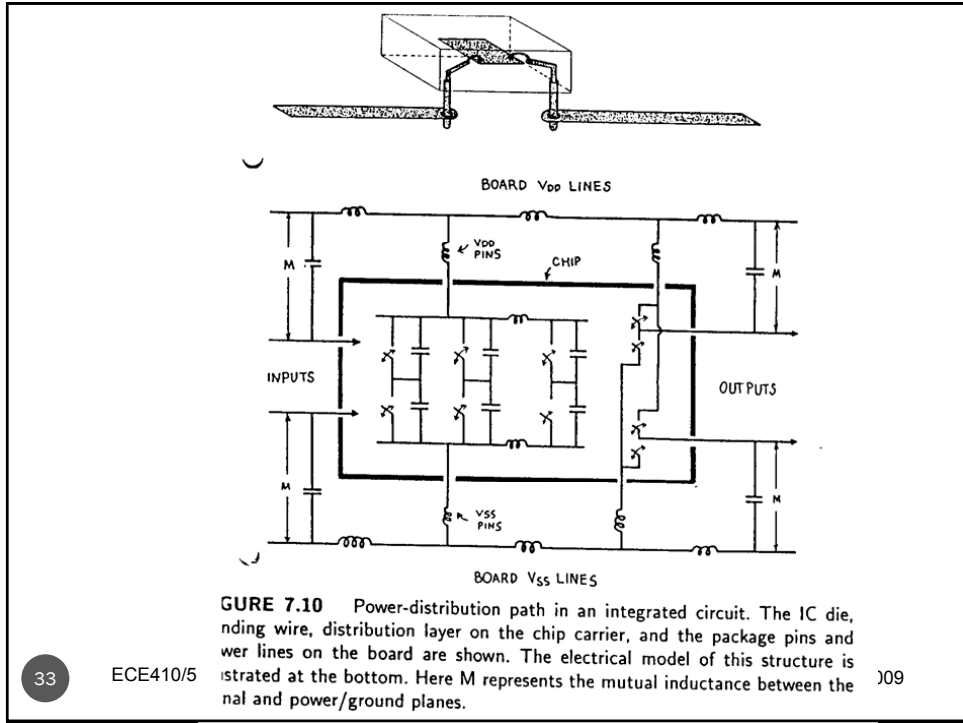
$$\Delta V = L \frac{di}{dt}$$

Figure 2.83 Driver circuit for the calculation of the mutual effect between L_{vss} and L_{vdd} on V_n .

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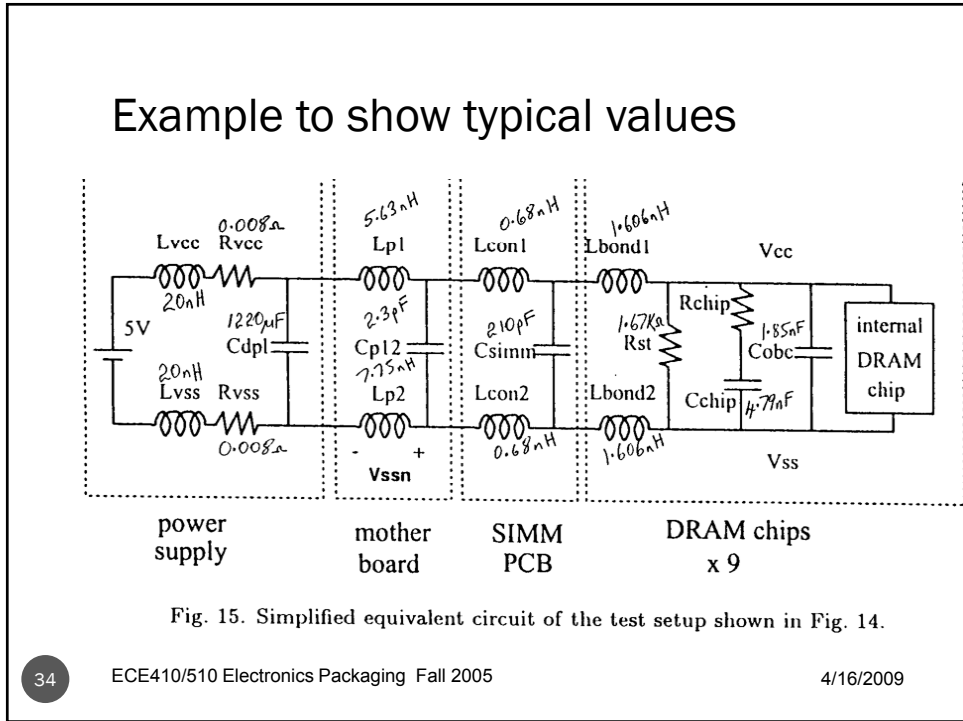
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B/C/D. Transmission line effects

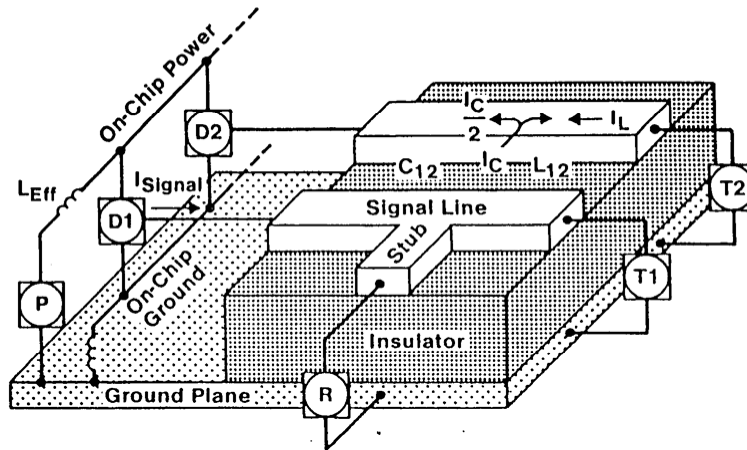


Figure 1-12. Causes of Reflected, Coupled, and Switching (ΔI) Noises.

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Lecture topics B: Transmission lines

(Z_0 , velocity, lossless, lossy)

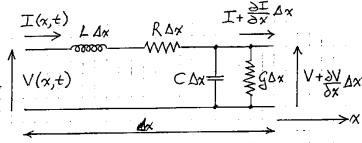
1. Transmission line theory
 - Characteristic impedance Z_0
 - Attenuation, dispersion, velocity
2. Z_0 calculations
3. Lossless line
 - Distortionless transmission
 - Shape factor
4. Z_0 for practical geometries
5. Effects of loss
 - Distortion

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1. Transmission line theory



$$V - (V + \frac{\partial V}{\partial x} \Delta x) = R \Delta x I + L \Delta x \frac{\partial I}{\partial t}$$

$$\text{ie. } -\frac{\partial V}{\partial x} = R I + L \frac{\partial I}{\partial t}$$

$$\text{Assume } V(x,t) = V(x) e^{j\omega t}$$

$$I(x,t) = I(x) e^{j\omega t}$$

$$\text{then } -\frac{\partial V(x)}{\partial x} = (R + j\omega L) I(x)$$

And similarly

$$I - (I + \frac{\partial I}{\partial x} \Delta x) = G \Delta x V + C \Delta x \frac{\partial V}{\partial t}$$

$$\text{gives } -\frac{\partial I(x)}{\partial x} = (G + j\omega C) V(x)$$

These give

$$\frac{d^2 V(x)}{dx^2} = (R + j\omega L)(G + j\omega C) V(x)$$

$$\& \frac{d^2 I(x)}{dx^2} = (G + j\omega C)(R + j\omega L) I(x)$$

2nd order differential equation has solution:

$$V(x) = A e^{-\lambda x} + B e^{+\lambda x}$$

$$\text{where } \lambda = [(R + j\omega L)(G + j\omega C)]^{1/2}$$

$$\text{ie. } V(x,t) = V(x) e^{j\omega t} = A e^{j\omega t - \lambda x} + B e^{j\omega t + \lambda x}$$

Forward wave (damped λ) Reverse wave (damped λ)

$$\text{Similarly } I(x) = -(R + j\omega L)^{-1} \frac{dV(x)}{dx}$$

$$= -\frac{[-A e^{-\lambda x} + B e^{+\lambda x}] \lambda}{(R + j\omega L)}$$

$$= \frac{A e^{-\lambda x} - B e^{+\lambda x}}{(R + j\omega L)^{1/2}} (G + j\omega C)^{1/2}$$

$$= \frac{A e^{-\lambda x} - B e^{+\lambda x}}{Z_0}$$

where the Characteristic Impedance is

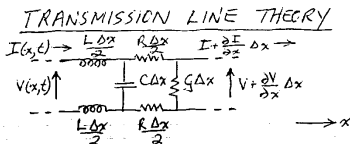
$$Z_0 = \sqrt{\frac{R + j\omega L}{G + j\omega C}}$$

Note: units Ω

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Summary



$$V(x,t) = A e^{j\omega t - \lambda x} + B e^{j\omega t + \lambda x}$$

$$I(x,t) = \frac{A e^{j\omega t - \lambda x}}{Z_0} - \frac{B e^{j\omega t + \lambda x}}{Z_0}$$

where

$$Z_0 = \sqrt{\frac{R + j\omega L}{G + j\omega C}} \quad (\text{units } \Omega)$$

Characteristic Impedance

&

$$\lambda = \sqrt{(R + j\omega L)(G + j\omega C)}$$

$$= \alpha + j\beta$$

Attenuation Dispersion

$$\text{wave velocity } v = \omega/\beta$$

Attenuation, dispersion, velocity:-

$$\lambda = [(R + j\omega L)(G + j\omega C)]^{1/2}$$

$$\text{write } \lambda = \alpha + j\beta$$

Real part α is attenuation

Imag. part β is dispersion

$$\lambda^2 = \alpha^2 - \beta^2 + 2j\beta\alpha = (RG - \omega^2 LC) + j\omega(RC + GL)$$

$$\therefore \alpha^2 - \beta^2 = RG - \omega^2 LC$$

$$2\alpha\beta = \omega(RC + GL)$$

$$\text{Substitute for } \beta = \frac{\omega}{2\alpha}(RC + GL)$$

$$\alpha^2 - \frac{\omega^2}{4\alpha^2}(RC + GL)^2 = (RG - \omega^2 LC)$$

$$(\alpha^2)^2 - (\alpha^2)(RG - \omega^2 LC) - \frac{\omega^2}{4}(RC + GL)^2 = 0$$

$$\alpha^2 = \frac{1}{2} \{ (RG - \omega^2 LC) \pm [(RG - \omega^2 LC)^2 + \omega^2 (RC + GL)^2]^{1/2} \}$$

$$\& \beta^2 = \alpha^2 - (RG - \omega^2 LC)$$

$$= \frac{1}{2} \{ -(RG - \omega^2 LC) \pm [(RG - \omega^2 LC)^2 + \omega^2 (RC + GL)^2]^{1/2} \}$$

By comparison with standard wave equations:

$$V(x,t) = A e^{j\omega t - \lambda x} = A e^{j\omega t} e^{-(\alpha + j\beta)x}$$

$$= A e^{-\alpha x} e^{j\omega(t - \beta x)}$$

$$\text{ie. velocity } v = \omega/\beta$$

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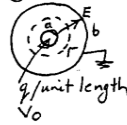
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2. Z_0 calculations

- Need L, C
- Also gives β , v
- Easiest geometry is coaxial line
 - (radial symmetry)

(a) Dielectric: C/unit length

GAUSS'S LAW $\oint \epsilon \vec{E} \cdot d\vec{s} = \sum q_i$



$$\epsilon E \cdot 2\pi r(\ell) = q(\ell)$$

$$\therefore E = \frac{q}{2\pi\epsilon} \cdot \frac{1}{r}$$

$$\therefore V_0 = -\int_b^a E \cdot dr = \frac{q}{2\pi\epsilon} \ln \frac{b}{a}$$

Capacitance/unit length $C = q/V_0 = 2\pi\epsilon / \ln(b/a)$

(b) Leakage conductance: G/unit length

(b) FOR LEAKAGE CONDUCTANCE: G /unit length



Current density $\vec{J} = \sigma \vec{E}$

& using E, V_0 from above $E = \frac{1}{r} \frac{V_0}{\ln(b/a)}$

$$\begin{aligned} \text{Conductance/unit length } G &= I/V_0 = \frac{\int J(r) \cdot 2\pi r \cdot \ell / \ell}{V_0} \\ &= \frac{\sigma}{V_0} \cdot 2\pi r \cdot \frac{1}{r} \cdot \frac{V_0}{\ln(b/a)} \\ &= 2\pi\sigma / \ln(b/a) \end{aligned}$$

Note: for $G \ll \omega C$ need $\sigma \ll \omega \epsilon$
or $\omega \gg \sigma/\epsilon$

(c) Inductance: L/unit length

(c) FOR INDUCTANCE: L/unit length



$$B = \mu H = \mu \frac{I}{2\pi r} \quad I = \int H \cdot ds$$

$$\text{Magnetic flux } \phi = \int_a^b B dr = \int_a^b \frac{\mu I}{2\pi} \ln(b/a)$$

$$L = \frac{\phi \ell}{I} = \frac{\mu}{2\pi} \ln(b/a) \text{ /unit length.}$$

3. Lossless lines

In practice $G \ll \omega C$ in practical systems

ie. set $G \approx 0$

$$Z_0 \Rightarrow \sqrt{\frac{L}{C} + \left(\frac{R}{\omega C}\right)}$$

$$\alpha^2 \Rightarrow \frac{1}{2} \omega^2 LC \left\{ \left[1 + \left(\frac{R}{\omega L}\right)^2 \right]^{1/2} - 1 \right\}$$

$$\beta^2 \Rightarrow \frac{1}{2} \omega^2 LC \left\{ \left[1 + \left(\frac{R}{\omega L}\right)^2 \right]^{1/2} + 1 \right\}$$

In practice $G \ll \omega C$ ie. set $G \approx C$

Also usually assume $R \ll \omega L$ for simplicity
(not always a valid assumption)

ie. set $R \approx 0$

Then:

$$Z_0 \Rightarrow \sqrt{L/C} \quad \text{Real, but non-dissipative}$$

$$\alpha \Rightarrow 0 \quad \text{ie. lossless}$$

$$\beta \Rightarrow \omega \sqrt{LC}$$

$$\text{and } v \Rightarrow \frac{\omega}{\omega \sqrt{LC}} = \frac{1}{\sqrt{LC}}$$

eg. Coaxial line



$$L = \frac{\mu}{2\pi} \ln(b/a) \text{ H/m}$$

$$C = 2\pi\epsilon / \ln(b/a) \text{ F/m}$$

$$\therefore Z_0 = \sqrt{\frac{\mu}{\epsilon}} \frac{\ln(b/a)}{2\pi}$$

$$= \sqrt{\frac{\mu}{\epsilon}} \times \text{Shape factor}$$

$$= \sqrt{\frac{\mu_0}{\epsilon_0}} \times \frac{\text{Shape factor}}{\sqrt{\epsilon_r}}$$

$$= 376.7 \Omega \left(\frac{S \cdot F}{\epsilon_r} \right)^{1/2}$$

$$\begin{aligned} v &= \frac{1}{\sqrt{\mu\epsilon}} \\ &\approx \left(\frac{\mu_0 \epsilon_0}{\mu \epsilon_r} \right)^{-1/2} \\ &= \frac{c}{\sqrt{\epsilon_r}} \end{aligned}$$

TABLE 5.2 CONDUCTANCE, CAPACITANCE, AND INDUCTANCE PER UNIT LENGTH FOR SOME STRUCTURES CONSISTING OF INFINITELY LONG CONDUCTORS HAVING THE CROSS SECTIONS SHOWN IN FIG. 5.12

Description	Capacitance per unit length, \mathcal{C}	Conductance per unit length, \mathcal{G}	Inductance per unit length, \mathcal{L}
Parallel-plane conductors, Fig. 5.12(a)	$\epsilon \frac{w}{d}$	$\sigma \frac{w}{d}$	$\mu \frac{d}{w}$
Coaxial cylindrical conductors, Fig. 5.12(b)	$\frac{2\pi\epsilon}{\ln(b/a)}$	$\frac{2\pi\sigma}{\ln(b/a)}$	$\frac{\mu}{2\pi} \ln \frac{b}{a}$
Parallel cylindrical wires, Fig. 5.12(c)	$\frac{\pi\epsilon}{\cosh^{-1}(d/a)}$	$\frac{\pi\sigma}{\cosh^{-1}(d/a)}$	$\frac{\mu}{\pi} \cosh^{-1} \frac{d}{a}$
Eccentric inner conductor, Fig. 5.12(d)	$\frac{2\pi\epsilon}{\cosh^{-1}\left(\frac{a^2+b^2-d^2}{2ab}\right)}$	$\frac{2\pi\sigma}{\cosh^{-1}\left(\frac{a^2+b^2-d^2}{2ab}\right)}$	$\frac{\mu}{2\pi} \cosh^{-1} \frac{a^2+b^2-d^2}{2ab}$
Shielded parallel cylindrical wires, Fig. 5.12(e)	$\frac{\pi\epsilon}{\ln \frac{d(b^2-d^2/4)}{a(b^2+d^2/4)}}$	$\frac{\pi\sigma}{\ln \frac{d(b^2-d^2/4)}{a(b^2+d^2/4)}}$	$\frac{\mu}{\pi} \ln \frac{d(b^2-d^2/4)}{a(b^2+d^2/4)}$

4. Practical Z_0

For $Z_0 = [376.7/\sqrt{\epsilon_r}] \times sf \ \Omega$

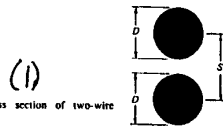


Figure E-2 Cross section of two-wire transmission line

The shape factor of the transmission line, sf , depends only on the shapes, sizes, and positions of the conductors. Two-wire transmission line (Figure E-2) has shape factor

$$sf = \frac{1}{\pi} \ln \left[\frac{S}{D} + \left(\frac{S^2}{D^2} - 1 \right)^{1/2} \right]$$

when both wires have diameter D . When the wires have diameters $D1$ and $D2$, the shape factor becomes

$$sf = \frac{1}{2\pi} \ln [x + (x^2 - 1)^{1/2}]$$

where

$$x = \frac{4S^2 - D1^2 - D2^2}{2D1D2}$$

(2) Twisting a two-wire transmission line to form a twisted-pair increases the average relative permittivity ϵ_r . For hard insulation with relative permittivity ϵ_r ,

$$\epsilon_r \approx 1 + (0.25 + 0.0004\Theta^2)(\epsilon_r - 1),$$

and for soft insulation (Teflon, polyvinyl chloride)

$$\epsilon_r \approx 1 + (0.25 + 0.001\Theta^2)(\epsilon_r - 1),$$

$$\Theta = \arctan(\pi S n) \text{ degrees,}$$

and n is the number of twists per meter.

(3) A wire near a ground plane (Figure E-3) has shape factor

$$sf = \frac{1}{2\pi} \ln \left[\frac{2S}{D} + \left(\frac{4S^2}{D^2} + 1 \right)^{1/2} \right]$$

(4) A laminar bus (Figure E-4) has shape factor

$$sf \approx \frac{1}{\pi} \ln \left(\frac{4S}{W} + \frac{W}{2S} \right) \text{ for } W \approx \frac{S}{2}, T \ll W,$$

$$sf \approx \frac{2}{\frac{2W}{S} + 2.42 - \frac{0.22S}{W} + \left(1 - \frac{S}{2W}\right)^6} \text{ for } W > \frac{S}{2}, T \ll W.$$

If an insulator separates the conductors (Figure E-1(c)),

$$\epsilon_r \approx \frac{\epsilon_r + 1}{2} + \frac{\epsilon_r - 1}{\left(4 + 20 \frac{S}{W}\right)^{1/2}}$$

(5) Microstrip (Figure E-5) has shape factor

$$sf \approx \frac{1}{2\pi} \ln \left(\frac{8S}{W} + \frac{W}{4S} \right) \quad \text{for } W \leq S, T \ll W,$$

$$sf \approx \frac{1}{\frac{W}{S} + 2.42 - \frac{0.44S}{W} + \left(1 - \frac{S}{W}\right)^6} \quad \text{for } W > S, T \ll W.$$

If an insulator separates the conductors (Figure E-1(c)),

$$\epsilon_r \approx \frac{\epsilon_r + 1}{2} + \frac{\epsilon_r - 1}{\left(4 + 40 \frac{S}{W}\right)^{1/2}}.$$

(6) Coplanar lines (Figure E-6) have shape factor

$$sf \approx \frac{1}{\pi} \ln \left[2 \frac{\left(\frac{2W}{S} + 1\right)^{1/2} + 1}{\left(\frac{2W}{S} + 1\right)^{1/2} - 1} \right] \quad \text{for } W \leq 2.414S, T \ll W,$$

$$sf \approx \frac{\pi}{4 \ln \left[2 \left(\frac{2W}{S} + 1\right)^{1/2} \right]} \quad \text{for } W > 2.414S, T \ll W.$$

If the lines are supported by an insulator on one side,

$$1 < \epsilon_r < \frac{\epsilon_r + 1}{2}.$$

(7) Triplate stripline (Figure E-7) has shape factor

$$sf \approx \frac{1}{2\pi} \ln \left[\frac{\exp\left(\frac{\pi W}{4S}\right) + 1}{\exp\left(\frac{\pi W}{4S}\right) - 1} \right] \quad \text{for } W \leq 1.117S, T \ll S,$$

$$sf \approx \frac{1}{1.765 + \frac{2W}{S}} \quad \text{for } W > 1.117S, T \ll S.$$

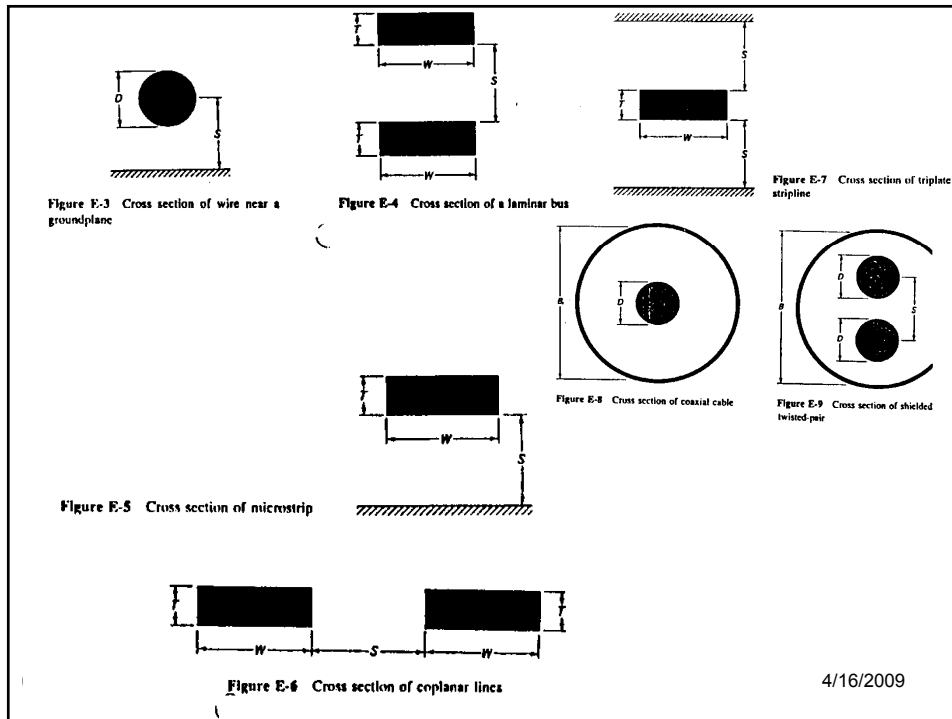
(8) Coaxial cable (Figure E-8) has shape factor

$$sf = \frac{1}{2\pi} \ln \left(\frac{B}{D} \right).$$

(9) Shielded twisted-pair (Figure E-9) has shape factor

$$sf = \frac{1}{\pi} \ln \left(\frac{2S}{D} \frac{B^2 - S^2}{B^2 + S^2} \right).$$

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5. Lossy lines

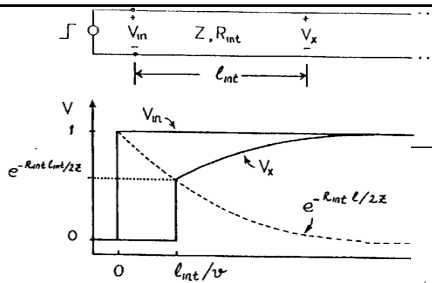


FIGURE 6.10 Waveforms in a lossy transmission line

The response of this line to a unit step input at a distance x from the beginning of the line is [6.1]:

$$V(x, t) = \left\{ e^{-Rx/2Z_0} + \frac{Rx}{2Z_0} \int_{t=x\sqrt{LC}}^t \left[\frac{e^{-Rt/2L}}{\sqrt{t^2 - x\sqrt{LC}}} \frac{I_1 R}{2L} \sqrt{t^2 - x\sqrt{LC}} \right] dt \right\} \times u(t - x\sqrt{LC})$$

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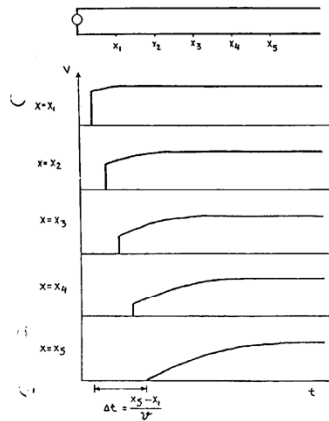


FIGURE 6.11 Waveform propagating along a lossy transmission line. The input to the transmission line is a unit voltage step, and the response is captured at successive points along the line. The size of the step is attenuated as the waveform travels down the line, and at a point far enough from the source, the response is like that of a distributed RC line.

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Lecture topics C: Transmission lines

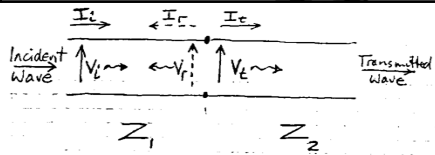
Transmission line reflections

1. Reflection coefficients
2. Basic cases:
 - Matched and open circuit
3. Generalized mismatches
 - Source and load
4. Bounce chart/lattice diagram
5. Reflections from discontinuities

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At discontinuity $Z_1 \rightarrow Z_2$
 and the relationships of the incident wave $V_i = I_i Z_1$
 cannot be maintained in the transmitted wave $V_t = I_t Z_2$
 without changes in V, I . Solution requires
 reflected wave $V_r = I_r Z_1$

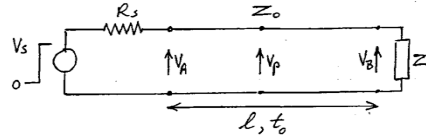
Boundary conditions $V_i + V_r = V_t$
 $I_i - I_r = I_t$

Gives $V_r = \frac{Z_2 - Z_1}{Z_2 + Z_1} V_i = \Gamma_V V_i$
 (Voltage) Reflection Coefficient
 & $I_r = \frac{Z_2 - Z_1}{Z_2 + Z_1} I_i = \Gamma_I I_i$
 (Current) Reflection Coefficient

Voltage transmission coefficient $V_t/V_i = 1 + \Gamma_V$

Voltage reflection at load $\Gamma_L = \frac{Z_L - Z_0}{Z_L + Z_0} \rightarrow 0$ for $Z_L = Z_0 = R_0$
 " " " source $\Gamma_S = \frac{R_S - Z_0}{R_S + Z_0} \rightarrow 0$ for $R_S = Z_0$

1. Reflection Coefficient



At source end: $V_i = \frac{Z_0}{R_s + Z_0} V_s$

Along line: $V_p = \frac{Z_0}{Z_0 + Z_0} 2V_i = V_i$
 V_i is propagating signal. Need equivalent of source.

At load end: $V_t = \frac{Z_L}{Z_0 + Z_L} 2V_i$
 $\rightarrow V_t = V_i$ if $Z_L = Z_0$

2. 3 significant cases:

$\Gamma_{VL} = (R_L - Z_0) / (R_L + Z_0)$

- Load $R_L = Z_0$ (above) $\Gamma_{VL} = 0$
- Open circuit load:
 - $R_S = Z_0$ ($\Gamma_{VS} = 1$)
 - $R_S = 0$ ($\Gamma_{VS} = -1$)
- Short circuit load $R_L = 0$, $\Gamma_{VL} = -1$

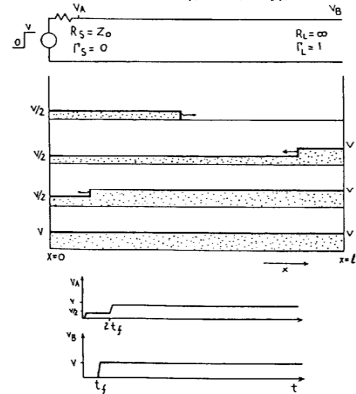


FIGURE 6.18 Termination at the source end: $R_S = Z_0, R_L = \infty$

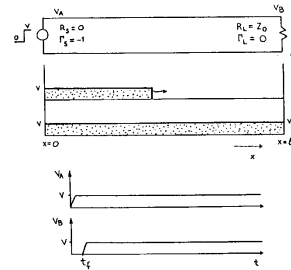


FIGURE 6.17 Termination at the receiving end: $R_S = 0, R_L = Z_0$

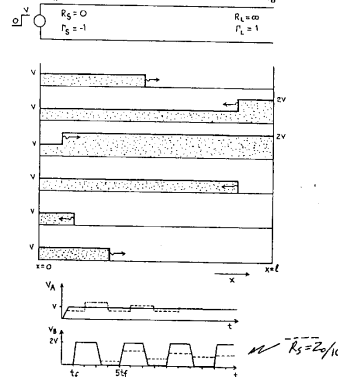
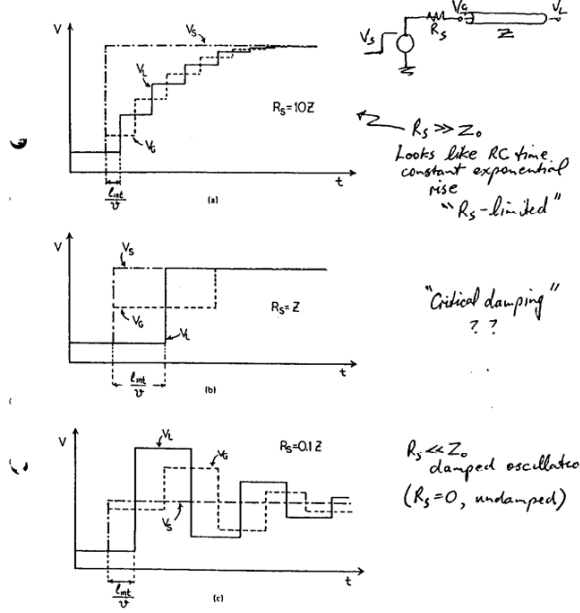


FIGURE 6.16 No termination: $R_S = 0, R_L = \infty$

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49 ECE410/51 **FIGURE 6.8** Waveforms for various R_S and Z_0 combinations in the circuit in Fig. 6.7. As can be seen by the t_{mi}/v markers, the time axes of the plots are not drawn at the same scale for clarity. The top plot $R_S = 10Z_0$ has the longest delay. 4/16/2009

3. Mismatched load &/or source

- 1 volt pulse, $Z_0 = 78\Omega$
- Consider $R_L = 78\Omega$ cases first, then vary R_L for
 - (a) $R_S = Z_0$
 - (b) $R_S \ll Z_0$
 - (c) $R_S \gg Z_0$

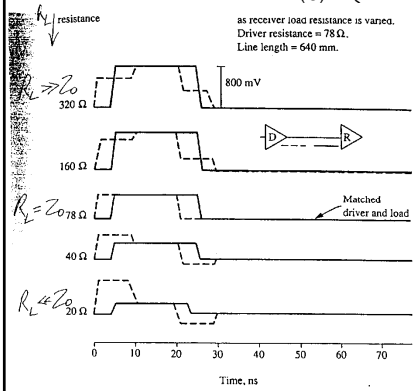


FIGURE 3-10 Same as Figure 3-9, but driver resistance is 78Ω . $R_S = Z_0$

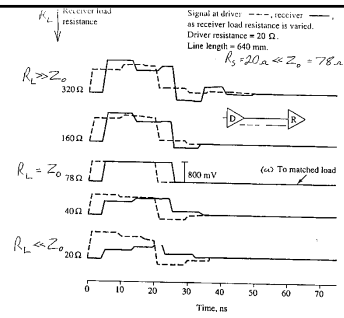


FIGURE 3-9 Multiple reflections on a transmission line. Signal at driver and receiver, driver resist 20Ω . R_S is varied from low to high values. Characteristic impedance Z_0 of line is 78Ω waveform is a 20-ns wide trapezoidal pulse with 1 ns rise and fall times and 1 V p into an open circuit.

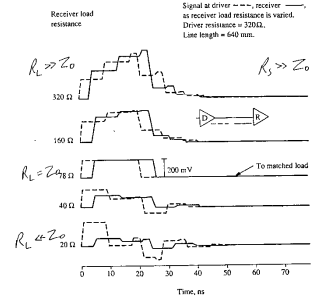


FIGURE 3-11 Same as Figure 3-9, but driver resistance is 320Ω .

4. Bounce chart (lattice diagram)

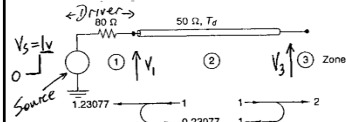


Figure 6.13 Lattice diagram of a LOW-to-HIGH transition.

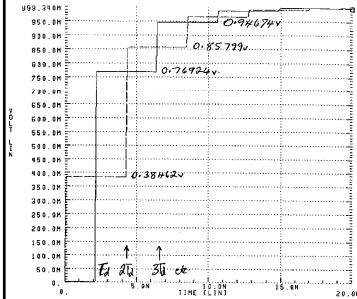


Figure 6.14 Voltage waveforms at source (dotted line) and receiver (solid line), L-to-H transition, $R_L > Z_0$. See Fig. 6.13.

- Calculate reflection coefficients
- Distance / time diagram
- Transfer data to waveform plots
- Example: Open circuit line

"BOUNCE" CHART / LATTICE DIAGRAM

(1) $R_S = 80 \Omega$ $Z_0 = 50 \Omega$ $R_L = \infty$
 $\Gamma_{VS} = \frac{80 - 50}{80 + 50} = \frac{3}{13}$ $\Gamma_{VL} = \frac{\infty - 50}{\infty + 50} = 1$
 $= 0.23077$

At $t=0$: $V_i = \frac{50}{50+80} V_s = \frac{5}{13} V = 0.38462 V$

$t = T_d$: Load $V_i = 0.38462 V$ $V_r = \Gamma_{VL} V_i = 0.38462 V$

& load voltage $V_3 = V_i + V_r = 0.76924 V$

$t = 2T_d$: Driver Reflected wave $V_r = \Gamma_{VS} \cdot 0.38462 V = 0.088757 V$

$V_2 = 0.38462 V + 0.088757 V = 0.47338 V$
original pulse + reflection back to load

$t = 3T_d$: Load Reflected wave $V_r = \Gamma_{VL} \cdot 0.47338 V = 0.47338 V$

$V_3 = 0.76924 V + 0.088757 V + 0.088757 V = 0.94674 V$
Previous value + (1 + \Gamma_{VL}) V_i = 0.17751 V

$t = 4T_d$: Driver Reflected wave $V_r = \Gamma_{VS} \cdot 0.088757 V = 0.02045 V$
 $V_i = 0.85799 V + (0.088757 V + 0.02045 V) = 0.96723 V$

5. Discontinuities

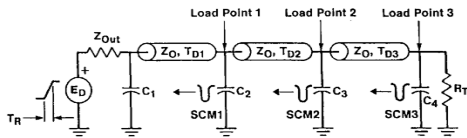
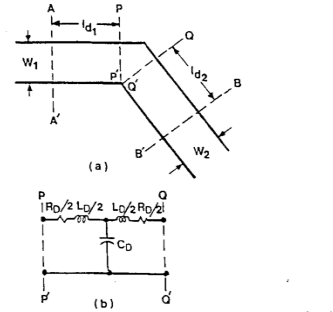


Figure 3.9 Discrete or Distributed Net Configurations. Note reflections from discontinuities.



A planar bend - top view; (b) Equivalent circuit

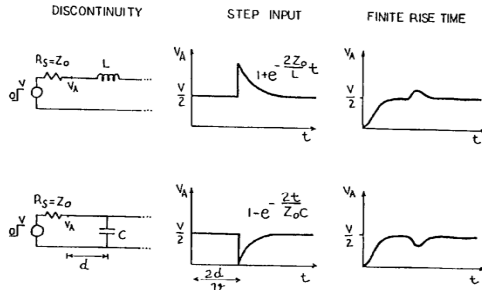


FIGURE 6.6 Inductive and capacitive discontinuities. The transmission line is driven by a signal generator with $R_S = Z_0$, and the reflected waveforms are observed at the source end. The line is either infinitely long or is terminated with $R_L = Z_0$ at the far end. Two types of reflected waveforms are plotted for each discontinuity: one assuming a step input (left) and another assuming a finite-rise-time input (right).

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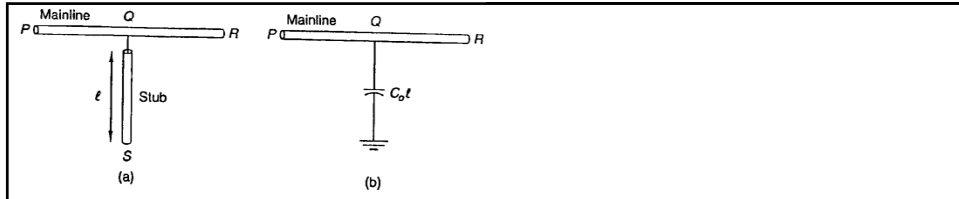
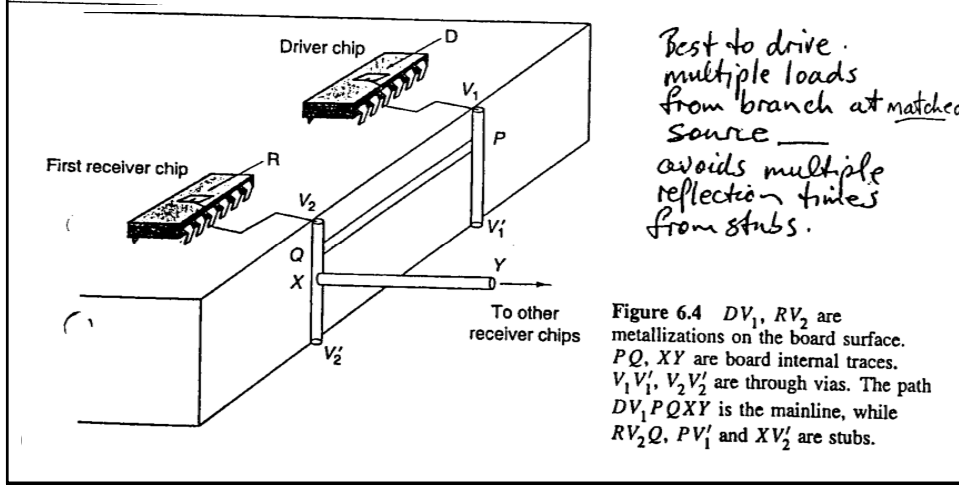


Figure 6.3 A short stub (a) reflects as a capacitor (b).



Best to drive multiple loads from branch at matched source — avoids multiple reflection times from stubs.

Figure 6.4 DV_1, RV_2 are metallizations on the board surface. PQ, XY are board internal traces. V_1V_1', V_2V_2' are through vias. The path DV_1PQXY is the mainline, while RV_2Q, PV_1' and XV_2' are stubs.

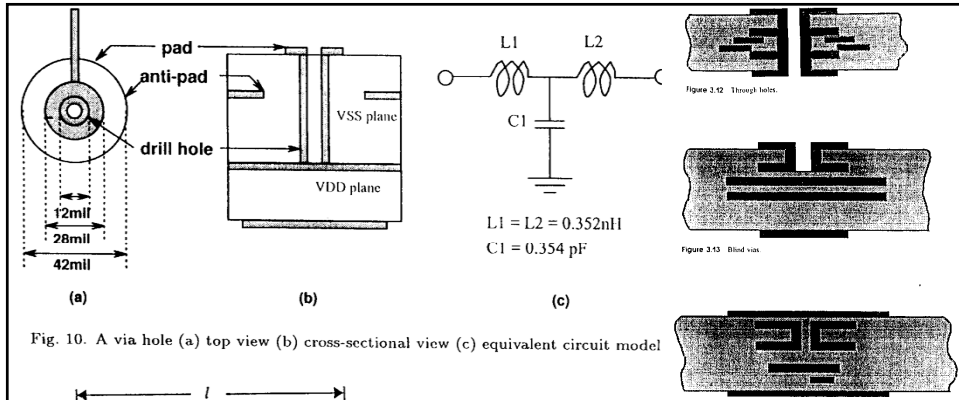


Fig. 10. A via hole (a) top view (b) cross-sectional view (c) equivalent circuit model

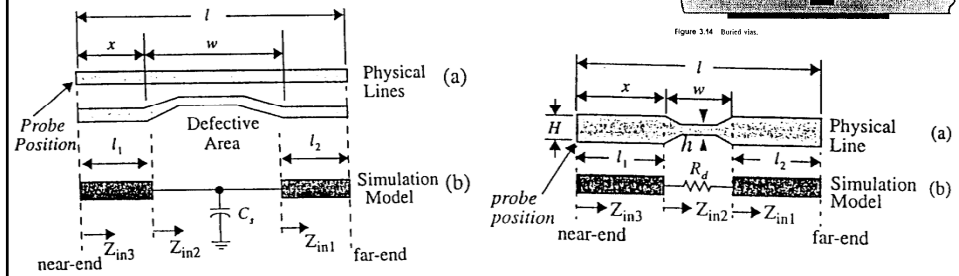
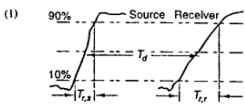


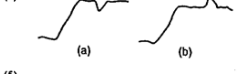
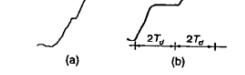
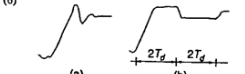



Figure 7. Simulation Model for an Interconnect with Near-Short Defect.

Figure 6. Simulation Model for an Interconnect with Near-Open Defect.

Summary

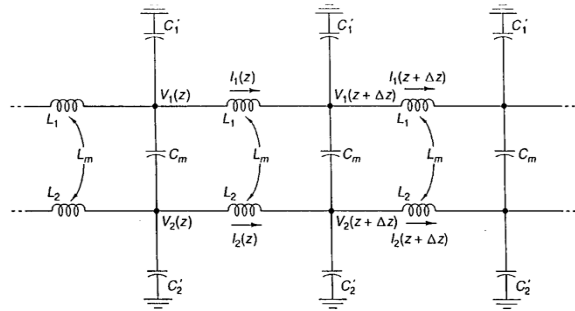
Waveform	Transmission line effect	Description/environment	Section
(1) 	Propagation delay T_d Risetime degradation ($T_{r,r} > T_{r,s}$)	Line is distributed if $2T_d \geq T_r$	9.1.4
(2) 	Ohmic drop (frequency-independent)	Steady-state attenuation	5.2
(3) 	Skin effect (frequency dependent)	Slow dribble-up at transition	10.4
(4) 	Reflection from lumped loads: (a) capacitor (b) inductor	Glitch accompanies every transition	6.2.2
(5) 	Undershoot on (a) short line (b) long line	Parallel-terminated line: (at receiver): $R_l < Z_0$	6.4
(6) 	Overshoot on (a) short line (b) long line	Parallel-terminated line (at receiver): $R_l > Z_0$ Series-terminated line (at source): $R_s > Z_0$	6.4
(7) 	Spurious noises: • crosstalk • switching • oscillations • others	Non-deterministic association with every transition	Chap. 7, 8

Lecture topics D: Transmission lines Crosstalk

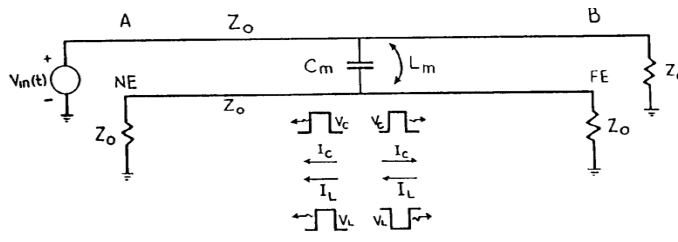
1. Inductive and capacitive coupling
2. Forward and backward noise
3. Far end and near end noise
4. Incremental model and formulae
5. Crosstalk examples
6. Capacitive crosstalk systems
7. No ground plane

1. Inductive and capacitive coupling

Incremental line model



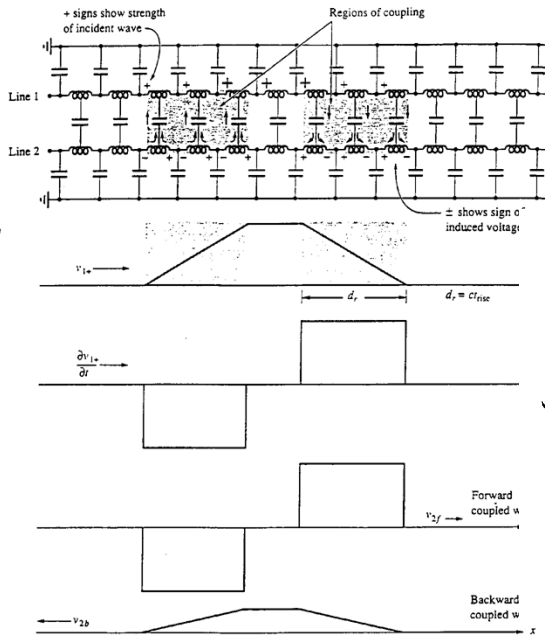
Crosstalk polarities



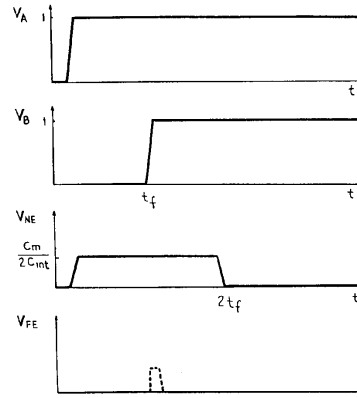
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2. Forward & backward noise



3. Near end & far end



4. Theory: line segment

(a) Capacitive

Consider line elements of length Δx

(b) Inductive

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Far end overview

For forward coupled wave, $t_0 \rightarrow$

At far end (FE):

$$V_{FF} = \left(\frac{C_m Z_0}{2} - \frac{L_m}{2Z_0} \right) \frac{V_s}{R} \leq \Delta x$$

$$= \frac{1}{2} \left(C_m Z_0 - \frac{L_m}{Z_0} \right) \frac{V_s}{R} l$$

$\rightarrow 0$ if $C_m Z_0 = L_m / Z_0$
 ie. if $\frac{L_m}{C_m} = Z_0^2 = \frac{L_0}{C_0}$

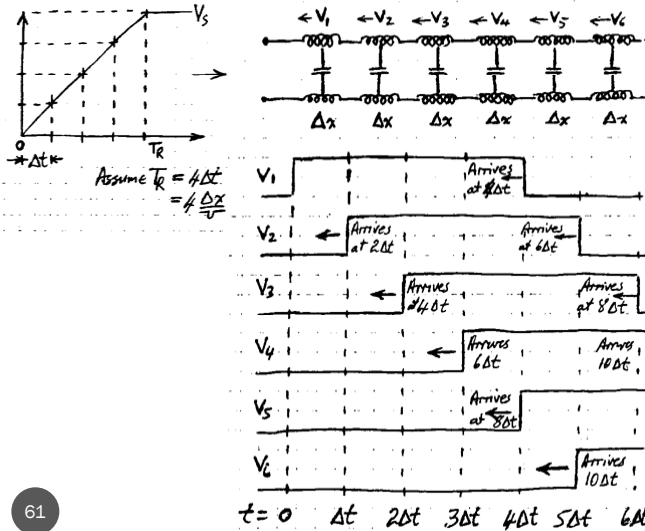
This is so if medium is "homogeneous"
 Approx true for most MCM "stripline" structures, etc. $\mu = \mu_0$ homogeneous, ϵ_r constant.

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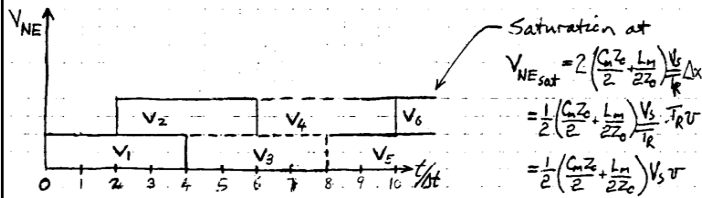
Backward wave model

For reverse coupled wave

Consider the near end (NE) as pulse starts:-

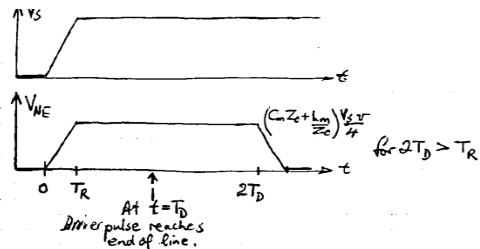


Near end pulse shape



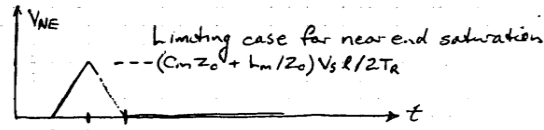
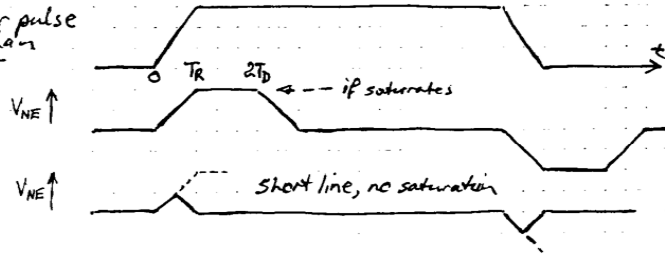
Note: Independent of T_R !!

Also independent of ϵ_r $C_m Z_0 v \propto \epsilon_r \epsilon_r^{-1/2} \epsilon_r^{-1/2}$
 $v/Z_0 \propto \epsilon_r^{-1/2} (\epsilon_r^{-1/2})^{-1}$



Near End Saturation

For driver pulse longer than $2l/v$



$T_R = 2T_D$ i.e. $2\frac{l}{v} = T_R$, $l = \frac{1}{2} v T_R$

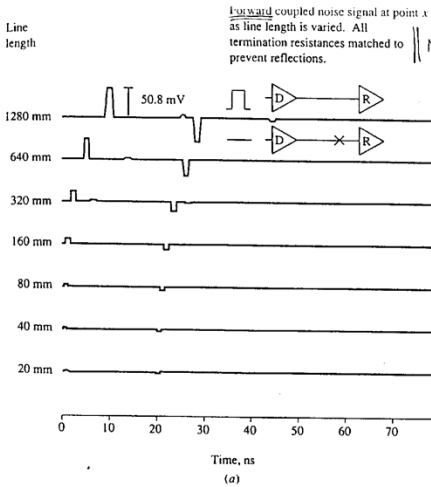
If need to reduce $V_{NE,max}$, need to increase T_R &/or decrease l
(i.e. decrease l/T_R) so cannot saturate.

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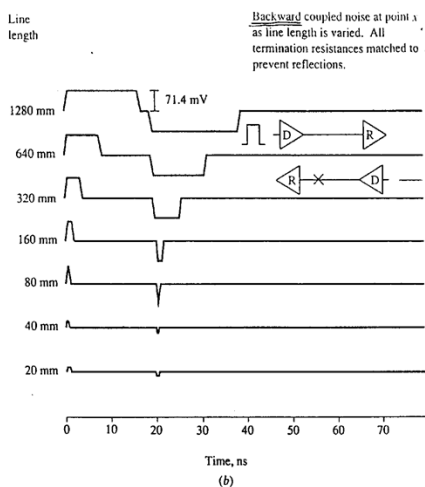
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5. Pulse crosstalk noise examples

Drive pulse: 0.5 volt, $t_{width} = 20ns$, $t_{rise} = t_{fall} = 1ns$



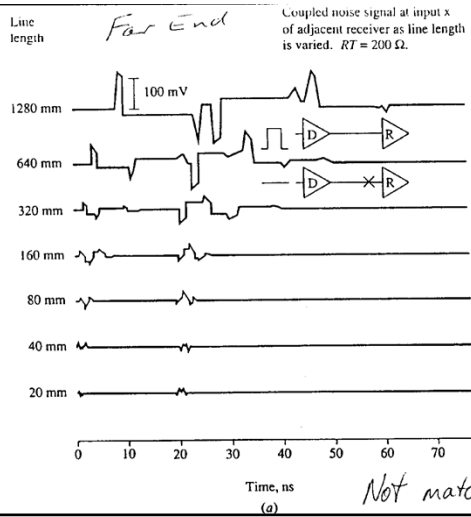
Forward noise: matched



Backward: matched

Not matched

Forward (Far end)



Backward (Near end)

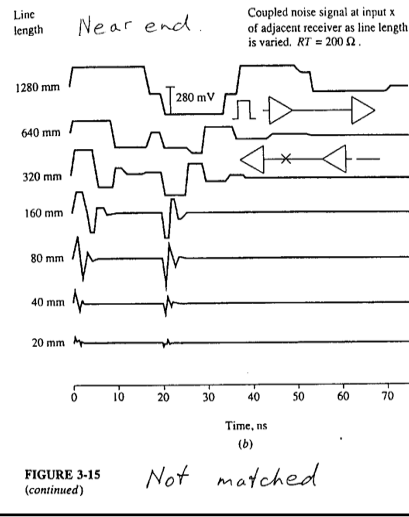


FIGURE 3-15 (continued)

6. Ground coupled crosstalk

$$\text{Crosstalk} \approx \frac{K}{1 + (D/H)^2}$$

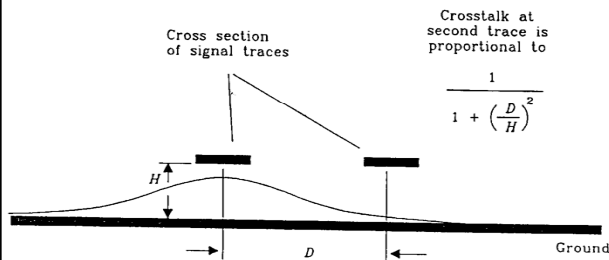


Figure 5.4 Cross section of two traces

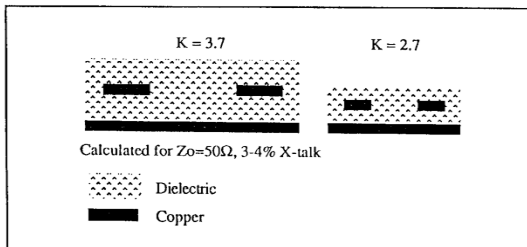


Figure 8.4 Increased circuit density through reduced dielectric constant.

7. Mutual capacitances

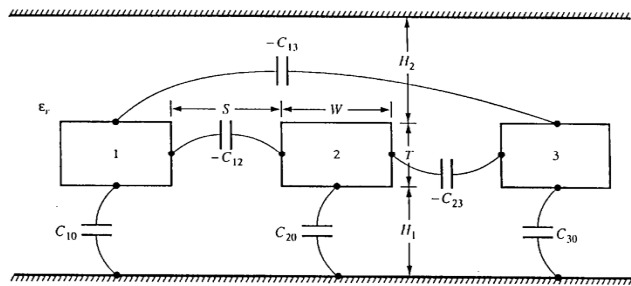
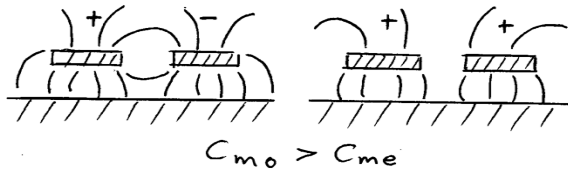


FIGURE 4-3
Cross section of three coupled lines in a homogeneous medium.

Even/odd modes



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Lecture topics E: Electromagnetic Modeling

Microstrip
Transmission line

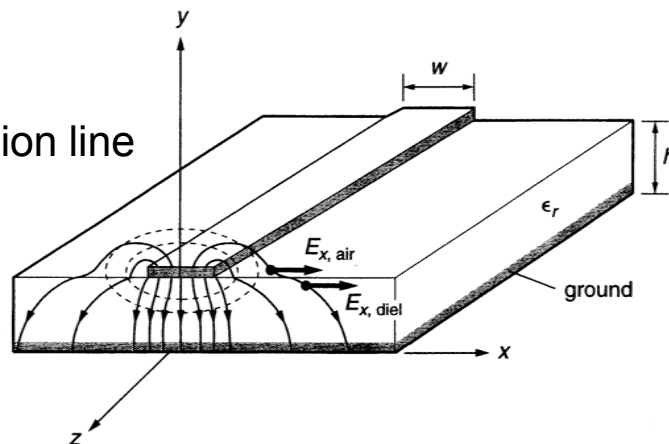
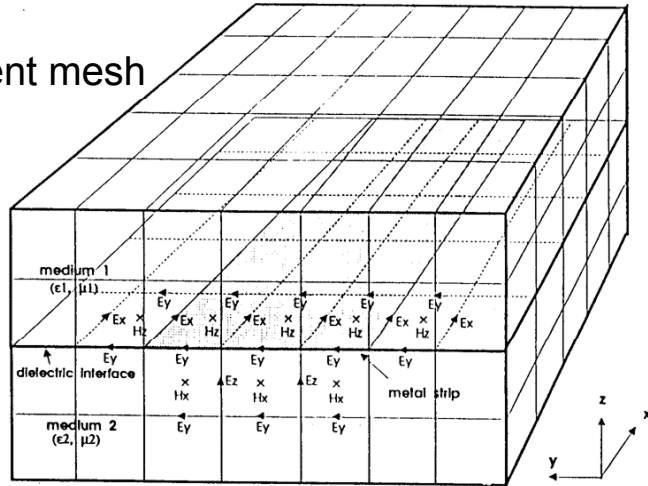


Figure 23.8 Sketch of a microstrip line. The electric field lines are sketched in solid line, and the magnetic field lines in dashed line.

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3. Electromagnetic Modeling (Fang)

Finite element mesh

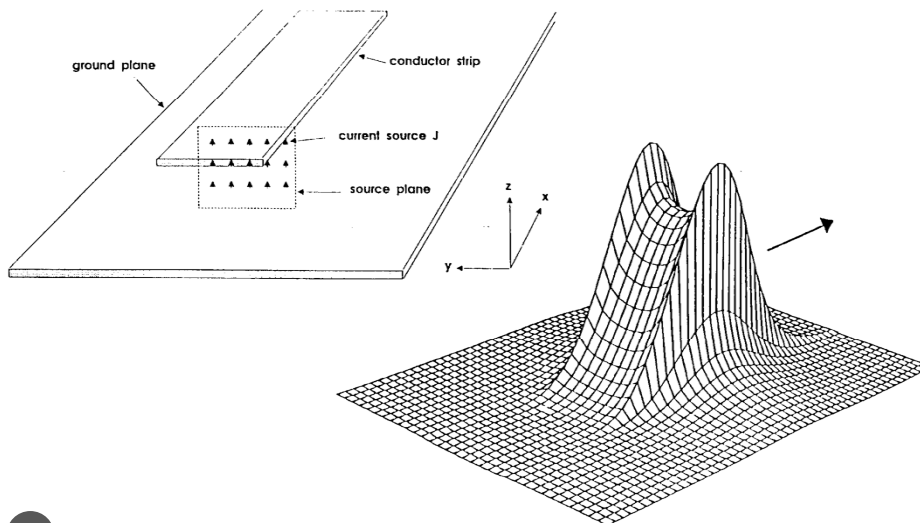


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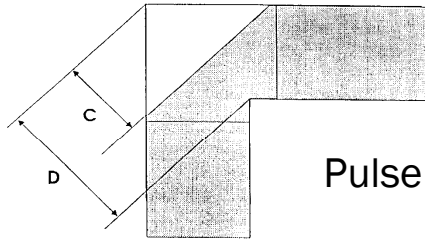
a. Current pulse excitation of line



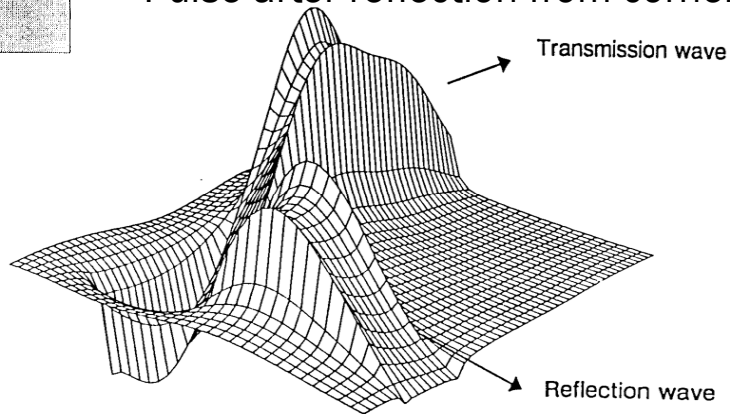
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Electric field distribution on line

b. Chamfered right angle bend



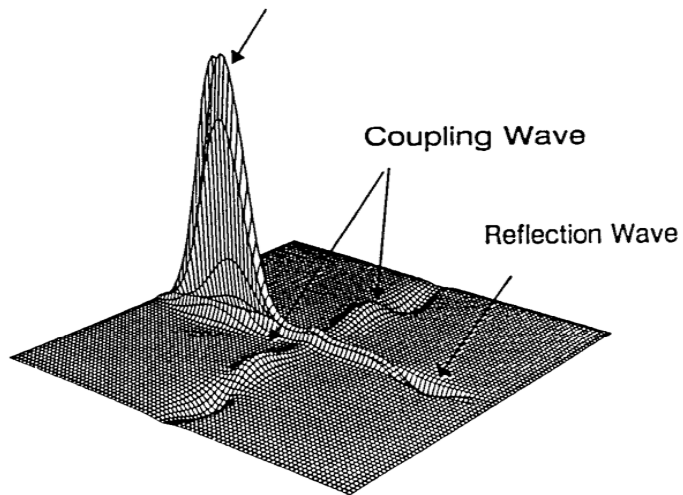
Pulse after reflection from corner



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c. Orthogonal line crosstalk

Transmission Wave



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Lecture topics F: Electromagnetic Compatibility

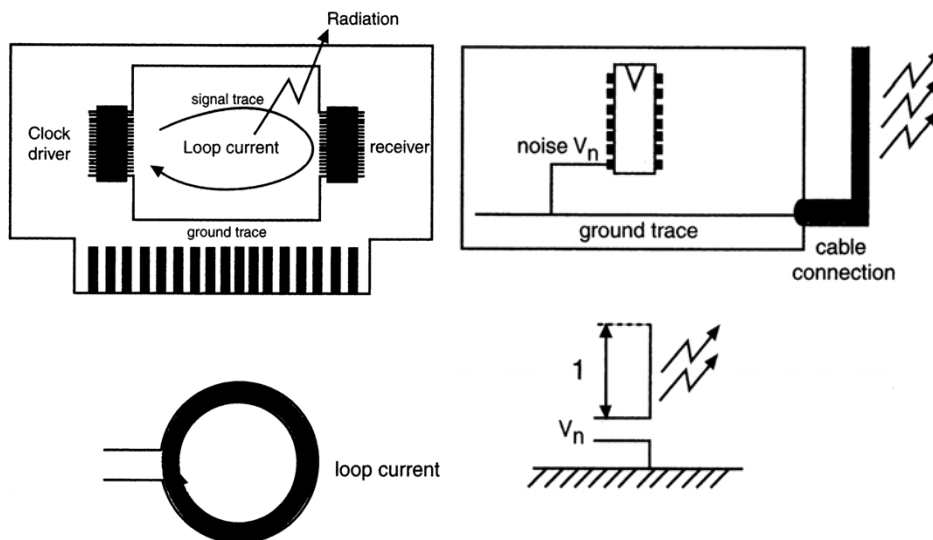
1. Antennas
2. Emissions
3. Susceptibility

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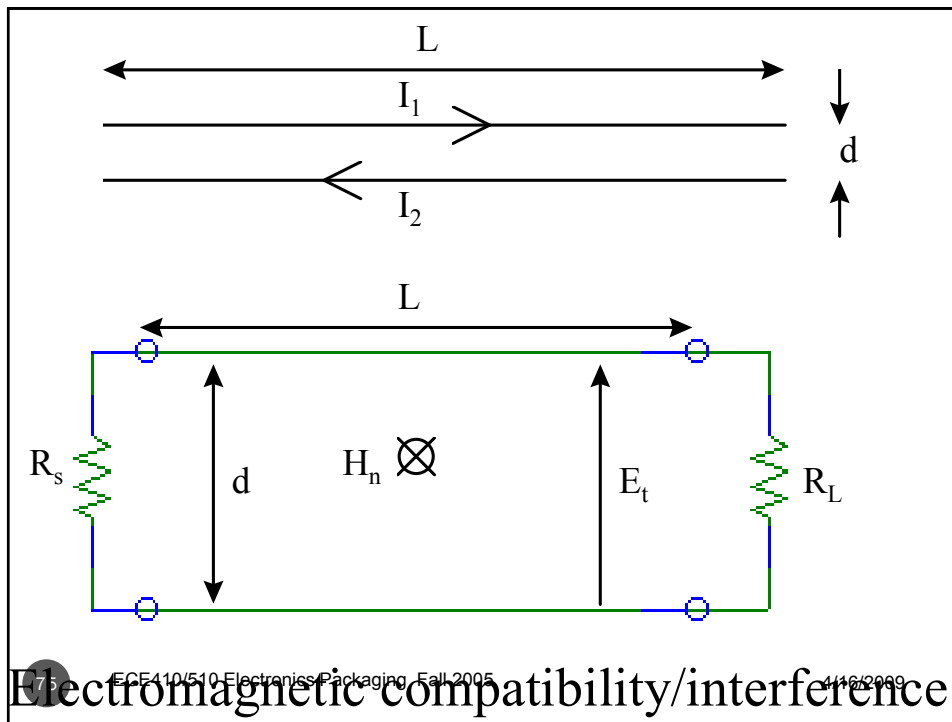
1. EMI/EMC Models: Loop/Dipole Antennas



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2. EMI/EMC Models: Emissions

- At “far field” distance $r (\geq \lambda = c/f)$ from the line of length L and area $A = L \cdot d$, the radiated electric field strength is

$$E = E_D + E_{CM}$$

- where E_D due to the differential current I_D is

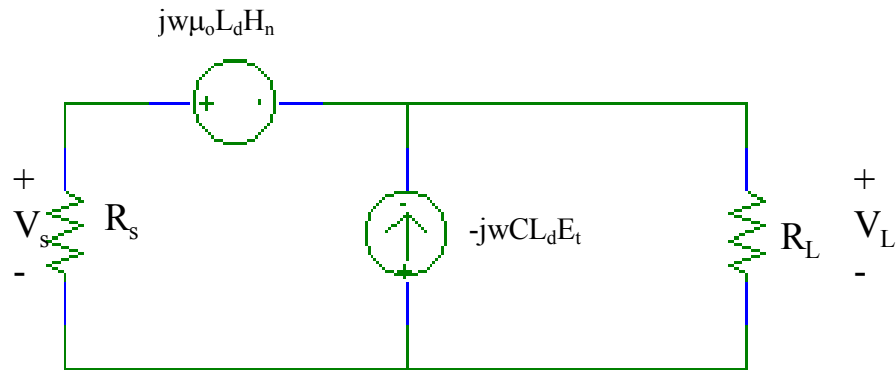
$$E_D = 131.6 \times 10^{-16} f^2 A I_D / r \quad \text{V/m}$$

- and E_{CM} due to the common mode current I_{CM} is (for $L \leq \lambda$)

$$E_{CM} = 4\pi \times 10^{-7} f^2 L I_{CM} / r \quad \text{V/m}$$

- where $I_D = (I_1 + I_2)/2$ and $I_{CM} = (I_1 - I_2)/2$. Common mode currents are ideally zero, but small values can lead to CM dominance over differential. For the differential current, the maximum value can be taken to be the supply current, but the user must specify a non-ideal common mode estimate. For digital systems, use $f = 2\pi/\tau_r$. For other geometries, other expressions for A are valid.
- There are many different standards for EM radiation limits, but for guidance the EU limit is $E \leq 100 \mu\text{V/m}$ at $r = 10\text{m}$ (class A) or 3m (class B).

EMI/EMC Models: Susceptibility



odels

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3. Susceptibility

- For the line shown, with capacitance C per unit length, e.g.
 - $C = \pi \epsilon_r \epsilon_0 / \ln(d/r_w)$
- for parallel wires, the induced voltages are
 - $V_s = -j\omega [R_L R_s / (R_L + R_s)] [Ld] [C - (\mu_0 / \eta_0) / R_L]$
 - $V_L = -j\omega [R_L R_s / (R_L + R_s)] [Ld] [C + (\mu_0 / \eta_0) / R_s]$
- where $E = E_t = \eta_0 H_n$, and $\eta_0 = 120\pi = 377\Omega$.
- As an example of an EU standard, the device must function in a field of $E = 3V/m$.

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