

Chapter 5

Steady-State Sinusoidal Analysis

1. Identify the frequency, angular frequency, peak value, rms value, and phase of a sinusoidal signal.
2. Solve steady-state ac circuits using phasors and complex impedances.

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3. Compute power for steady-state ac circuits.
4. Find Thévenin and Norton equivalent circuits.
5. Determine load impedances for maximum power transfer.
6. Solve balanced three-phase circuits.

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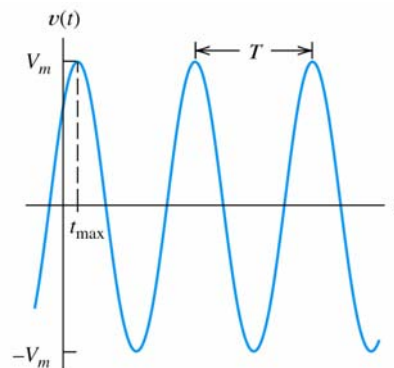


Figure 5.1 A sinusoidal voltage waveform given by $v(t) = V_m \cos(\omega t + \theta)$.
 Note: Assuming that θ is in degrees, we have $t_{\max} = \frac{-\theta}{360} \times T$.
 For the waveform shown, θ is -45° .

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SINUSOIDAL CURRENTS AND VOLTAGES

V_m is the **peak value**

ω is the **angular frequency** in radians
per second

θ is the **phase angle**

T is the **period**

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Frequency $f = \frac{1}{T}$

Angular frequency $\omega = \frac{2\pi}{T}$

$$\omega = 2\pi f$$

$$\sin(z) = \cos(z - 90^\circ)$$

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Root-Mean-Square Values

$$V_{\text{rms}} = \sqrt{\frac{1}{T} \int_0^T v^2(t) dt} \quad I_{\text{rms}} = \sqrt{\frac{1}{T} \int_0^T i^2(t) dt}$$

$$P_{\text{avg}} = \frac{V_{\text{rms}}^2}{R} \quad P_{\text{avg}} = I_{\text{rms}}^2 R$$

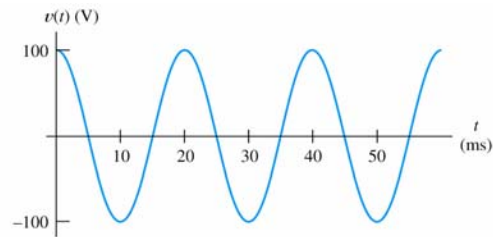
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RMS Value of a Sinusoid

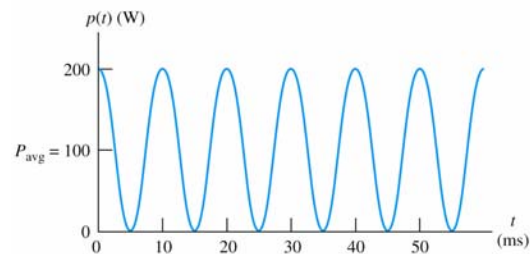
$$V_{\text{rms}} = \frac{V_m}{\sqrt{2}}$$

The rms value for a sinusoid is the peak value divided by the square root of two. This is not true for other periodic waveforms such as square waves or triangular waves.

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(a)



(b)

Figure 5.2 Voltage and power versus time for Example 5.1.

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Phasor Definition

$$\text{Time function : } v_1(t) = V_1 \cos(\omega t + \theta_1)$$

$$\text{Phasor : } \mathbf{V}_1 = V_1 \angle \theta_1$$

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Adding Sinusoids Using Phasors

Step 1: Determine the phasor for each term.

Step 2: Add the phasors using complex arithmetic.

Step 3: Convert the sum to polar form.

Step 4: Write the result as a time function.

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Using Phasors to Add Sinusoids

$$v_1(t) = 20 \cos(\omega t - 45^\circ)$$

$$v_2(t) = 10 \cos(\omega t + 60^\circ)$$

$$\mathbf{V}_1 = 20 \angle -45^\circ$$

$$\mathbf{V}_2 = 10 \angle -30^\circ$$

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$$\begin{aligned}
\mathbf{V}_s &= \mathbf{V}_1 + \mathbf{V}_2 \\
&= 20\angle -45^\circ + 10\angle -30^\circ \\
&= 14.14 - j14.14 + 8.660 - j5 \\
&= 23.06 - j19.14 \\
&= 29.97\angle -39.7^\circ
\end{aligned}$$

$$v_s(t) = 29.97 \cos(\omega t - 39.7^\circ)$$

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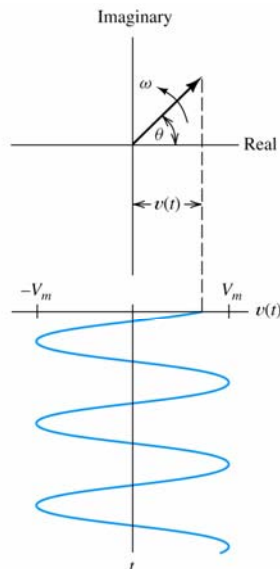


Figure 5.4 A sinusoid can be represented as the real part of a vector rotating counterclockwise in the complex plane.

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Sinusoids can be visualized as the real-axis projection of vectors rotating in the complex plane. The phasor for a sinusoid is a snapshot of the corresponding rotating vector at $t = 0$.

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Phase Relationships

To determine phase relationships from a phasor diagram, consider the phasors to rotate counterclockwise. Then when standing at a fixed point, if \mathbf{V}_1 arrives first followed by \mathbf{V}_2 after a rotation of θ , we say that \mathbf{V}_1 leads \mathbf{V}_2 by θ . Alternatively, we could say that \mathbf{V}_2 lags \mathbf{V}_1 by θ . (Usually, we take θ as the smaller angle between the two phasors.)

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To determine phase relationships between sinusoids from their plots versus time, find the shortest time interval t_p between positive peaks of the two waveforms. Then, the phase angle is $\theta = (t_p/T) \times 360^\circ$. If the peak of $v_1(t)$ occurs first, we say that $v_1(t)$ leads $v_2(t)$ or that $v_2(t)$ lags $v_1(t)$.

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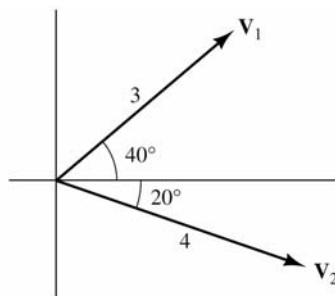


Figure 5.5 Because the vectors rotate counterclockwise, v_1 leads v_2 by 60° (or, equivalently, v_2 lags v_1 by 60° .)

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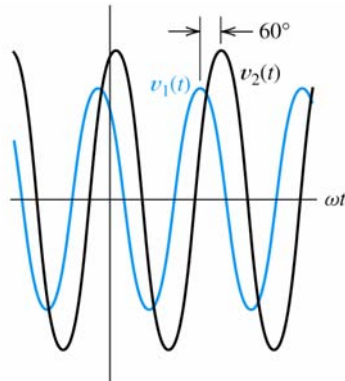
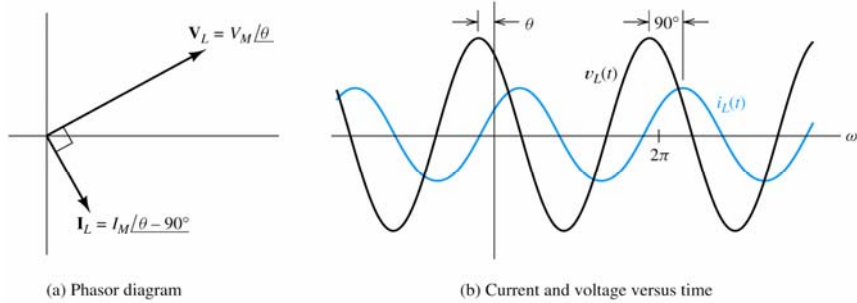


Figure 5.6 The peaks of $v_1(t)$ occur 60° before the peaks of $v_2(t)$. In other words, $v_1(t)$ leads $v_2(t)$ by 60° .

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(a) Phasor diagram

(b) Current and voltage versus time

Figure 5.7 Current lags voltage by 90° in a pure inductance.

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COMPLEX IMPEDANCES

$$\mathbf{V}_L = j\omega L \times \mathbf{I}_L$$

$$Z_L = j\omega L = \omega L \angle 90^\circ$$

$$\mathbf{V}_L = Z_L \mathbf{I}_L$$

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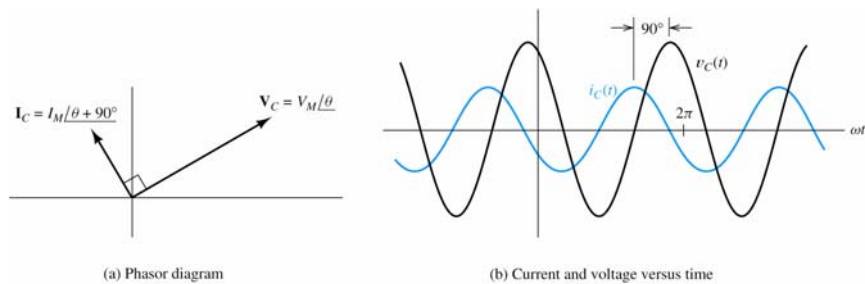


Figure 5.8 Current leads voltage by 90° in a pure capacitance.

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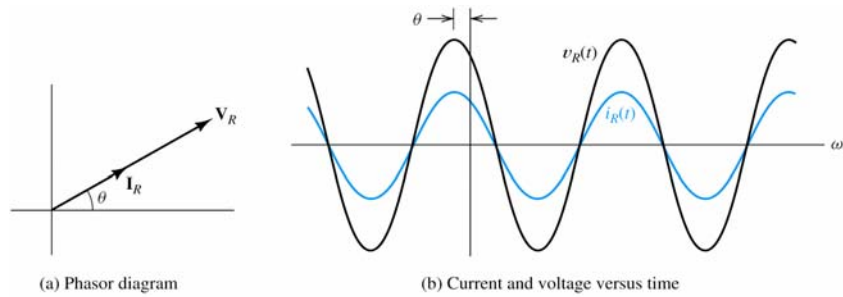


Figure 5.9 For a pure resistance, current and voltage are in phase.

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$$\mathbf{V}_C = Z_C \mathbf{I}_C$$

$$Z_C = -j \frac{1}{\omega C} = \frac{1}{j\omega C} = \frac{1}{\omega C} \angle -90^\circ$$

$$\mathbf{V}_R = R \mathbf{I}_R$$

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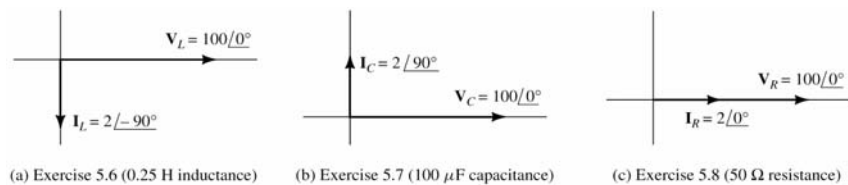


Figure 5.10 Answers for Exercises 5.6, 5.7, and 5.8. The scale has been expanded for the currents compared to the voltages so the current phasors can be easily seen.

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Kirchhoff's Laws in Phasor Form

We can apply KVL directly to phasors. The sum of the phasor voltages equals zero for any closed path.

The sum of the phasor currents entering a node must equal the sum of the phasor currents leaving.

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Circuit Analysis Using Phasors and Impedances

1. Replace the time descriptions of the voltage and current sources with the corresponding phasors. (All of the sources must have the same frequency.)

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2. Replace inductances by their complex impedances $Z_L = j\omega L$. Replace capacitances by their complex impedances $Z_C = 1/(j\omega C)$. Resistances have impedances equal to their resistances.
3. Analyze the circuit using any of the techniques studied earlier in Chapter 2, performing the calculations with complex arithmetic.

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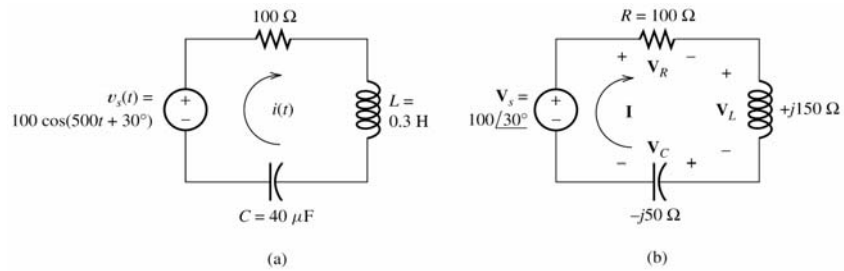


Figure 5.11 Circuit for Example 5.3.

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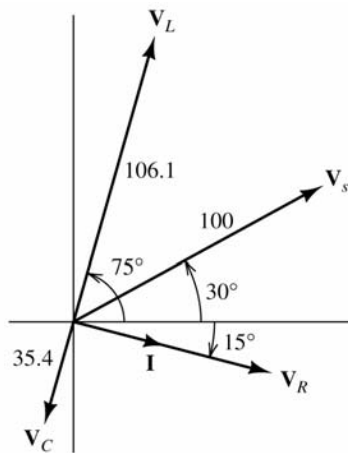
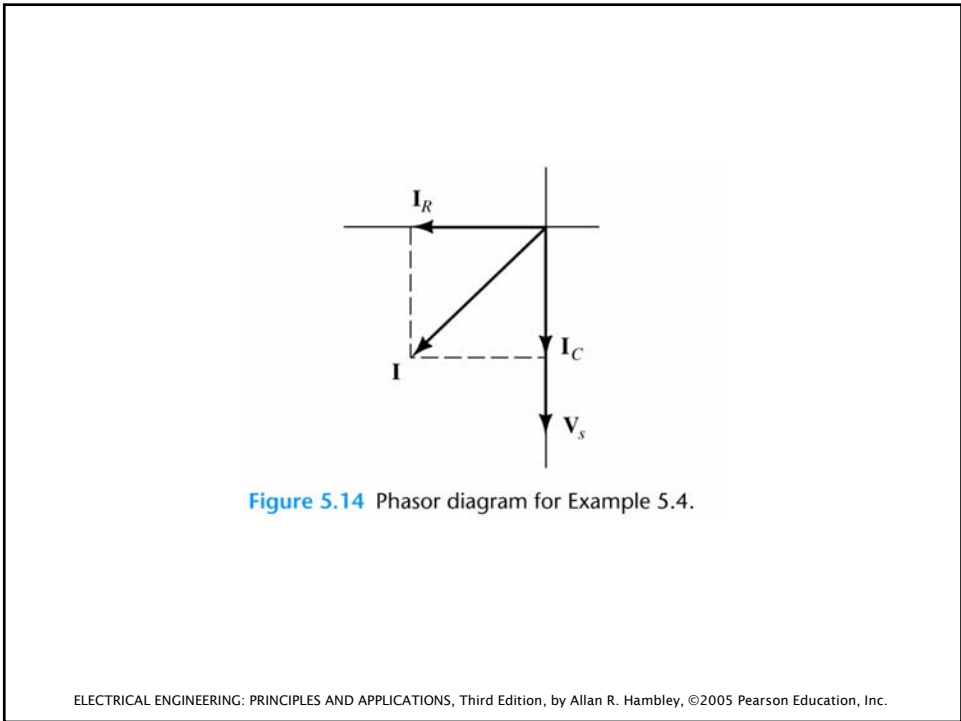
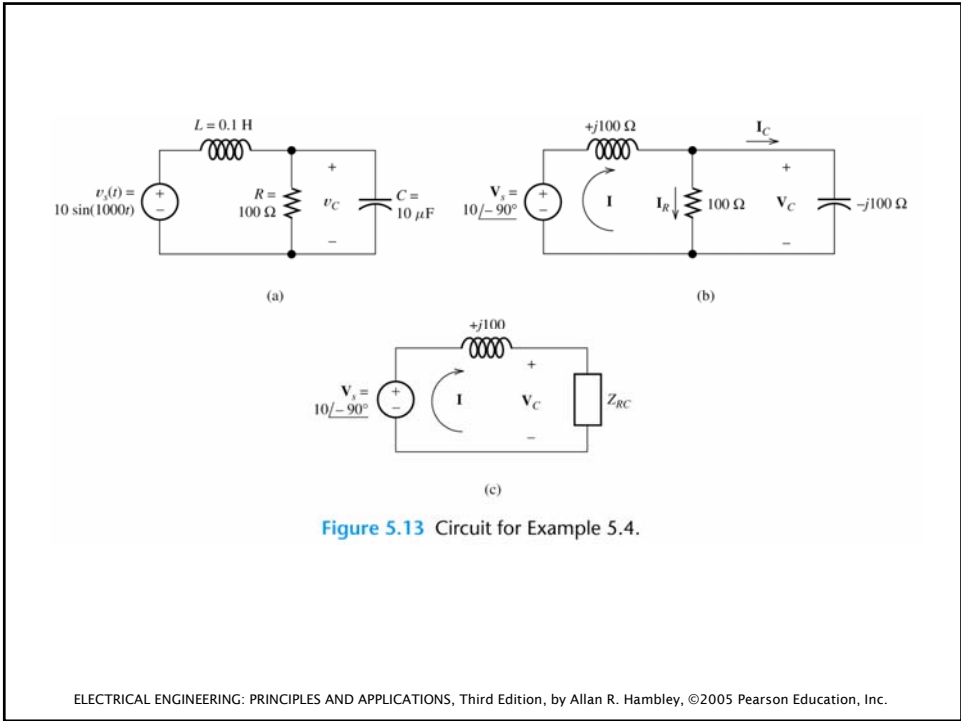


Figure 5.12 Phasor diagram for Example 5.3.

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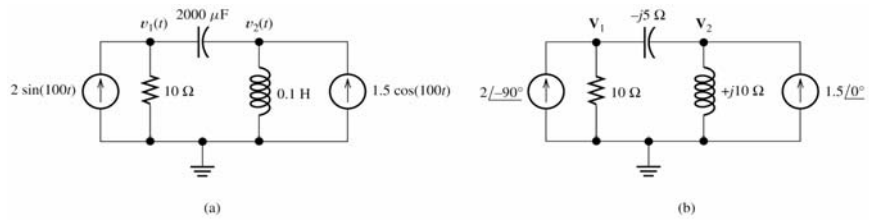


Figure 5.15 Circuit for Example 5.5.

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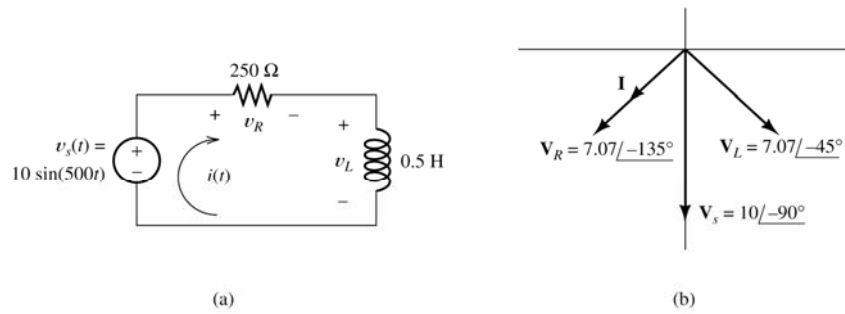


Figure 5.16 Circuit and phasor diagram for Exercise 5.9.

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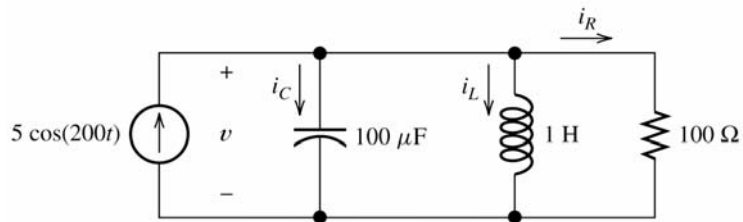


Figure 5.17 Circuit for Exercise 5.10.

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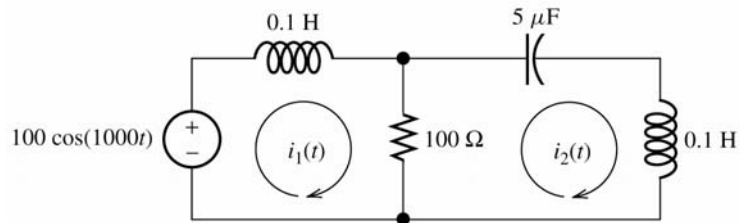


Figure 5.18 Circuit for Exercise 5.11.

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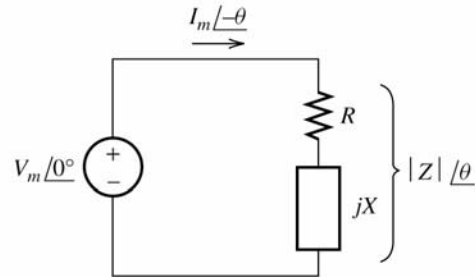


Figure 5.19 A voltage source delivering power to a load impedance $Z = R + jX$.

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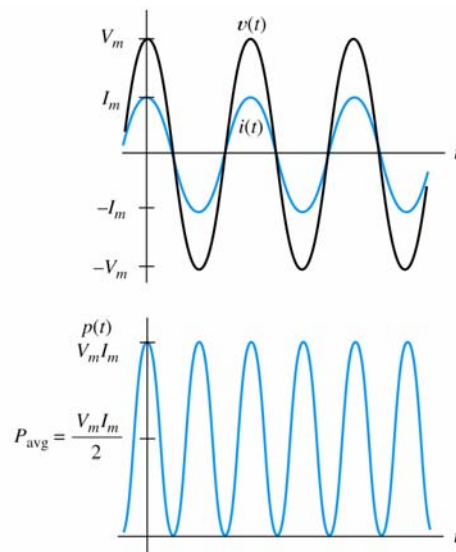
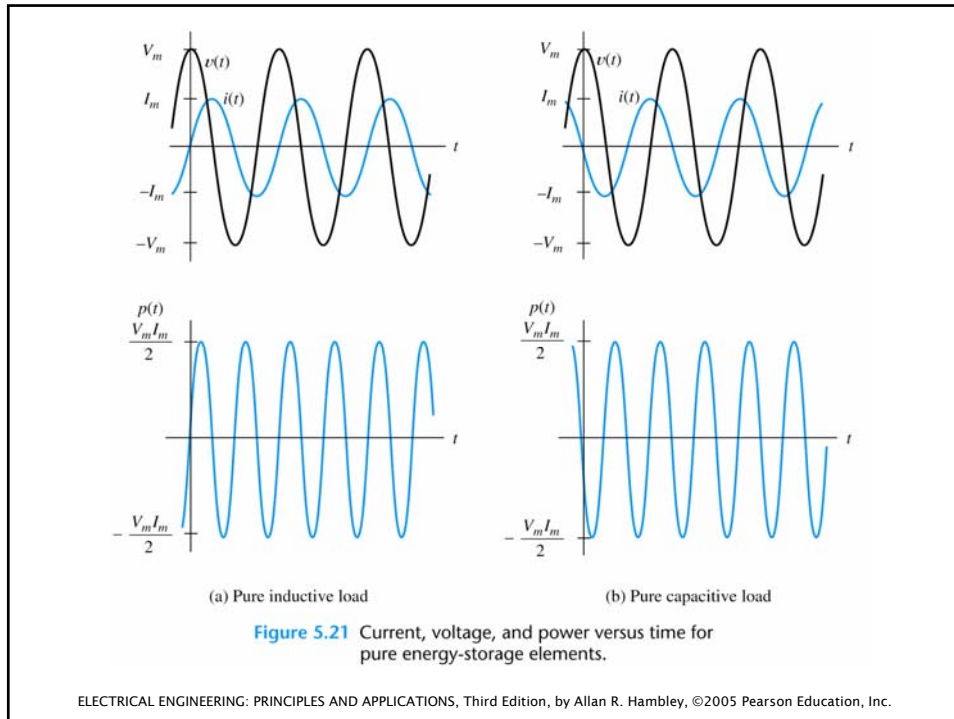


Figure 5.20 Current, voltage, and power versus time for a purely resistive load.

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AC Power Calculations

$$P = V_{\text{rms}} I_{\text{rms}} \cos(\theta)$$

$$\text{PF} = \cos(\theta)$$

$$\theta = \theta_v - \theta_i$$

$$Q = V_{\text{rms}} I_{\text{rms}} \sin(\theta)$$

$$\text{apparent power} = V_{\text{rms}} I_{\text{rms}}$$

$$P^2 + Q^2 = (V_{\text{rms}} I_{\text{rms}})^2$$

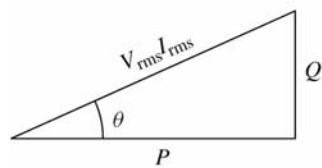
$$P = I_{\text{rms}}^2 R$$

$$P = \frac{V_{R\text{rms}}^2}{R}$$

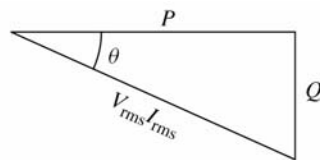
$$Q = I_{\text{rms}}^2 X$$

$$Q = \frac{V_{X\text{rms}}^2}{X}$$

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(a) Inductive load (θ positive)



(b) Capacitive load (θ negative)

Figure 5.22 Power triangles for inductive and capacitive loads.

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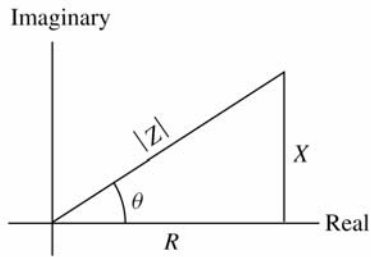


Figure 5.23 The load impedance in the complex plane.

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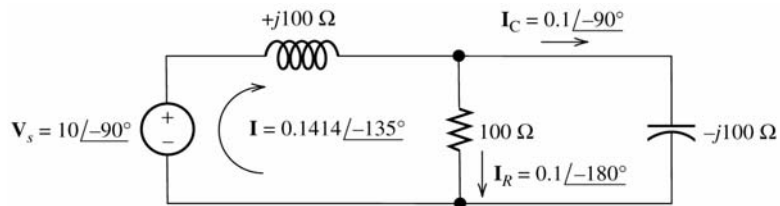


Figure 5.24 Circuit and currents for Example 5.6.

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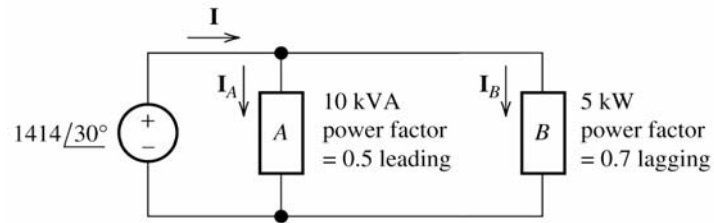
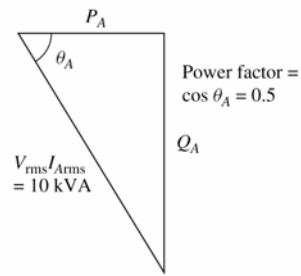
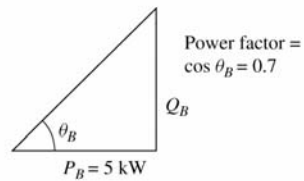


Figure 5.25 Circuit for Example 5.7.

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(a)



(b)

Figure 5.26 Power triangles for loads *A* and *B* of Example 5.7.

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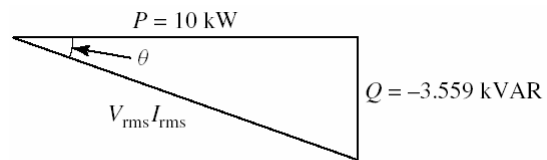


Figure 5.27 Power triangle for the source of Example 5.7.

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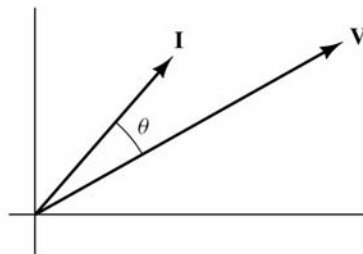


Figure 5.28 Phasor diagram for Example 5.7.

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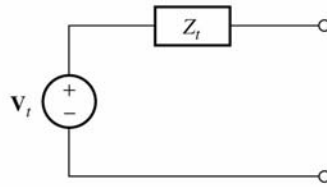


Figure 5.29 The Thévenin equivalent for an ac circuit consists of a phasor voltage source v_t in series with a complex impedance Z_t .

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THÉVENIN EQUIVALENT CIRCUITS

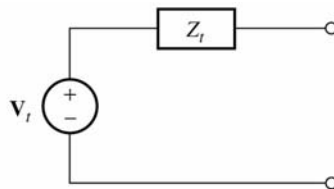


Figure 5.29 The Thévenin equivalent for an ac circuit consists of a phasor voltage source v_t in series with a complex impedance Z_t .

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The Thévenin voltage is equal to the open-circuit phasor voltage of the original circuit.

$$\mathbf{V}_t = \mathbf{V}_{oc}$$

We can find the Thévenin impedance by zeroing the independent sources and determining the impedance looking into the circuit terminals.

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The Thévenin impedance equals the open-circuit voltage divided by the short-circuit current.

$$\mathbf{Z}_t = \frac{\mathbf{V}_{oc}}{\mathbf{I}_{sc}} = \frac{\mathbf{V}_t}{\mathbf{I}_{sc}}$$

$$\mathbf{I}_n = \mathbf{I}_{sc}$$

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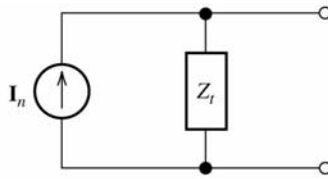
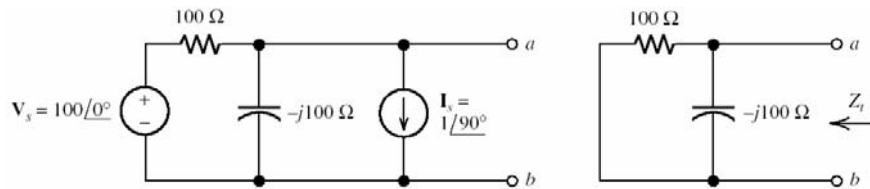


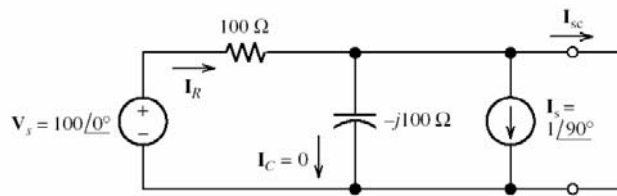
Figure 5.30 The Norton equivalent circuit consists of a phasor current source I_n in parallel with the complex impedance Z_T .

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(a) Original circuit

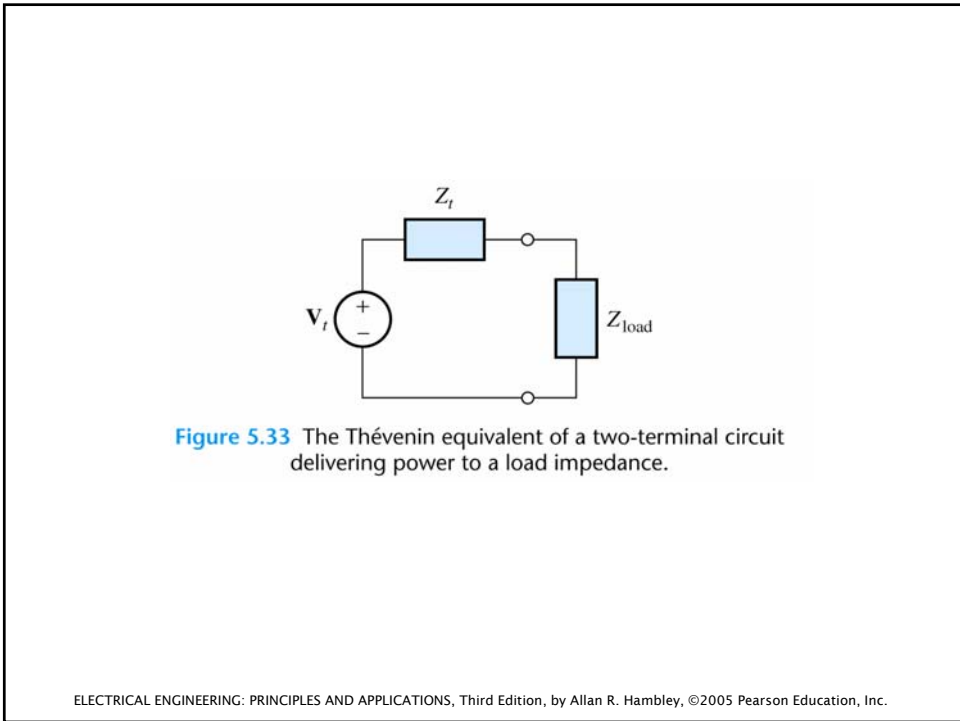
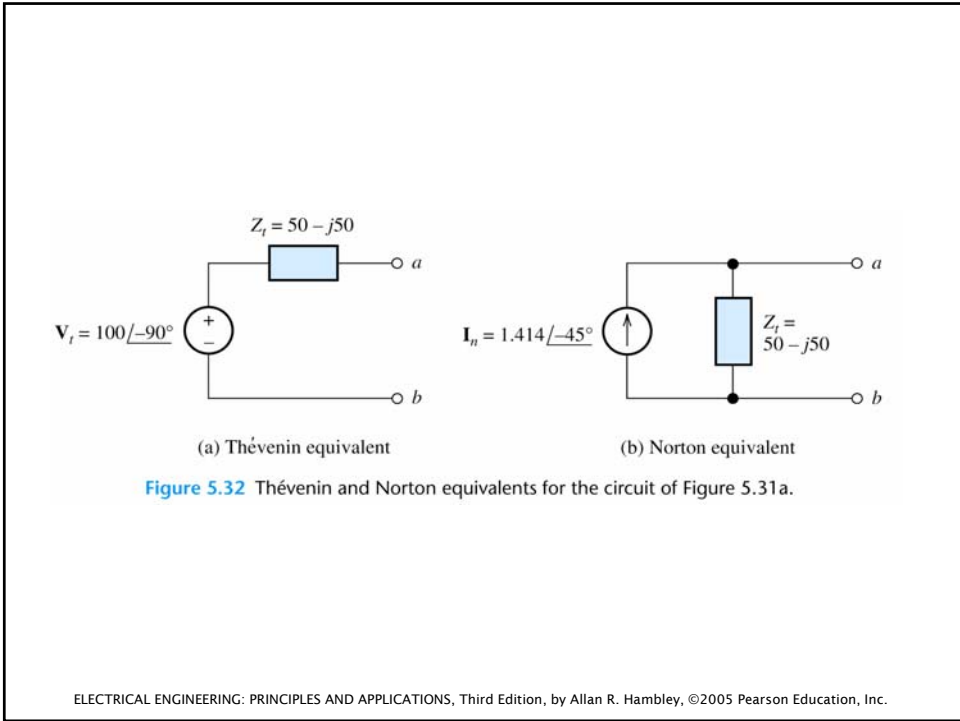
(b) Circuit with the sources zeroed



(c) Circuit with a short circuit

Figure 5.31 Circuit of Example 5.9.

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Maximum Average Power Transfer

If the load can take on any complex value, maximum power transfer is attained for a load impedance equal to the complex conjugate of the Thévenin impedance.

If the load is required to be a pure resistance, maximum power transfer is attained for a load resistance equal to the magnitude of the Thévenin impedance.

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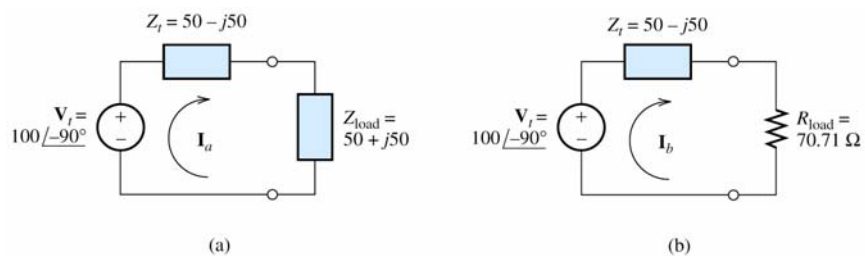


Figure 5.34 Thévenin equivalent circuit and loads of Example 5.10.

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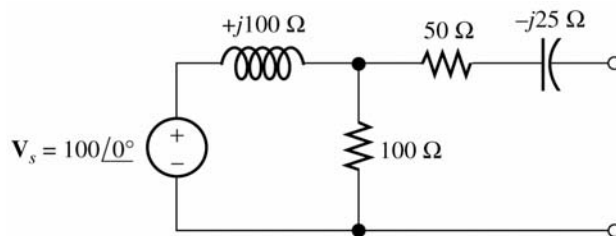


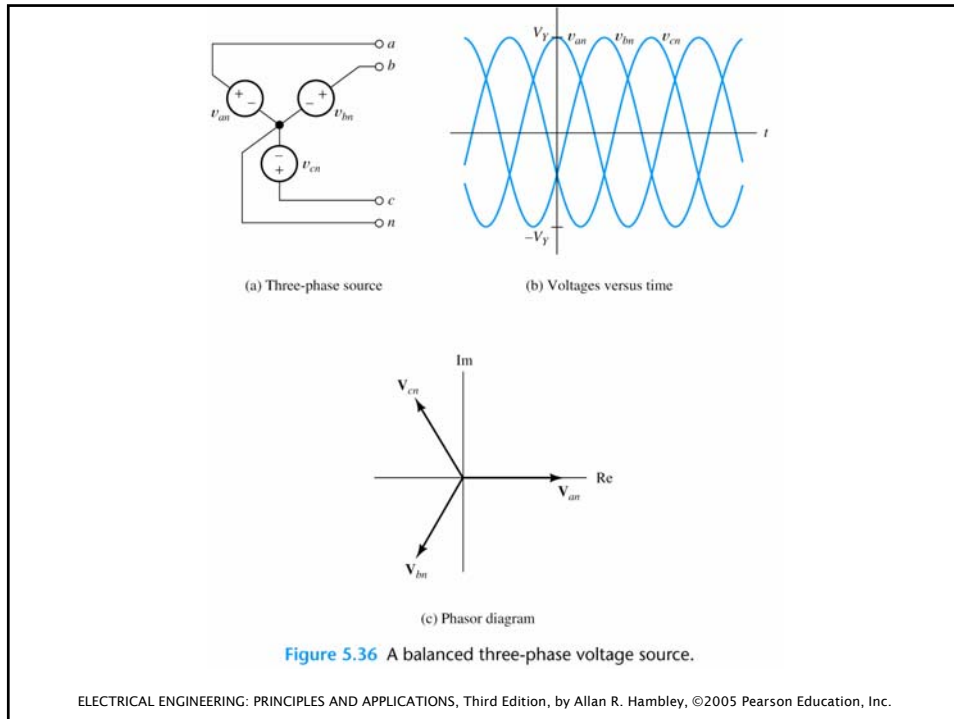
Figure 5.35 Circuit of Exercises 5.14 and 5.15.

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BALANCED THREE-PHASE CIRCUITS

Much of the power used by business and industry is supplied by three-phase distribution systems. Plant engineers need to be familiar with three-phase power.

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Phase Sequence

Three-phase sources can have either a positive or negative phase sequence.

The direction of rotation of certain three-phase motors can be reversed by changing the phase sequence.

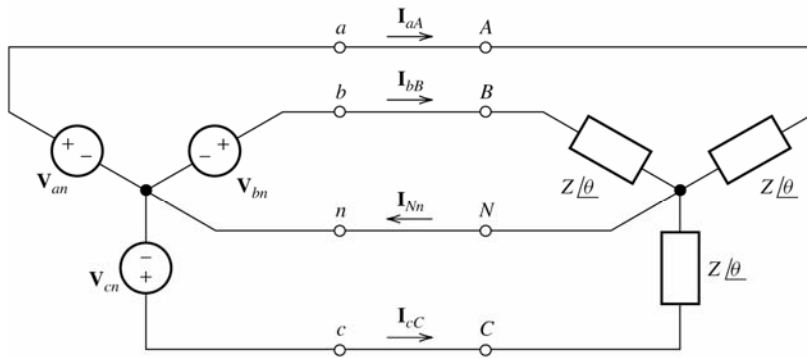


Figure 5.37 A three-phase wye-wye connection with neutral.

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Wye-Wye Connection

Three-phase sources and loads can be connected either in a wye configuration or in a delta configuration.

The key to understanding the various three-phase configurations is a careful examination of the wye-wye circuit.

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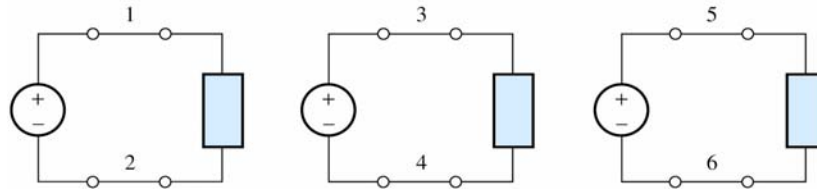


Figure 5.38 Six wires are needed to connect three single-phase sources to three loads. In a three-phase system, the same power transfer can be accomplished with three wires.

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$$P_{\text{avg}} = p(t) = 3V_{Y_{\text{rms}}} I_{L_{\text{rms}}} \cos(\theta)$$

$$Q = 3 \frac{V_Y I_L}{2} \sin(\theta) = 3V_{Y_{\text{rms}}} I_{L_{\text{rms}}} \sin(\theta)$$

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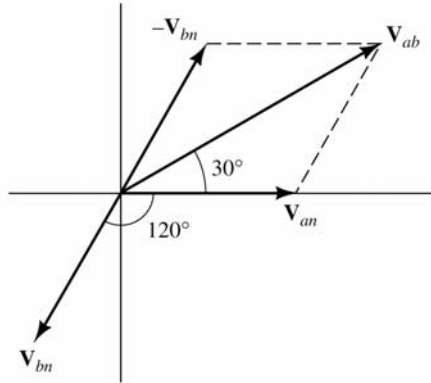
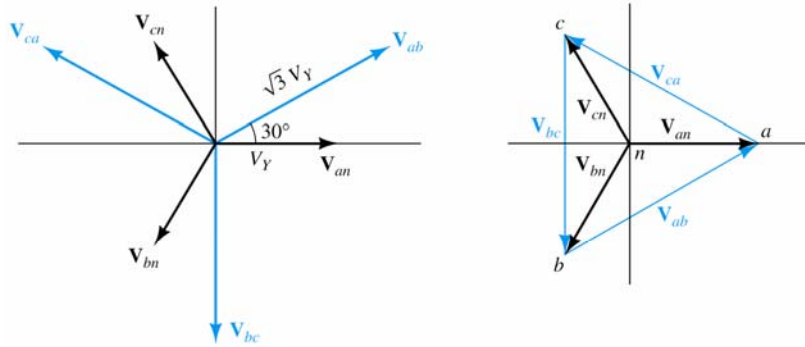


Figure 5.39 Phasor diagram showing the relationship between the line-to-line voltage v_{ab} and the line-to-neutral voltages v_{an} and v_{bn} .

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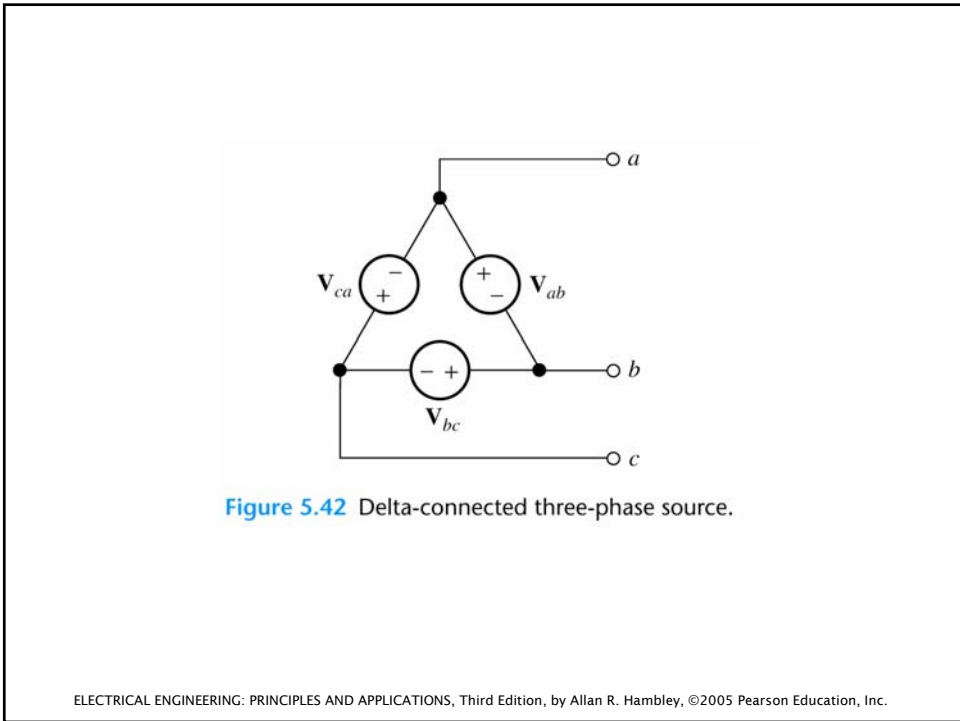
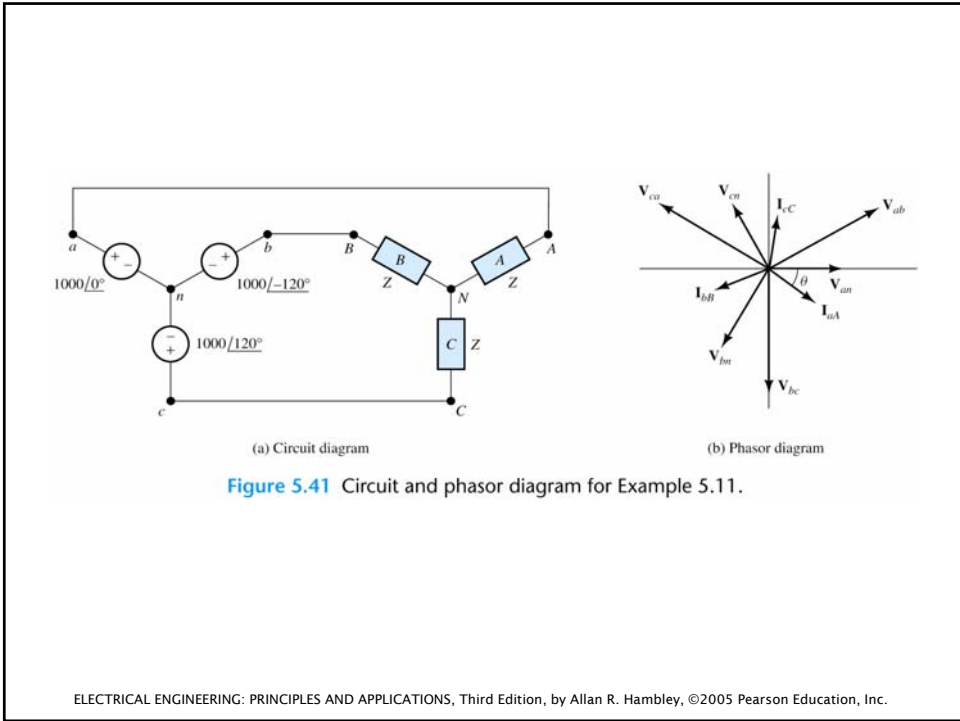


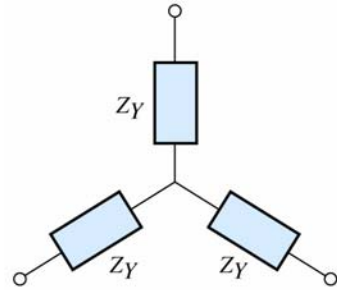
(a) All phasors starting from the origin

(b) A more intuitive way to draw the phasor diagram

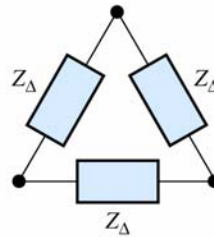
Figure 5.40 Phasor diagram showing line-to-line voltages and line-to-neutral voltages.

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(a) Wye-connected load

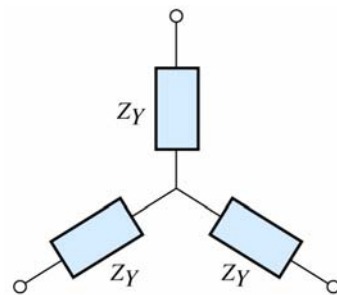


(b) Delta-connected load

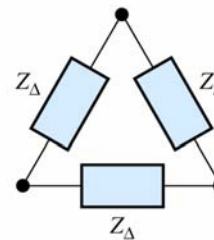
Figure 5.43 Loads can be either wye-connected or delta-connected.

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$$Z_{\Delta} = 3Z_Y$$



(a) Wye-connected load



(b) Delta-connected load

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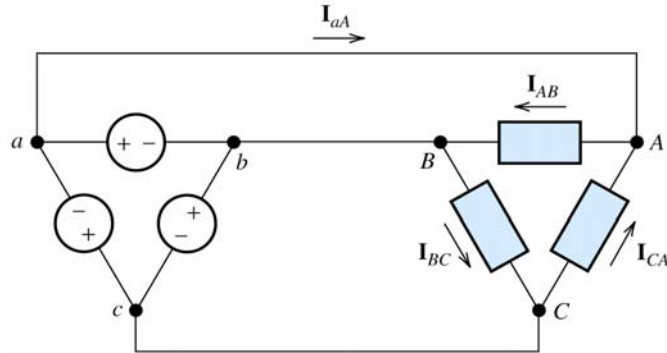


Figure 5.44 A delta-connected source delivering power to a delta-connected load.

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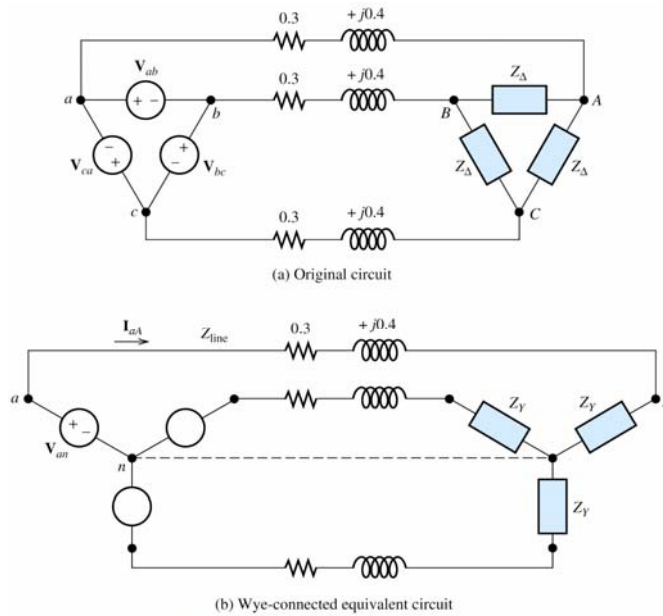


Figure 5.45 Circuit of Example 5.12.

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