

ECE 241 LECTURE 11: AC POWER (& FREQUENCY RESPONSE)

From past work: $p = vi = i^2 R = v^2/R$ for resistance R

For sinusoidal voltage/current, power varies sinusoidally, too.

In practice, usually want AVERAGE power P

$$\begin{aligned} P &= \frac{1}{T} \int_0^T i^2 R dt = \frac{1}{T} \int_0^T I_m^2 \sin^2 \omega t R dt = \frac{1}{T} \int_0^T I_m^2 R \frac{1}{2} (1 - \cos 2\omega t) dt \\ &= \frac{1}{T} \cdot \frac{I_m^2}{2} R \cdot T = I_{RMS}^2 R \quad \text{where } I_{RMS} = \frac{I_m}{\sqrt{2}} \\ &= V_{RMS}^2 / R \quad \text{typically written as } I^2 R \text{ or } V^2 / R \end{aligned}$$

Power measurement by "wattmeter":

v applied to "voltage coil" \rightarrow creates current $\propto v$, & hence magnetic field $\propto v$

i applied to "current/field coil" \rightarrow produces torque in magnetic field $\propto v i$

Torque \rightarrow deflection, averaged by inertia (e.g. cannot follow 60Hz)

For v, i out of phase by θ \rightarrow reading = $VI \cos \theta$

Note: For 110V 60Hz, V_{RMS} actually 120V

& for $v = \sqrt{2} \cdot 120V \cdot \sin \omega t$, $\sqrt{2} \times 120V \approx 170V$

REACTIVE POWER

$$P_R = i^2 R = v^2 / R$$

i, v positive even when $i, v < 0$
Hence power dissipated throughout cycle.

For Inductor

Energy stored as current increases
to max $I_m = \frac{1}{2} L I_m^2$

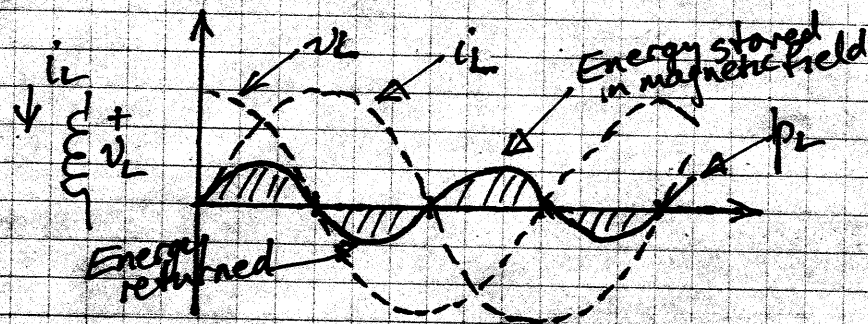
then returned to circuit as current
decreases to zero

Power positive when absorbed (ie. being stored), negative when returned.

$$i_L = I_m \cos(\omega t - \pi/2) = \sqrt{2} I \sin \omega t$$

$$\therefore v_L = L \frac{di}{dt} = \sqrt{2} I L \cos \omega t \cdot \omega$$

$$\begin{aligned} \& \ p_L = i_L v_L = 2 I^2 \omega L \sin \omega t \cos \omega t \\ & = I^2 \omega L \sin 2\omega t \\ & = I^2 X_L \sin 2\omega t \end{aligned}$$



Capacitor

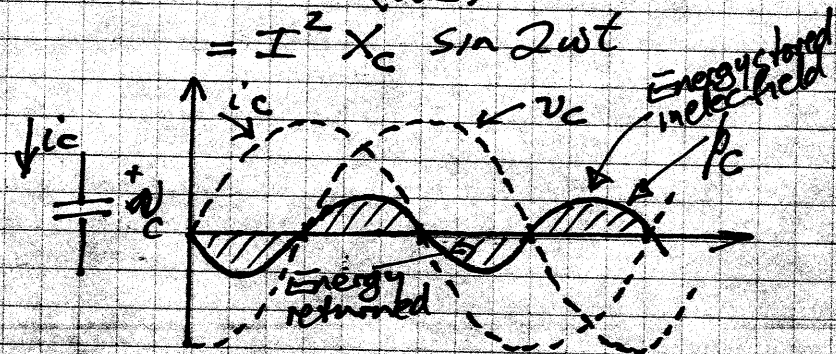
Energy stored as voltage increases
to max $V_m = \frac{1}{2} C V_m^2$

then returned to circuit as voltage
decreases to zero.

$$i_C = I_m \cos(\omega t - \pi/2) = \sqrt{2} I \sin \omega t$$

$$\therefore v_C = \frac{1}{C} \int i_C dt + V_0 = -\sqrt{2} \frac{I}{\omega C} \cos \omega t \cdot \frac{1}{\omega}$$

$$\begin{aligned} \& \ p_C = i_C v_C = -2 I^2 \left(\frac{1}{\omega C}\right) \sin \omega t \cos \omega t \\ & = 2 I^2 \left(\frac{-1}{\omega C}\right) \sin \omega t \cos \omega t \\ & = I^2 X_C \sin 2\omega t \end{aligned}$$



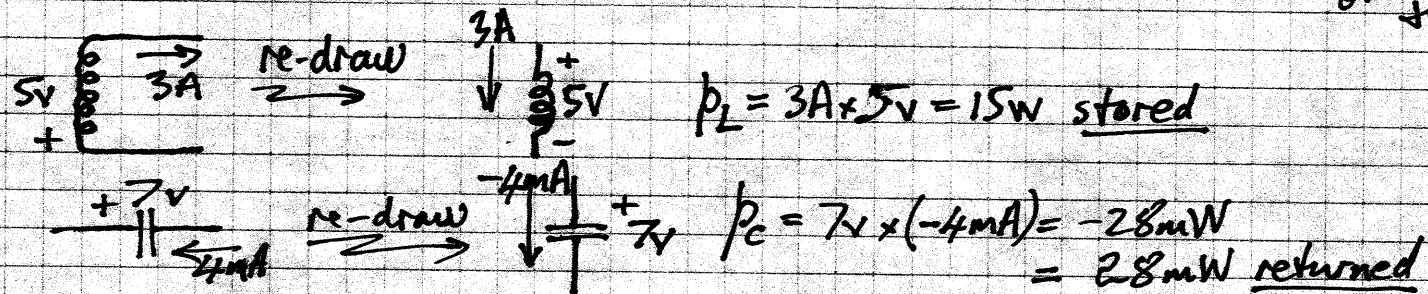
Note:

No net power consumption by L or C
Periodic storage/return of energy

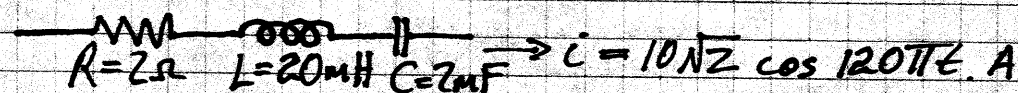
Power $P_x = I^2 X \sin 2\omega t$, Amplitude $I^2 X$

Define Reactive Power $P_x = I^2 X = \frac{V^2}{X} = Q$ ← convention (but used for other things too)

Exercise 7.1



Exercise 7.2



Max. Instantaneous powers

$$p_{R_{max}} = I_m^2 R = (10\sqrt{2})^2 \times 2 = 400W$$

$$p_{L_{max}} = I^2 X_L = 100 \cdot 120\pi \cdot 20 \times 10^{-3} = 240\pi = 754W$$

$$p_{C_{max}} = I^2 X_C = 100 \cdot \frac{1}{120\pi \cdot 2 \times 10^{-6}} = 132.6W$$

Note p_L and $p_C = I^2 X \sin 2\omega t \xrightarrow{\text{max}} I^2 X$ when $\sin 2\omega t = 1$

Average power in series combination = $I^2 R = 10^2 \times 2 = 200W$
since L, C consume no average power

POWER FACTOR

General case of a complex impedance

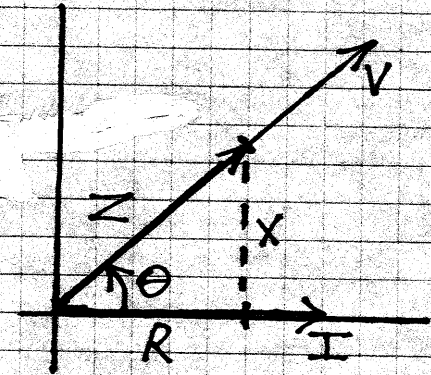
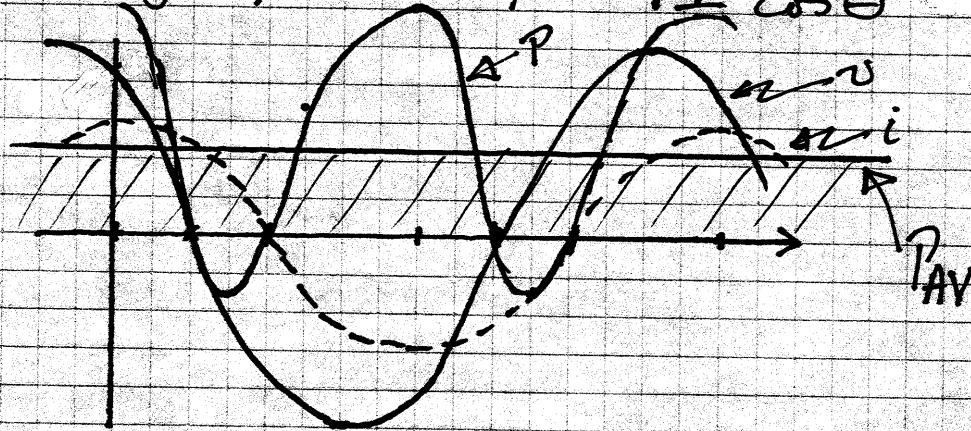
$$\vec{V} = \vec{Z} \vec{I} = (Z \angle \theta) \vec{I}$$

$$V = Z I \text{ magnitudes}$$

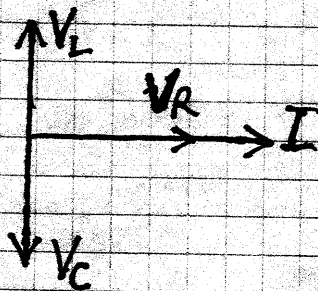
$$p = vi = \sqrt{2} V \cos(\omega t + \theta) \cdot \sqrt{2} I \cos \omega t = 2 VI \cos(\omega t + \theta) \cos \omega t$$

$$= VI \cos \theta + VI \cos(2\omega t + \theta)$$

Hence average power $P = VI \cos \theta$



Definition: Power Factor $pf = \cos \theta = \frac{P}{VI}$



Inductance: Current lags voltage \rightarrow lagging power factor

Capacitance: Current leads voltage \rightarrow leading power factor

$$X = Z \sin \theta \text{ (above)} \text{ so } Q = P_x = I^2 X = I^2 Z \sin \theta = VI \sin \theta$$

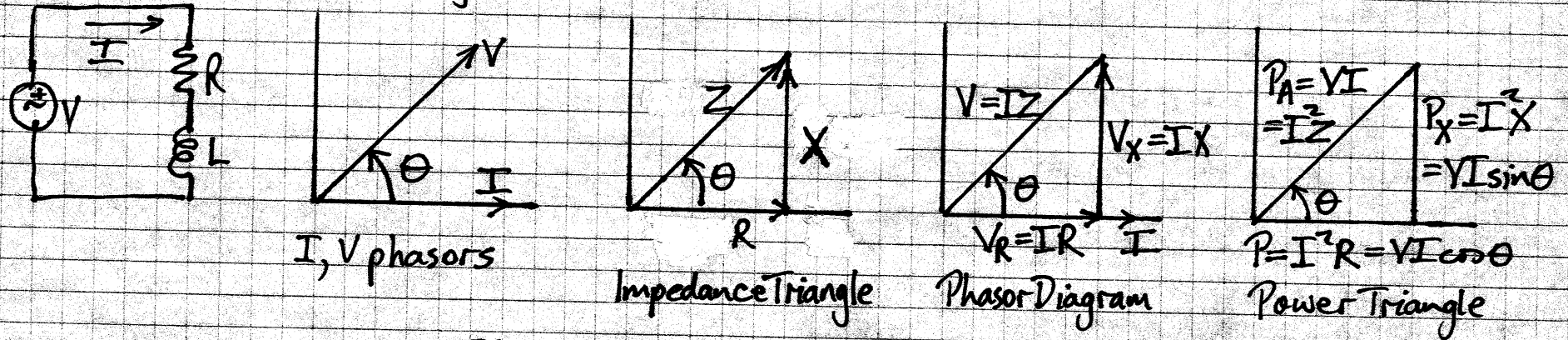
$\sin \theta = \text{"reactive factor"}$

$Q = P_x$ in volt-amps reactive \rightarrow VARs

COMPLEX POWER

AC power $\rightarrow VI \cos \theta$
 Reactive power $\rightarrow VI \sin \theta$

For inductive load eg. motor



$$\begin{aligned} \text{Apparent Power} &= \tilde{P}_A = VI \cos \theta + j VI \sin \theta = VI \angle \theta \\ &= P + j P_x (= P + j Q) = P_A \angle \theta \end{aligned}$$

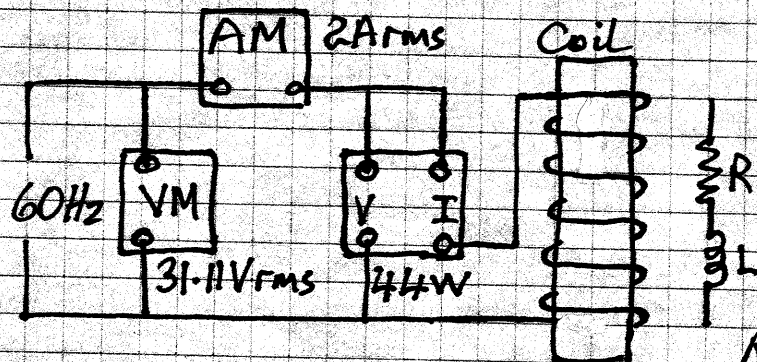
Units of apparent power \rightarrow volt-amps (VA)

Phase angle: $\theta > 0$ & $P_x = VI \sin \theta > 0$ for current lags voltage (inductive)

$\theta < 0$ & $P_x = VI \sin \theta < 0$ for current leads voltage (capacitive)

Real power $VI \cos \theta > 0$ for $-90^\circ < \theta < +90^\circ$

Exercise 7.3 Find L & R for meter readings shown



$$\text{Real } P = I^2 R \quad \therefore R = \frac{P}{I^2} = \frac{44 \text{ W}}{(2 \text{ A})^2} = 11 \Omega$$

$$\text{pf } \cos \theta = \frac{P}{VI} = \frac{44}{2 \times 31.1} = 0.707$$

$$\therefore \theta = 45^\circ$$

$$\text{Reactive } P_x = VI \sin \theta = 2 \times 31.1 \sin 45^\circ = 44 \text{ VAR}$$

$$\therefore X_L = \frac{P_x}{I^2} = \frac{44}{2^2} = 11 \Omega = \omega L \quad \therefore L = \frac{11}{2\pi 60} = 0.029 \text{ H}$$

Exercise 7.4 For a load: $v = 10\sqrt{2} \cos(25t + \pi/8) \text{ V}$ & $i = 3.5\sqrt{2} \sin(25t + 3\pi/4) \text{ A}$

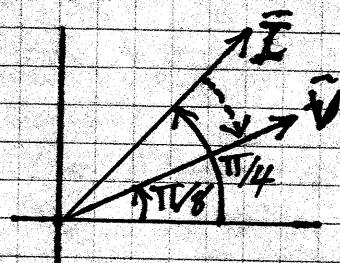
(a) Calculate pf

$$\& v = 10 / \pi/8$$

$$\therefore \theta = \pi/8 - \pi/4 = -\pi/8$$

$$\text{So pf} = \cos(-\pi/8) = \cos 22.5^\circ = 0.9239$$

First need i as $\cos \rightarrow i = 3.5\sqrt{2} \cos(25t + \pi/4) = 3.5 / \pi/4$



$\theta =$ angle by which \vec{V} leads \vec{I}

(b) Calculate load average power and reactive power

$$P = VI \cos \theta = 10 \times 3.5 \times 0.924 = 32.3 \text{ watts}$$

$$Q = P_x = VI \sin \theta = 10 \times 3.5 \times \sin(-22.5^\circ) = -13.4 \text{ VARs}$$

Exercise 7.5 20kW load heating (real) + 150 kVA @ 0.6 lagging pf
 Supply is 4000V. (induction motors)

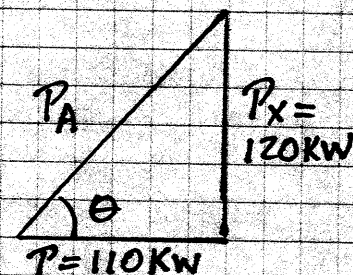
Determine total current and overall pf.

$$P_H = 20 \text{ kW} \quad P_M = 150 \times 0.6 = 90 \text{ kW}$$

$$P_{XH} = 0 \quad P_{XM} = 150 \sin \theta = 150 (1 - \cos^2 \theta)^{1/2} = 150 (1 - 0.6^2)^{1/2} = 150 \sqrt{0.64} \\ = 150 \times 0.8 = 120 \text{ kW}$$

$$\therefore \text{Total real power} = 20 + 90 = 110 \text{ kW}$$

$$\text{Total reactive power} = 0 + 120 = 120 \text{ kW}$$



$$\text{pf} = \cos \theta = \cos \left(\arctan \frac{120}{110} \right) = 0.676$$

$$P_A = (110^2 + 120^2)^{1/2} / \arctan \frac{120}{110} = 162.79 / 47.49^\circ \text{ KVA}$$

$$\& \text{ Total current} = \frac{P_A}{V} = \frac{162.8 \times 10^3 \text{ VA}}{4000 \text{ V}} = 40.7 \text{ A}$$

Note that to supply this load requires wire to carry 40.7A and a 163KVA transformer.
 Much of this requirement is due to the unnecessary reactive power.

If $\text{pf} = 1$, ie. $\theta = 0$, would only need 110 KVA transformer and $\frac{110,000}{4,000} = 27.5 \text{ A}$ wire, and also less $I^2 R$ losses in wire etc.

Also, power costs are by apparent KVA.

Usually industrial equipment is inductive \rightarrow lagging pf.
 Add C to move pf \rightarrow 1

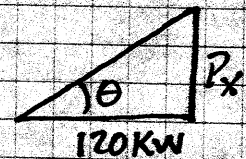
EXERCISE 7.6 Plant loads specified in the table. Specify equipment to correct to 0.95 pf lagging.

Load	P_A (KVA)	θ ($^\circ$)	pf	P (KW)	P_x (KVAR)	V (volts)
Initial	170	45	0.71	120		4000
Required			0.95	120		4000

$$\theta_{\text{req'd}} = \cos^{-1} 0.95 = 18.2^\circ$$

\therefore Reduce reactive power to

$$P_x = 120 \tan 18.2^\circ = 39.44 \text{ KVAR}$$



$$\text{Initial } P_x = 120 \tan 45^\circ = 120 \text{ KVAR}$$

$$\text{ie. Correction needed} = 39.44 - 120 = -80.56 \text{ KVAR}$$

Negative correction needs capacitor C with $P_{xc} = \frac{V^2}{X_c} = V^2(-\omega C)$

$$\text{ie. } C = \frac{P_{xc}}{-\omega V^2} = \frac{-80.56 \times 10^3}{-(2\pi 60)(4000)^2} = 13.4 \mu\text{F}$$

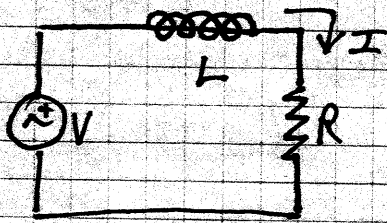
So, complete table

Load	P_A (KVA)	θ ($^\circ$)	pf	P (KW)	P_x (KVAR)
Initial	170	45	0.71	120	120
Final	126.3	18.2	0.95	120	39.44
Correction	-43.7			0	-80.56

$$P_A^2 = P^2 + P_x^2 = 120^2 + 39.44^2$$

$$P_A = 126.3 \text{ KVA}$$

FREQUENCY RESPONSE



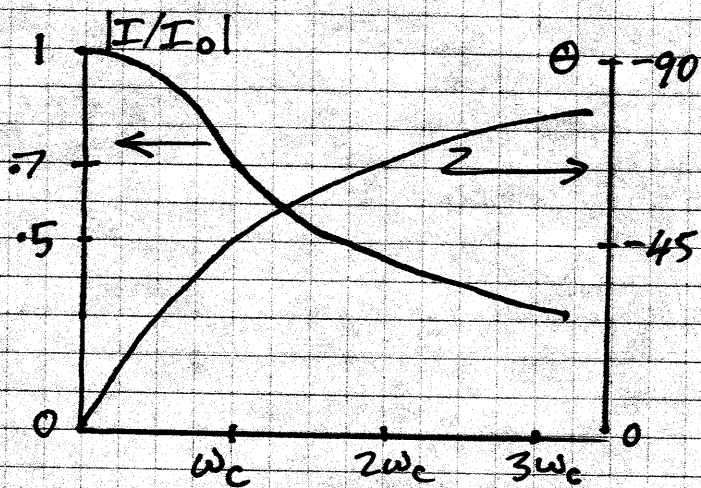
$$I(\omega) = \frac{\bar{V}}{Z} = \frac{\bar{V}}{R + j\omega L} = \frac{\bar{V}/R}{1 + j\omega \frac{L}{R}} \xrightarrow[\omega=0]{\text{DC}} \bar{I}_0 = \bar{V}/R$$

$$\begin{aligned} \frac{\hat{I}}{\bar{I}_0} &= \frac{1}{1 + j\omega \frac{L}{R}} = \frac{1 - j\omega \frac{L}{R}}{1 + (\omega \frac{L}{R})^2} = \frac{[1 + (\omega \frac{L}{R})^2]^{-1/2}}{1 + (\omega \frac{L}{R})^2} \angle \arctan -\frac{\omega L}{R} \\ &= \frac{1}{\sqrt{1 + (\omega \frac{L}{R})^2}} \angle \arctan -\frac{\omega L}{R} = \frac{\hat{I}}{\bar{I}_0} \angle \theta \end{aligned}$$

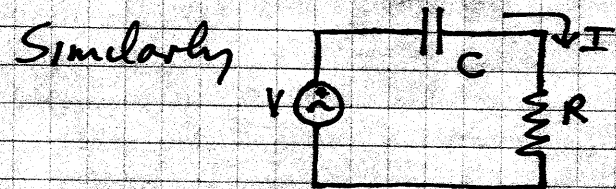
At $\omega_c = R/L$

$$\frac{\hat{I}}{\bar{I}_0} = \frac{1}{\sqrt{2}} \angle \arctan -1 = 0.707 \angle -45^\circ$$

$I^2 R = \frac{1}{2} I_0^2 R$ i.e. this is the "half-power" freq



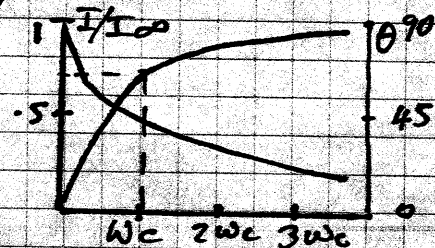
Low pass filter



$$\hat{I} = \frac{\bar{V}}{Z} = \frac{\bar{V}}{R - j/\omega C} = \frac{\bar{V}/R}{1 - \frac{j}{\omega RC}} \xrightarrow[\omega \rightarrow \infty]{\text{HF}} \bar{I}_0 = \frac{\bar{V}}{R}$$

$$\frac{\hat{I}}{\bar{I}_0} = \frac{1}{1 - j/\omega RC} = \frac{1}{\sqrt{1 + (\omega RC)^2}} \angle \arctan 1/\omega RC$$

At $\omega_c = 1/RC$ $|\frac{\hat{I}}{\bar{I}_0}| \rightarrow \frac{1}{\sqrt{2}}$



ASSIGNMENT #5

P 6.14

6.16

6.20

6.22

7.3

7.5

7.9

7.10