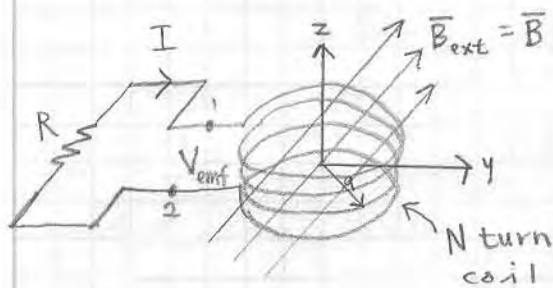


## Inductor in a changing Magnetic Field



An inductor is formed by winding  $N$  turns of a conducting wire into circular loops of radius  $a$ . The inductor loop is centered at the origin in the  $x$ - $y$  plane and connected to a resistor  $R$ .

In the presence of an external magnetic field  $\vec{B}_{\text{ext}} = B_0(\hat{y}2 + \hat{z}3)\sin(\omega t)$

Note: The external magnetic field is time varying therefore according to Faraday's law (6.6) an electromotive force is induced.

$$V_{\text{emf}} = V_{\text{emf}}^{\text{tr}} + V_{\text{emf}}^{\text{m}} = V_{\text{emf}}^{\text{tr}} + 0$$

Since the loop is stationary the motional emf equals 0 (p. 257).

The magnetic flux density linking each coil is given by:

$$\Phi = \int_S \vec{B} \cdot d\vec{s} \quad (6.5)$$

Note: The surface we are integrating over is in the  $x$ - $y$  plane, therefore  $\hat{z} = \hat{n}$  and we need to use  $ds_z = \hat{z} r dr d\theta$  (Table 3-1) cylindrical coordinates used to match problem geometry.

$$\Phi = \int_0^{2\pi} \int_0^a (B_0(\hat{y}2 + \hat{z}3)\sin(\omega t)) \cdot \hat{z} r dr d\theta$$

$$= \int_0^{2\pi} \int_0^a (\hat{y}B_0 2\sin(\omega t) + \hat{z}B_0 3\sin(\omega t)) \cdot \hat{z} r dr d\theta \quad \text{Note: } \hat{z} \cdot \hat{y} = 0$$

$$\hat{z} \cdot \hat{z} = 1$$

$$= \int_0^{2\pi} \int_0^a B_0 3\sin(\omega t) r dr d\theta$$

$$= 3B_0 \sin(\omega t) \int_0^{2\pi} d\theta \int_0^a r dr$$

$$= 3B_0 \sin(\omega t) (2\pi) \left( \frac{r^2}{2} \Big|_0^a \right)$$

$$\Phi = 3\pi a^2 B_0 \sin(\omega t) \quad \text{Wb}$$

Note: If the surface area is planar and the magnetic field is uniform then to save time we should realize that the  $\Phi$  is just  $B_n A_s$  where  $A_s$  is the surface area.

$$A_s = \pi a^2, \quad B_n = B_z = B_0 3\sin(\omega t)$$

$$\Phi = B_z \cdot A_s = 3\pi a^2 B_0 \sin(\omega t)$$

if  $N=10$ ,  $B_0 = 0.2 \text{ T}$ ,  $a = 0.1 \text{ m}$ ,  $\omega = 10^3 \text{ rad/s}$

$$V_{\text{emf}} = V_{\text{emf}}^{\text{tr}} = -N \frac{d\Phi}{dt} = -N \frac{d}{dt} \int_S \vec{B} \cdot d\vec{S} = -N \frac{d}{dt} (3\pi a^2 B_0 \sin(\omega t))$$

$$= -N 3\pi a^2 B_0 \cos(\omega t) \omega$$

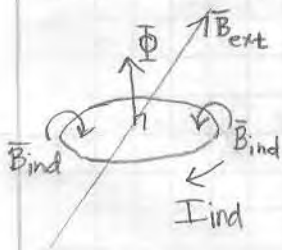
$$= -10 \cdot 3\pi \cdot 0.1^2 \cdot 0.2 \cos(10^3 t) 10^3$$

$$V_{\text{emf}} = -60\pi \cos(10^3 t) \text{ V}$$

At  $t=0$   $\frac{d\Phi}{dt} = \frac{d}{dt} (3\pi a^2 B_0 \sin(\omega t)) = 3\pi a^2 B_0 \omega \cos(\omega t) = 3\pi a^2 B_0 \omega$

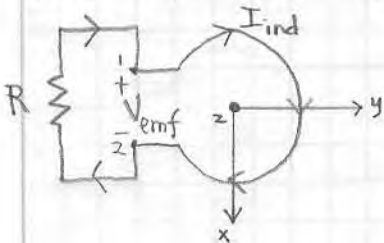
Since  $\frac{d\Phi}{dt} > 0$  the external  $\vec{B}(t)$  is increasing and from ...

Lenz's Law; the current in the loop is always in such a direction as to oppose the change of magnetic flux  $\Phi(t)$  that produced it.



from the R.H.R. for magnetic field near a wire, thumb in direction of current with four fingers curled around the wire in the direction of the magnetic field.

Looking down on the circuit from  $+z$  the induced current moves in the clockwise direction.



Since the current propagates from node 1 to node 2, node 1 must be at a higher potential (positive).

$$V_{\text{emf}} = V_{\text{emf}}^{\text{tr}} = V_1 - V_2 = -60\pi \approx -188.5 \text{ V @ } t=0$$

For  $R = 1 \text{ k}\Omega$

$$V_{\text{emf}} = I_{\text{ind}} R$$

(neglecting wire resistance)

$$I_{\text{ind}}(t) = \frac{V_{\text{emf}}(t)}{R} = \frac{-60\pi \cos(10^3 t)}{R}$$

At  $t=0$

$$I_{\text{ind}}(0) = \frac{-60\pi \cos(0)}{10^3} \approx -188.5 \text{ mA}$$