This material is adapted from a presentation constructed by Gerry Dozier at Auburn University

- Evolutionary Computation is the field of study devoted to the design, development, and analysis is problem solvers based on natural selection (simulated evolution).
- Evolution has proven to be a powerful search process.
- Evolutionary Computation has been successfully applied to a wide range of problems including:
 - Aircraft Design,
 - Routing in Communications Networks,
 - Tracking Windshear,
 - Game Playing (Checkers [Fogel])

Introduction to Evolutionary Computation (Applications cont.)

- Robotics,
- Air Traffic Control,
- Design,
- Scheduling,
- Machine Learning,
- Pattern Recognition,
- Job Shop Scheduling,
- VLSI Circuit Layout,
- Evolvable Hardware

• An Example Evolutionary Computation

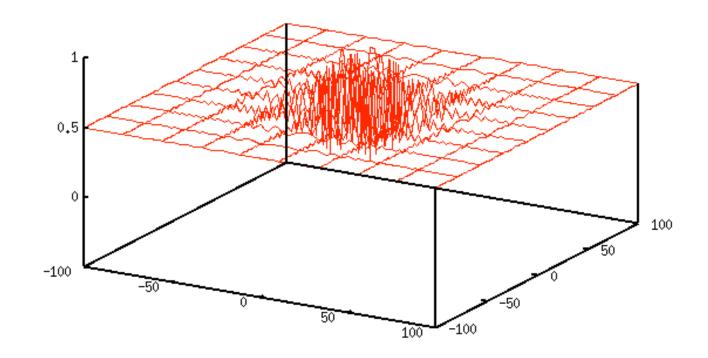
```
Procedure EC{
    t = 0;
    Initialize Pop(t);
    Evaluate Pop(t);
    While (Not Done)
    {
        Parents(t) = Select_Parents(Pop(t));
        Offspring(t) = Procreate(Parents(t));
        Evaluate(Offspring(t));
        Pop(t+1) = Replace(Pop(t),Offspring(t));
        t = t + 1;
    }
}
```

- In an Evolutionary Computation, a population of candidate solutions (CSs) is randomly generated.
- Each of the CSs is evaluated and assigned a fitness based on a user specified evaluation function. The evaluation function is used to determine the 'goodness' of a CS.
- A number of individuals are then selected to be parents based on their fitness. The *Select_Parents* method must be one that balances the urge for selecting the best performing CSs with the need for population diversity.

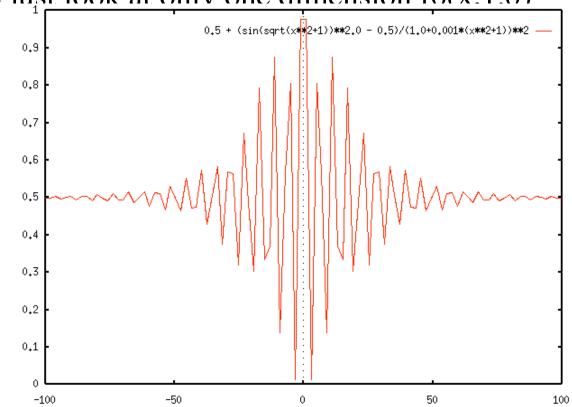
- The selected parents are then allowed to create a set of offspring which are evaluated and assigned a fitness using the same evaluation function defined by the user.
- Finally, a decision must be made as to which individuals of the current population and the offspring population should be allowed to survive.

- Once a decision is made the survivors comprise the next generation (Pop(t+1)).
- This process of selecting parents based on their fitness, allowing them to create offspring, and replacing weaker members of the population is repeated for a user specified number of cycles.
- Stopping conditions for evolutionary search could be:
 - The discovery of an optimal or near optimal solution
 - Convergence on a single solution or set of similar solutions,
 - When the EC detects the problem has no feasible solution,
 - After a user-specified threshold has been reached, or
 - After a maximum number of cycles.

- Let's walk through a simple example!
- Let's say you were asked to solve the following problem:
 - Maximize:
 - $f6(x,y) = 0.5 + (\sin(\operatorname{sqrt}(x^2+y^2))^2 0.5)/(1.0 + 0.001(x^2+y^2))^2$
 - Where x and y are take from [-100.0,100.0]
 - You must find a solution that is greater than 0.99754, and
 - you can only evaluate a total of 4000 candidate solutions (CSs)
- This seems like a difficult problem. It would be nice if we could see what it looks like! This may help us determine a good algorithm for solving it.



• If we just look at only one dimension f6(x.1.0)



- Let's develop a simple EC for solving this problem
- An individual (chromosome or CS)
 - $-\langle x_i, y_i \rangle$
 - $fit_i = f6(x_i, y_i)$

```
Procedure simpleEC{
       t = 0;
       Initialize Pop(t); /* of P individuals */
       Evaluate Pop(t);
       while (t \le 4000-P) {
          Select_Parent(\langle x_{mom}, y_{mom} \rangle); /* Randomly */
          Select Parent (\langle x_{dad}, y_{dad} \rangle); /* Randomly */
          Create Offspring (\langle x_{kid}, y_{kid} \rangle):
               x_{kid} = rnd(x_{mom}, x_{dad}) + N_x(0, []);
               y_{kid} = rnd(y_{mom}, y_{dad}) + N_y(0, []);
          fit_{kid} = Evaluate(\langle x_{kid}, y_{kid} \rangle);
          Pop(t+1) = Replace(worst, kid); {Pop(t)-{worst}} [ {kid}
          t = t + 1;
```

Introduction to Evolutionary Computation: Reading List

- 1. Bäck, T., Hammel, U., and Schwefel, H.-P. (1997). "Evolutionary Computation: Comments on the History and Current State," *IEEE Transactions on Evolutionary Computation*, VOL. 1, NO. 1, April 1997.
- 2. Spears, W. M., De Jong, K. A., Bäck, T., Fogel, D. B., and de Garis, H. (1993). "An Overview of Evolutionary Computation," *The Proceedings of the European Conference on Machine Learning*, v667, pp. 442-459. (http://www.cs.uwyo.edu/~wspears/papers/ecml93.pdf)
- 3. De Jong, Kenneth A., and William M. Spears (1993). "On the State of Evolutionary Computation", *The Proceedings of the Int'l Conference on Genetic Algorithms*, pp. 618-623. (http://www.cs.uwyo.edu/~wspears/papers/icga93.pdf)