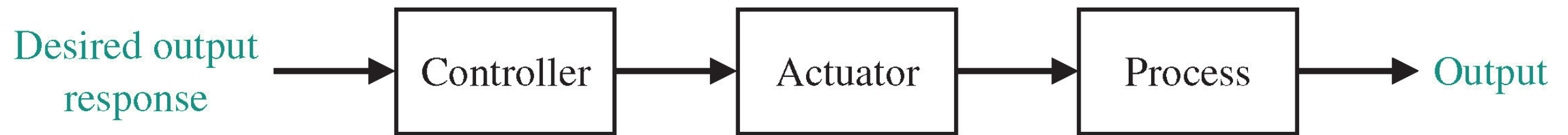


FIGURE 1.1 Process to be controlled.



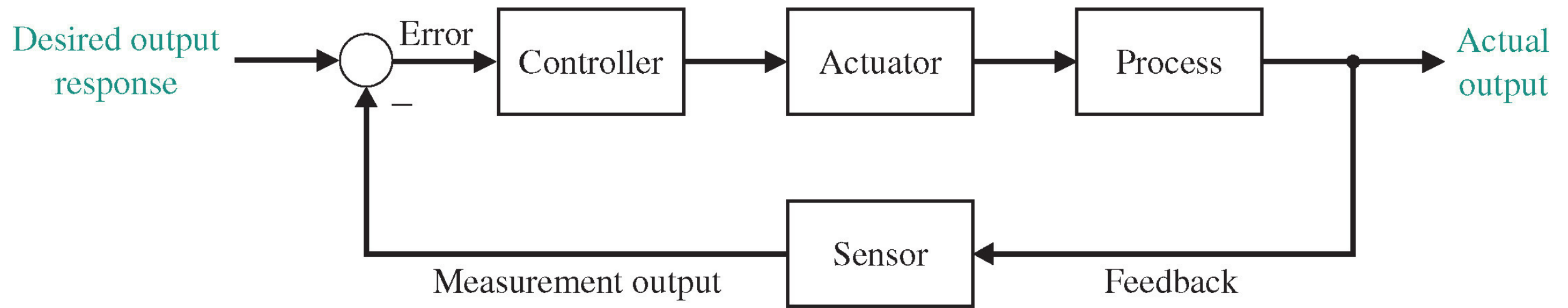
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FIGURE 1.2 Open-loop control system (without feedback).



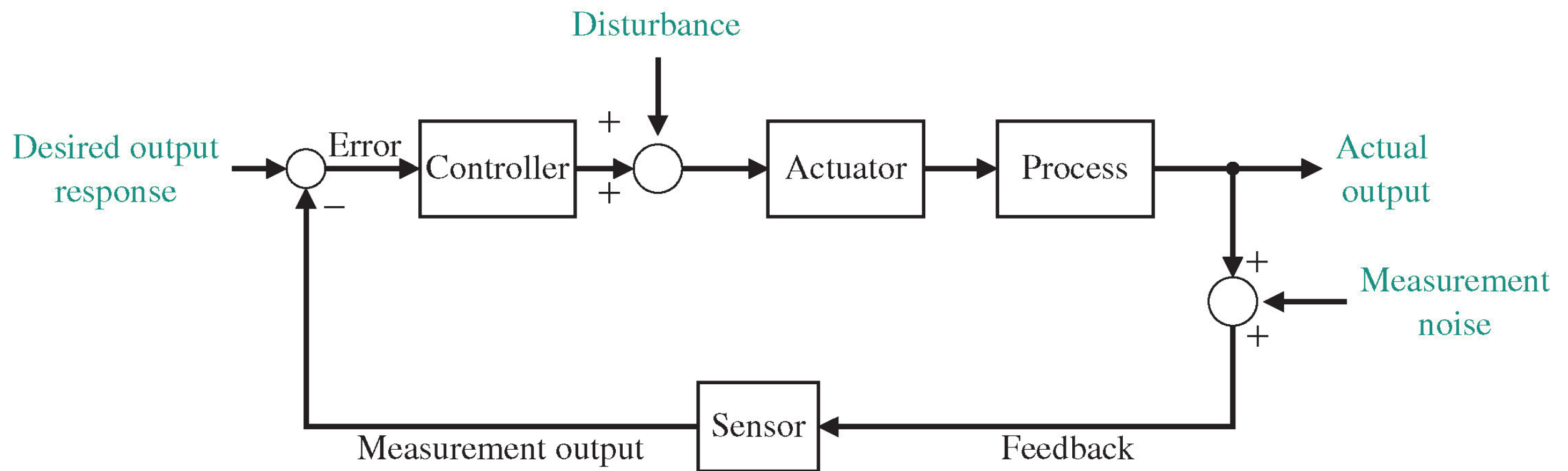
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FIGURE 1.3 Closed-loop feedback control system (without feedback).



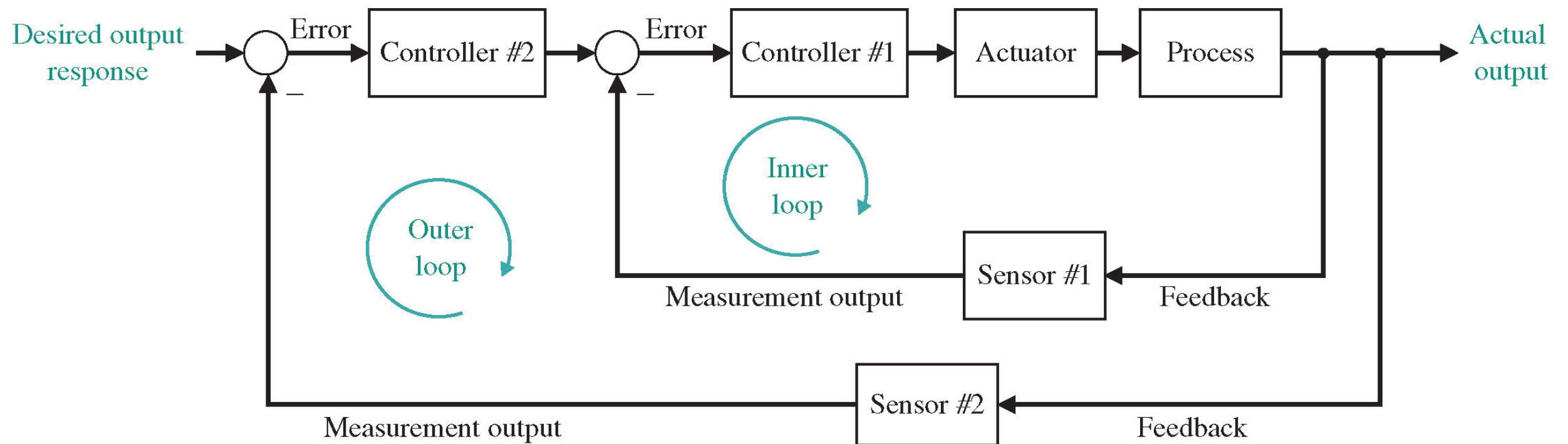
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FIGURE 1.4 Closed-loop feedback system with external disturbances and measurement noise.



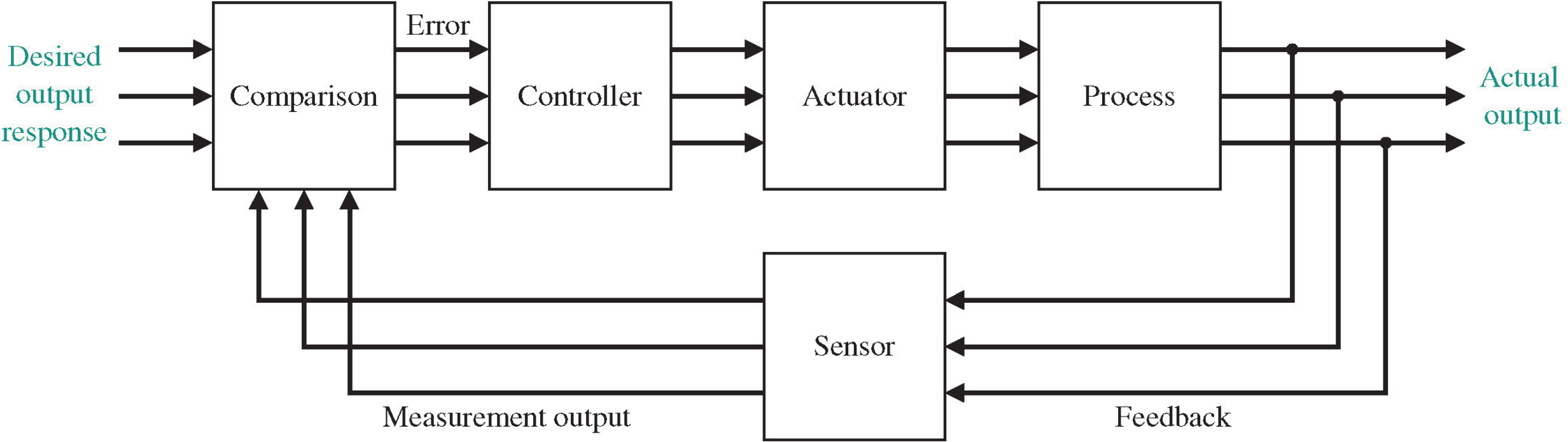
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FIGURE 1.5 Multiloop feedback system with an inner loop and an outer loop.



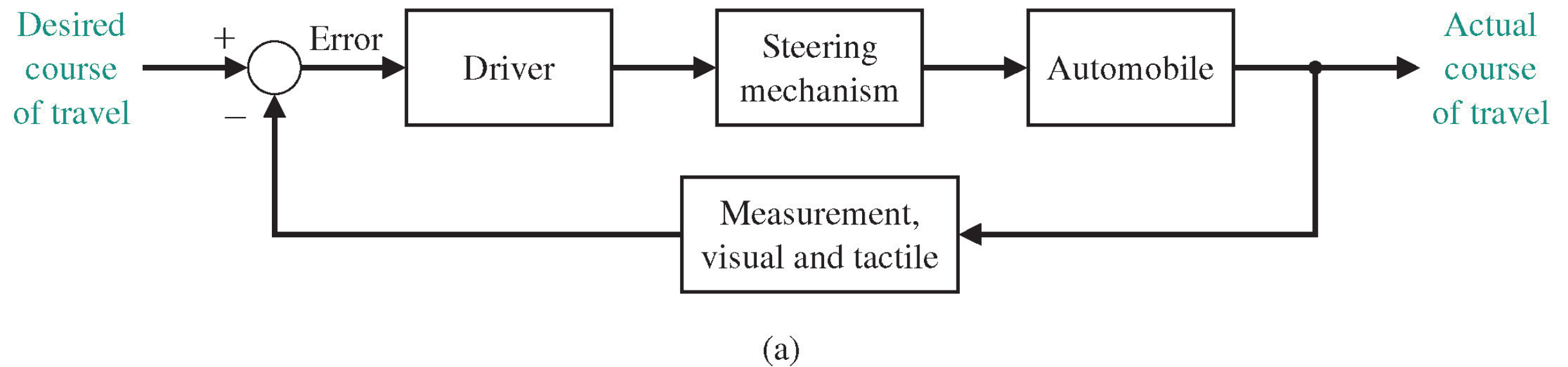
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FIGURE 1.6 Multivariable control system.



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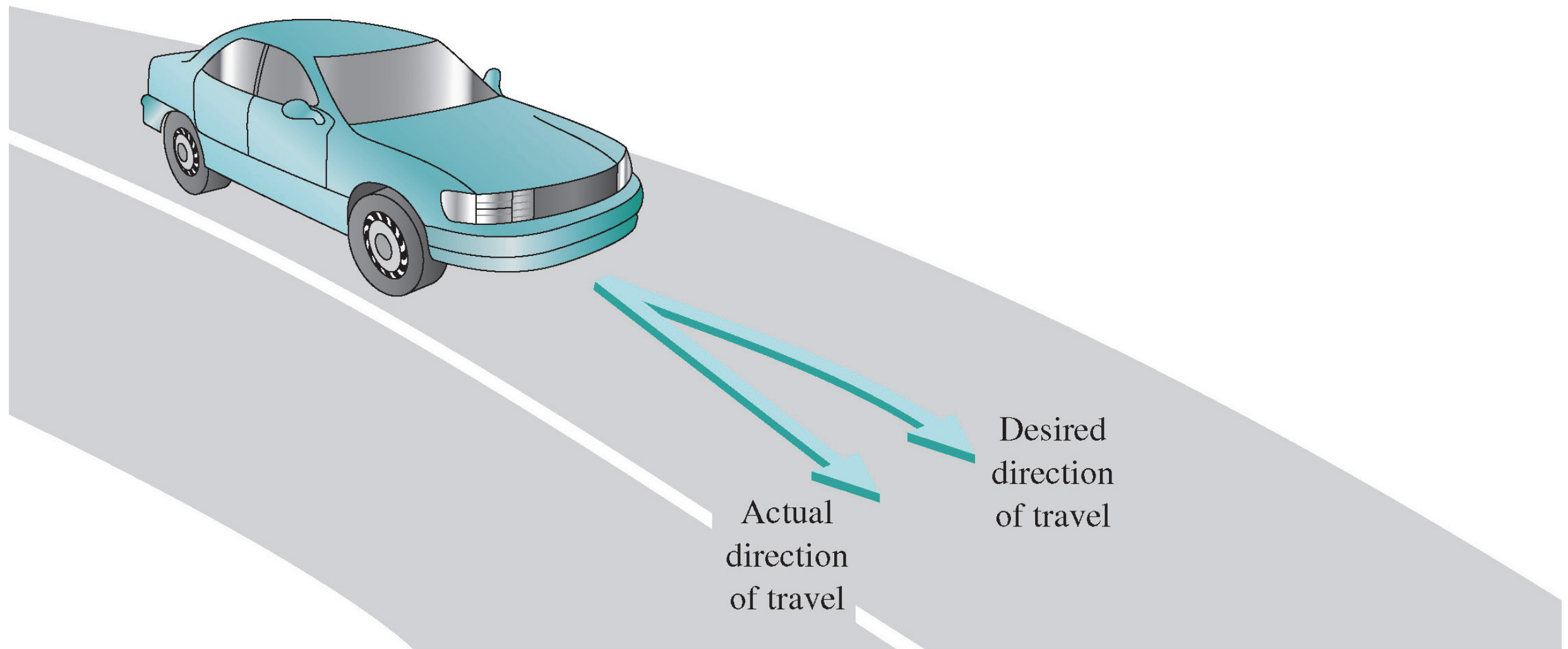
FIGURE 1.10 (a) Automobile steering control system. (b) The driver uses the difference between the actual and the desired direction of travel to generate a controlled adjustment of the steering wheel. (c) Typical direction-of-travel response.



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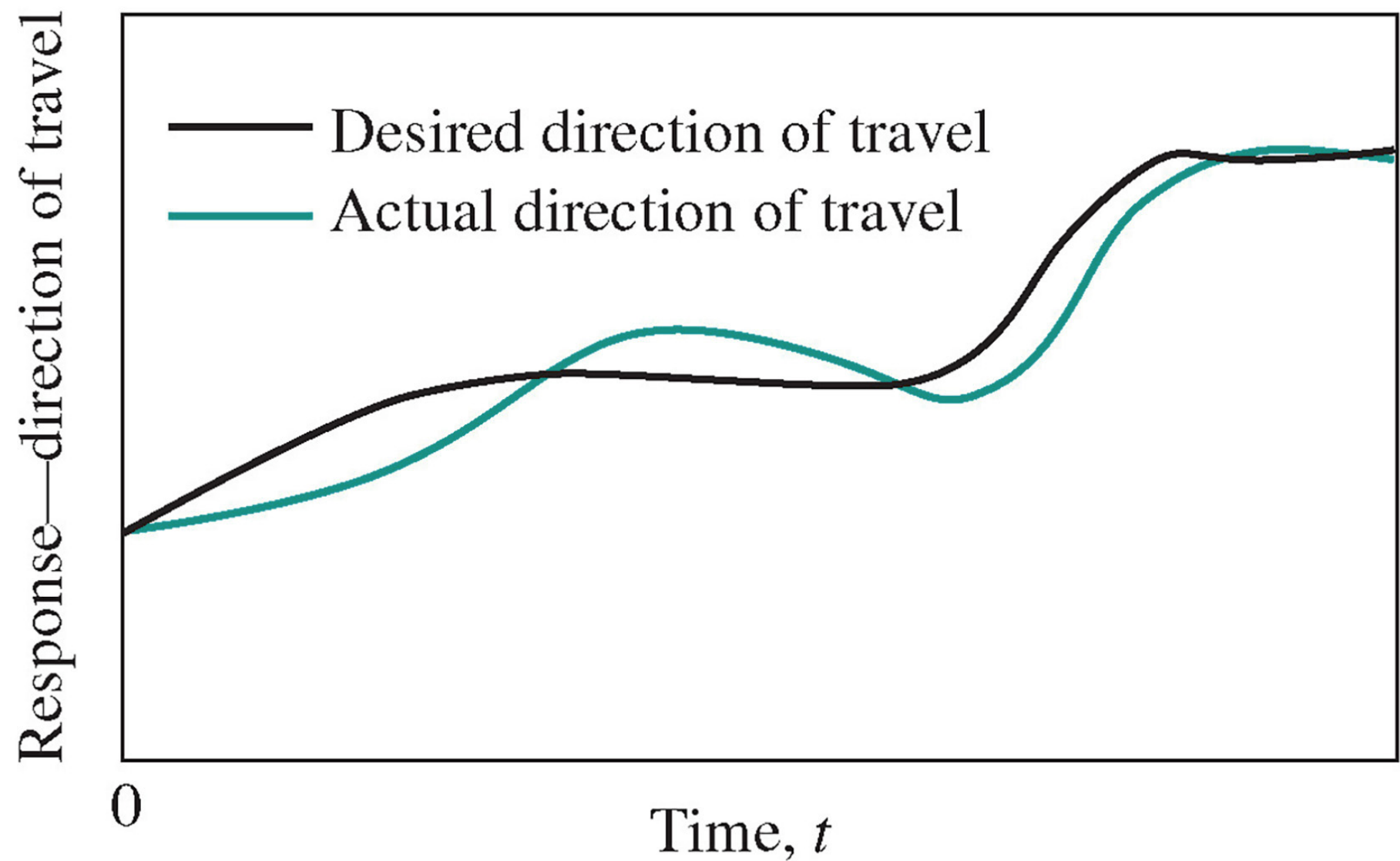
FIGURE 1.10 (continued) (a) Automobile steering control system. (b) The driver uses the difference between the actual and the desired direction of travel to generate a controlled adjustment of the steering wheel. (c) Typical direction-of-travel response.



(b)

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FIGURE 1.10 (continued) (a) Automobile steering control system. (b) The driver uses the difference between the actual and the desired direction of travel to generate a controlled adjustment of the steering wheel. (c) Typical direction-of-travel response.



(c)

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