

Computer Graphics

Prof. Feng Liu

Fall 2018

<http://www.cs.pdx.edu/~fliu/courses/cs447/>

11/15/2018

Last time

- Polygon Mesh and Modeling

Today

- Modeling Technologies
- **Final Exam:** December 4 (Tuesday) 17:30-19:00

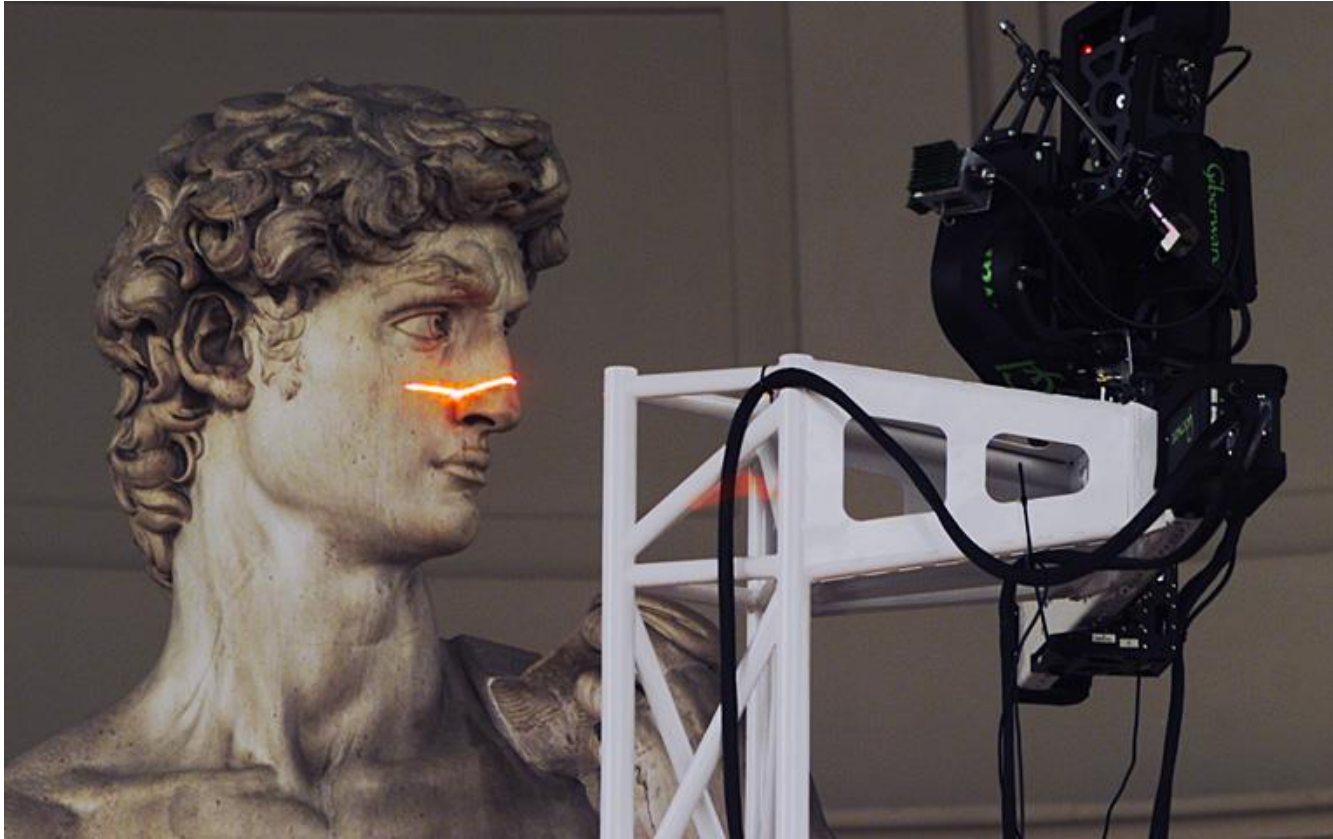
Modeling Techniques

- Obtaining polygonal meshes
 - Hierarchical modeling
 - Instancing and Parametric Instancing
 - Constructive Solid Geometry
 - Sweep Objects
 - Subdivision
-

So you need a mesh...

- Buy it (or find a free one)
 - Free meshes typically are not very good quality
 - User defined: A user builds the mesh
 - Tools help with specifying many vertices and faces quickly
 - Take any user-friendly modeling technique, and extract a mesh representation from it
 - Scan a real object
 - 3D probe-based systems
 - Range finders
 - Image based reconstruction
 - Take a bunch of pictures, and infer the object's shape
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Scanning in Action



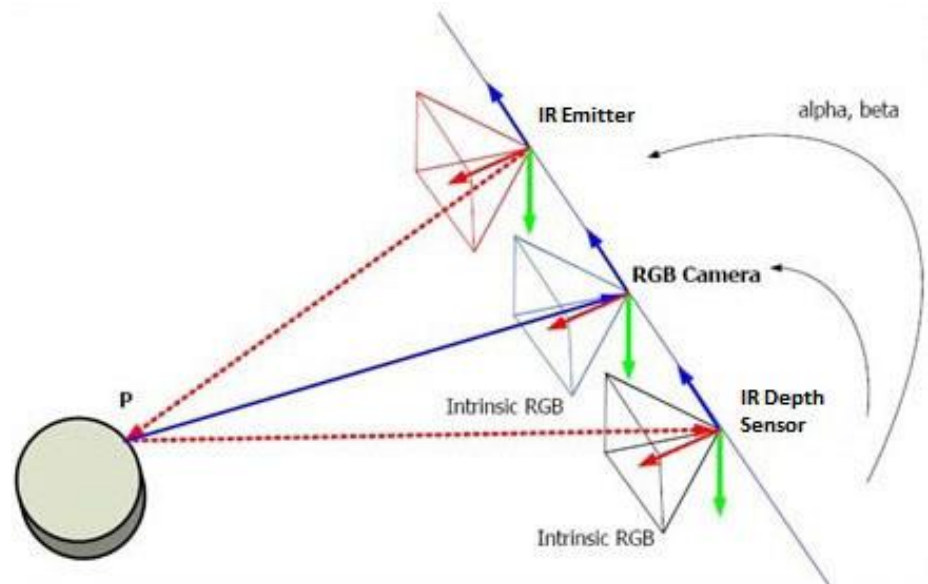
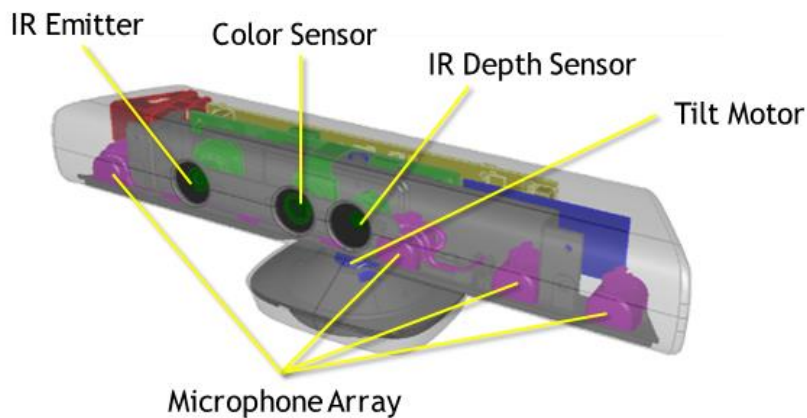
<https://accademia.stanford.edu/mich/>

Meshes from Scanning

- Laser scanners sample 3D positions
 - One method uses triangulation
 - Another method uses time of flight
 - Some take images also for use as textures
 - Famous example: Scanning the David
 - Software then takes thousands of points and builds a polygon mesh out of them
 - Research topics:
 - Reduce the number of points in the mesh
 - Reconstruction and re-sampling!
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Consumer Depth Cameras

- Microsoft Kinect I
 - Stereo triangulation



Consumer Depth Cameras

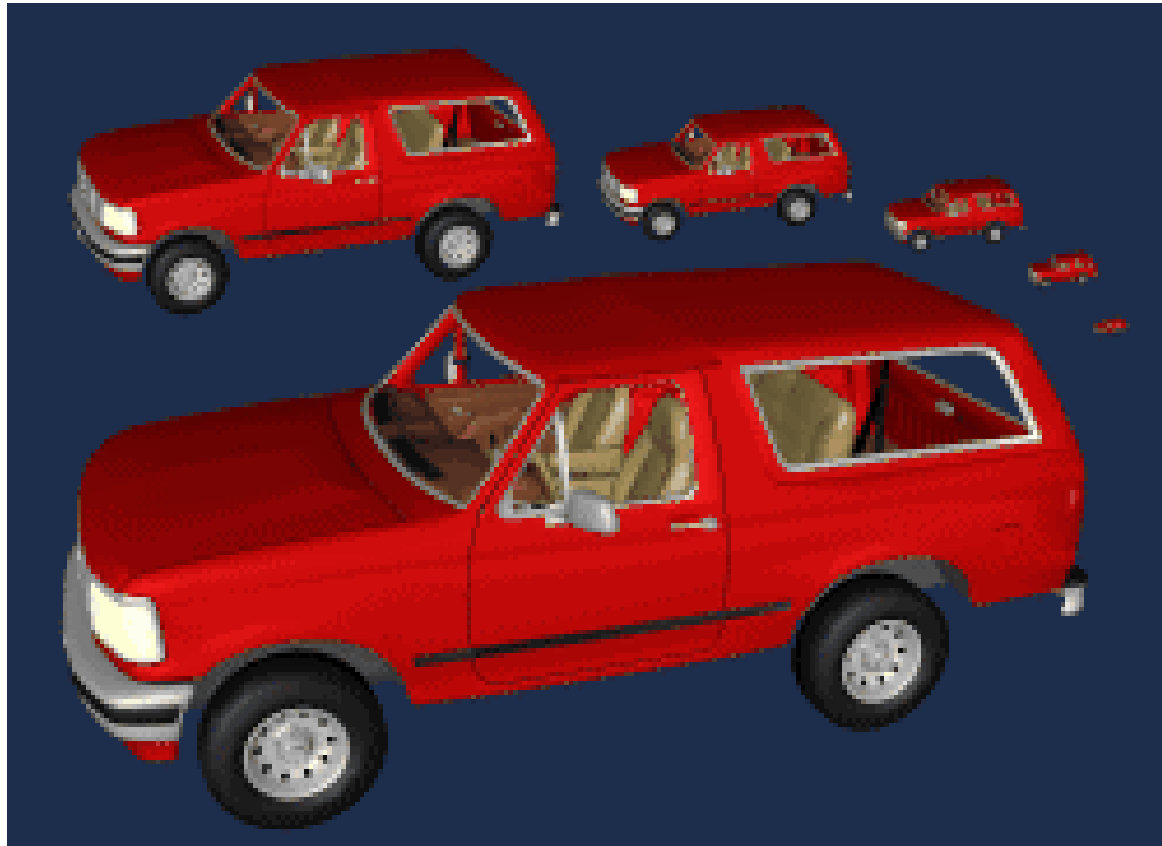
- Microsoft Kinect I
 - Stereo triangulation
- Intel creative depth camera (early version)
 - Time of flight



Level Of Detail

- There is no point in having more than 1 polygon per pixel
 - Or a few, if anti-aliasing
 - Level of detail strategies attempt to balance the resolution of the mesh against the viewing conditions
 - Must have a way to reduce the complexity of meshes
 - Must have a way to switch from one mesh to another
 - An ongoing research topic, made even more important as laser scanning becomes popular
 - Also called mesh decimation, multi-resolution modeling and other things
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Level of Detail



http://www.cs.unc.edu/~geom/SUCC_MAP/

Problems with Polygons

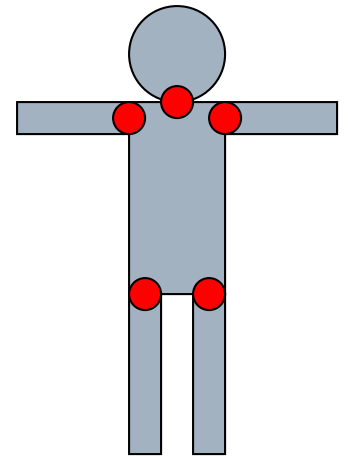
- They are inherently an approximation
 - Things like silhouettes can never be perfect without very large numbers of polygons, and corresponding expense
 - Normal vectors are not specified everywhere
 - Interaction is a problem
 - Dragging points around is time consuming
 - Maintaining things like smoothness is difficult
 - Low level representation
 - Eg: Hard to increase, or decrease, the resolution
 - Hard to extract information like curvature
-

More Object Representations

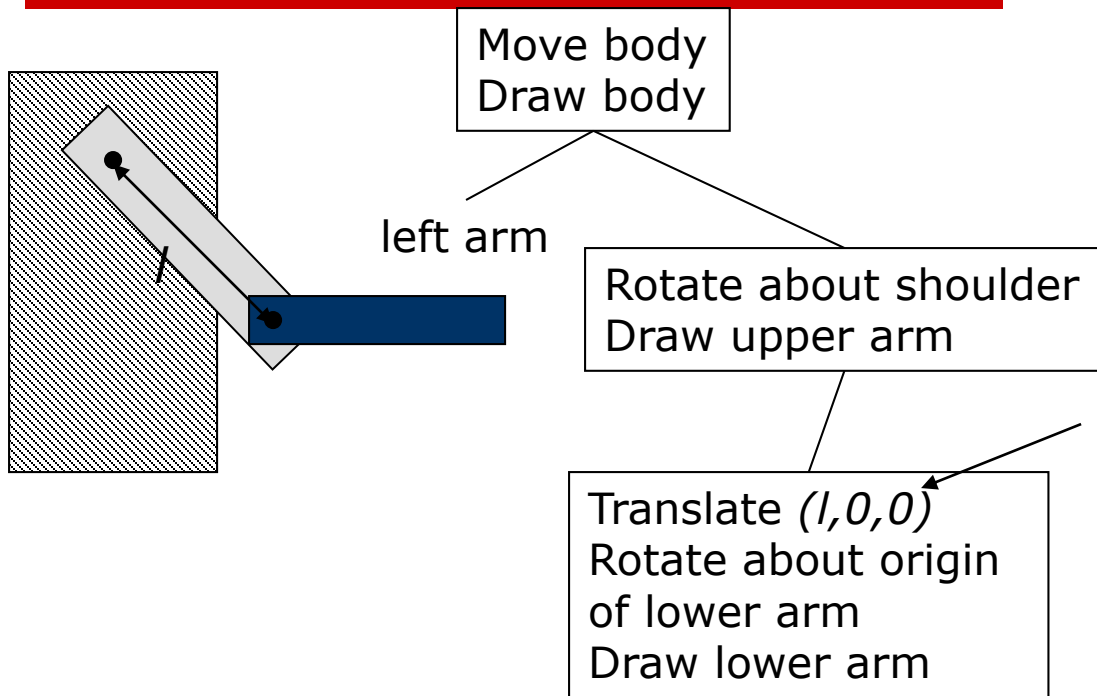
- Hierarchical modeling
 - Instancing and Parametric Instancing
 - Constructive Solid Geometry
 - Sweep Objects
 - Subdivision
 - ...
-

Hierarchical Modeling

- Hierarchical model: Group of meshes related by a tree (or graph) structure
 - Properties of children are derived from their parents
 - Most useful for animating polygonal meshes
- Consider a walking (humanoid, classic) robot:
 - How would you move the robot around?
 - Does the entire robot move in the same way?
 - Does the position of one part of the robot depend on other parts?



Hierarchical Model Example



Important Point:

- Every node has its own local coordinate system.
 - This makes specifying transformations much much easier.
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Hierarchical Details

- Generally represented as a tree, with transformations and instances at any node
 - Can use a general graph, but resolving inheritance conflicts is a problem
 - Rendered by traversing the tree, applying the transformations, and rendering the instances
 - Particularly useful for animation
 - Human is a hierarchy of body, head, upper arm, lower arm, etc...
 - Animate by changing the transformations at the nodes
 - Other things can be inherited (colors, surface properties)
-

OpenGL Support

- OpenGL defines `glPushMatrix()` and `glPopMatrix()`
 - Takes the current matrix and pushes it onto a stack, or pops the matrix off the top of the stack and makes it the current matrix
 - Note: Pushing does not change the current matrix
- Rendering a hierarchy (recursive):

```
RenderNode (tree)
    glPushMatrix()
        Apply node transformation
        Draw node contents
        RenderNode (children)
    glPopMatrix()
```

Instancing

- Sometimes you need many copies of the “same” object
 - Like chairs in a room
 - Define one chair, the base or the prototype
 - Create many *instances* (copies) of it, and apply a different transformation to each
 - Appears in scene description languages (Renderman, Inventor) as “defining” a label for an object
 - Advantages?
-

OpenGL Support

- OpenGL defines *display lists* for encapsulating commands that are executed frequently

```
list_id = glGenLists(1);  
glNewList(list_id, GL_COMPILE);  
glBegin(GL_TRIANGLES);  
    draw some stuff  
glEnd();  
glEndList();
```

And later

```
glCallList(list_id);
```

More Display Lists

- Almost any command can go in a display list
 - Viewing transformation set-up
 - Lighting set-up
 - Surface property set-up
 - But some things can't
 - Causes strange bugs - always check that a command can go in a display list
 - The list can be:
 - `GL_COMPILE`: things don't get drawn, just stored
 - `GL_COMPILE_AND_EXECUTE`: things are drawn, and also stored
-

Display Lists Good/Bad

- You should use display lists when:
 - You do the same thing over and over again
 - The commands are supported
 - Nothing changes about the way you do it
 - Advantages:
 - Can't be much slower than the original way
 - Can be much faster
 - Disadvantages:
 - Can't use various commands that would offer other speedups
 - For example, can't use `glVertexPointer()`
-

Parametric Instancing

- Many things, called primitives, are conveniently described by a label and a few parameters
 - Cylinder: Radius, length, does it have end-caps, ...
 - Bolts: length, diameter, thread pitch, ...
 - Other examples?
 - This is a modeling format:
 - Provide software that knows how to draw the object given the parameters, or knows how to produce a polygonal mesh
 - How you manage the model depends on the rendering style
 - Can be an exact representation
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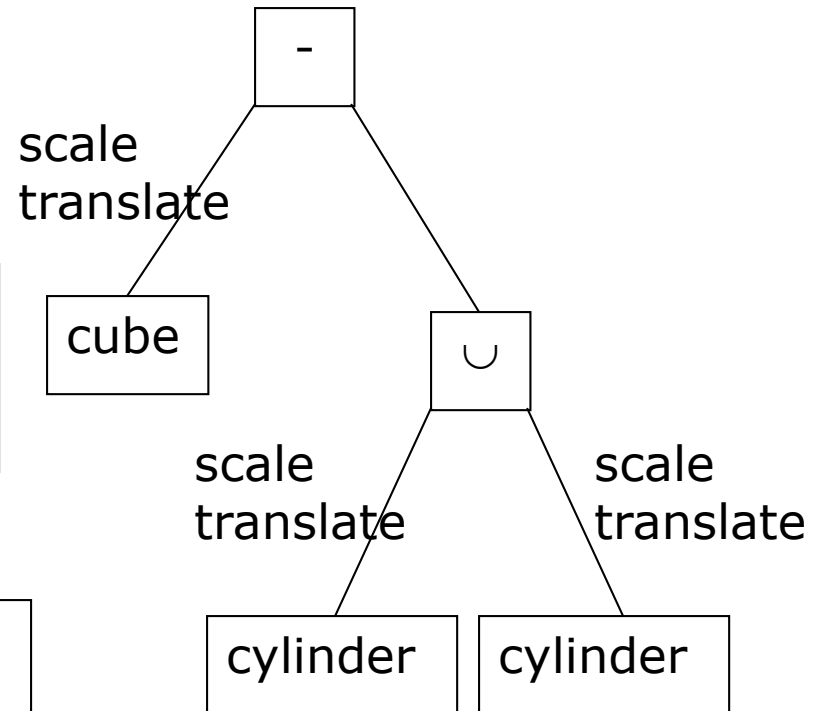
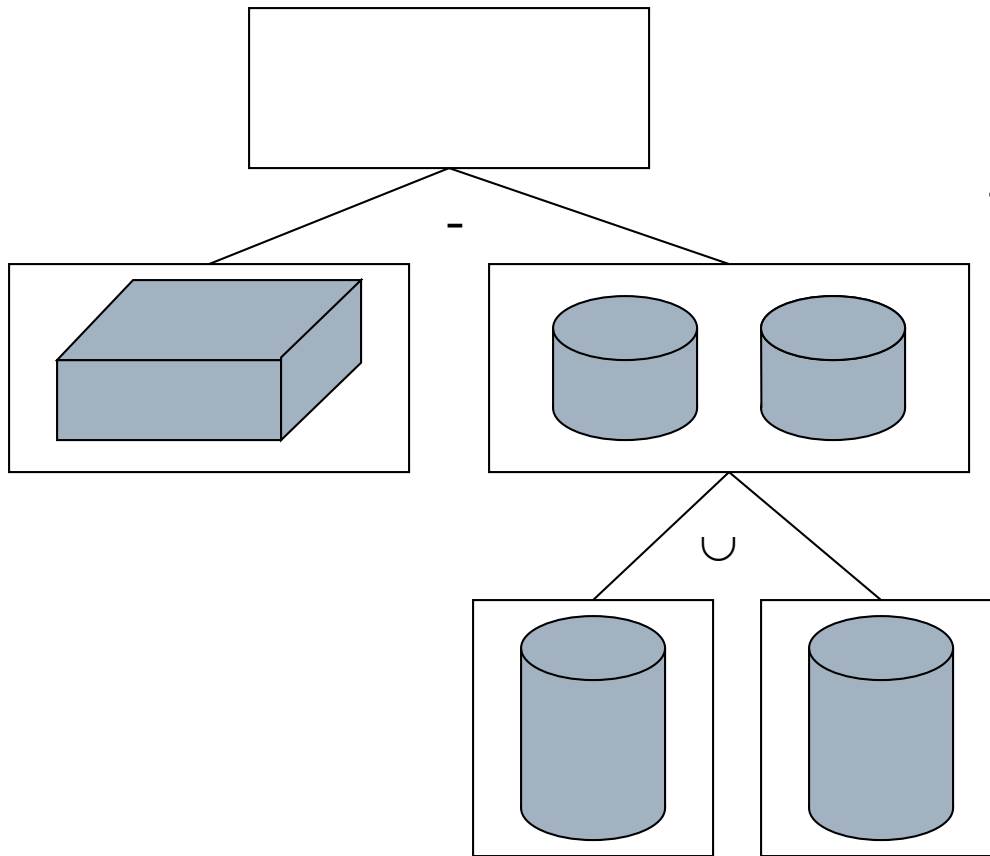
Rendering Instances

- Generally, provide a routine that takes the parameters and produces a polygonal representation
 - Conveniently brings parametric instancing into the rendering pipeline
 - May include texture maps, normal vectors, colors, etc
 - OpenGL utility library (glu) defines routines for cubes, cylinders, disks, and other common shapes
 - Renderman does similar things, so does POVray, ...
 - The procedure may be dynamic
 - For example, adjust the polygon resolution according to distance from the viewer
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Constructive Solid Geometry (CSG)

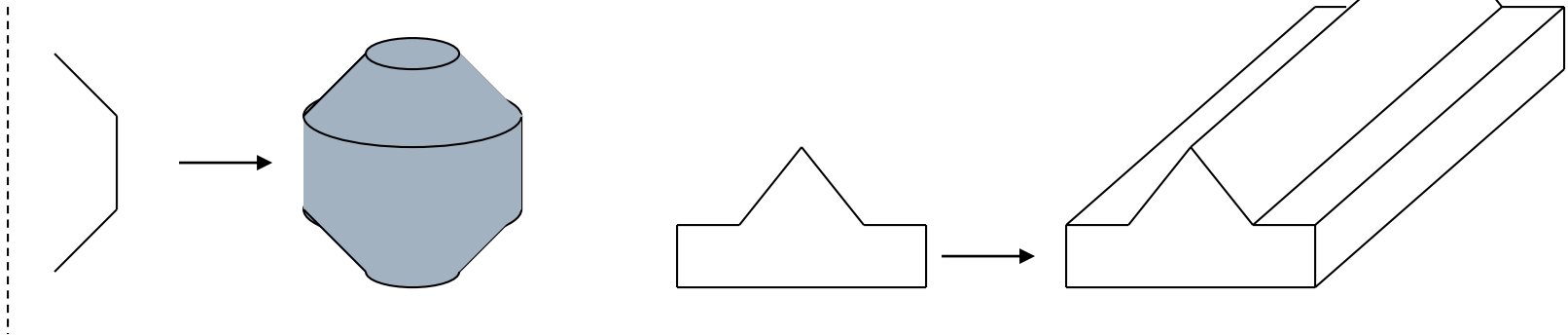
- Based on a tree structure, like hierarchical modeling, but now:
 - The internal nodes are set operations: union, intersection or difference (sometimes complement)
 - The edges of the tree have transformations associated with them
 - The leaves contain only geometry
 - Allows complex shapes with only a few primitives
 - Common primitives are cylinders, cubes, etc, or quadric surfaces
 - Motivated by computer aided design and manufacture
 - *Difference* is like drilling or milling
 - A common format in CAD products
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CSG Example



Sweep Objects

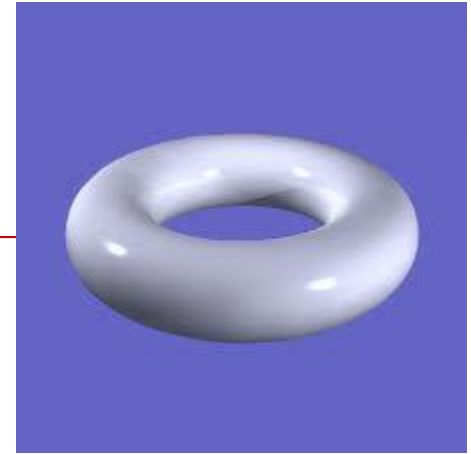
- Define a *polygon* by its edges
- Sweep it along a *path*
- The path taken by the edges form a surface - the sweep surface
- Special cases
 - Surface of revolution: Rotate edges about an axis
 - Extrusion: Sweep along a straight line



Rendering Sweeps

- Convert to polygons
 - Break path into short segments
 - Create a copy of the sweep polygon at each segment
 - Join the corresponding vertices between the polygons
 - May need things like end-caps on surfaces of revolution and extrusions
 - Normals come from sweep polygon and path orientation
 - Sweep polygon defines one texture parameter, sweep path defines the other
-

A Circular Tube (A torus)



□ What do we sweep, along what path?

```
Vector3      points[2][8];
int          start_i = 0;
int          end_i = 1;
for ( int i = 0 ; i < 8 ; i++ )
    points[start_i][i] = TorusPoint(7,i);
for ( int j = 0 ; j < 8 ; j++ ) {
    glBegin(GL_TRIANGLE_STRIP);
    for ( int i = 0 ; i < 8 ; i++ ) {
        glVertex3fv(points[start_i][i]);
        points[end_i][i] = TorusPoint(j, i);
        glVertex3fv(points[end_i][i]);
    }
    glVertex3fv(points[start_i][0]); //close the loop
    glVertex3fv(points[end_i][0]);
    glEnd();
    int      temp = start_i; start_i = end_i; end_i = temp;
}
```

General Sweeps

- The path maybe any curve
 - The polygon that is swept may be transformed as it is moved along the path
 - Scale, rotate with respect to path orientation, ...
 - One common way to specify is:
 - Give a poly-line (sequence of line segments) as the path
 - Give a poly-line as the shape to sweep
 - Give a transformation to apply at the vertex of each path segment
 - Difficult to avoid self-intersection
-

Smooth versus General

- Polygon meshes are very general, but hard to model with
 - In a production context (film, game), creating a dense, accurate mesh requires lots of work
 - Biggest problem is smoothness
 - We desire a way to “smooth out” a polygonal mesh
 - We can model at a coarse level, and automatically fill in the smooth parts
 - *Subdivision surfaces* are part of the answer
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Subdivision Schemes

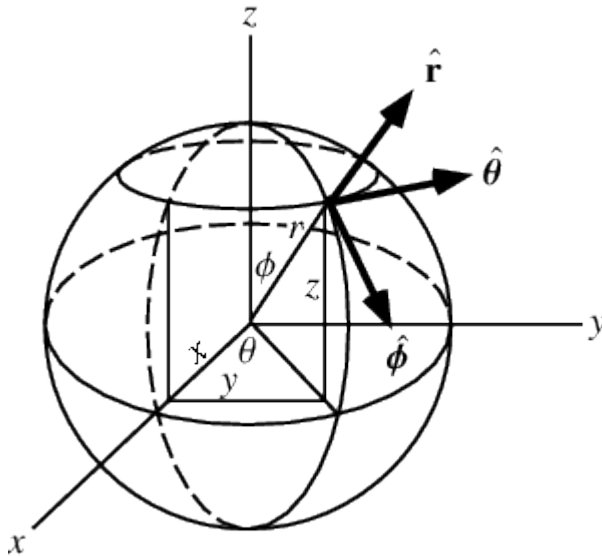
- Basic idea: Start with something coarse, and refine it into smaller pieces, smoothing along the way
 - We will see how it can be used for modeling specific objects, and as a modeling scheme in itself
 - In this lecture:
 - Subdivision for tessellating a sphere
 - Subdivision for fractal surfaces
-

Tessellating a Sphere

- Spheres are frequently parameterized in polar coordinates:

$$y = \sin\theta \sin\phi, \quad x = \cos\theta \sin\phi, \quad z = \cos\phi$$

$$0 \leq \theta \leq 2\pi, \quad -\pi/2 \leq \phi \leq \pi/2$$

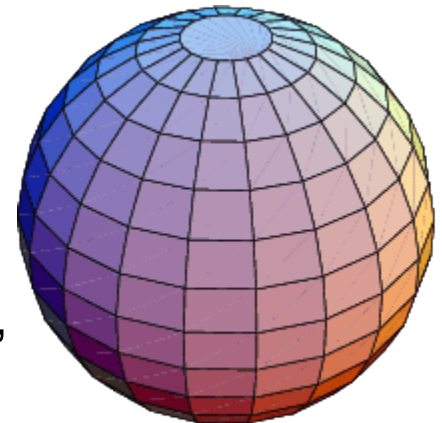


Tessellating a Sphere

- Spheres are frequently parameterized in polar coordinates:

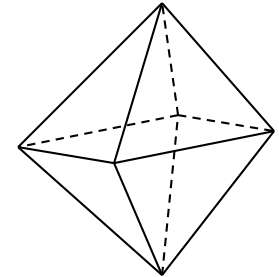
$$y = \sin\theta\sin\phi, \quad x = \cos\theta\sin\phi, \quad z = \cos\phi$$
$$0 \leq \theta \leq 2\pi, \quad -\pi/2 \leq \phi \leq \pi/2$$

- Tessellation: The process of approximating a surface with a polygon mesh
- One option for tessellating a sphere:
 - Step around and up the sphere in constant steps of θ and ϕ
 - Problem: Polygons are of wildly different sizes, and some vertices have very high degree

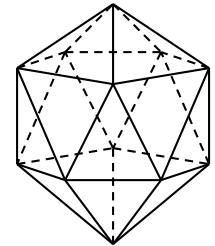


Subdivision Method

- Begin with a coarse approximation to the sphere, that uses only triangles
 - Two good candidates are platonic solids with triangular faces: Octahedron, Icosahedron
 - They have uniformly sized faces and uniform vertex degree
- Repeat the following process:
 - Insert a new vertex in the middle of each edge
 - Push the vertices out to the surface of the sphere
 - Break each triangular face into 4 triangles using the new vertices

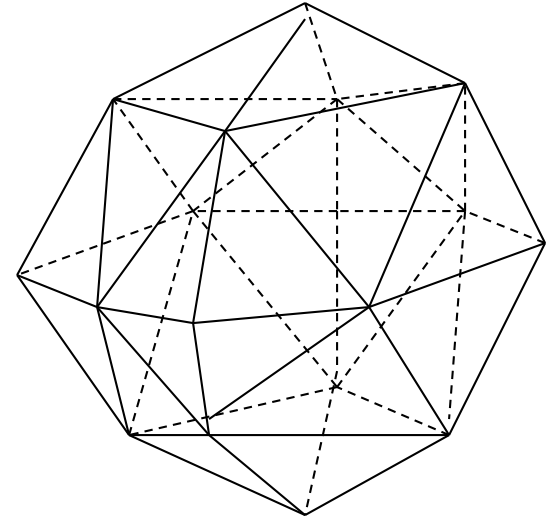
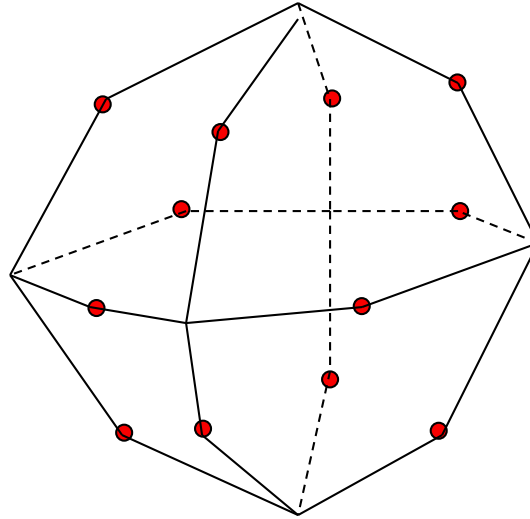
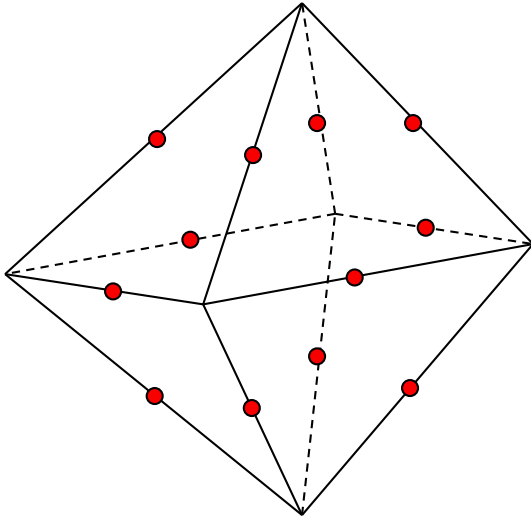


Octahedron

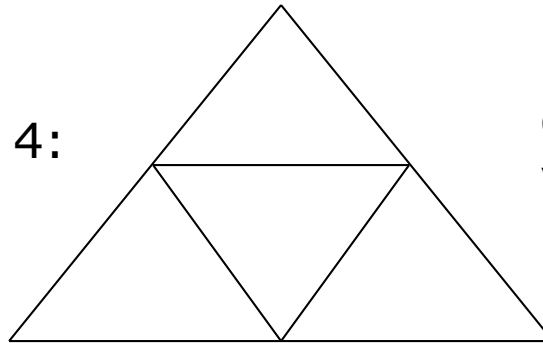


Icosahedron

The First Stage



Each face gets split into 4:



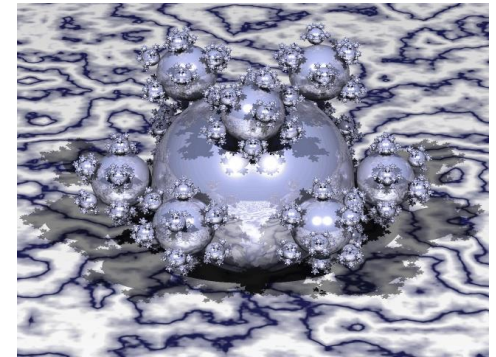
Each new vertex is degree 6, original vertices are degree 4

Sphere Subdivision Advantages

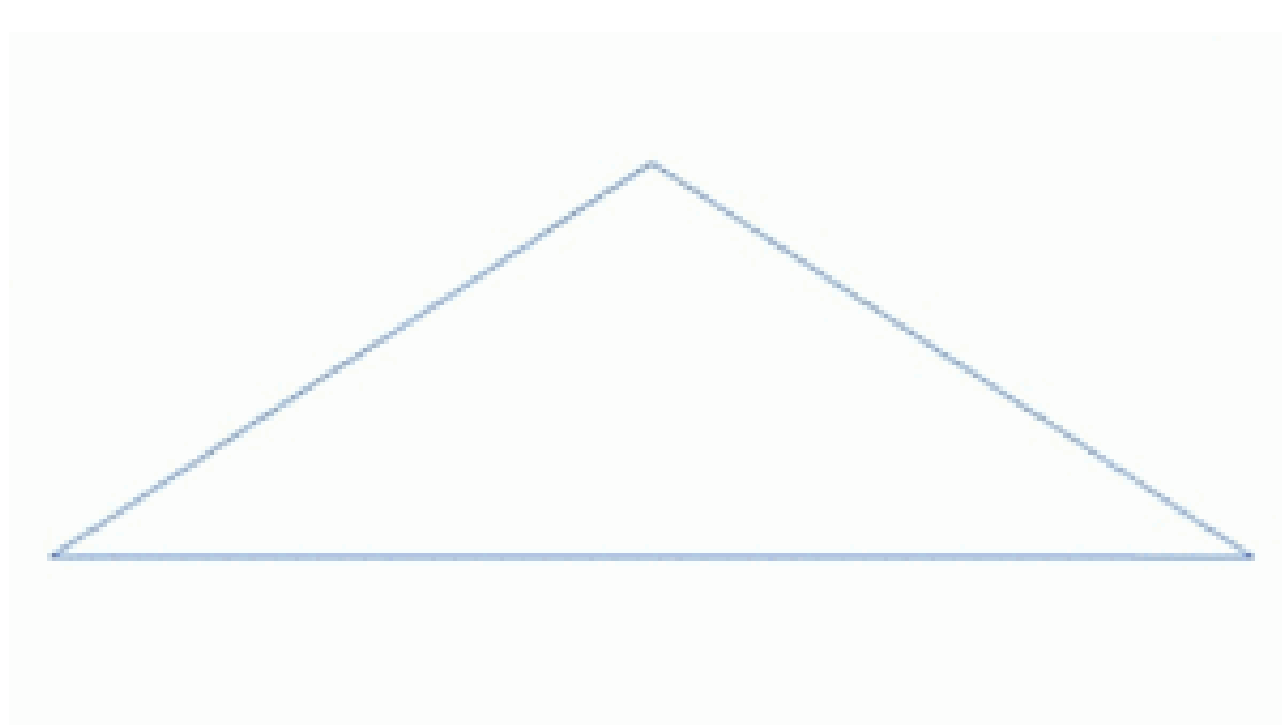
- All the triangles at any given level are the same size
 - Relies on the initial mesh having equal sized faces, and properties of the sphere
 - The new vertices all have the same degree
 - Mesh is *regular (or uniform)* in newly generated areas
 - Makes it easier to analyze what happens to the surface
 - The location and degree of existing vertices does not change
-

Fractal Surfaces

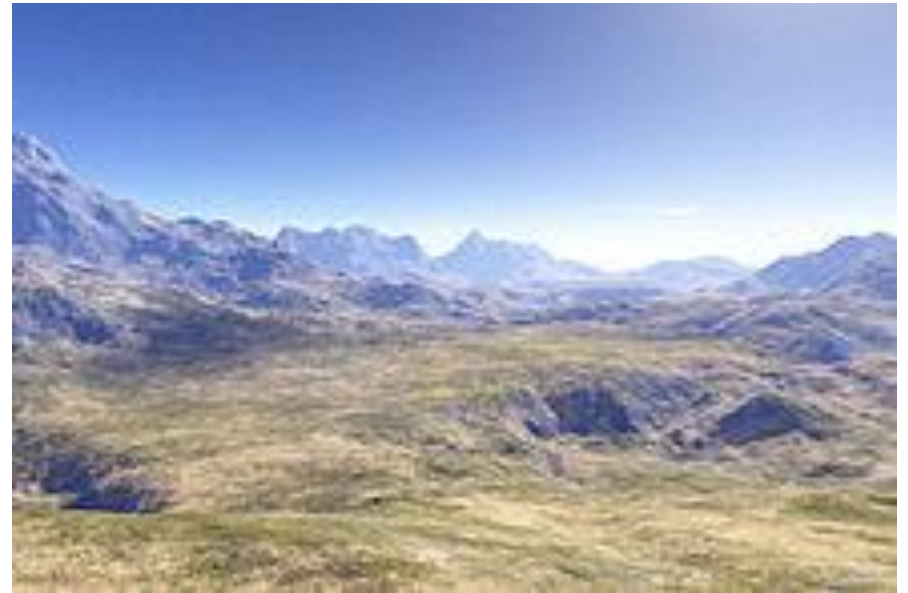
- Fractals are objects that show self similarity
 - The word is overloaded - it can also mean other things
- Landscapes and coastlines are considered fractal in nature
 - Mountains have hills on them that have rocks on them and so on
 - Continents have gulfs that have harbors that have bays and so on



Fractal



Fractal



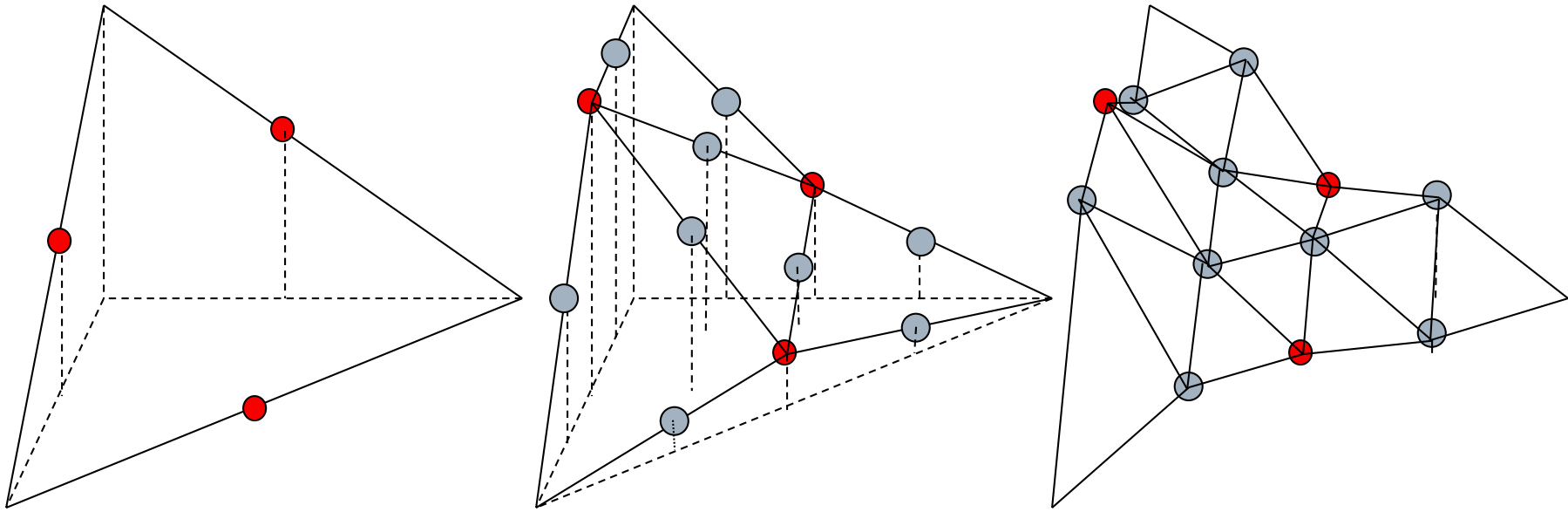
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 - Landscapes and coastlines are considered fractal in nature
 - Mountains have hills on them that have rocks on them and so on
 - Continents have gulfs that have harbors that have bays and so on
 - Subdivision is the natural way of building fractal surfaces
 - Start with coarse features, subdivide to finer features
 - Different types of fractals come from different subdivision schemes and different parameters to those schemes
-

Fractal Terrain (1)

- Start with a coarse mesh
 - Vertices on this mesh won't move, so they can be used to set mountain peaks and valleys
 - Also defines the boundary
 - Mesh must not have dangling edges or vertices
 - Every edge and every vertex must be part of a face
 - Also define an “up” direction
 - Then repeatedly:
 - Add new vertices at the midpoint of each edge, and randomly push them up or down
 - Split each face into four, as for the sphere
-

Fractal Terrain Example



A mountainside

Fractal Terrain Details

- There are options for choosing where to move the new vertices
 - Uniform random offset
 - Normally distributed offset - small motions more likely
 - Procedural rule - eg *Perlin noise*
 - Reducing the offset of new points according to the subdivision level is essential
 - Define a scale, s , and a ratio, k , and at each level: $s_{i+1}=ks_i$
 - Colors are frequently chosen based on “altitude”
-

Fractal Terrain Algorithm

- ❑ The hard part is keeping track of all the indices and other data
- ❑ Same algorithm works for subdividing sphere

```
Split_One_Level(struct Mesh terrain)
```

```
    Copy old vertices
```

```
    for all edges
```

```
        Create and store new vertex
```

```
        Create and store new edges
```

```
    for all faces
```

```
        Create new edges interior to face
```

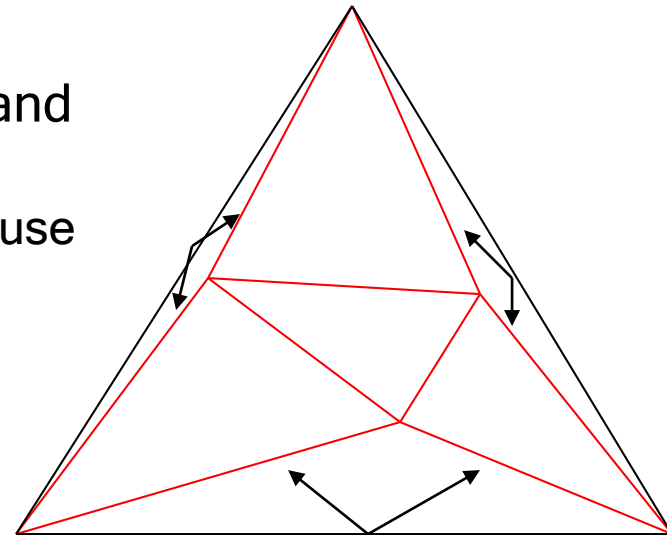
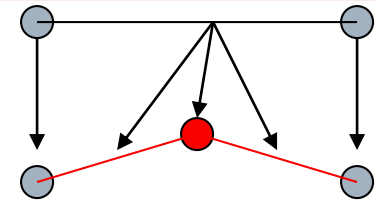
```
        Create new faces
```

```
    Replace old vertices, edges and faces
```

Subdivision Operations

- Split an edge, create a new vertex and two new edges
 - Each edge must be split exactly once
 - Need to know endpoints of edge to create new vertex

- Split a face, creating new edges and new faces based on the old edges and the old and new vertices
 - Require knowledge of which new edges to use
 - Require knowledge of new vertex locations



Data Structure Issues

- We must represent a polygon mesh so that the subdivision operations are easy to perform
 - Questions influencing the data structures:
 - What information about faces, edges and vertices must we have, and how do we get at it?
 - Should we store edges explicitly?
 - Should faces know about their edges?
-

Next Time

Implicit Surfaces