

# Arduino Programming

## Part 2

EAS 199A

Lecture 6

Fall 2010

# Overview

- Variables: assigning and using
  - ❖ int
  - ❖ float
- Loops
  - ❖ for loops

# Assigning and Using Variables

## Arduino web site

- ❖ <http://www.arduino.cc/en/Tutorial/Variables>
- ❖ <http://arduino.cc/en/Tutorial/Foundations>

## Defining and using variables:

- ❖ All variables must be declared before use
- ❖ Declaration consists of a type specification and the variable name
- ❖ A declaration may also include an assignment
- ❖ Use meaningful variable names
- ❖ Add comments to further clarify meaning

```
int    red_pin;           // declaration only
int    blue_pin = 5;      // declaration and assignment
int    greenPin = 0;
float  scale = 5.0/1024.0; // Convert 10-bit value
                               // to 5V scale
char   name = 'Bob';
```

# int Variables

An int is a 16 bit, signed integer

- ❖ See: <http://www.arduino.cc/en/Reference/Int>
- ❖ Storage requires two bytes or 16 bits
- ❖  $2^{16} = 65536$
- ❖ Split into negative and positive range:  $-32,768$  to  $32,767$
- ❖ Computations are rounded and rolled-over as needed

Examples:

```
int  sensorVal;           //  declaration only
int  sensorPin = 3;       //  declaration and assignment

sensorVal = analogRead(sensorPin);    //  assignment
```

# float Variables

A float is a signed number with a fractional part

- ❖ See: <http://www.arduino.cc/en/Reference/Float>
- ❖ Stored in 32 bits (twice as much memory as an int)
- ❖ Range:  $-3.4028235 \times 10^{38}$  to  $3.4028235 \times 10^{38}$
- ❖ Floating point arithmetic introduces rounding

## Examples:

```
int    sensorVal;           // value returned from analog input
int    sensorPin = 3;      // pin assigned to analog input
int    range = 1024;       // Maximum range of 10 bit value
float  voltage;            // Voltage of the input signal
float  maxVoltage = 5.0;   // Maximum range of analog input

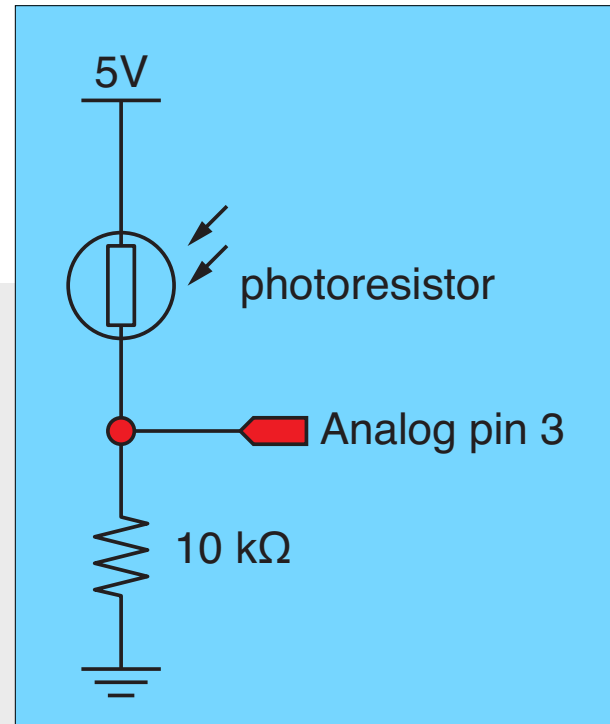
sensorVal = analogRead(sensorPin);    // get reading

// convert to floating point voltage
voltage = float(sensorVal)*maxVoltage/float(range);
```

# Try it! Measure photoresistor output

Build the photoresistor circuit  
and run this program

```
int    sensorVal;  
int    sensorPin = 3;  
float  voltage;  
float  input2volts = 5.0/1024.0;  
  
void setup () {  
    Serial.begin(9600);  
}  
  
void loop () {  
    sensorVal = analogRead(sensorPin);  
    voltage = float(sensorVal)*input2volts;  
    Serial.print("Voltage = ");  
    Serial.println(voltage);  
}
```



# Loops

## Loops allow code to be repeated

- ❖ Repeated code goes in a block, surrounded by { }
- ❖ for loops
  - ▶ need a counter
- ❖ while loops
  - ▶ need an escape

```
int i; // declare counter
for ( i=0; i<=12; i++ ) { // standard structure
    Serial.println(i); // send value of i to serial monitor
}
```

# Loops

Initial value of counter

`i=0` only on first pass through the loop

Stopping test: Continue while this condition is true

```
int i; // declare counter
for ( i=0; i<=12; i++ ) { // standard structure
    Serial.println(i); // send value of i to serial monitor
}
```

Increment: How to change `i` on each pass through the loop



# Loops

## Common loop: increment by one

```
for ( i=0; i<=12; i++ ) { // increment by one
    ... code block goes here
}
```

## Common loop: increment by two

```
for ( i=0; i<=12; i+=2 ) { // increment by two
    ... code block goes here
}
```

## Decrement by one

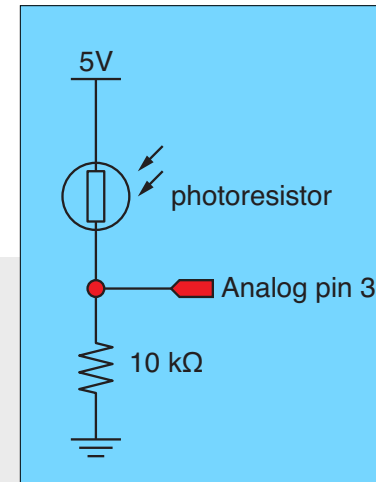
```
for ( i=12; i>=0; i-- ) { // decrement by one
    ... code block goes here
}
```

# Try it! Modify the photoresistor program

## Change the loop function

(modify your previous code)

```
void loop () {  
  float sensorAve;  
  int   sensorSum;  
  int   nave=5;  
  
  sensor_sum = 0.0;  
  for ( i=1; i<=nave; i++ ) {  
    sensorVal = analogRead(sensorPin);  
    sensorSum = sensorSum + sensorVal;  
  }  
  sensorAve = float(sensorSum)/float(nave);  
  voltage = sensorAve*input2volts;  
  Serial.print("Average voltage = ");  
  Serial.println(voltage);  
}
```



**This code contains errors that you will need to fix before it runs!**

# Test it! Break your code to learn how it works

## Change nave

- ❖ Increase nave from 5 to 10, 50, 100, 500
- ❖ Why is the reading negative for large nave?
- ❖ How can you fix this by changing the variable type for sensorSum?

## Add print statements inside the averaging loop

```
Serial.print("\t Reading = ");  
Serial.println(sensorVal);
```