

# Arduino Programming

## Part 2

EAS 199A

Lecture 6

Fall 2011

# Overview

- Variable types
  - ❖ int
  - ❖ float
- Loops
  - ❖ for loops
  - ❖ while loops (another day)

# Assigning and Using Variables

## Arduino web site

- ❖ <http://arduino.cc/en/Reference/HomePage>
- ❖ <http://www.arduino.cc/en/Tutorial/Variables>
- ❖ <http://arduino.cc/en/Tutorial/Foundations>

## The more common variable types are

- ❖ integers:
  - ▶ int, long, unsigned int, unsigned long
- ❖ floating point values: (numbers with fractional parts)
  - ▶ float, double
- ❖ characters and character strings
  - ▶ char, string, String
- ❖ arrays

# Integers are used for counting

`int`

- ❖ integers in the range  $-32,768$  to  $32,767$

`unsigned int`

- ❖ integers in the range  $0$  to  $65,535$

`long`

- ❖ integers in the range  $-2,147,483,648$  to  $2,147,483,647$

`unsigned long`

- ❖ integers in the range  $0$  to  $4,294,967,295$

# Practical usage of `int` and `long`

Use an `int` for most common tasks requiring integers

- ❖ Use an `int` for most loop counters:

```
int i, n=16;

for ( i=0; i<n; i++) {
    // loop body
}
```

- ❖ An `int` is returned by a built-in functions, e.g. `analogRead`

```
int val, photo_pin=4;
val = analogRead(photo_pin);
```

# Practical usage of `int` and `long`

Use a `long` when the range of values is very large, e.g. measuring the system time in milliseconds

```
long start_time, current_time;
long wait_time = 86400000; // one day

void setup() {
    start_time = millis();
    Serial.begin(9600);
}

void loop() {
    current_time = millis();
    if ( (current_time - start_time) > wait_time ) {
        Serial.println("24 hours has passed");
        start_time = current_time;
    }
}
```

# Floating point numbers are used for computing with fractional values

## `float`

- ❖ numbers with fractional part
- ❖ values in the range  $-3.4028235 \times 10^{38}$  to  $3.4028235 \times 10^{38}$

## Practical advice

- ❖ Use a `float` in formulas when fractional values are needed
- ❖ A `float` can be very large or small
- ❖ floating point math involves small rounding errors

# Integer and floating point variables use different arithmetic rules

Integer math: Division rounds to nearest int

```
int  a, b, c;

a = 4;
b = 3;
c = a/b;    // Value of 1 is stored in c
```

Floating point math

```
float  x, y, z;

x = 4.0;    // Include "point zero" to reinforce
y = 3.0;    //         that x and y are floats
z = x/y;    // Value of 1.3333333 is stored in z
```



# Use conversion functions to change type

Convert to an integer:

```
a = int(x);
```

Convert to a floating point value:

```
x = float(i);
```

## Practical Advice

Use explicit type conversion functions to convey your intent

# Defining and Using Variables

- ❖ All variables must be declared before use
- ❖ Declaration consists of a type specification and the variable name
- ❖ A declaration may also include an assignment
- ❖ Use meaningful variable names
- ❖ Add comments to further clarify meaning

## Examples

```
int    red_pin;           // declaration only
int    blue_pin = 5;      // declaration and assignment
int    greenPin = 0;

float  voltage;           // Voltage of the input signal
float  maxVoltage = 5.0; // Maximum range of analog input

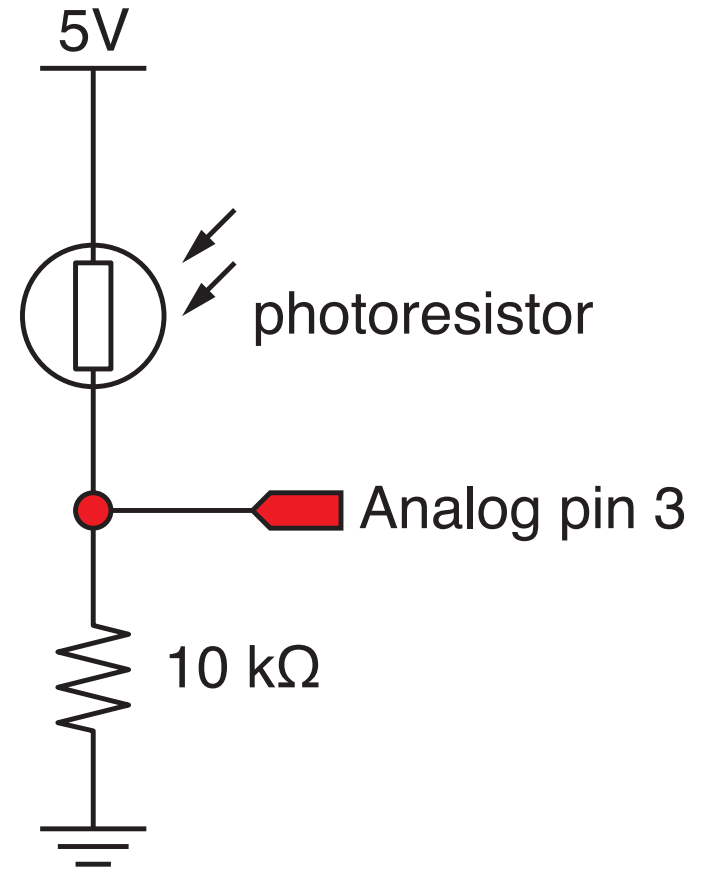
sensorVal = analogRead(sensorPin); // get reading

// convert to floating point voltage
voltage = float(sensorVal)*maxVoltage/float(range);
```

# Case study: Use floats to store sensor values

## Use photo-resistor circuit to create sensor input

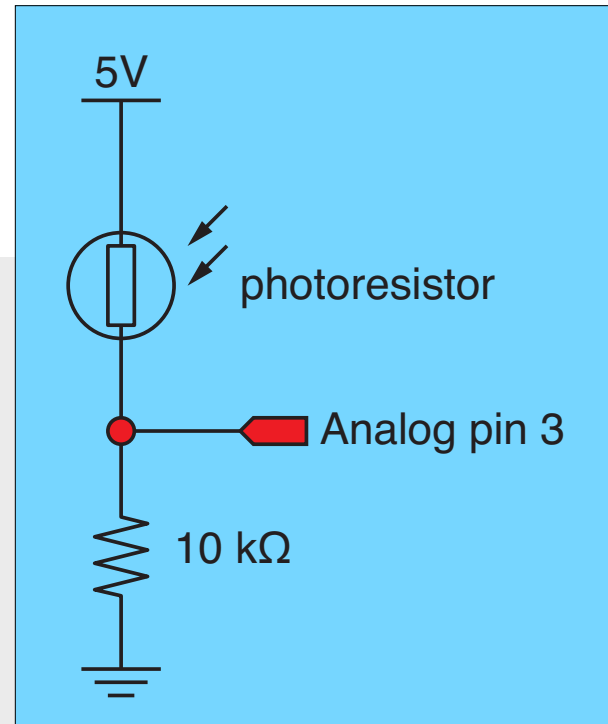
- ❖ Convert input reading to a voltage using floating point variables
- ❖ Use loops to compute the average of sensor readings



# Try it! Measure photoresistor output

Build the photo-resistor circuit  
and run this program

```
int    sensorVal;  
int    sensorPin = 3;  
float  voltage;  
float  input2volts = 5.0/1023.0;  
  
void setup () {  
    Serial.begin(9600);  
}  
  
void loop () {  
    sensorVal = analogRead(sensorPin);  
    voltage = float(sensorVal)*input2volts;  
    Serial.print("sensorVal, voltage = ");  
    Serial.print(sensorVal);    Serial.print("  ");  
    Serial.println(voltage);  
}
```



# Loops

# Loops

## Loops allow code to be repeated

- ❖ Repeated code goes in a block, surrounded by { }
- ❖ for loops
  - ▶ need a counter
- ❖ while loops
  - ▶ need an escape

```
int i; // declare counter
for ( i=0; i<=12; i++ ) { // standard structure
    Serial.println(i); // send value of i to serial monitor
}
```

# Loops

Initial value of counter

`i=0` only on first pass through the loop

Stopping test: Continue while this condition is true

```
int i; // declare counter
for ( i=0; i<=12; i++ ) { // standard structure
    Serial.println(i); // send value of i to serial monitor
}
```

Increment: How to change `i` on each pass through the loop

# Loops

## Common loop: increment by one

```
for ( i=0; i<=12; i++ ) { // increment by one
    ... code block goes here
}
```

## Common loop: increment by two

```
for ( i=0; i<=12; i+=2 ) { // increment by two
    ... code block goes here
}
```

## Decrement by one

```
for ( i=12; i>=0; i-- ) { // decrement by one
    ... code block goes here
}
```

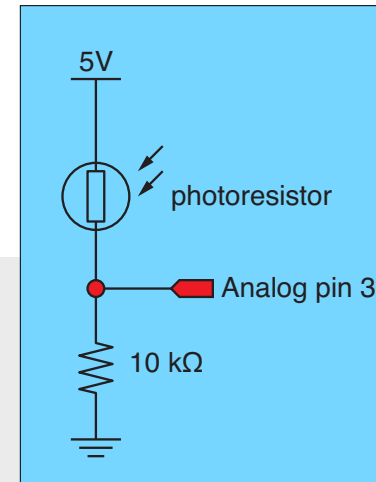


# Try it! Modify the photoresistor program

## Change the loop function

(modify your previous code)

```
void loop () {  
  float sensorAve;  
  int   sensorSum;  
  int   nave=5;  
  
  sensor_sum = 0.0;  
  for ( i=1; i<=nave; i++ ) {  
    sensorVal = analogRead(sensorPin);  
    sensorSum = sensorSum + sensorVal;  
  }  
  sensorAve = float(sensorSum)/float(nave);  
  voltage = sensorAve*input2volts;  
  Serial.print("Average voltage = ");  
  Serial.println(voltage);  
}
```



**This code contains errors that you will need to fix before it runs!**

# Test it! Break your code to learn how it works

## Change nave

- ❖ Increase nave from 5 to 10, 50, 100, 500
- ❖ Why is the reading negative for large nave?
- ❖ How can you fix this by changing the variable type for sensorSum?

## Add print statements inside the averaging loop

```
Serial.print("\t Reading = ");  
Serial.println(sensorVal);
```