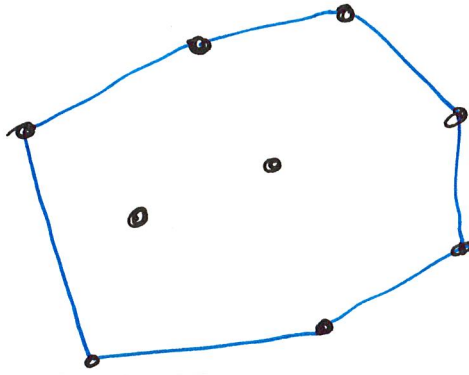


Convex Hull



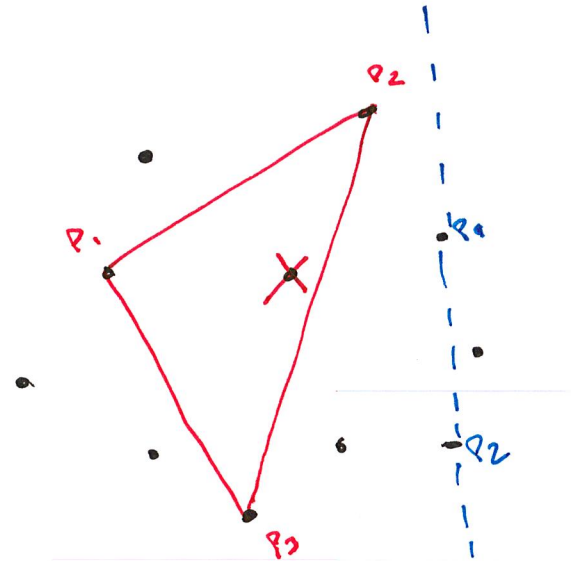
- Given a set of n points S , find the smallest convex polygon containing all the points
- we'll present the convex polygon as the ordered sequence of vertices

Brute Force #1 $O(n^4)$

- Any point inside any triangle is not part of the hull
- sort by polar angle around a centroid

Brute Force #2 $O(n^3)$

- For each line segment (pair of points) if all other points are on the same side of that line, the segment is part of the hull.

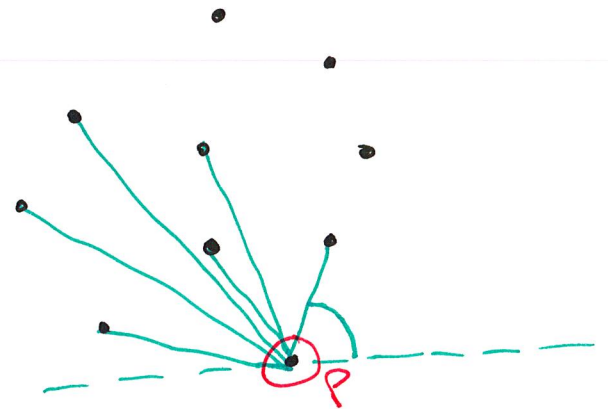


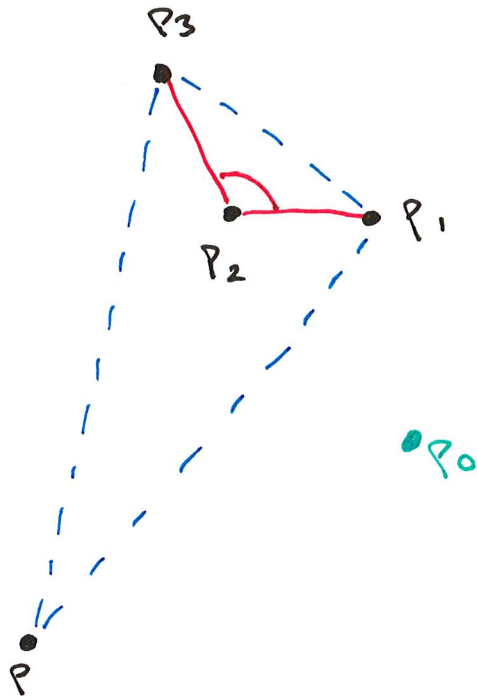
Graham's Scan

1. Find a known point on the hull p
2. Sort the remaining points by polar angle in counter-clockwise order around p

3. Process the points in consecutive triples P_1, P_2, P_3
- If $\angle P_1 P_2 P_3 < \pi$ then

P_2 is in the interior of the triangle $P P_1 P_3$ therefore not part of the hull

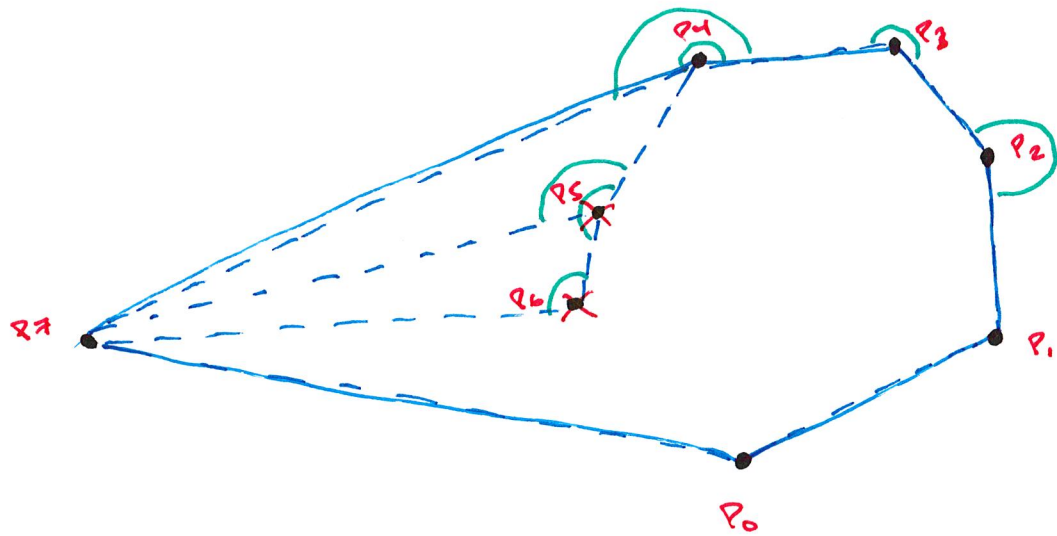




- If $\angle P_1P_2P_3 < \pi$ discard P_2 and try

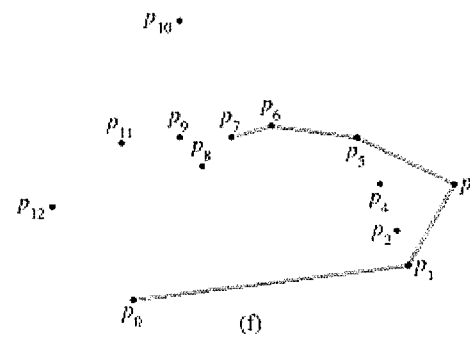
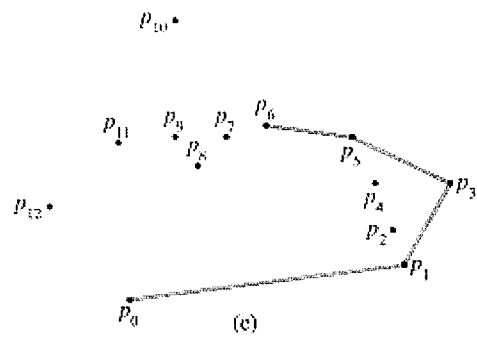
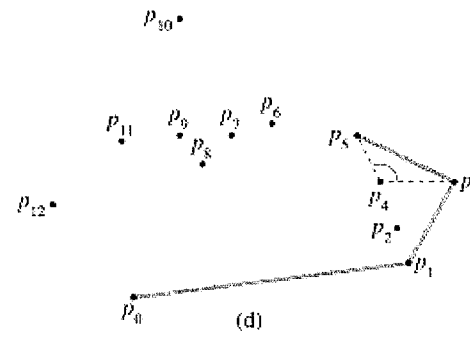
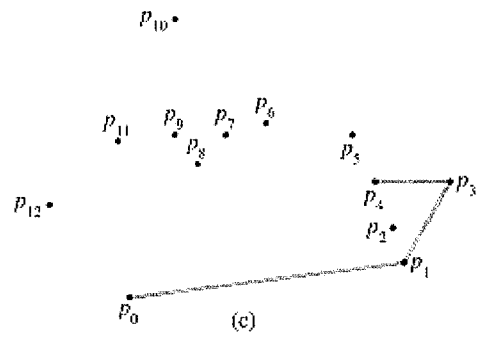
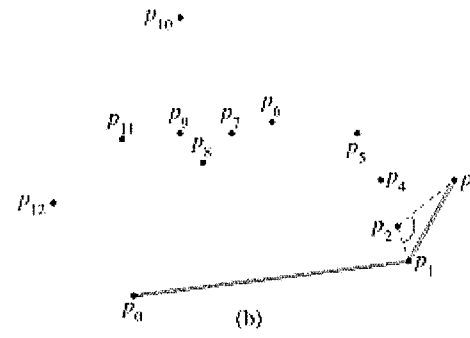
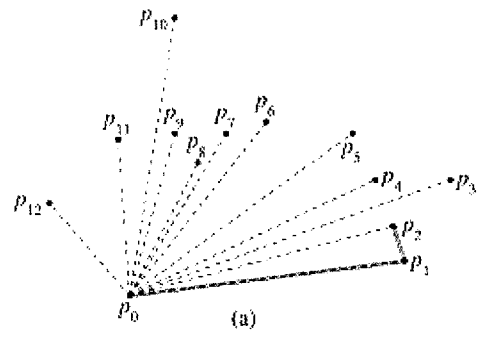
$P_0 P_1 P_3$

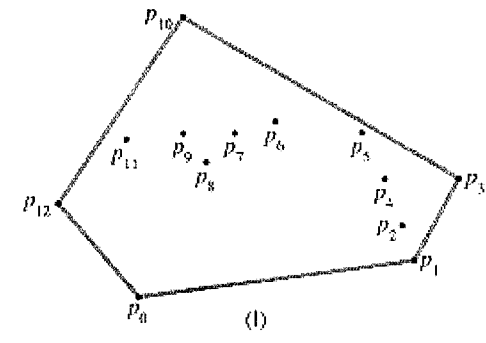
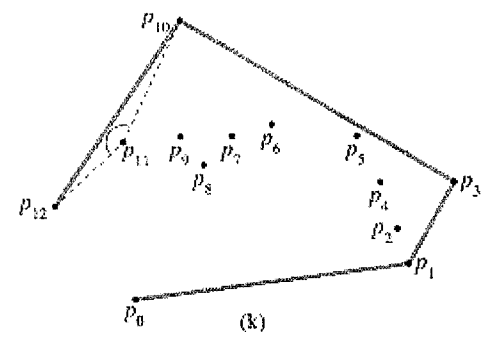
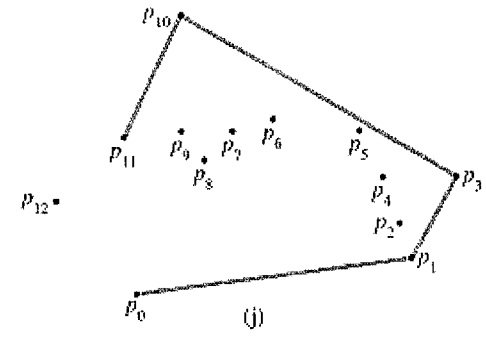
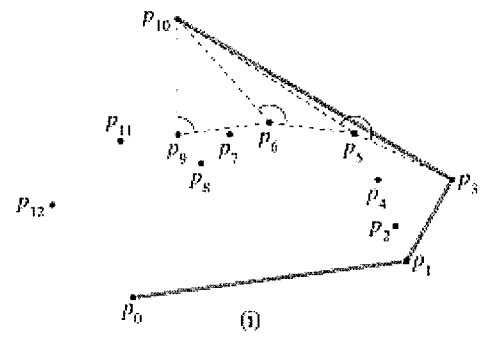
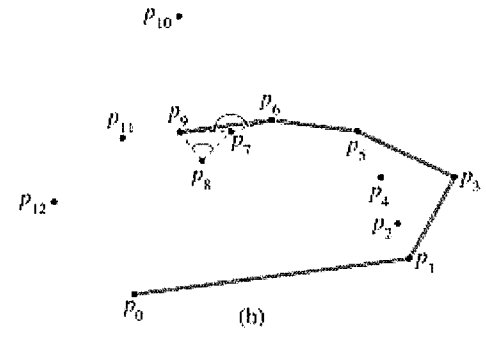
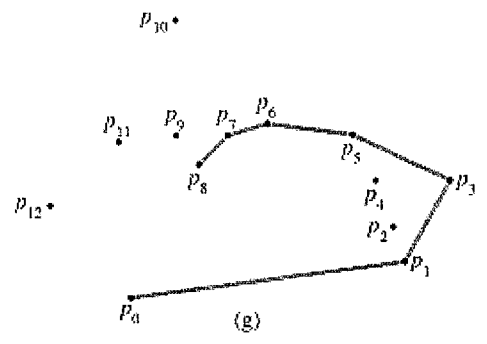
- otherwise advance to $P_2 P_3 P_4$



GRAHAMSCAN(Q)

- 1 let p_0 be the point in Q with the lowest y -coordinate $\Theta(n)$
- 2 let $\langle p_1, p_2, \dots, p_m \rangle$ be the remaining points in Q
sorted by polar angle around p_0 $\Theta(n \log n)$
- 3 **if** $m < 2$
- 4 **return** "convex hull is empty"
- 5 **else** let S be an empty stack
- 6 PUSH(p_0, S)
- 7 PUSH(p_1, S)
- 8 PUSH(p_2, S)
- 9 **for** $i = 3$ **to** m
- 10 **while** the angle formed by p_i and the top 2 elements
of S makes a non-left turn } $\Theta(n)$
- 11 POP(S)
- 12 PUSH(p_i, S)
- 13 **return** S





PotD: Singleton Finder

- Given a sorted array in which each element appears twice and one element appears only once. Give a divide and conquer algorithm to find that element with complexity $O(\log n)$
- Example

input: [1, 1, 3, 3, 4, 5, 5, 7, 7, 8, 8]

output: 4