

Haskell for the Cloud



Andrew P. Black

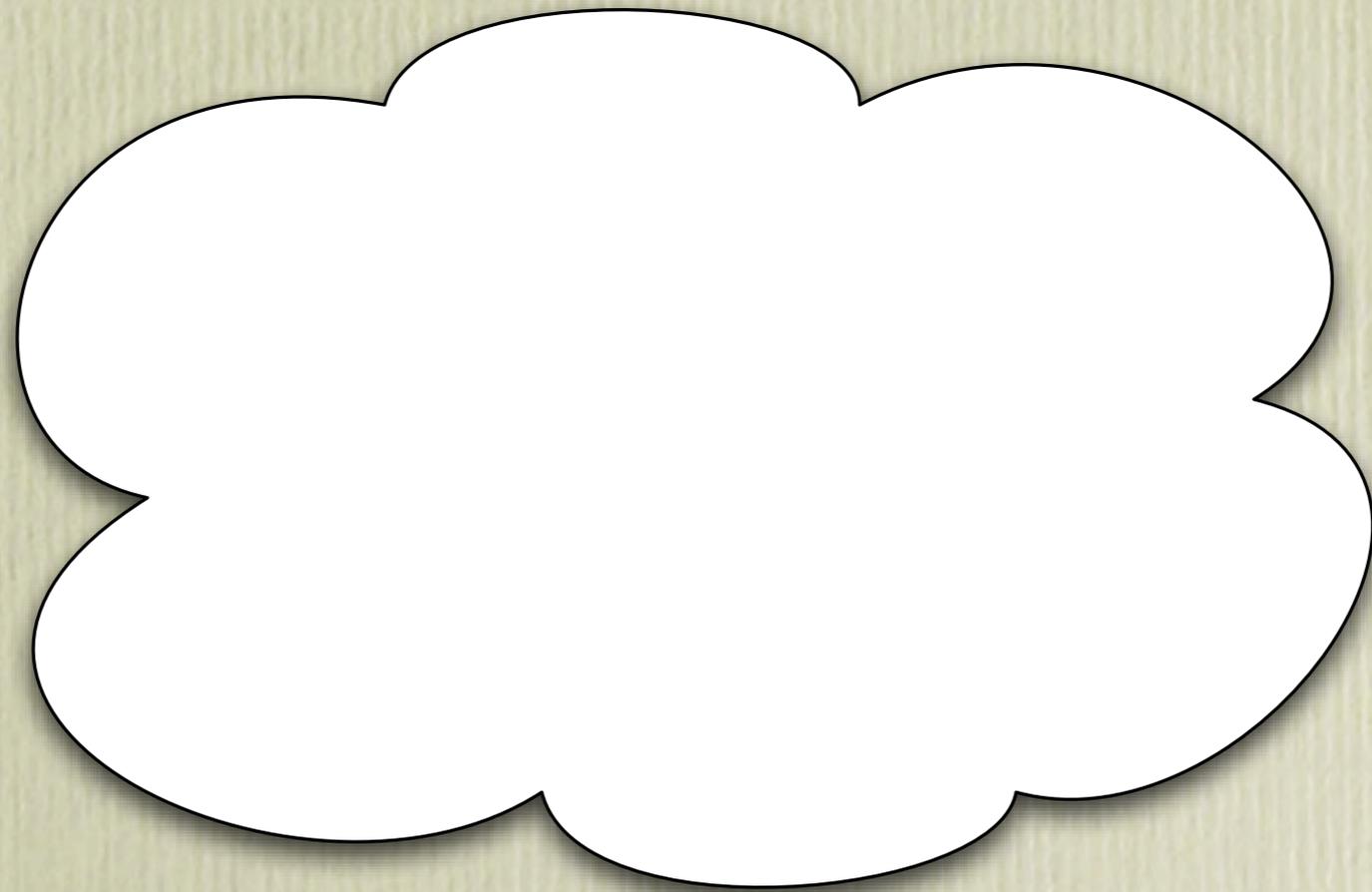
Joint work with Jeff Epstein & Simon Peyton Jones

Cloud Haskell in a Nutshell

- A DSL for Cloud Computing implemented as a Haskell library
 - From Erlang:
 - ▶ Processes with message-passing parallelism
 - ▶ Failure and recovery model
 - From Haskell:
 - ▶ Types: purity and monads
 - ▶ Typed Channels
 - ▶ Shared-memory concurrency *within* a process

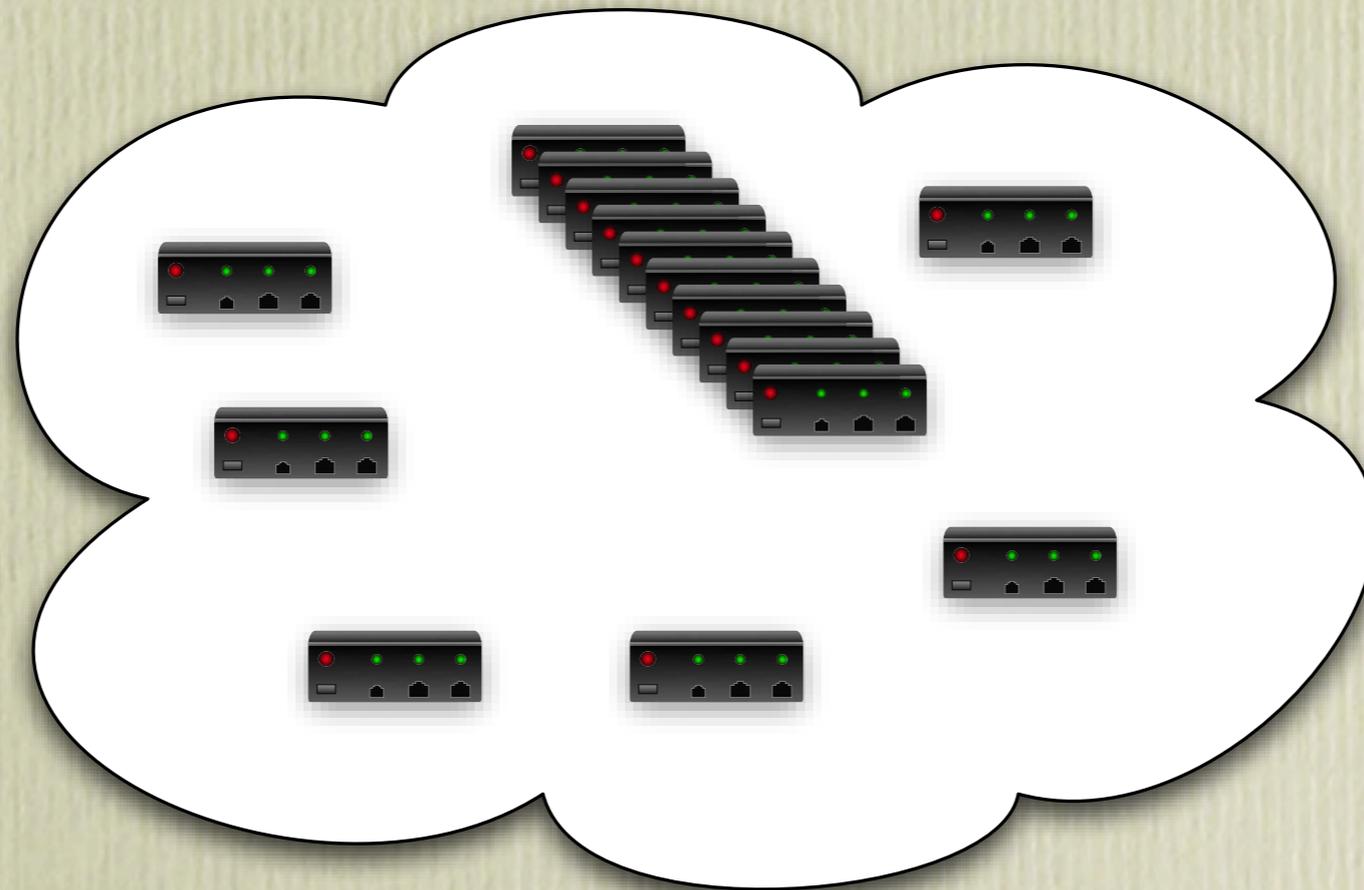
What's a Cloud?

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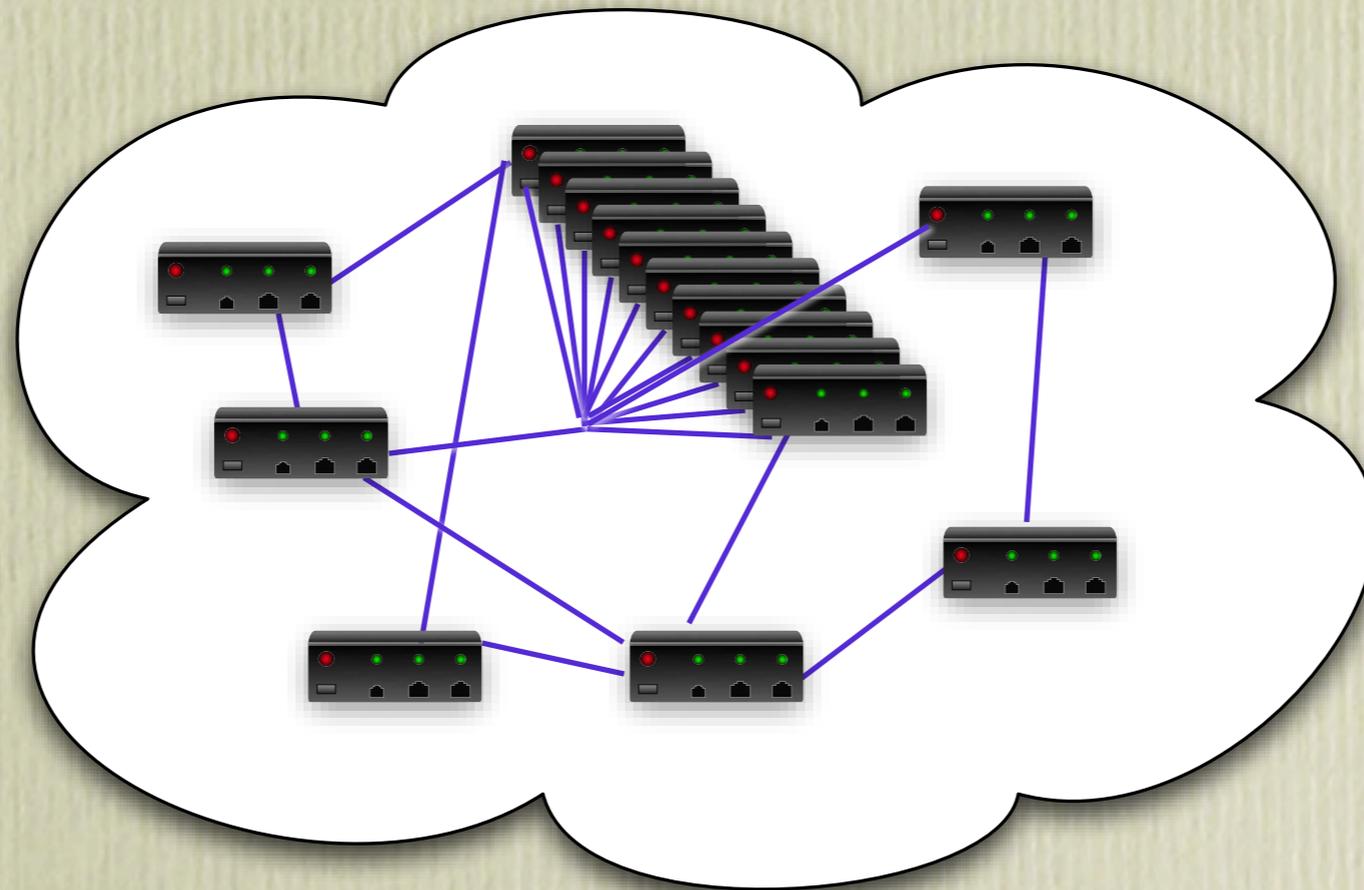
many separate processors



What's a Cloud?

many separate processors

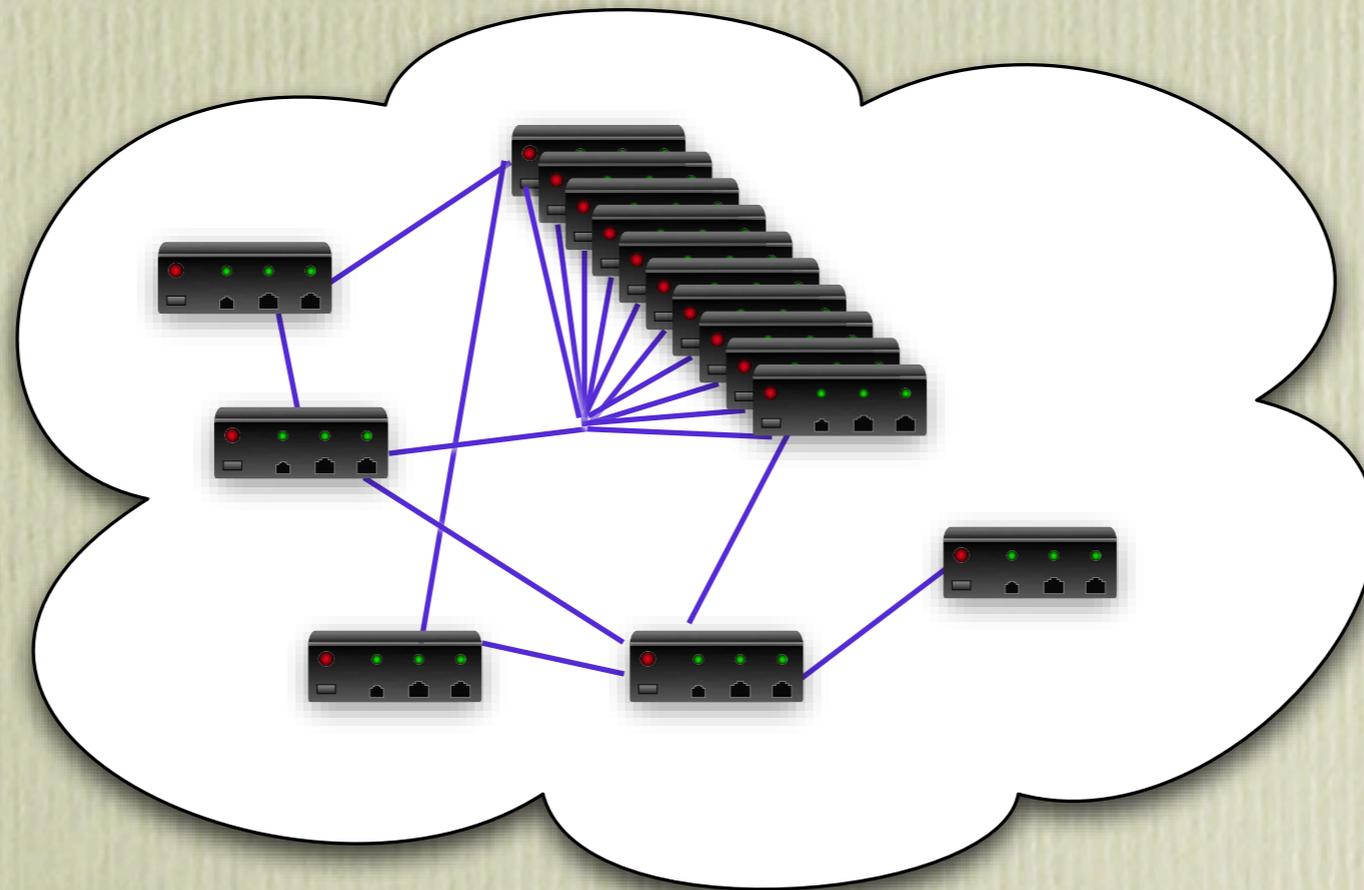
connected by a network



What's a Cloud?

many separate processors connected by a network

independent failure modes



This Talk:

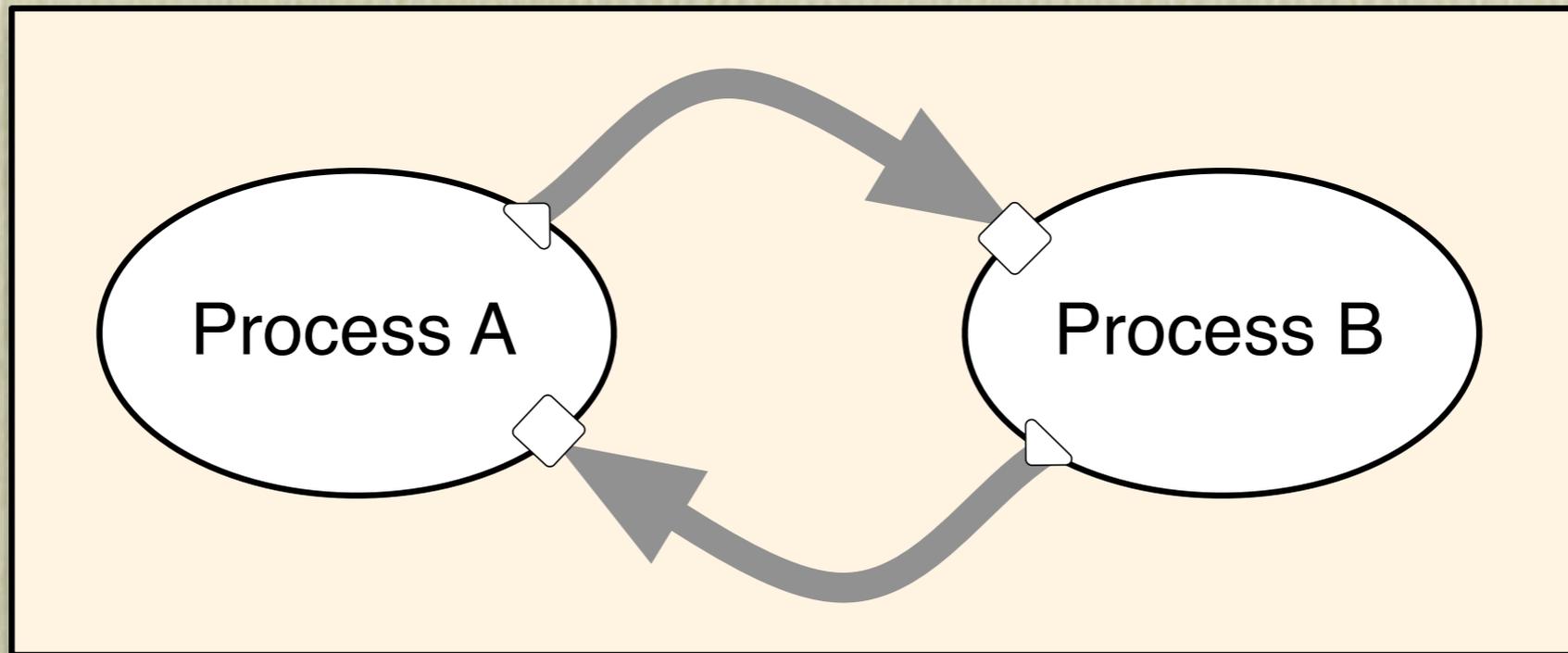
1. Erlang-style concurrency in Haskell
 - Processes, messages & failures
2. Typed Channels
3. Serialization of function closures
4. Assessment
 - Example applications

Erlang in Haskell

- Processes & Messages
- Linking Processes
- Selective Receive of Messages

Processes & Messages

- Process: a concurrent activity that has the ability to send and receive messages



- Processes *cannot* share memory

```
instance Monad ProcessM
```

```
instance MonadIO ProcessM
```

```
send :: Serializable a => ProcessId -> a -> ProcessM ()
```

```
expect :: Serializable a => ProcessM a
```

```
instance Monad ProcessM
instance MonadIO ProcessM
send  :: Serializable a => ProcessId -> a -> ProcessM ()
expect :: Serializable a => ProcessM a
```

- Ping pong:

```
data Ping = Ping ProcessId
data Pong = Pong ProcessId
— omitted: Serializable instance for Ping and Pong
```

```
ping :: ProcessM ()
ping = do { self ← getSelfPid
          ; Pong partner ← expect
          ; send partner (Ping self)
          ; ping }
```

```
instance Monad ProcessM
instance MonadIO ProcessM
send  :: Serializable a => ProcessId -> a -> ProcessM ()
expect :: Serializable a => ProcessM a
```

- Compare with the Erlang version:

```
ping() -> receive
    {pong, Partner} -> Partner ! {ping, self()}
end,
ping().
```

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— omitted: Serializable instance for Ping and Pong
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```
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```

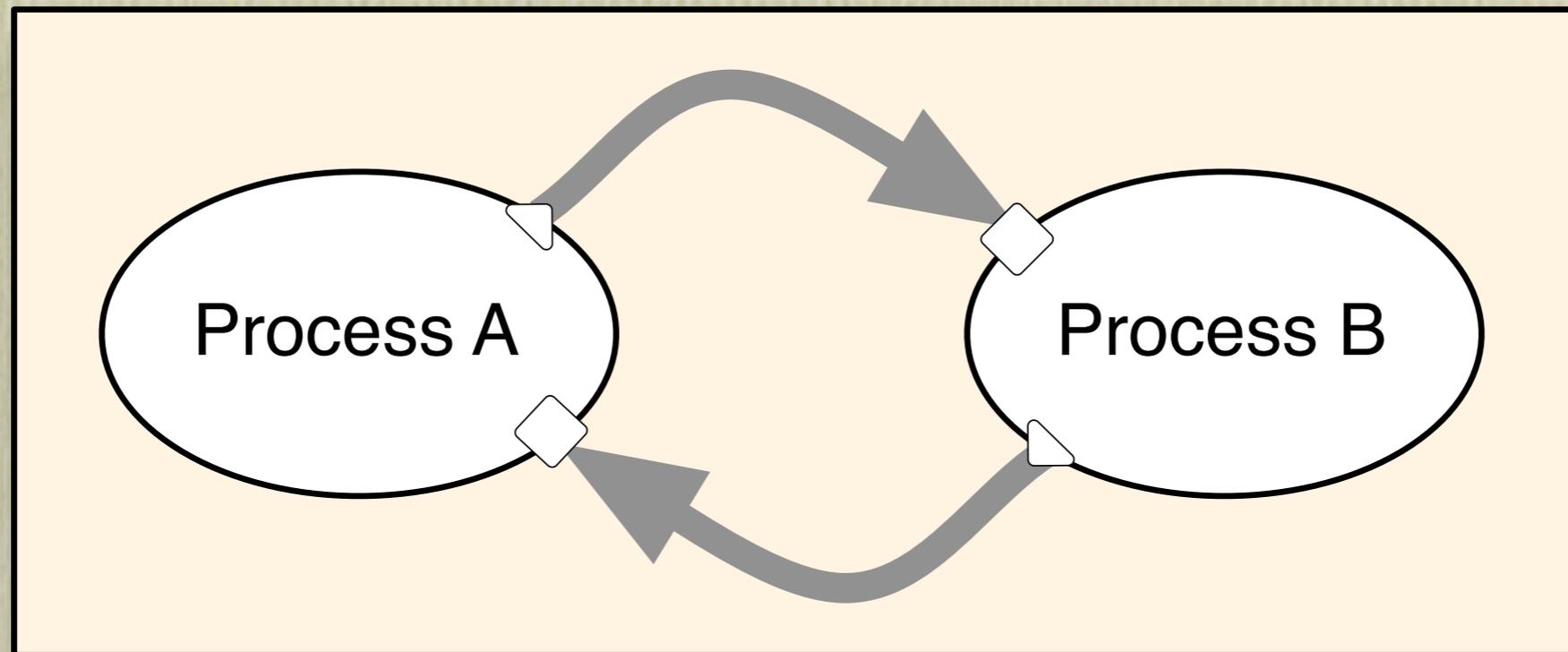
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instance MonadIO ProcessM
```

```
send :: Serializable a => ProcessId -> a -> ProcessM ()
```

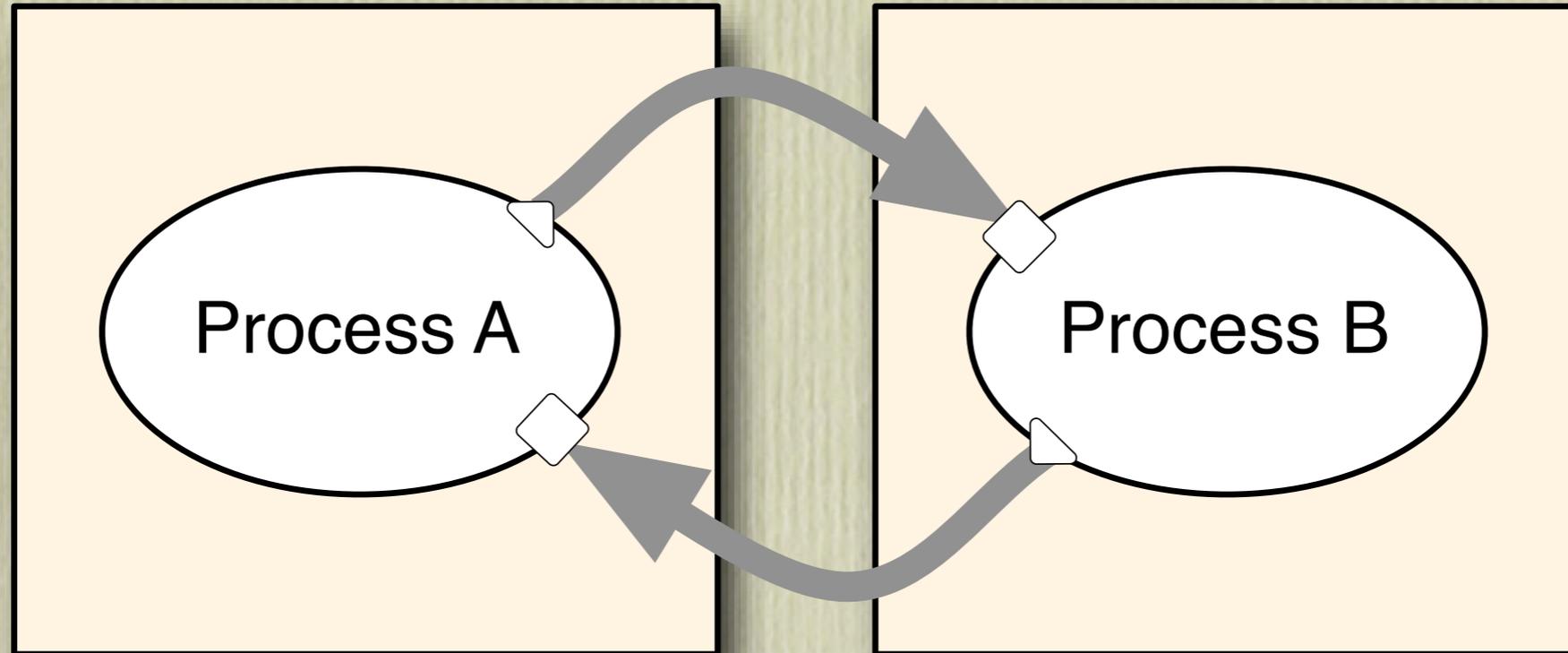
```
expect :: Serializable a => ProcessM a
```

- Key idea: only Serializable values can be sent in messages.
- Certain values are *deliberately* not serializable
 - MVars, IVars and TVars, in particular

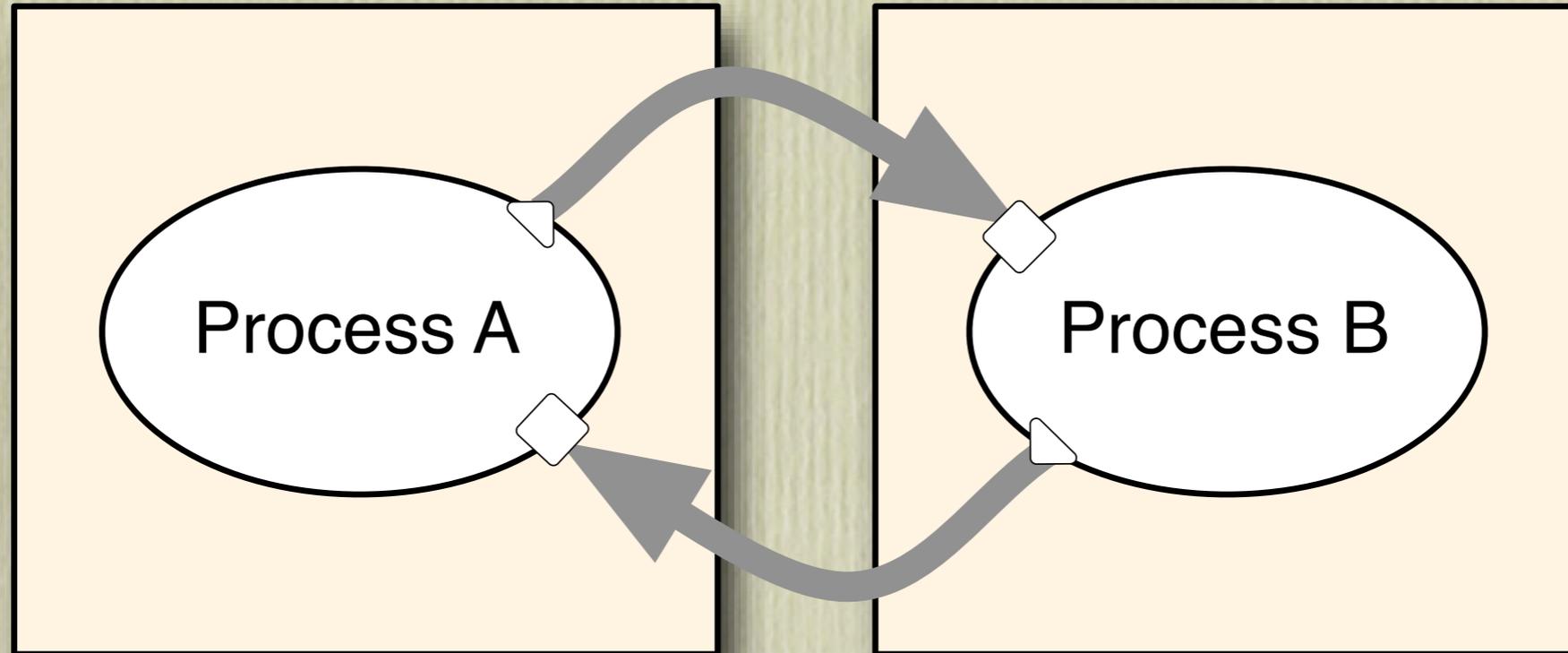
- Consequently:



Consequently:

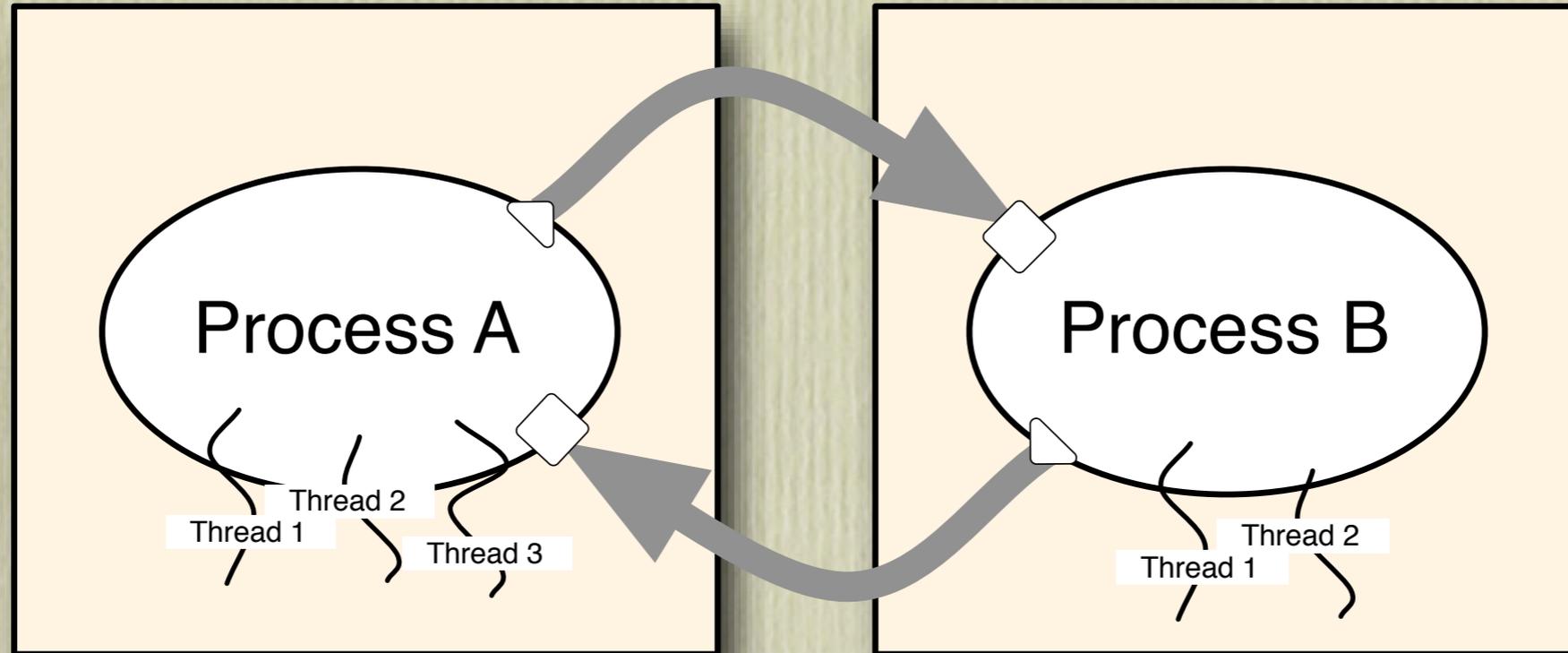


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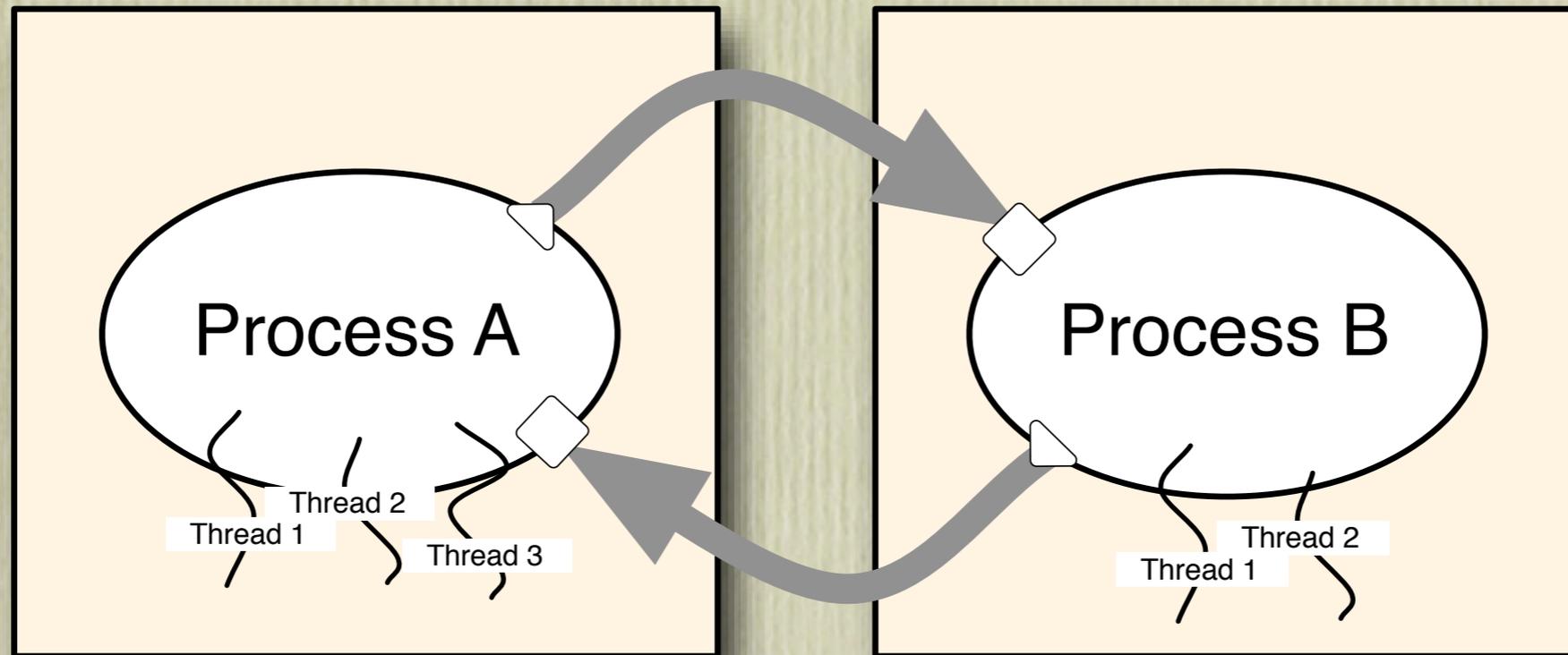


Processes can be moved from one computer to another without invalidating the programming model

Consequently:



Consequently:



Concurrent Haskell's threads, MVars, STM, etc., can all be used *inside* a single Process

Why?

Why?

- Would it be possible to serialize MVars?

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Why?

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 - = Is it possible to simulate shared memory in a distributed memory environment?
 - Yes!
- Would it be a good idea to serialize MVars?
 - We don't think so.

Why?

- Would it be possible to serialize *MVars*?
 - = Is it possible to simulate shared memory in a distributed memory environment?
 - Yes!
- Would it be a good idea to serialize *MVars*?
 - We don't think so.
 - Glasgow Distributed Haskell disagrees!

Starting & Positioning Processes

- A Node (address space, or virtual computer) is identified by a NodeId
- Processes are created by spawn
 - First try:

— wrong

```
spawn :: NodeId → ProcessM () → ProcessM ProcessId
do { pingProc ← spawn someNode ping
    ; pongProc ← spawn otherNode pong
    ; send pingProc (Pong pongProc) }
```

Actual type of Spawn

— wrong

```
spawn :: NodeId → ProcessM () → ProcessM ProcessId
do { pingProc ← spawn someNode ping
    ; pongProc ← spawn otherNode pong
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```

— right

```
spawn :: NodeId → Closure (ProcessM ())
                               → ProcessM ProcessId
```

Actual type of Spawn

— wrong

`spawn :: NodeId → ProcessM () → ProcessM ProcessId`

— right

`spawn :: NodeId → Closure (ProcessM ())
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Actual type of Spawn

— wrong

```
spawn :: NodeId → ProcessM () → ProcessM ProcessId
```

— right

```
spawn :: NodeId → Closure (ProcessM ())  
      → ProcessM ProcessId
```

More about Closures later

Selective Receive

- Erlang provides selective receive by pattern-matching on atoms.

```
math() →  
  receive  
    {add, Pid, Num1, Num2} →  
      Pid ! Num1 + Num2;  
    {divide, Pid, Num1, Num2} when Num2 ≠ 0 →  
      Pid ! Num1 / Num2;  
    {divide, Pid, _, _} →  
      Pid ! div_by_zero  
  end,  
  math().
```

- Haskell programmers would use type constructors instead of atoms:

```
data MathOp = Add ProcessId Double Double
            | Divide ProcessId Double double
            | Answer Double
            | DivByZero
```

- However, this breaks modularity, e.g, it forces servers to respond to Answer and clients to respond to Add.

- It's better to use several independent types:

```
data Add          = Add ProcessId Double Double
data Divide       = Divide ProcessId Double Double
data DivByZero    = DivByZero
```

- However, now we need something more than expect, because we don't know which message will arrive first.

match & receiveWait

```
math :: ProcessM ()
```

```
math =
```

```
  receiveWait
```

```
  [ match (λ(Add pid num1 num2) →  
          send pid (num1 + num2)),  
    matchIf (λ(Divide _ _ num2) → num2 ≠ 0)  
            (λ(Divide pid num1 num2) →  
              send pid (num1 / num2)),  
    match (λ(Divide pid _ _) →  
          send pid DivByZero) ]
```

```
  >>> math
```

match & receiveWait

```
math :: ProcessM ()
```

```
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            (λ(Divide pid num1 num2) →  
              send pid (num1 / num2)),  
    match (λ(Divide pid _ _) →  
          send pid DivByZero) ]
```

```
  >>> math
```

```
match :: Serializable a =>  
(a → ProcessM q) → MatchM q ()
```

match & receiveWait

math :: ProcessM ()

math =

receiveWait

```
[ match (λ(Add pid num1 num2) →  
        send pid (num1 + num2)),  
  matchIf (λ(Divide _ _ num2) → num2 ≠ 0)  
    (λ(Divide pid num1 num2) →  
      send pid (num1 / num2)),  
  match (λ(Divide pid _ _) →  
        send pid DivByZero) ]
```

≫ math

receiveWait ::

[MatchM q ()] → ProcessM q

match :: Serializable a ⇒

(a → ProcessM q) → MatchM q ()

match & receiveWait

```
math :: ProcessM ()
```

```
math =
```

```
  receiveWait
```

```
  [ match (λ(Add pid num1 num2) →  
          send pid (num1 + num2)),
```

```
    matchIf (λ(Divide _ _ num2) → num2 ≠ 0)
```

```
      (λ(Divide pid num1 num2) →  
        send pid (num1 / num2))
```

```
    match (λ(Divide pid _ _) →  
          send pid DivByZero)
```

```
  >>> math
```

```
receiveWait ::
```

```
[MatchM q ()] → ProcessM q
```

```
matchIf :: Serializable a ⇒  
(a → Bool) → (a →  
ProcessM q) → MatchM q ()
```

```
match :: Serializable a ⇒  
(a → ProcessM q) → MatchM q ()
```

Also: receiveTimeout and matchUnkown

```
instance Monad MatchM
```

```
receiveWait    :: [MatchM q ()] → ProcessM q
```

```
receiveTimeout :: Int → [MatchM q ()]
```

```
                → ProcessM (Maybe q)
```

```
match    :: Serializable a ⇒ (a → ProcessM q)
```

```
          → MatchM q ()
```

```
matchIf  :: Serializable a ⇒ (a → Bool)
```

```
          → (a → ProcessM q) → MatchM q ()
```

```
matchUnknown :: ProcessM q → MatchM q ()
```

Typed Channels

- We can use types to ensure that processes are prepared to accept the messages that are sent to them
- Instead of sending a message to a process, we send it on a channel, specialized for a single type
 - A channel is a pair of ports: a send port and a receive port

Channel Interface

`newChan` :: Serializable a ⇒
 ProcessM (SendPort a, ReceivePort a)

`sendChan` :: Serializable a ⇒
 SendPort a → a → ProcessM ()

`receiveChan` :: Serializable a ⇒
 ReceivePort a → ProcessM a

`mergePortsBiased` :: Serializable a ⇒
 [ReceivePort a] → ProcessM (ReceivePort a)

`mergePortsRR` :: Serializable a ⇒
 [ReceivePort a] → ProcessM (ReceivePort a)

SendPort a is serializable; ReceivePort a is *not* serializable

Ping-Pong: once more, with Channels

```
ping2 :: SendPort Ping → ReceivePort Pong →  
                                             ProcessM ()
```

```
ping2 pingout pongin =  
  do { (Pong partnersPort) ← receiveChan pongin  
      ; sendChan partnersPort (Ping pingin)  
      ; ping2 pingout pongin }
```

Combing Ports

- Suppose that we have several communication partners,
 - e.g., messages arrive from the hardware that we are monitoring, and from other control processes in the network.
- We want to receive from one of several ports.

MergePortsBiased	CombinePortsBiased
MergePortsRR	CombinePortsRR

Serializing function closures

- Sending a function to a remote address space involves serializing not only its code, but also its free variables:

— wrong

```
sendFunc :: SendPort (Int → Int) → Int → ProcessM ()
```

```
sendFunc p x = sendChan p (λy → x + y + 1)
```

- The function being sent is $(\lambda y \rightarrow x + y + 1)$, which captures the variable x .

Key insight

- Whether a function is serializable or not has nothing to do with its *type*.
 - It depends on whether it has free variables,
 - whether those free variables are serializablewhich are *not* extensional properties of the function

Prior Solutions

- Make the runtime responsible for serializing anything and everything
 - But some things should be serialized specially
 - And others should not be serialized at all
- Java does essentially this
- Yet: *de*-serialization must still be built-in
 - this requires runtime reflection

More modest magic

- Some functions are easy to serialize
 - those with no free variables
 - How? Serialize the code address
 - assuming the same code is running at both ends
- We need a way of characterizing such definitions as a *type*:

instance Serializable (Static a)

- Intuition: values of type (Static a) are always serializable, regardless what a is!

Static and non-Static types

- Two new terms: static exp and unstatic exp
 - intuition: static exp is well-typed iff exp can be serialized.
- Top-level bindings are tagged S; all others are tagged D
- A term static exp has type τ iff $\text{exp} :: \tau$ and all the free variables in exp are S-bound

$$\Gamma ::= \overline{x :_{\delta} \sigma}$$

$$\delta ::= S \mid D$$

$$\Gamma \downarrow = \{x :_s \sigma \mid x :_s \sigma \in \Gamma\}$$

$$\frac{\Gamma \downarrow \vdash e : \tau}{\Gamma \vdash \text{static } e : \text{Static } \tau}$$

(Static intro)

$$\frac{\Gamma \vdash e : \text{Static } \tau}{\Gamma \vdash \text{unstatic } e : \tau}$$

(Static elim)

Examples:

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$\text{id} :: a \rightarrow a$

$\text{id } x = x$

id is s -bound, but has a non-static type.

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$f :: \text{Static } a \rightarrow (\text{Static } a, \text{Int})$

$f x = (x, 3)$

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Examples:

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$x :_D \text{Static } a$

$\text{static } (\text{length} \circ \text{filter id})$

Free variables of a static term need not have static types

- So what? We need to serialize functions that *do* have free variables.
- Static values make it possible to do closure conversion
- Let's try:

— wrong

data Closure a where

MkClosure :: Static (env → a) → env → Closure a

- This makes the environment explicit:
 - env is the (existentially quantified) type of the environment of our function

- Slight snag: env is not serializable
- OK: let's make it so!

— still wrong

data Closure a where

MkClosure :: Serializable env =>

Static (env → a) → env → Closure a

deriving Typeable

- Now serialization is easy:

instance Binary (Closure a) where

put (MkClosure f env) = put f >> put env

- But what about *de*-serialization?

- Deserialization is a problem because, at the receiving end, we don't know what env is.
 - Can we send a representation of its type?
 - And then what?
 - Do a run-time type-class lookup?
 - Send a representation of the de-serialization function?
 - This would require us to serialize closures ...
- Simple and (in hindsight!) obvious solution:
 - get rid of the existential!

The solution

— finally right

data Closure a where

```
MkClosure :: Static (ByteString → a) → ByteString → Closure a
```

- Isn't this awfully restrictive?

No! *Any* env that is serializable is equipped with encode and decode functions that convert it to and from a ByteString!

- The (de)-serialization is now done at closure-construction time

Examples

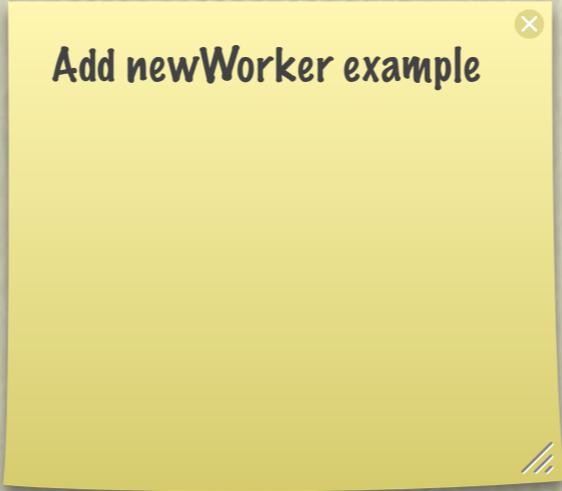
```
sendFunc :: SendPort (Closure (Int → Int)) → Int → ProcessM ()
```

```
sendFunc p x = sendChan p clo
```

```
  where clo = MkClosure (static sfun) (encode x)
```

```
sfun :: ByteString → Int → Int
```

```
sfun = λbs → let x = decode bs  
              in λy → x + y + 1
```



Add newWorker example

Example

p is a SendPort that expects a
(Closure (Int→Int))

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```
in λy → x + y + 1
```

sfun *de-serializes* its
own argument

In the Closure
we put a *pre-
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Add newWorker example

Summary

- New type constructor `Static`, with built-in serialization.
- A new term form `(static e)`
- A new primitive function `unstatic :: Static a → a`
- These primitives let us construct closures manually and control when and how they are serialized.
 - This looks tiresome, and programmers will probably want some syntactic support: future work

Faking it

- Static is not yet implemented in GHC
- We use Template Haskell workarounds

```
sendFunc :: SendPort (Closure (Int → Int)) → Int → ProcessM ()
sendFunc p x = sendChan p ($ (mkClosure 'add1) x)

add1 :: Int → Int → Int
add1 x y = x + y + 1

$(remotable ['add1])
```

- Programmer is still doing closure-conversion
 - by defining `add1` as a top-level function whose first argument is an explicit environment (`Int`)
 - `mkClosure` operates on the *names* of functions:
 - ▶ `mkClosure :: Name → Q Exp`

Assessment

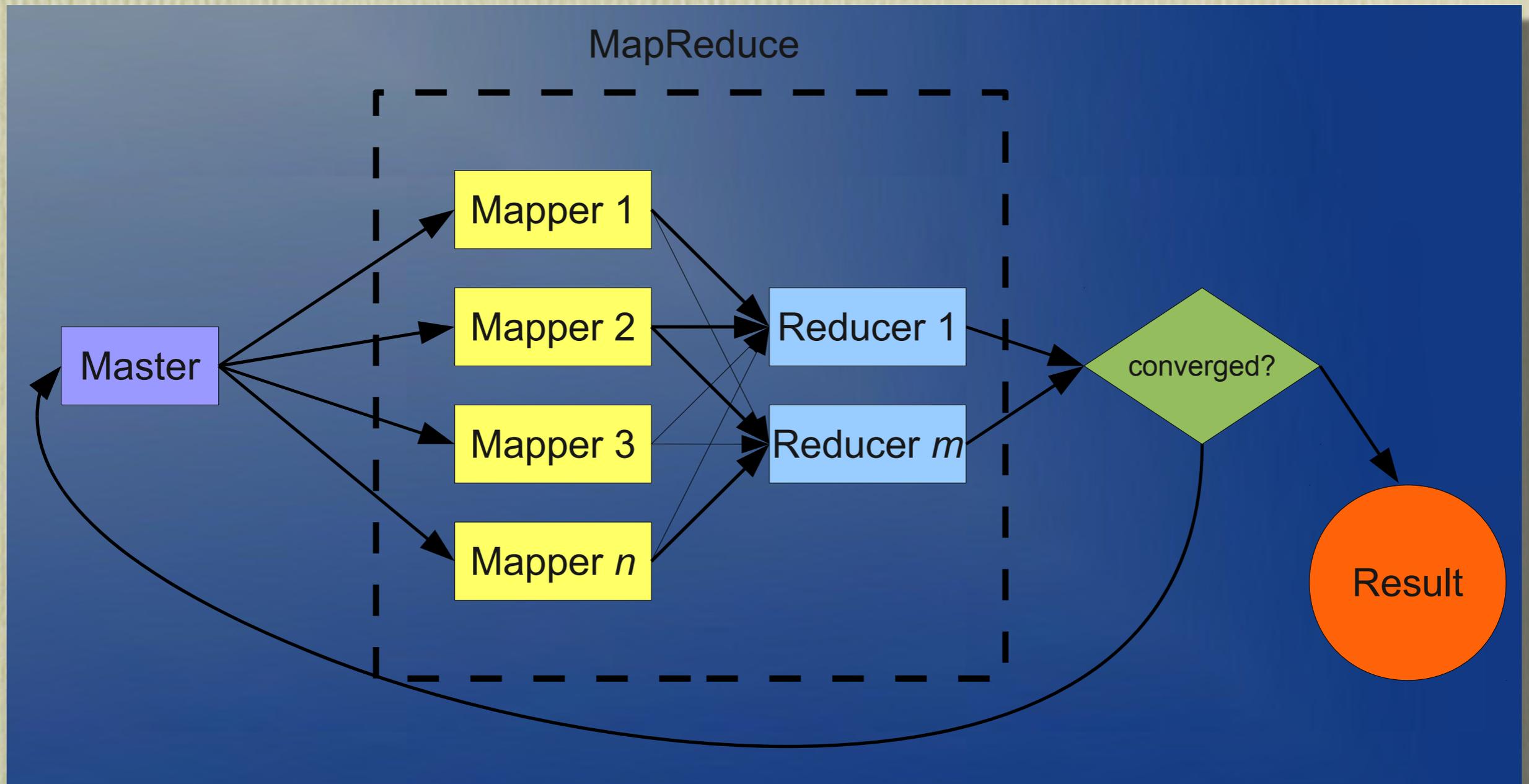
- Limited experience so far
- Small examples on local networks, and k -means on an Amazon EC2 cluster.

k -means

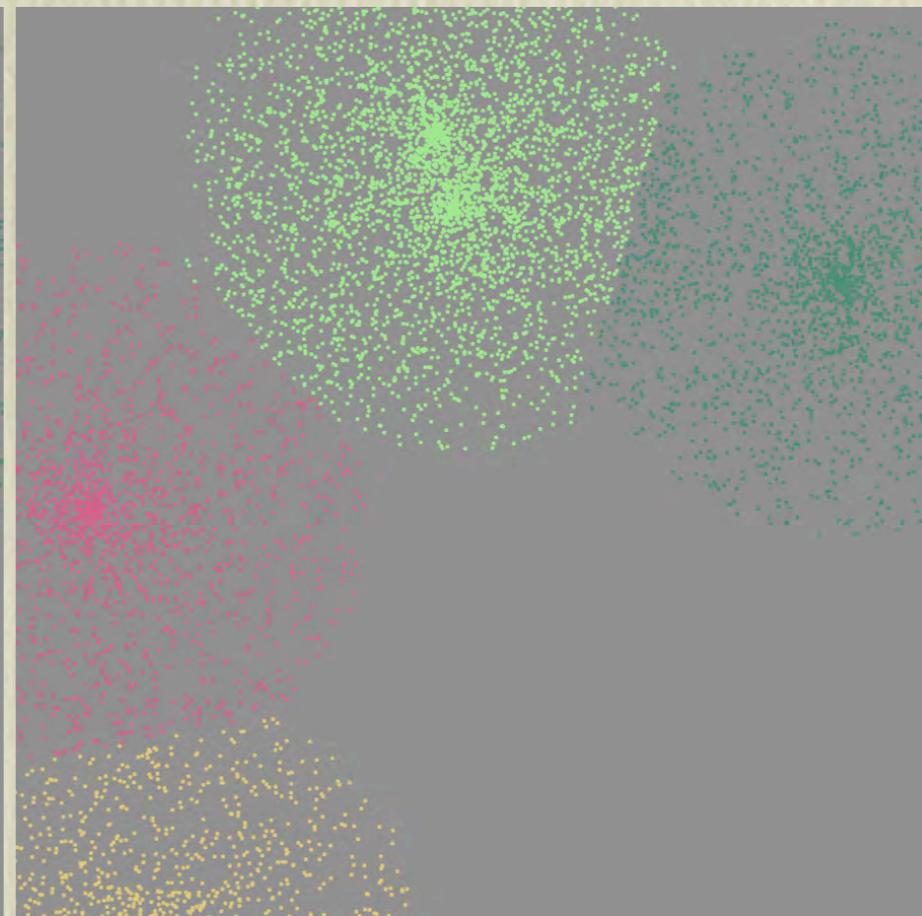
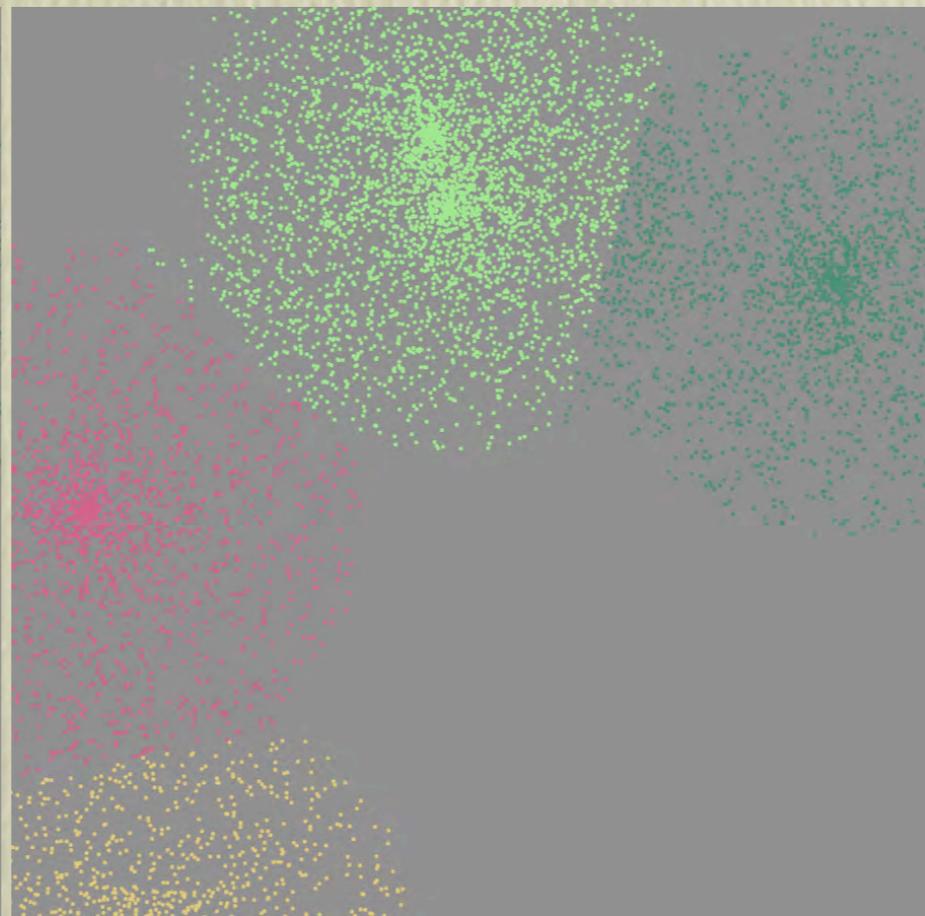
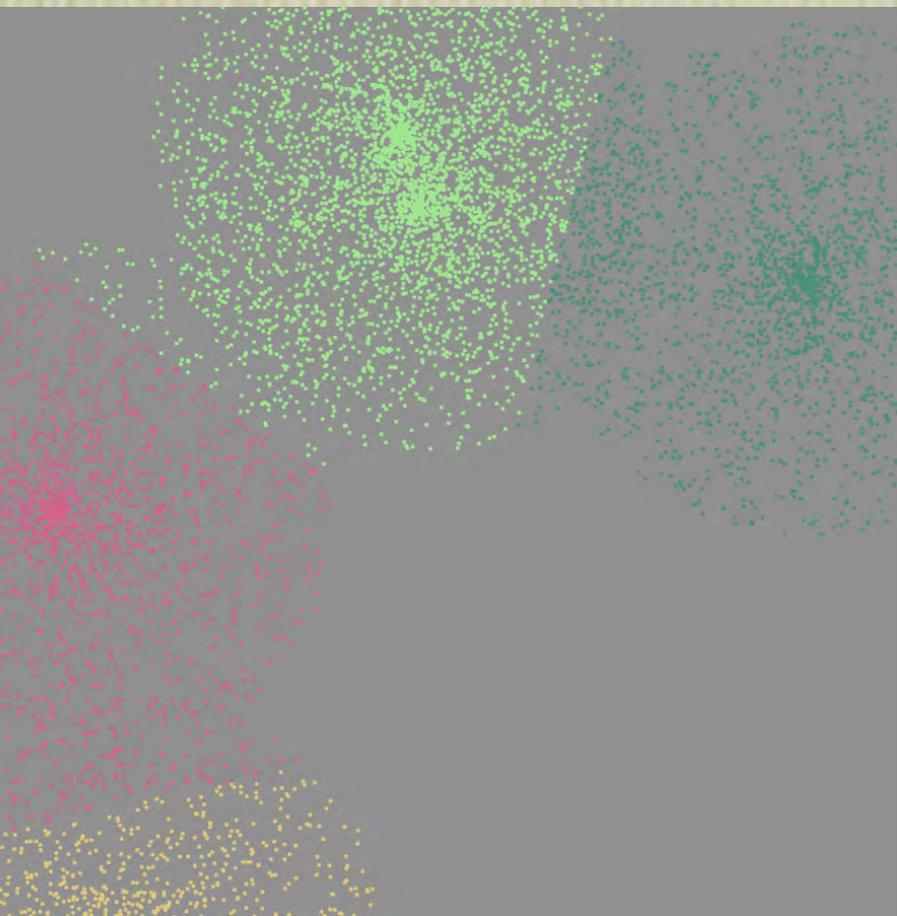
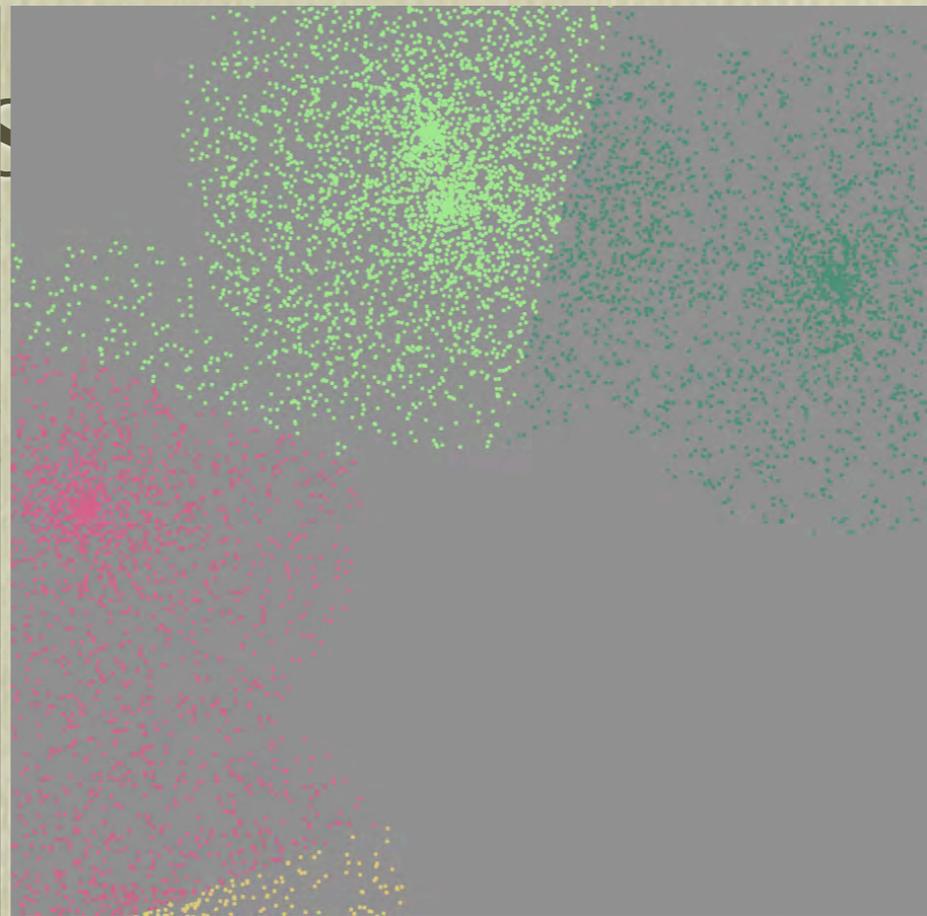
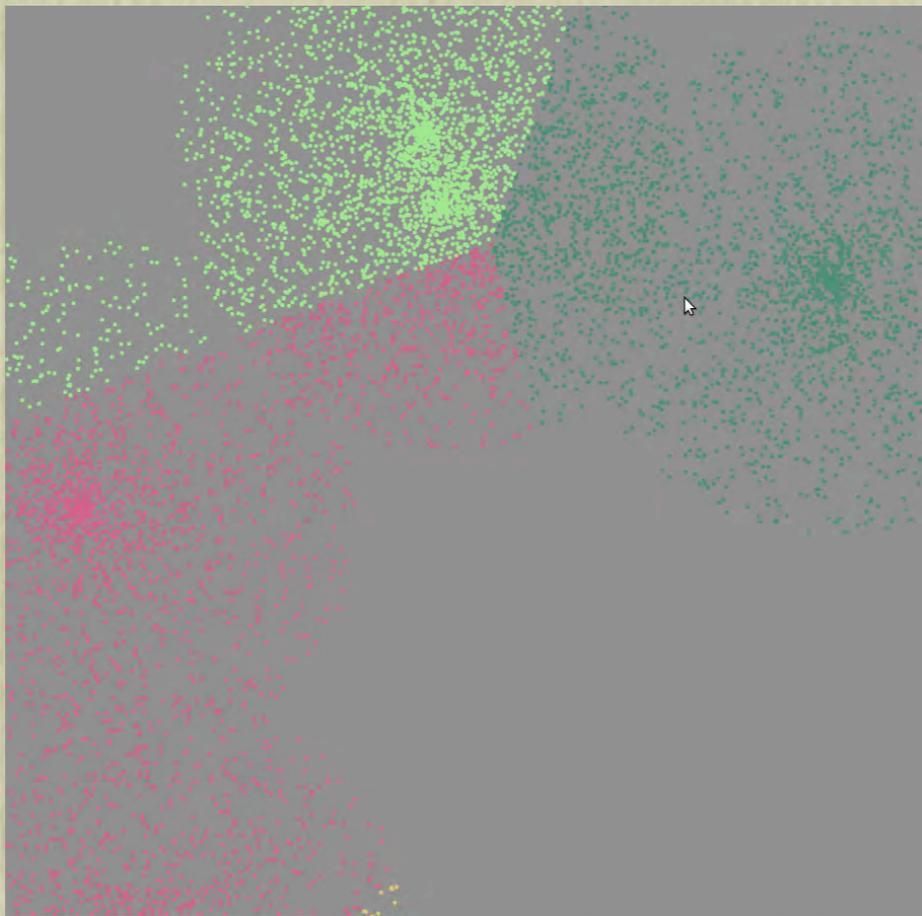
Data clustering algorithm:

1. Guess at centroids of k clusters
2. Put each point in nearest cluster
3. Compute the centroids of these cluster of points
4. Use the computed centroids as the next guess
5. Continue until convergence

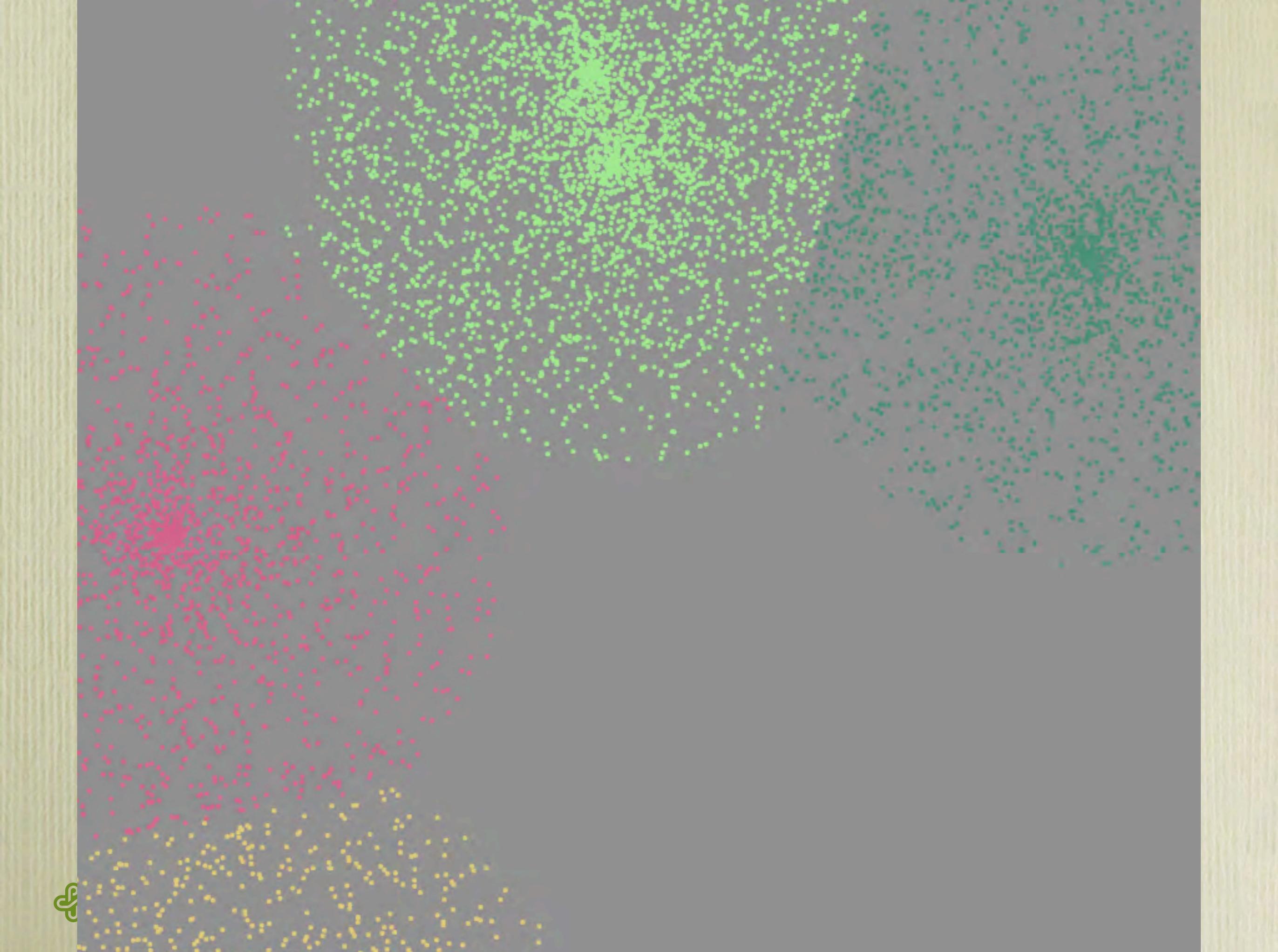
k -means



k -means results



k -means results



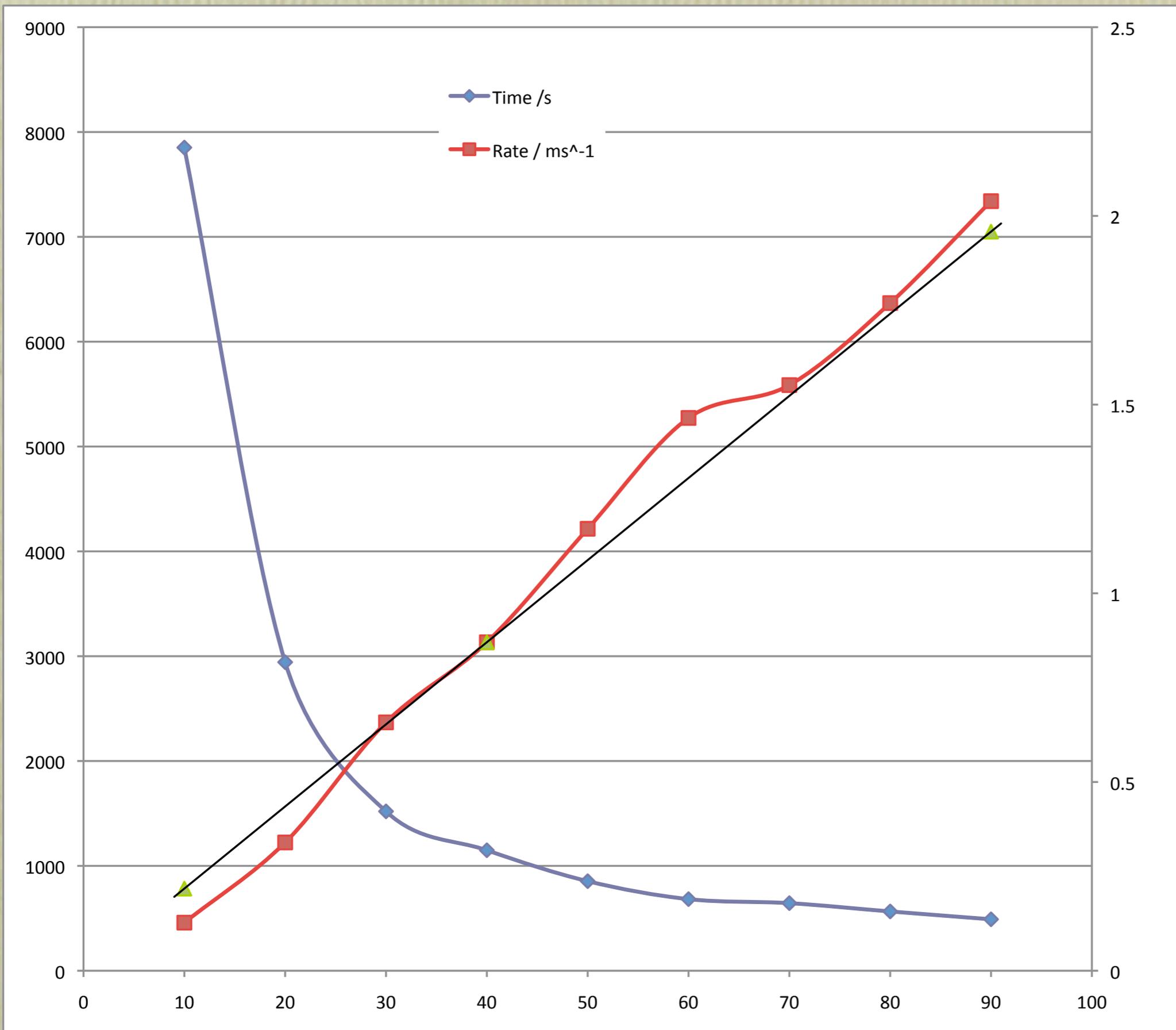
k-means results

nodes:
m1.small (1
core, 1.7 GB)

1 million
100-D points

one reducer

5 iterations



Related Work

- Inspired by Erlang
 - Also by Ciel execution engine and the Skywriting language [Murray *et al*]
- MPI from the HPC community
 - language independent
- RPC and RMI mechanisms
 - Birrell & Nelson, Emerald, CORBA, Java RMI, SOAP, ...

- Distributed functional languages: GDH (distributed shared memory), Concurrent ML, paraML
 - Acute [Sewell *et al.*]: uses runtime representations of datatypes
 - HashCaml: does support serialization of function values, also with explicit type-passing
 - Alice [Rossberg's Thesis]
 - Clean: type-safe pickling, including function closures
- Our design point: serialization of closures is *not* built-in

Future Work

- Low level: implement Static in GHC
- Restartable task level
 - inspired by Skywriting project
 - tasks: idempotent, restartable computations
 - system tracks data dependencies between tasks
 - allocates tasks to processors
 - recovers from failure

Summary

- Cloud Haskell: a *starting point* for building distributed applications
- Contributions:
 - Typed version of Erlang's process & messaging interfaces
 - Typed channels; receive port is not Serializable
 - Serialization of function closures
 - It works (on 90 Amazon EC2 nodes)