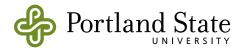
#### CS311—Computational Structures

# Regular Languages and Regular Grammars

Lecture 6



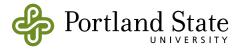
#### What we know so far:

- RLs are closed under product, union and \*
- Every RL can be written as a RE, and every RE represents a RL
- Every RL can be recognized by a NFA
  - and we know how to build it
- NFAs and DFA have the same "power"
- Every NFA can be turned in to a DFA
  - "the subset construction"



#### What's Next?

- How to turn a FSA into a regular grammar
  - and vice-versa
- Minimal-state DFAs
  - Myhill-Nerode Theorem
    - Language indistinguishability



- A grammar is a set of rules for transforming strings
  - Strings can involve variables and terminal symbols
  - S → abcT
- We derive a string of terminals by repeatedly applying rules beginning from a designated start variable (often S)
  - The language defined by a grammar is the set of strings that can be derived



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     Variables
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  - Strings can involve variables and terminal symbols
  - S → abcT Terminal symbols
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#### Regular Grammars

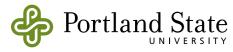
Hein Section 11.4.1

- What's a Regular Grammar?
  - A particular kind of grammar in which all the productions have one of these forms:

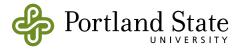
$$S \rightarrow \varepsilon$$
  $S \rightarrow w$   $S \rightarrow T$   $S \rightarrow wT$ 

- w is a sequence of terminal symbols
- at most one variable can appear on the rhs, and it must be on the right.
- Examples:

$$S \rightarrow abcY \quad Y \rightarrow aZa \quad S \rightarrow AB$$





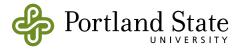


a*	

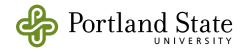


a\* S→ε | aS





$$a^*$$
  $S \rightarrow \epsilon \mid aS$   
 $a+b$   $S \rightarrow a \mid b$ 



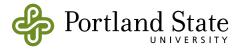
$$a^*$$
  $S \rightarrow \varepsilon \mid aS$ 
 $a+b$   $S \rightarrow a \mid b$ 
 $(a+b)^*$ 



$$a^* \quad S \rightarrow \varepsilon \mid aS$$
 $a+b \quad S \rightarrow a \mid b$ 
 $(a+b)^* \quad S \rightarrow \varepsilon \mid aS \mid bS$ 



$$a^*$$
  $S \rightarrow \varepsilon \mid aS$ 
 $a+b$   $S \rightarrow a \mid b$ 
 $(a+b)^*$   $S \rightarrow \varepsilon \mid aS \mid bS$ 
 $a^* + b^*$ 



$$a^*$$
  $S \rightarrow \varepsilon \mid aS$ 
 $a+b$   $S \rightarrow a \mid b$ 
 $(a+b)^*$   $S \rightarrow \varepsilon \mid aS \mid bS$ 
 $a^* + b^*$   $S \rightarrow A \mid B$ 
 $A \rightarrow \varepsilon \mid aA$ 
 $B \rightarrow \varepsilon \mid bB$ 



#### Languages and Grammars

- Any regular language has a regular grammar
- Any regular grammar generates a regular language

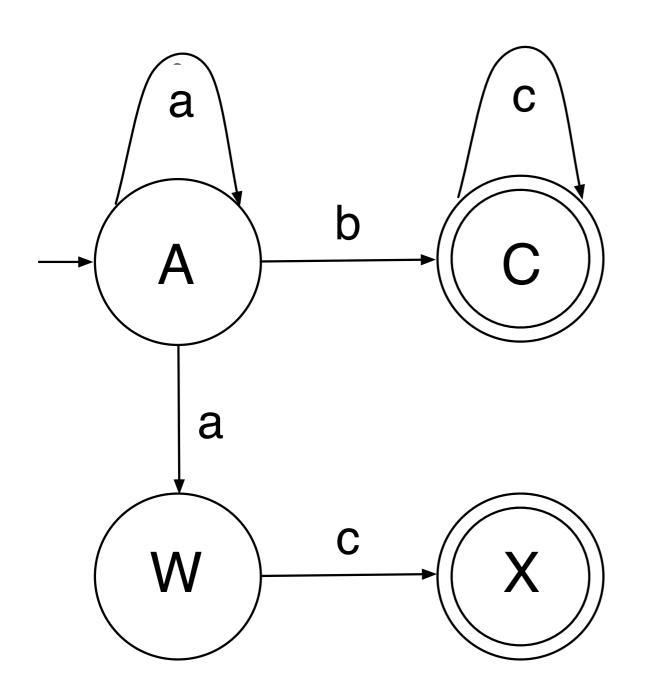


#### From NFA to Regular Grammar

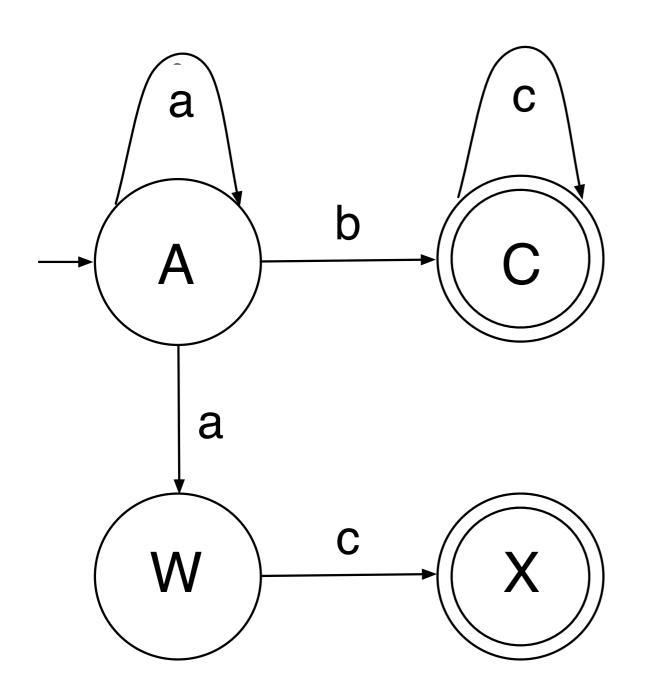
Hein Algorithm 11.11

- 1. Rename the states Q to a set of upper-case letters
- 2. The start symbol of the grammar is the name of the start state q<sub>0</sub>.
- 3. For each transition  $(I) \xrightarrow{a} (J)$ , create the production  $I \rightarrow aJ$ .
- For each transition (I) → (J), create the production I→J.
- 5. For each final state K, create the production  $K \rightarrow \epsilon$ .

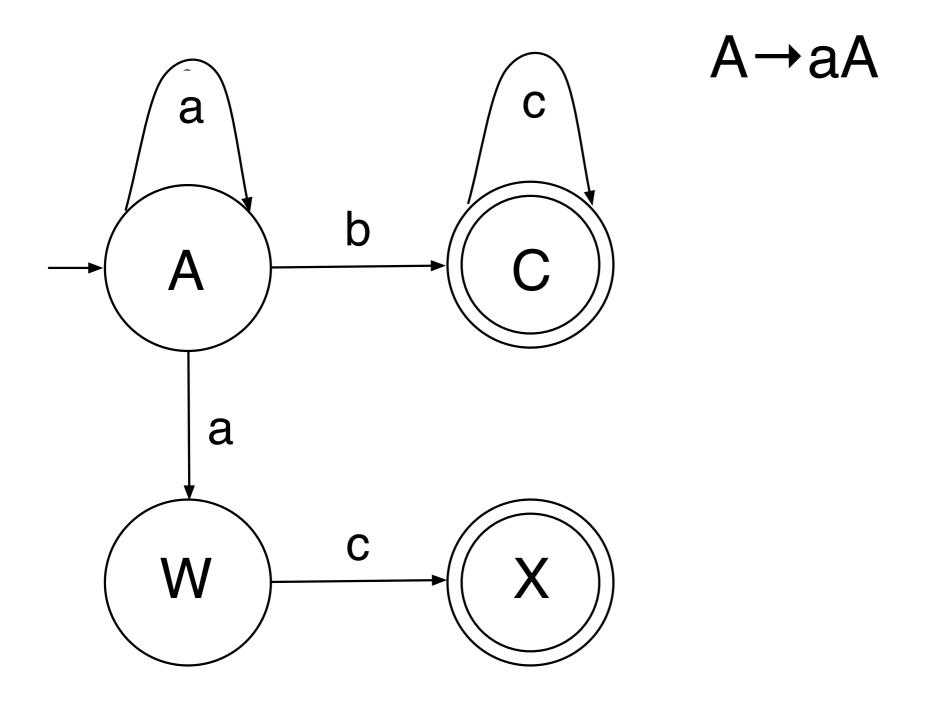




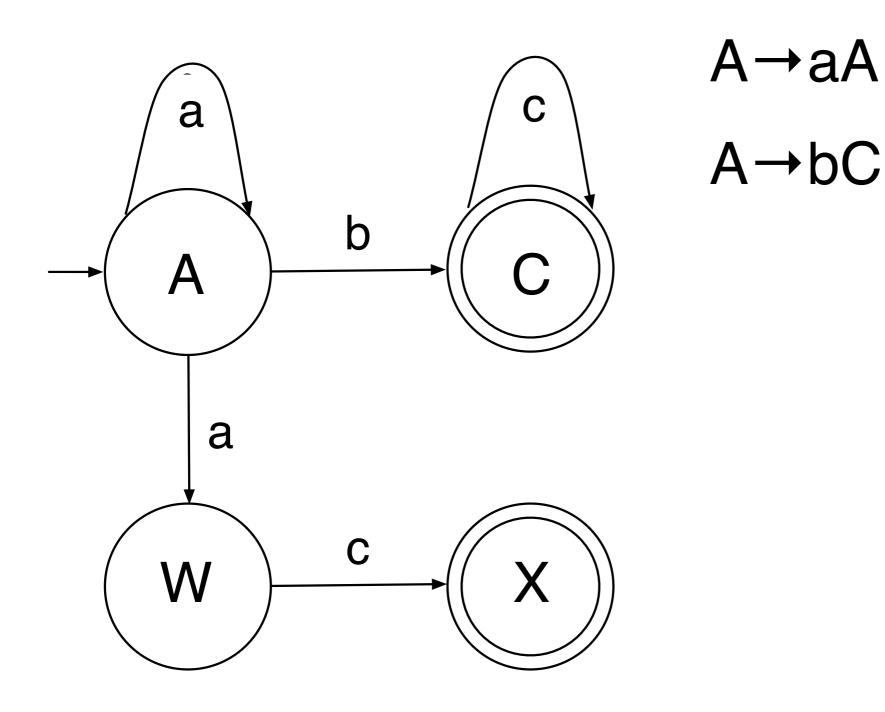




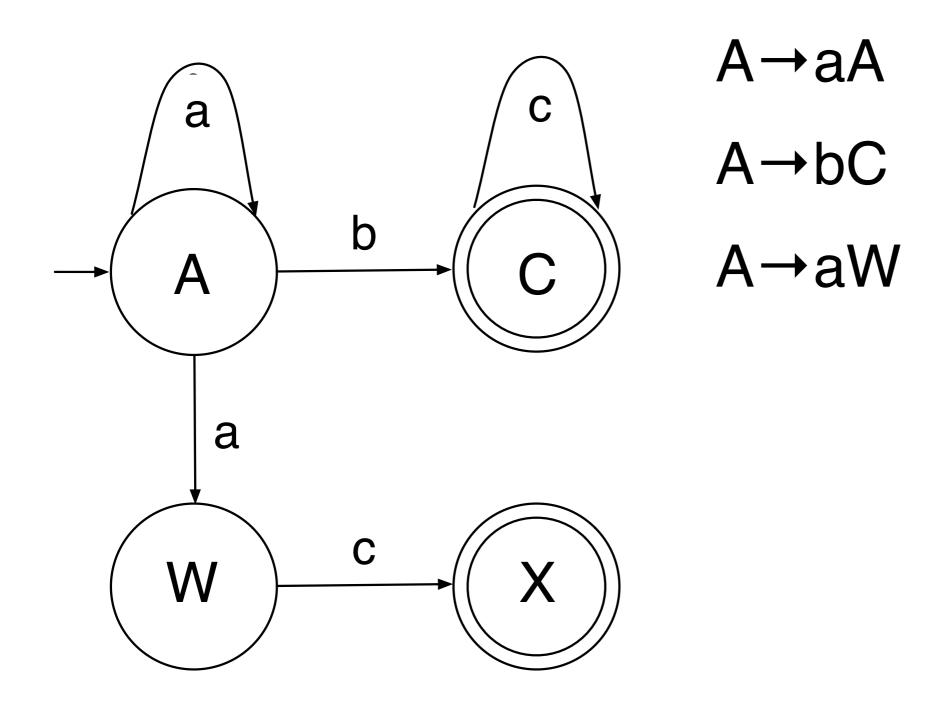


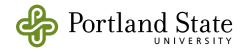


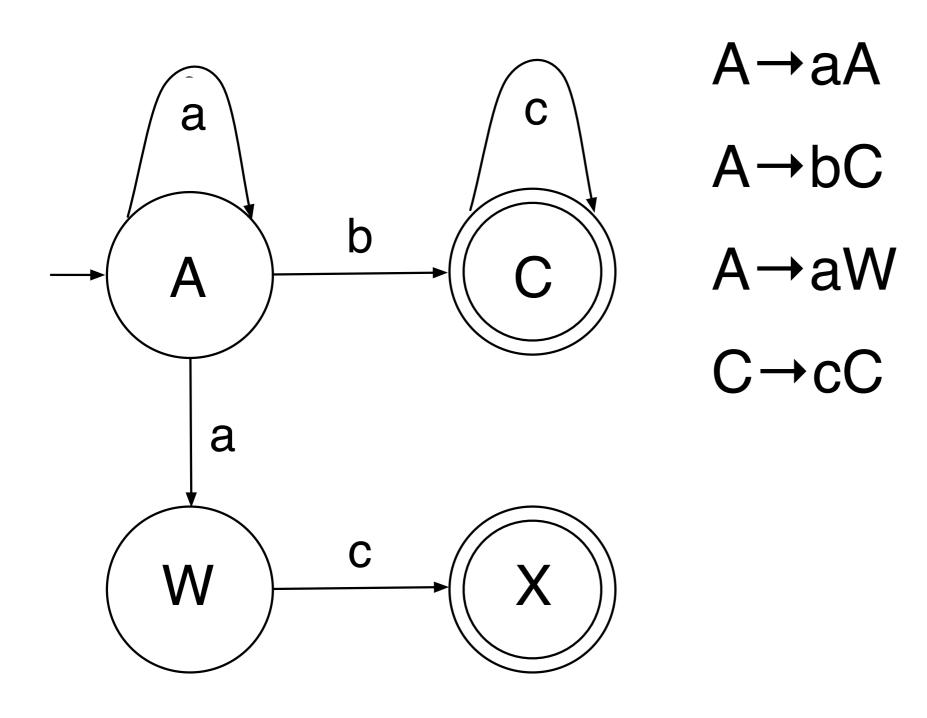




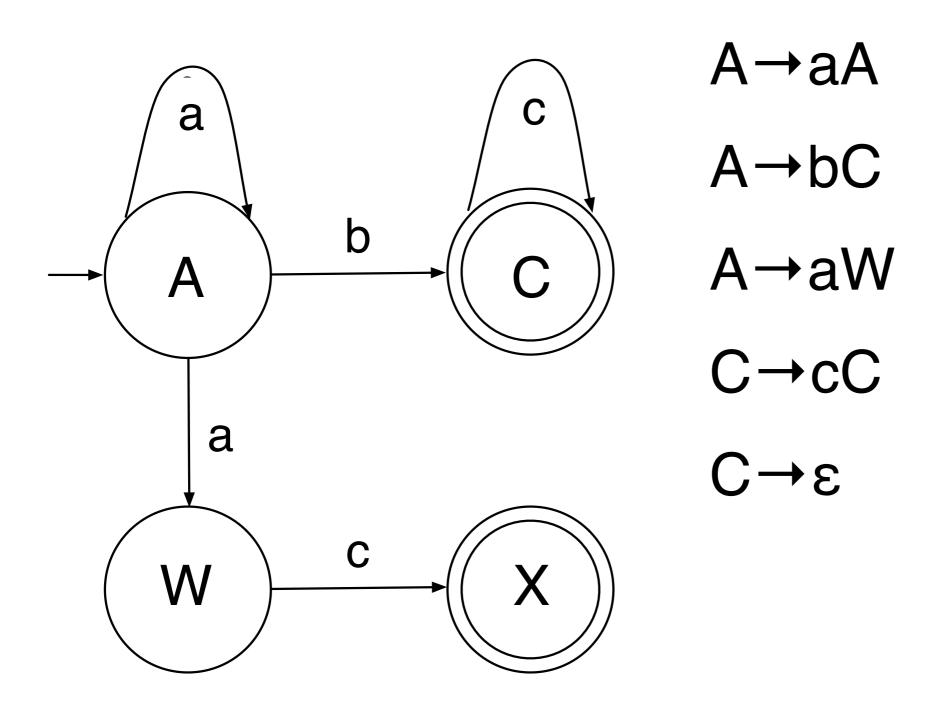


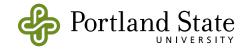


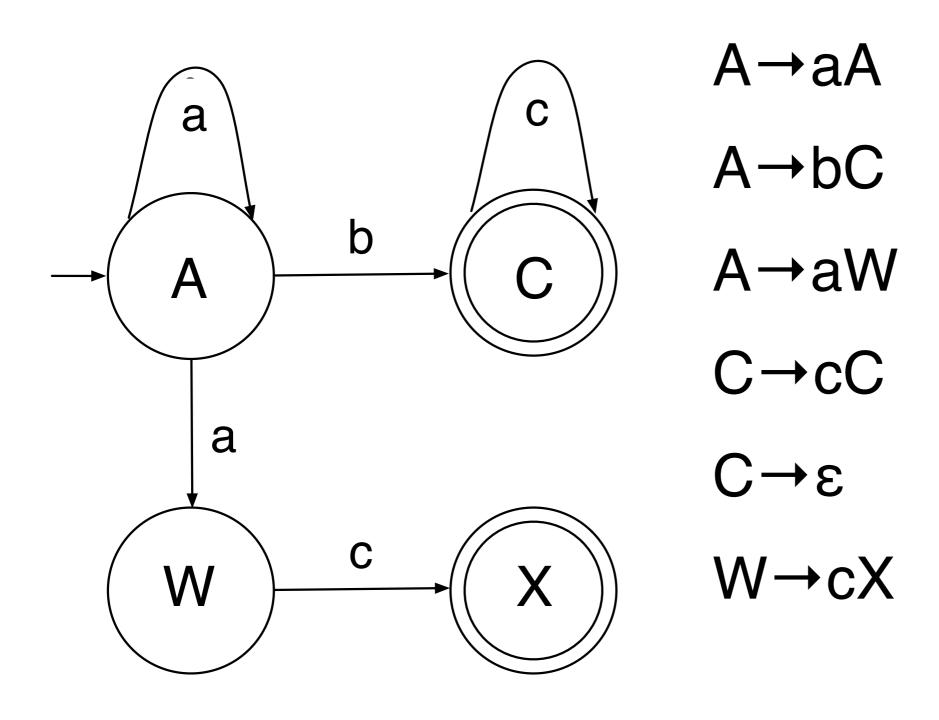


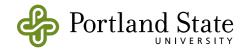


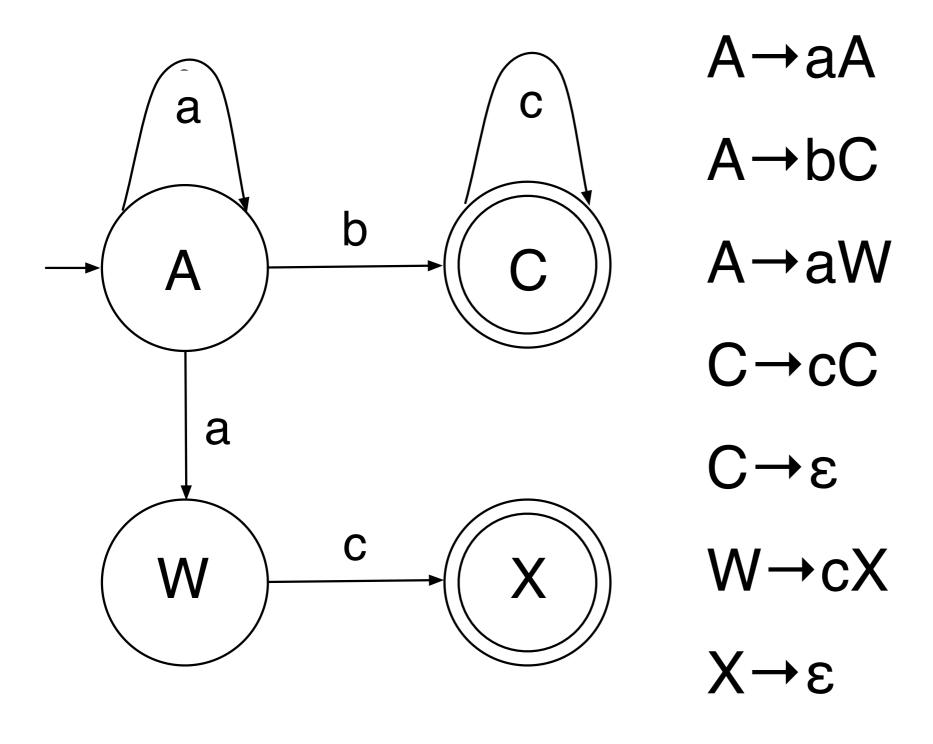


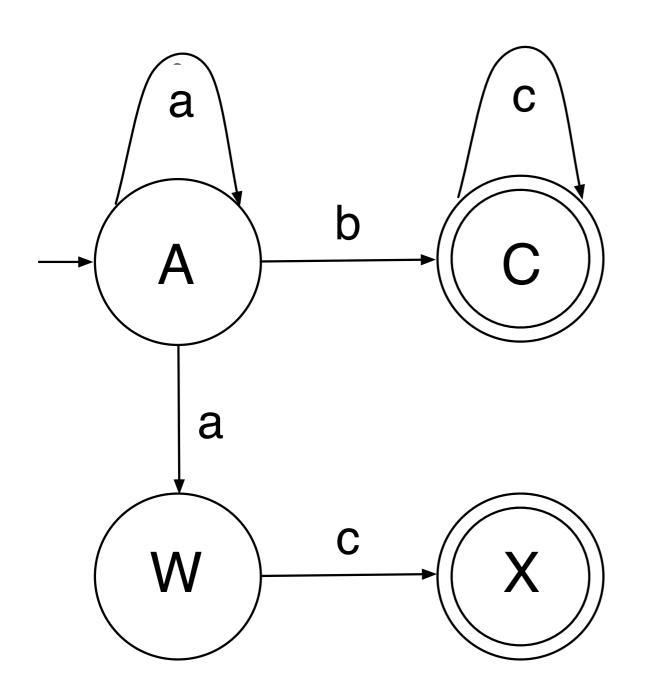




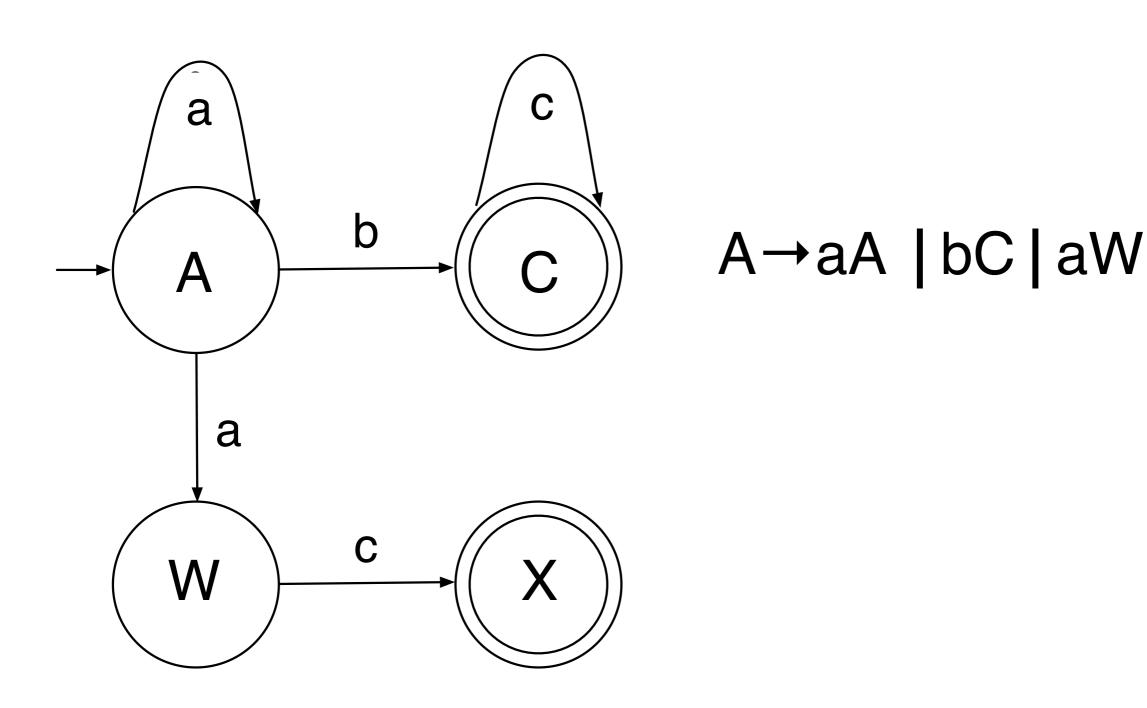




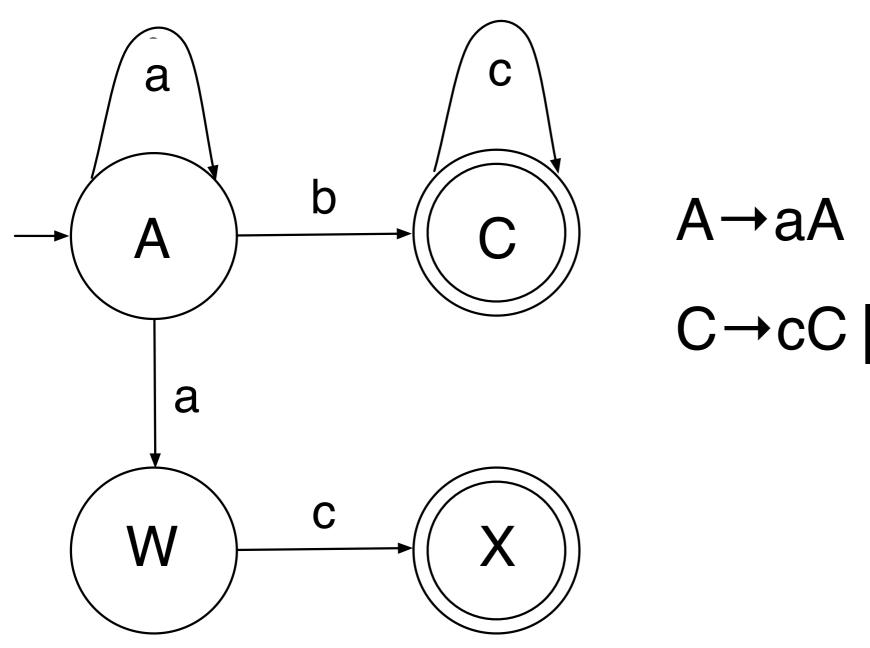


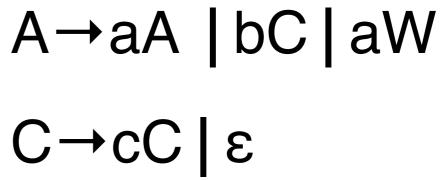


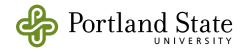


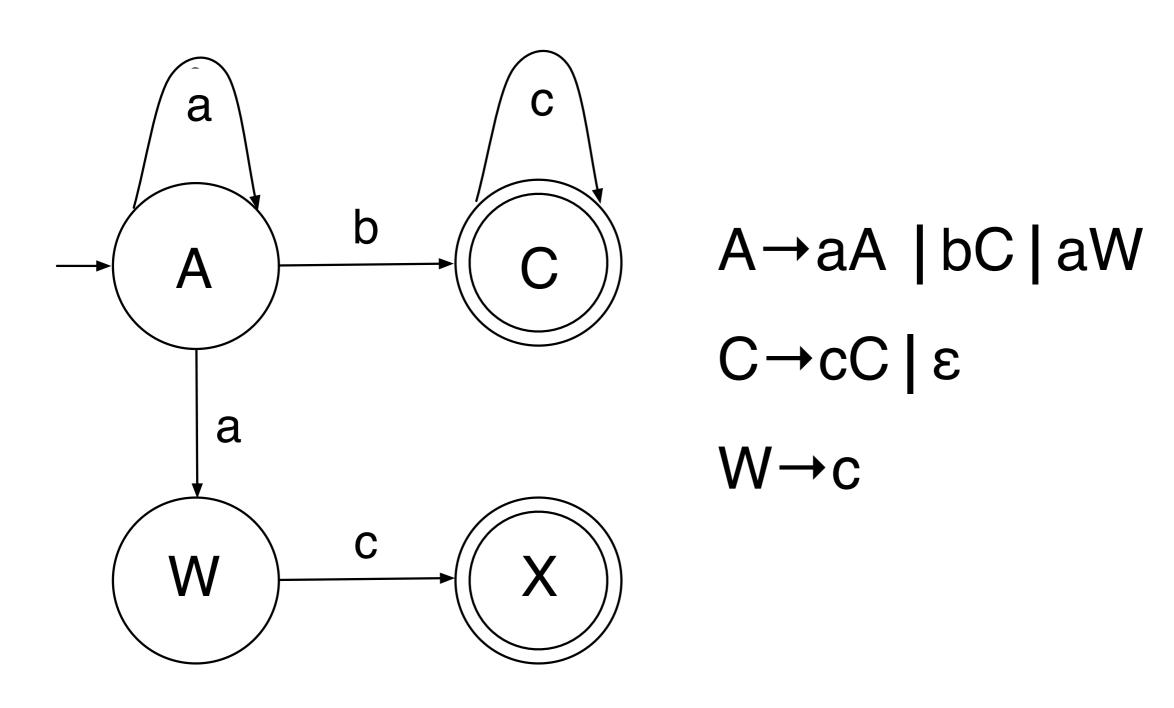














#### From Regular Grammar to FSM

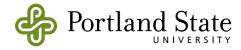
Hein Algorithm 11.12

- 1. Transform the grammar so that all productions are of the form  $A \rightarrow x$  or  $A \rightarrow xB$ , where x is either a single letter or  $\epsilon$ .
- 2. The start state of the NFA is the grammar's start symbol.
- 3. Create state  $Q_F$  and add it to the set F of final states.
- 4. For each production  $I \rightarrow aJ$ , create the transition  $U \rightarrow aJ$
- 5. For each production  $I \rightarrow J$ , create the transition  $(I) \xrightarrow{\varepsilon} (J)$
- 6. For each production  $K \rightarrow \varepsilon$ , add K to the set of final states F
- 7. For each production  $I \rightarrow a$ , create the transition  $(I) \xrightarrow{a} (Q_F)$



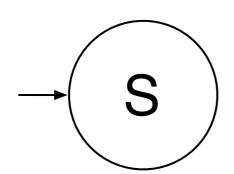
$$S \rightarrow B$$

$$B\rightarrow \epsilon$$

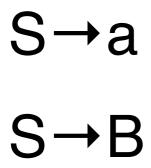


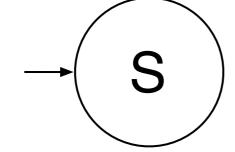
$$S \rightarrow B$$



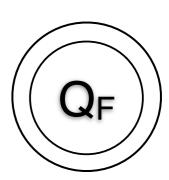


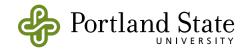






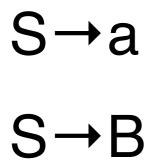
$$B \rightarrow \epsilon$$



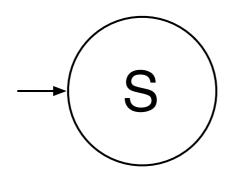


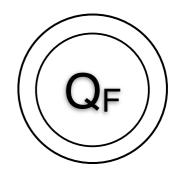
B

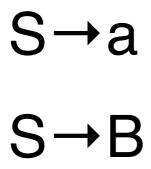






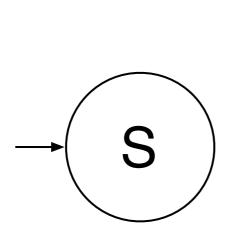


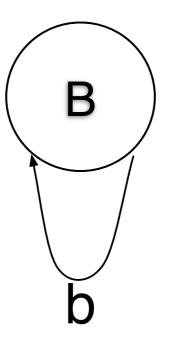


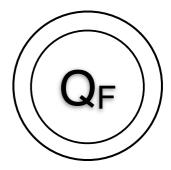


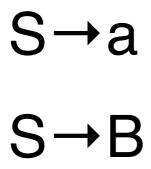






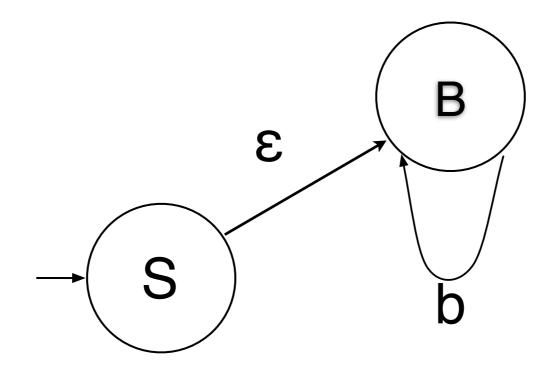


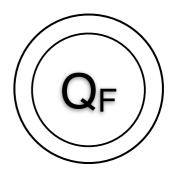


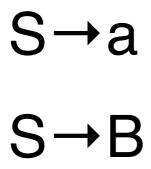


 $B \rightarrow \epsilon$ 

B→bB

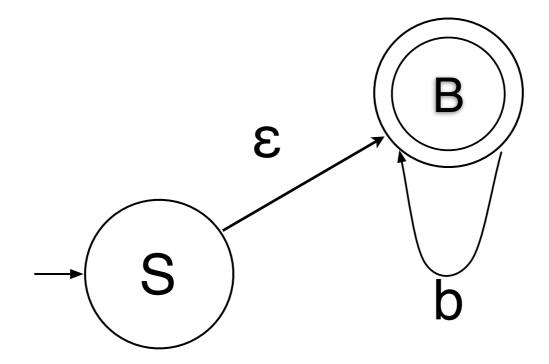


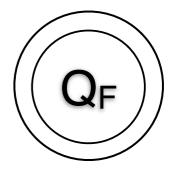


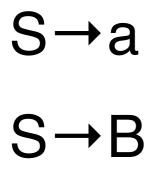


 $B\rightarrow \epsilon$ 

B→bB

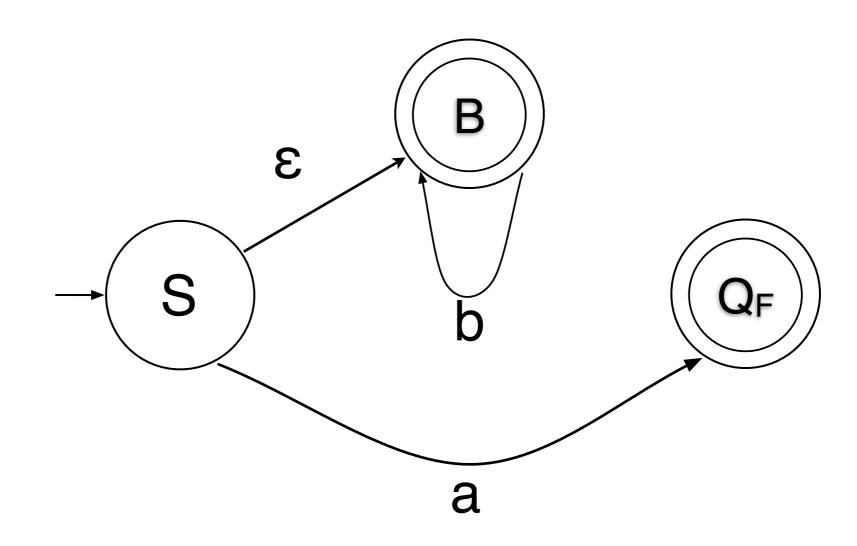


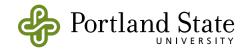


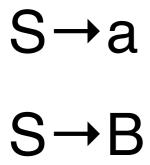


B→ε

B→bB

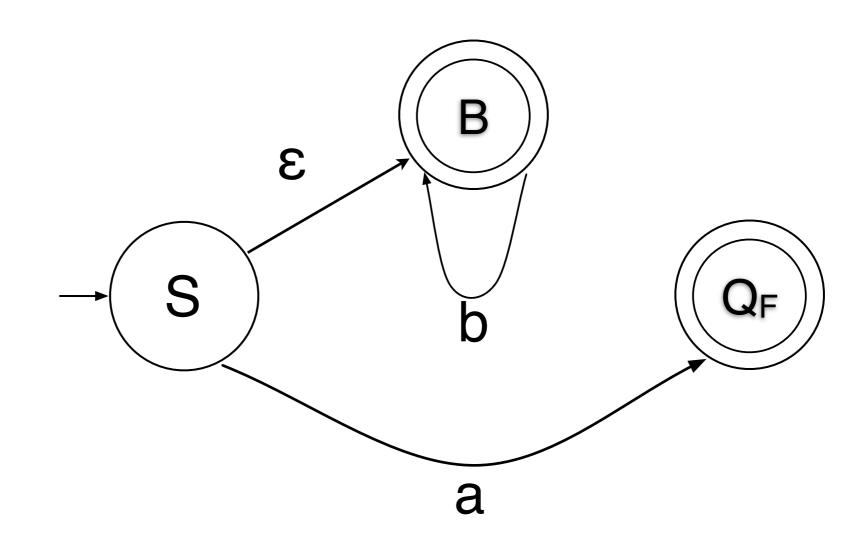






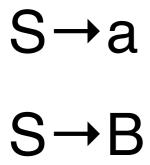
B→ε

B→bB



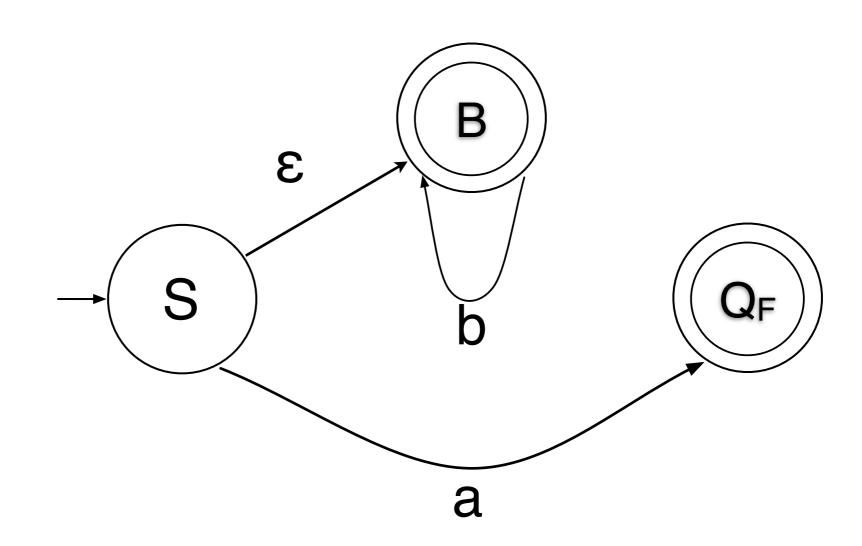
What's the language?





B→ε

B→bB



What's the language?

$$a + b^*$$



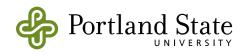
# Language Indistinguishability

- Consider a language L over an alphabet A.
- Two strings x, y ∈ A\* are Lindistinguishable if for all z ∈ A\*, xz ∈ L
  whenever yz ∈ L. We write x ≡ y
- ■L is an equivalence relation
- The *index* of L is the number of equivalence classes induced by ≡<sub>L</sub>



# Example: $L = a + b^*$

a + b\* = { ε, a, b, bb, bbb, bbbb, ...}
 a = L b ?
 ε = L b ?
 aa = L ab ?
 ab = L bb ?



# Example: $L = a + b^*$

•  $a + b^* = \{ \epsilon, a, b, bb, bbb, bbb, ... \}$ 

$$a \equiv_L b$$
?

$$aa \equiv_{L} ab$$
?

$$ab \equiv_{L} bb$$
?

 What are the equivalence classes of ≡<sub>L</sub>?

```
1. {a}
```

- 2. {b, bb, bbb, bbbb, ...}
- 3.  $\{\epsilon\}$
- 4. everything else



## Myhill-Nerode Theorem

- The equivalence relation ≡<sub>L</sub> characterizes exactly what the state of an automaton that accepts L needs to remember about the read portion of the input:
  - if the read portion of the input is x, then the state needs to remember the equivalence class [x].
  - This is sufficient, because if x ≡<sub>L</sub> y, then it does not matter if the read portion of the input was x or y; all that matters (for deciding whether to accept or reject) is the future portion of the input, say z, because xz ∈ L iff yz ∈ L.
  - It is also necessary, because if x ≠ y, then there is some possible future portion z of the input such that xz needs to be accepted and yz rejected (or vice versa).



## Theorem Statement (Part A)

If the index of a language A is k, then there is a k-state DFA  $M_A$  such that  $L(M_A) = A$ 



### Mimimum-state DFA

- For any language L, there is a unique mimimum-state DFA that recognizes L
  - unique means "unique up to an isomorphism", that is, a renaming of the states.
- Any DFA can be transformed into a minimum-state DFA



## Equivalent States

Two states p and q in a DFA
m={Q, Σ, q₀, δ, F} are equivalent if,
for all z ∈ Σ\*,

 $\hat{\delta}(p,z)$  is a final state exactly when  $\hat{\delta}(q,z)$  is a final state, i.e.,

$$p \equiv q \text{ iff } \forall z \in \Sigma^*. (\hat{\delta}(p, z) \in F) \equiv (\hat{\delta}(q, z) \in F)$$

Is this an equivalence relation?

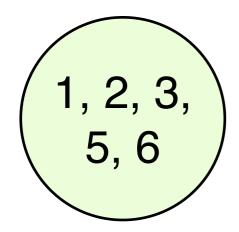


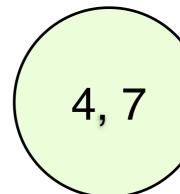
### How to Calculate State Equivalence

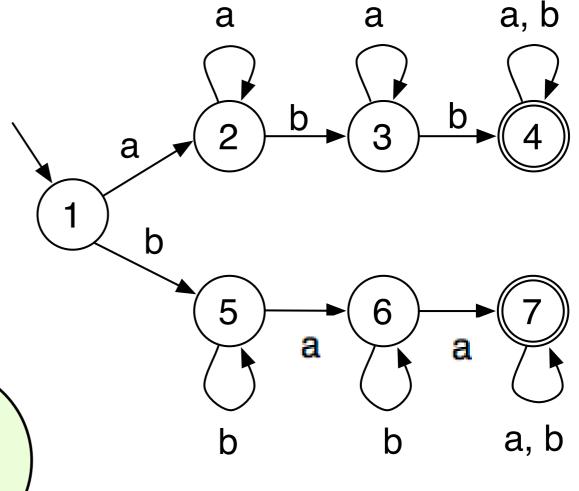
#### Example:

3 and 4 are not equivalent (why)?

First guess:

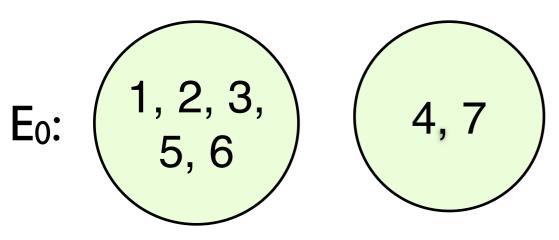






This works for strings w of length 0

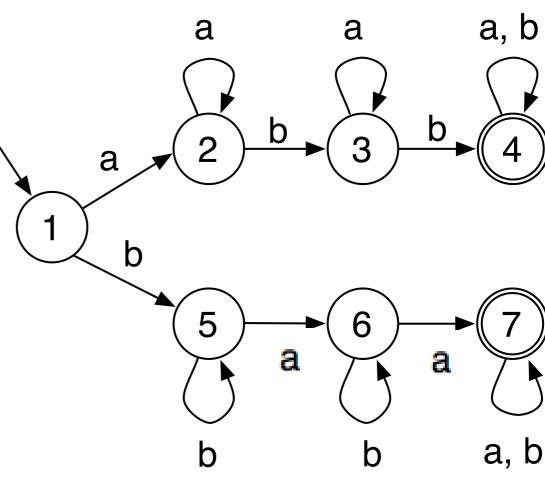




- Take states 1 and 2
  - for all single-character inputs, do we end up in equivalent states?

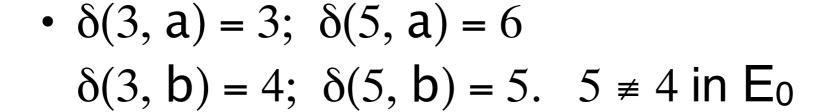
• 
$$\delta(1, a) = 2$$
;  $\delta(2, a) = 2$   
 $\delta(1, b) = 5$ ;  $\delta(2, b) = 3$ .  $5 = 3$  in  $E_0$ 

 So the pair <1, 2> stays in the same equivalence class in the next guess, E<sub>1</sub>

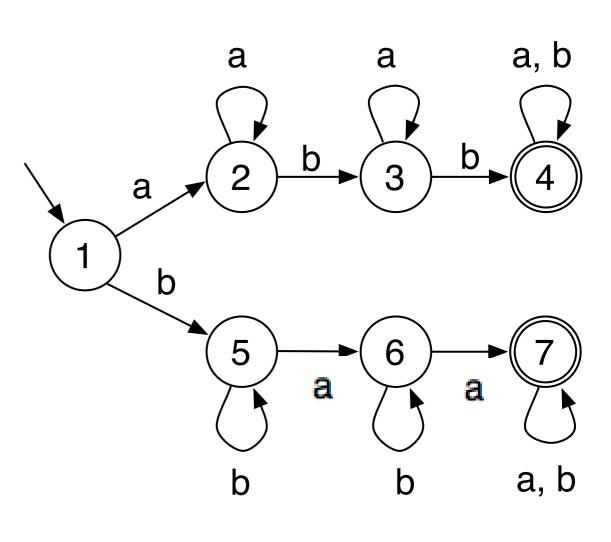


E<sub>0</sub>: 
$$\begin{pmatrix} 1, 2, 3, \\ 5, 6 \end{pmatrix}$$
  $\begin{pmatrix} 4, 7 \end{pmatrix}$ 

- What about states 3 and 5?
  - for all single-character inputs, do we end up in equivalent states?



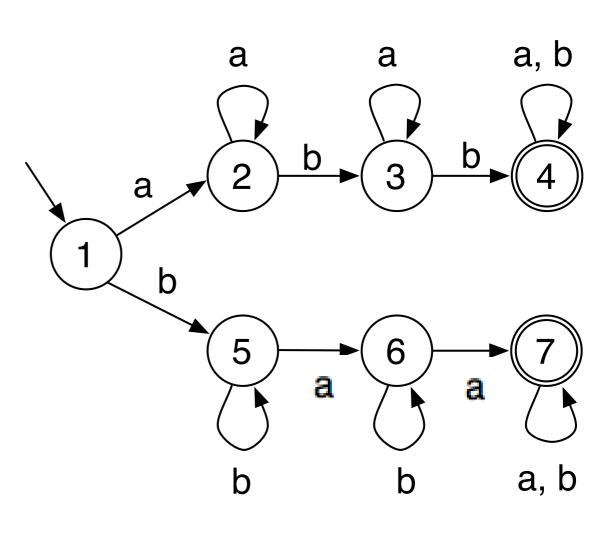
 So the states 3 and 5 are not in the same equivalence class in the next guess, E<sub>1</sub>



- What about states1 and 5 ?
  - for all single-character inputs, do we end up in equivalent states?

• 
$$\delta(1, a) = 2$$
;  $\delta(5, a) = 6$   
 $\delta(1, b) = 5$ ;  $\delta(5, b) = 5$ .  $2 \neq 6$  in E<sub>1</sub>

 So the states 1 and 5 are not in the same equivalence class in the next guess, E<sub>2</sub>



- Then we repeat to get the next guess E<sub>2</sub>
- The equivalence relation  $E_n$  represents states that act in the same way after reading input strings of length n
- Remember, a relation is nothing more than a set of pairs.
- So we build
   E<sub>0</sub> ⊇ E<sub>1</sub> ⊇ E<sub>2</sub> ⊇ ...
- When do we stop?



# Minimizing a DFA

How can we easily compute whether or not two states p and q in a DFA are equivalent?

Suppose that they are not equivalent:

Then some (finite) string z will be accepted when the machine starts in p, and rejected when the machine starts in q.

$$p \not\equiv q \text{ iff } \exists z \in \Sigma^*. (\hat{\delta}(p,z) \in F) \not\equiv (\hat{\delta}(q,z) \in F)$$



# Minimizing a DFA

How can we easily compute whether or not two states p and q in a DFA are equivalent?

Suppose that they are not equivalent:

Then some (finite) string z will be accepted when the machine starts in p, and rejected when the machine starts in q.

$$p \not\equiv q \text{ iff } \exists z \in \Sigma^*. (\hat{\delta}(p, z) \in F) \not\equiv (\hat{\delta}(q, z) \in F)$$
  
 $p \equiv q \text{ iff } \forall z \in \Sigma^*. (\hat{\delta}(p, z) \in F) \equiv (\hat{\delta}(q, z) \in F)$ 



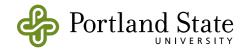
## Computing sets of equivalent states

$$E_0 \ni \langle p, q \rangle$$
 where  $p \in F \equiv q \in F$ 

$$E_1 = E_0 \setminus \{\langle p, q \rangle \mid \exists a \in \Sigma. \langle \delta(p, a), \delta(q, a) \rangle \notin E_0\}$$

•

$$E_{n+1} = E_n \setminus \{\langle p, q \rangle \mid \exists \ a \in \Sigma. \langle \delta(p, a), \delta(q, a) \rangle \notin E_n \}$$



# Constructing a Minimal DFA

#### Hein Construction 11.10

#### Algorithm to Construct a Minimum-State DFA

(11.10)

Given: A DFA with set of states S and transition table T. Assume

that all states that cannot be reached from the start state

have already been thrown away.

Output: A minimum-state DFA recognizing the same regular lan-

guage as the input DFA.

1. Construct the equivalent pairs of states by calculating the descending sequence of sets of pairs  $E_0 \supset E_1 \supset \cdots$  defined as follows:

 $E_0 = \{\{s, t\} \mid s \text{ and } t \text{ are distinct and either both states are final or both states are nonfinal}\}.$ 

 $E_{i+1} = \{\{s, t\} \mid \{s, t\} \in E_i \text{ and for every } a \in A \text{ either } T(s, a) = T(t, a) \text{ or } \{T(s, a), T(t, a)\} \in E_i\}.$ 

The computation stops when  $E_k = E_{k+1}$  for some index k.  $E_k$  is the desired set of equivalent pairs.

- 2. Use the equivalence relation generated by the pairs in  $E_k$  to partition S into a set of equivalence classes. These equivalence classes are the states of the new DFA.
- 3. The *start state* is the equivalence class containing the start state of the input DFA.
- 4. A *final state* is any equivalence class containing a final state of the input DFA.
- 5. The transition table  $T_{\min}$  for the minimum-state DFA is defined as follows, where [s] denotes the equivalence class containing s and a is any letter:  $T_{\min}([s], a) = [T(s, a)]$ .