## Garbage Collection

**Andrew Tolmach** 

(Slides prepared by Marius Nita.)

#### **Motivation**

Problems with manual memory management:

- ♦ It is extremely tedious and error-prone.
- ♦ It introduces software engineering issues (Who is supposed to free the memory?)
- ♦ It is by no means intrinsically efficient. (free is not free.)
- ♦ In many cases, the costs outweigh the benefits.

## Hoping to cover

- Motivation & basics
- ♦ Introduction to three families of collection algorithms:
  - Reference Counting
  - Mark & Sweep
  - Copying Collection
- Advanced issues and topics

## **Garbage Collection (GC)**

- The automatic reclamation of unreachable memory (aka garbage).
- Universally used for high level languages with closures and complex data structures that are allocated implicitly.
- Useful for any language that supports heap allocation.
- It removes the need for explicit deallocation (no more delete and free).
- ♦ Let the GC implementor deal with memory corruption issues once and for all.

#### How does it work?

#### Typically:

- ♦ The user program (mutator) is linked against a library known as the runtime system (RTS) (e.g. libc).
- ♦ In the RTS resides the memory allocation service, which exposes an allocation routine to the user program.
- ♦ When the user program desires more memory, it invokes the allocation routine (e.g. malloc).
- ♦ The allocation service may then perform a collection to free unused memory before the allocation routine returns.

**Terminology** 

Heap: A directed graph whose nodes are dynamically allocated records and whose edges are pointers between nodes. Typically laid out in a contiguous memory space.

Root set: The set of pointers **into** the heap from an external source (e.g. the stack, global variables).

Live data: The set of heap records that are **reachable** by following paths starting at members of the root set.

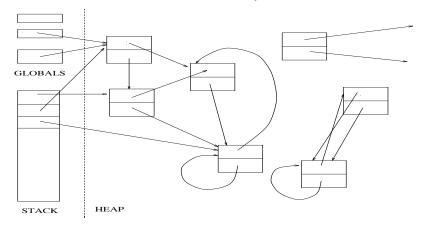
Garbage: The set of heap records that are **not** live.

Note: reachability is a conservative liveness estimate.

5

## Simple heap model

For simplicity, consider a simple heap of "cons cells:" two-field records, both fields are pointers to other records.



### Reference counting

Most straightforward collection strategy.

- Add a counter field to each record.
- Increment a record's counter when taking a new pointer to it.
- Decrement it when releasing a pointer to it.
- ♦ When it reaches 0, put the record on a free list.
- When allocating a new record, check the free list first.

## Reference counting

- simple, easy to understand and implement
- immediate reclamation of storage: no extended periods of time in which the collector might be running while the mutator waits

### Reference counting

- simple, easy to understand and implement
- immediate reclamation of storage: no extended periods of time in which the collector might be running while the mutator waits

However,

9

#### 0-2

## Reference counting

- simple, easy to understand and implement
- immediate reclamation of storage: no extended periods of time in which the collector might be running while the mutator waits

#### However,

- space overhead (extra field per record)
- speed overhead (every pointer assignment is wrapped in counter operations and checks)
- too simple-minded (can't collect cyclic garbage)

## Stop & Collect

There is no need to get rid of garbage if you do not need more space.

A better approach is to wait until the allocator fails to allocate new memory due to lack of space. Then,

- ♦ The collector takes over and frees enough memory to satisfy the allocation request.
- ♦ The allocation now succeeds (or we're out of memory).
- Control is returned to the mutator.

This is known as stop & collect; mutator is effectively paused while the collector runs.

## Mark & Sweep

#### Two phases:

- 1. Mark each live record by tracing all pointers starting at the root.
- 2. Sweep unmarked records (garbage) onto a free list, making them available for reuse. Unmark marked cells at the same time.

Already marked records are ignored in the marking step, so termination is guaranteed.

11

## **M&S: implementation**

## **M&S: implementation**

```
struct cell {
  int mark:1;
  struct cell *c[2];
};
struct cell *free, heap[HEAPSIZE], *roots[ROOTS];
```

Initially all cells are on free list. Use c[0] to link members of free list.

```
void init_heap() {
  for (i=0; i < HEAPSIZE-1; i++)
    heap[i].c[0] = &(heap[i+1]);
  heap[HEAPSIZE-1].c[0] = 0;
  free = &(heap[0]);
}</pre>
```

12

## **M&S: implementation**

```
void gc() {
                                 void sweep() {
 for (i=0; i<ROOTS; i++)</pre>
                                    for (i=0; i<HEAPSIZE; i++)</pre>
    mark(roots[i]);
                                      if (heap[i].mark)
                                        /* unmark live data */
  sweep();
                                        heap[i].mark = 0;
void mark(struct cell *cell)
                                        /* sweep garbage */
                                        heap[i].c[0] = free;
  if (!cell->mark) {
                                        free = &(heap[i]);
    cell->mark = 1;
    mark(cell->c[0]);
                                  }
    mark(cell->c[1]);
```

## **M&S: implementation**

```
void gc() {
                                 void sweep() {
  for (i=0; i<ROOTS; i++)</pre>
                                    for (i=0; i<HEAPSIZE; i++)</pre>
    mark(roots[i]);
                                      if (heap[i].mark)
                                        /* unmark live data */
  sweep();
                                        heap[i].mark = 0;
void mark(struct cell *cell)
                                        /* sweep garbage */
                                        heap[i].c[0] = free;
  if (!cell->mark) {
                                        free = &(heap[i]);
    cell->mark = 1:
    mark(cell->c[0]);
    mark(cell->c[1]);
```

Notice anything "strange" about mark?

14-a

## **Copying collection**

- Divide the heap into two semi-spaces.
- ♦ Allocate into one space (the to-space).
- When it fills up, move the live data to the from-space and reverse the roles of the two spaces.
- Must reassign all pointers as a consequence. (Can't have a copying collector for C!)
- Inherently compacting no fragmentation problems, good spatial locality.

## **M&S:** pointer reversal

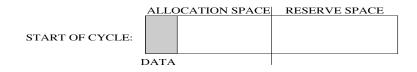
#### It's recursive!

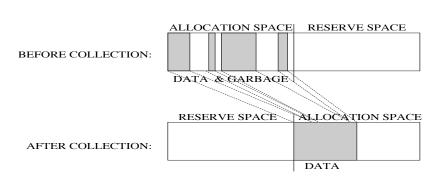
```
void mark(struct cell *cell)
{
   if (!cell->mark) {
     cell->mark = 1;
     mark(cell->c[0]);
     mark(cell->c[1]);
  }
}
```

It could use a **lot** of stack, hence a lot of memory!

A trick called **pointer reversal** can be used to avoid this problem.

## Copying (cont'd)

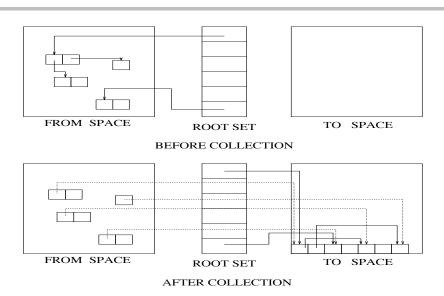




## Copying (cont'd)

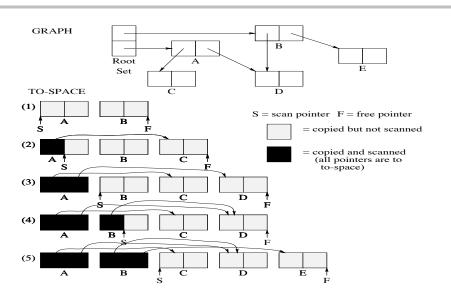
- ♦ The live data is traversed breadth-first using the to-space itself as the queue (Cheney's algorithm).
- When a record is copied, a forwarding pointer pointing to the new location is left in the original.
- Subsequent attempts to forward that same record will immediately observe the forwarding pointer.

## Copying (cont'd)



18

## **Copying: details**



# **Copying: implementation**

19

```
struct cell *allocate() {
struct cell {
  struct cell *c[2];
                                      if (free == end) {
                                        /* no room */
                                        gc();
struct cell space[2][HALFSIZE];
                                        if (free == end)
struct cell *roots[ROOTS];
                                          /* still no room */
struct cell *free =
                                          die():
                &(space[0][0]);
                                      };
struct cell *end =
                                      return free++;
         &(space[0][HALFSIZE]);
int from_space = 0;
int to_space = 1;
```

## **Copying: implementation**

```
gc() {
  int i;
  struct cell *scan = &(space[to_space][0]);
  free = scan;
  for (i = 0 ; i < ROOTS; i++)
    roots[i] = forward(roots[i]);
  while (scan < free) {
    scan->c[0] = forward(scan->c[0]);
    scan->c[1] = forward(scan->c[1]);
    scan++;
  };
  from_space = 1-from_space;
  to_space = 1-to_space;
  end = *(space[from_space][HALFSIZE]);
}
```

# **Copying: implementation**

```
struct cell *forward(struct cell *p) {
   if (p >= &(space[from_space][0]) &&
        p < &(space[from_space][HALFSIZE]))
   {
      if (p->c[0] >= &(space[to_space][0]) &&
            p->c[0] < &(space[to_space][HALFSIZE]))
        return p->c[0];
   else {
      *free = *p;
      p->c[0] = free++;
      return p->c[0];
   }
} else return p;
```

22

#### **Conclusions: M&S**

#### Pros:

- ♦ Big win is that it can use the whole heap for allocation.
- Works well in systems with large amounts of live data many long lived objects.

#### Cons:

- ♦ Fragmentation is a real problem.
- Allocation can be expensive in a heavily fragmented heap.
- Potential spatial locality issues, bad cache behavior.

### **Conclusions: Copying**

#### Pros:

- Simple to understand and implement.
- Allocation is very fast: contiguous free memory.
- Good locality, favorable effect on cache behavior.

#### Cons:

- ♦ It can use only half the heap space for allocation a real concern in systems with limited memory.
- Poor performance in systems with large amounts of live data.

## **Further Issues**

- Distinguishing pointers from integers.
- ♦ Handling records of various sizes, arrays.
- ♦ Finding and passing the root set.
- ♦ Avoiding unnecessary scanning of long-lived data.
- Minimizing collection pauses.
- ♦ Improving memory utilization.

These lead to study of other varieties of collectors: conservative, generational, incremental, compacting, etc.