

CS321 Languages and Compiler Design I

Fall 2010

Lecture 14

SYNTAX-DIRECTED TYPE CHECKING

Consider a simple language of declarations, statements, and expressions.

$$P \rightarrow D ; S \quad \{ S.env = D.env; \}$$

Actions for declarations synthesize environment attributes:

$$D \rightarrow \epsilon \quad \{ D.env := empty \}$$

$$D \rightarrow id : T_1 ; D_1 \quad \{ D.env := extend(D_1.env, binding(id, T_1.type)) \}$$

$$T \rightarrow bool \quad \{ T.type := boolean \}$$

$$T \rightarrow int \quad \{ T.type := integer \}$$

$$T \rightarrow array \text{ of } T_1 \quad \{ T.type := array(T_1.type) \}$$

$$T \rightarrow pair \ T_1 \ T_2 \quad \{ T.type := T_1.type \times T_2.type \}$$

EXPRESSIONS

Actions for expressions **check** for compatible operands and **synthesize** attribute type:

$E \rightarrow \text{num}$	$\{ E.type := integer \}$
$E \rightarrow \text{id}$	$\{ E.type := \text{lookup}(E.env, \text{id}) \}$
$E \rightarrow (E_1, E_2)$	$\{ E_1.env = E.env; E_2.env = E.env; E.type = E_1.type \times E_2.type \}$
$E \rightarrow E_1 \text{ div } E_2$	$\{ E_1.env = E.env; E_2.env = E.env;$ <i>if not</i> $(E_1.type = integer \text{ and } E_2.type = integer)$ <i>then</i> <i>issue type error;</i> $E.type := integer \}$
$E \rightarrow E_1 \text{ or } E_2$	$\{ E_1.env = E.env; E_2.env = E.env;$ <i>if not</i> $(E_1.type = boolean \text{ and } E_2.type = boolean)$ <i>then</i> <i>issue type error;</i> $E.type := boolean \}$

Issuing error might or might not stop the checking process. If it doesn't, try to choose a synthesized type value that prevents a cascade of messages from a single mistake.

MORE EXPRESSIONS

$E \rightarrow E_1 [E_2]$ $\{ E_1.env = E.env; E_2.env = E.env;$
 if $(E_1.type = array(T) \text{ and } E_2.type = integer)$ *then*
 $E.type := T;$
 else issue type error $\}$

$E \rightarrow E_1.fst$ $\{ E_1.env = E.env;$
 if $E_1 = T_1 \times T_2$ *then*
 $E.type := T_1;$
 else issue type error;

$E \rightarrow E_1 < E_2$ $\{ E_1.env = E.env; E_2.env = E.env;$
 if not $(E_1.type = integer \text{ and } E_2.type = integer)$ *then*
 issue type error;
 $E.type := boolean \}$

$E \rightarrow E_1 = E_2$ $\{ E_1.env = E.env; E_2.env = E.env;$
 if not $((E_1.type = boolean \text{ or } E_1.type = integer)$
 and $E_1.type = E_2.type)$ *then*
 issue type error;
 $E.type := boolean \}$

CHECKING STATEMENTS

In most languages, statements don't have a type, so no point in synthesizing an attribute. Actions just check component types:

$$\begin{aligned} S \rightarrow \text{id} := E_1 & \quad \{ E_1.\text{env} = S.\text{env}; \\ & \quad \text{if } E_1.\text{type} \neq \text{lookup}(S.\text{env}, \text{id}) \text{ then} \\ & \quad \text{issue type error} \} \\ & \quad (\text{Must also check that id is an l-value} \\ & \quad \text{that can be assigned into.}) \\ S \rightarrow \text{if } E_1 \text{ then } S_1 & \quad \{ E_1.\text{env} = S.\text{env}; S_1.\text{env} = S.\text{env}; \\ & \quad \text{if } E_1.\text{type} \neq \text{boolean} \text{ then} \\ & \quad \text{issue type error} \} \\ S \rightarrow S_1 ; S_2 & \quad \{ S_1.\text{env} = S.\text{env}; S_2.\text{env} = S.\text{env}; \} \end{aligned}$$

PROCEDURE/FUNCTION DEFINITIONS AND CALLS

Can describe type of function as $type_1 \times type_2 \times \dots \times type_n \rightarrow type$

$D \rightarrow id (F_1) : T_1 ; D_1 \quad \{ D.env := extend(D_1.env, binding(id, F_1.type \rightarrow T_1.type)) \}$

$F \rightarrow id : T_1 \quad \{ F.type := T_1.type \}$

$F \rightarrow id : T_1 , F_1 \quad \{ F.type := T_1.type \times F_1.type \}$

$E \rightarrow id (A_1) \quad \{ A_1.env = E.env;$
 if $lookup(E.env, id) = T_1 \rightarrow T_2$ *then*
 if $A_1.type \neq T_1$ *then*
 issue type error
 $E.type := T_2$
 else
 issue type error $\}$

$A \rightarrow E_1 \quad \{ E_1.env = A.env;$
 $A.type := E_1.type \}$

$A \rightarrow E_1 , A_1 \quad \{ E_1.env = A.env;$
 $A.type := E_1.type \times A_1.type \}$

TYPE CONVERSIONS

Implicit conversions (or “**coercions**”) occur as a result of applying semantic rules of the language, e.g., perhaps evaluating $r + i$, where r is a real and i is an integer, causes implicit conversion of the fetched value of i to a real before the addition. This complicates type-checking:

$$E \rightarrow E_1 + E_2 \quad \{ E_1.env = E.env; E_2.env = E.env; \\ \text{case } (E_1.type, E_2.type) \text{ of} \\ \quad (integer, integer): E.type := integer \\ \quad (integer, real): \\ \quad (real, integer): \\ \quad (real, real): E.type := real \\ \quad otherwise: \text{issue type error} \}$$

The relationship between integer and real is a special case of **subtyping** (more later).

TYPE EQUIVALENCE

When do two identifiers have the “same” type, or “compatible” types?

E.g., if a has type t_1 , b has type t_2 and f has type $t_2 \rightarrow t_3$, how must t_1 and t_2 be related for these to make sense?

```
a := b  
f (a)
```

To maintain **type safety** we must insist at a minimum that t_1 and t_2 are **structurally equivalent**.

Structural equivalence is defined inductively:

- Primitive types are equivalent iff they are exactly the same type.
- Cartesian product types are equivalent if their corresponding component types are equivalent. (Record field names are typically ignored.)
- Disjoint union types are equivalent if their corresponding component types are equivalent.
- Mapping types (arrays and functions) are the same if their domain and range types are the same.

EQUIVALENCE (CONTINUED)

Another way to say this: two types are equal if they have the same set of values.

Recursive types are a challenge. Are these two types structurally equivalent?

```
type t1 = { a:int, b: POINTER TO t1 };  
type t2 = { a:int, b: POINTER TO t2 };
```

Intuitively yes, but it's (a little) tricky for a type-checking algorithm to determine this!

TYPE NAMES

Question of equivalence is more interesting if language has type **names**, which arise for two main reasons:

- As a convenient shorthand to avoid giving the full type each time. E.g.,

```
function f(x:int * bool * real) : int * bool * real = ...
type t = int * bool * real
function f(x:t) : t = ...
```

- As a way of improving program correctness by subdividing values into types according to their meaning **within the program**.

```
type polar = { r:real, a:real };
type rect  = { x:real, y:real };
function polar_add(x:polar,y:polar) : polar ...
function rect_add(x:rect,y:rect) : rect ...
var a:polar; c:rect;
a := (150.0,30.0) (* ok *)
polar_add(a,a)    (* ok *)
c := a            (* type error *)
rect_add(a,c)     (* type error *)
```

For this to be useful, some structurally equivalent types must be treated **as inequivalent**.

NAME EQUIVALENCE

Simplistic idea: Two types are equivalent iff they have the same **name**.

Supports polar/rect distinction.

But pure name equivalence is very restrictive, e.g.:

```
type ftemp = real
type ctemp = real
var x:ftemp, y:ftemp, z: ctemp;
x := y; (* ok *)
x := 10.0; (* probably ok *)
x := z; (* type error *)
x := 1.8 * z + 32.0; (* probably type error *)
```

Different types now seem **too** distinct; can't even convert from one form of real to another.

NAME EQUIVALENCE (CONTINUED)

Also: what about unnamed type expressions?

```
type t = int * int
procedure f(x: int * int) = ...
procedure g(x: t) = ...
var a:t = (3,4)
g(a); (* ok *)
f(a); (* ok or not ?? *)
```

Because of these problems with pure name equivalence, most languages use **mixed** solutions.

C TYPE EQUIVALENCE

C uses structural equivalence for array and function types, but name equivalence for struct, union, and enum types. For example:

```
char a[100];  
void f(char b[]);  
f(a); /* ok */  
  
struct polar{float x; float y;};  
struct rect{float x; float y;};  
struct polar a;  
struct rect b;  
a = b; /* type error */
```

A type defined by a typedef declaration is actually just an abbreviation for an existing type.

Note that this policy makes it easy to check equivalence of recursive types, which can only be built using structs.

```
struct fred {int x; struct fred *y;} a;  
struct bill {int x; struct fred *y;} b;  
a = b; /* type error */
```

ML TYPE EQUIVALENCE

ML uses structural equivalence, except that each datatype declaration creates a new type unlike all others.

```
datatype polar = POLAR of real * real
datatype rect = RECT of real * real
val a = POLAR(1.0,2.0) and b = RECT(1.0,2.0)
if (a = b) ... (* type error *)
```

Note that the mandatory use of constructors makes it possible to uniquely identify the types of literals.

Note that a datatype need not declare a record:

```
datatype fahrenheit = F of real
datatype celsius = C of real
val a = F 150.0 and b = C 150.0
if (a = b) ... (* type error *)
fun convert(F x) = C(1.8 * x + 32.0) (* ok *)
```

For type abbreviation, ML offers the `type` declaration, which simply gives a new name for an existing type.

```
type centigrade = celsius
fun g(x:centigrade) = if x = b ... (* ok *)
```

JAVA TYPE EQUIVALENCE

Java uses nearly strict name equivalence, where names are either:

- One of eight built-in **primitive** types (`int`, `float`, `boolean`, etc.), or
- Declared classes or interfaces (**reference** types).

The only non-trivial type expressions that can appear in a source program are **array** types, which are compared structurally, using name equivalence for the ultimate element type. Java has no mechanism for type abbreviations.

Java types form a **subtyping** hierarchy:

- If class A extends class B , then A is a subtype of B .
- If class A implements interface I , then A is a subtype of I .
- If numeric type τ can be coerced to numeric type u without loss of precision, then τ is a subtype of u .

If T_1 is a subtype of T_2 , then a value of type T_1 can be used wherever a value of T_2 is expected.