CS321 Languages and Compiler Design I Winter 2012 Lecture 14a

RECORD SUBTYPING

Can be structural or nominal (just like type equivalence).

Basic **structural** rule is:

$$\frac{R_1 \text{ has all the fields of } R_2 \text{ and maybe more}}{R_1 \lhd R_2}$$

(Depending on how record accesses are implemented, the extra fields in R_1 may need to be added at the end of the record to ensure safety.)

Under **nominal** equivalence, we require the record subtyping relation to be explicitly declared. E.g. in **fab**, given these declarations:

we have $C \triangleleft B$ and $B \triangleleft A$.

Don't get confused: B is a **subtype** of A even though a B value has **more** fields than an A value.

DEFININING SUBTYPING

We write $T \triangleleft U$ for "T is a subtype of U."

The intended meaning is that a value of type T may be used wherever a valud of type U is needed.

We can describe valid subtyping using inference rules.

Fundamental rules:

$$\overline{T \triangleleft T}$$

$$\frac{T \lhd U \quad U \lhd W}{T \lhd W}$$

Typical subtyping rules for primitive types:

and others, depending on language.

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MORE STRUCTURAL SUBTYPING RULES

Pairs

Given immutable pair types $T_1 \times T_2$, whose values are constructed with (e_1, e_2) and dereferenced with e.fst and e.snd, we have this **covariant** rule:

$$\frac{T_1 \lhd U_1 \quad T_2 \lhd U_2}{T_1 \times T_2 \lhd U_1 \times U_2}$$

Functions

Given function types of the form $T_1 \times T_2 \times \ldots \times T_n \to T$, we have

$$\frac{U_1 \lhd T_1 \quad U_2 \lhd T_2 \quad \dots \quad U_n \lhd T_n \qquad \quad T \lhd U}{T_1 \times T_2 \times \dots \times T_n \to T \lhd U_1 \times U_2 \times \dots \times U_n \to U}$$

This rule is **covariant** on the result type but **contravariant** on the argument types.

FUNCTION SUBTYPING EXAMPLES

To see why the function rule is appropriate, consider the following **fab** code fragments (with the definitions of A,B,C above):

```
func f (g : B -> B) {
   var b0 : B = B {a = 100, b = true};
   var b1 = g (b0);
   if b1.b then ... else ...}

func g1 (x:A) : C {
   if x.a = 0 then ... else ...;
   return C {a = 100, b = true, c = 3.14} }

func g2 (x:C) : B { if x.c > 2.71 then ... else ...;
   }

func g3 (x:B) : A { return A {a = 100} }
```

The call f(g1), which is legal (matches the subtyping rule), works fine. The call f(g2), which illegally treats the argument as covariant, fails because f passes a B (rather than a C) to g2, so the lookup x.c fails. The call f(g3), which illegally treats the result as contravariant, fails because g3 returns only an A (rather than a B) to f, so the lookup b1.b fails.

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SUBTYPING ARRAYS (CONTINUED)

Clearly we cannot let subtyping be **contravariant** in T: if it were, the call f(za) would be legal, but it would fail when f tries to look up the b component.

But also, we cannot let subtyping be **covariant** in T. If it were, the sequence

```
g(zc);
if (zc[0].c > 2.71) then ... else ...
```

would be legal. But this sequence fails because g updates the 0'th element of zc to contain a B rather than a C; after the return the lookup of zc [0] . c fails.

Note that Java actually **does** permit covariant subtyping of arrays. To avoid safety problems, every store into an array (of reference types) – such as the assignment in g – is checked at **runtime** to ensure that the stored value is of the same type as the array. So in this example, calling g(zc) would pass the type checker but generate a checked runtime error (exception).

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SUBTYPING ARRAYS

For the **fab** array types @T (i.e. array of T), the safe structural subtyping rule is:

$$\overline{\mathbf{Q}T \lhd \mathbf{Q}T}$$

This rule is **invariant** on the array element type.

To see why neither covariance nor contravariance is appropriate, consider the following **fab** fragments (with the definitions of A,B,C above):

```
func f (x: @B) { if x[0].b then ... }

func g (x: @B) { x[0] = B{a = 10, b = true} }

var wa = A {a = 10};

var za = @A {1 of wa};

var wc = C {a = 10, b = true, c = 3.14};

var zc = @C {1 of wc}
```

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